

An introduction to deciding higher-order matching

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Methods for verifying finite and infinite state systems

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- ▶ model checking + equivalence checking
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- ▶ Equivalence checking: is state s equivalent to t ?
- ▶ Mostly computing dyadic fixed points e.g. bisimulations to solve it. May need algebraic/combinatorial properties of reachability sets/generators of graph

Active research goal: transfer these techniques to

finite/infinite state systems with **binding**

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3. \vdots \vdots \vdots
4. Application of tree automata and games to deciding higher-order matching
[Comon, Jurski 1997; Stirling 2005-2009, work described here]

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abbreviated to $(A_1, \dots, A_n, \mathbf{0})$
- ▶ order of $\mathbf{0}$ is 1;
- ▶ order of $(A_1, \dots, A_n, \mathbf{0})$ is $k + 1$ where k is maximum of orders of A_i s

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1. if x (f) has type A then $x : A \in T$ ($f : A \in T$)
2. if $t : B \in T$ and $x : A \in T$ then $\lambda x.t : A \rightarrow B \in T$
3. if $t : A \rightarrow B \in T$ and $u : A \in T$ then $(tu) : B \in T$

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- ▶ order of $t : A = \text{order } A$
- ▶ closed $t : A$ no free variables
- ▶ $t, t' : A$ are α -equivalent renamings of each other

Dynamics: reduction

$$\begin{array}{l} (\beta) \quad (\lambda x.t)v \rightarrow_{\beta} t\{v/x\} \quad \{\cdot/\cdot\} \text{ Substitution} \\ (\eta) \quad \lambda x.(tx) \rightarrow_{\eta} t \quad x \text{ not free in } t \end{array}$$

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- ▶ **Facts** Strong normalisation and confluence (of \rightarrow_{β} , \rightarrow_{η} , $\rightarrow_{\beta\eta}$)
- ▶ **Equivalence:** $t =_{\beta\eta} t'$ if there are s, s'

$$\begin{array}{l} t \rightarrow_{\beta\eta}^* s \\ t' \rightarrow_{\beta\eta}^* s' \\ \parallel_{\alpha} \end{array}$$

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 - ▶ Inf = η -long β -normal form
 - ▶ If t, v are in Inf and $tv \rightarrow_{\beta}^* s$ and s in β -normal form then s is Inf
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- No η -reductions when terms in Inf
- ▶ $T_A(C)$ is the set of closed Inf terms of type A whose constants belong to C .

Example

- ▶ $x : (\mathbf{0}, \mathbf{0}) \lambda x. x : ((\mathbf{0}, \mathbf{0}), \mathbf{0}, \mathbf{0})$ in β -normal form not Inf

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- ▶ Notation: $\lambda x_1 \dots x_k.t$ abbreviates $\lambda x_1 \dots \lambda x_k.t$
- ▶ Monster type $M = (((\mathbf{0}, \mathbf{0}), \mathbf{0}), \mathbf{0}, \mathbf{0})$, has order 5
- ▶ $\lambda xy.x(\lambda z_1.x(\lambda z_2.z_1y)) \in T_M(\emptyset)$
when $x : (((\mathbf{0}, \mathbf{0}), \mathbf{0}), \mathbf{0}, \mathbf{0})$, $z_i : (\mathbf{0}, \mathbf{0})$ and $y : \mathbf{0}$.

Decision questions

- ▶ Higher-order unification
- ▶ $v = u$ contains free variables x_1, \dots, x_n
- ▶ Solution $\theta = \{t_1/x_1, \dots, t_n/x_n\}$ such that $v\theta =_{\beta\eta} u\theta$
Simultaneous substitution

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Simultaneous substitution
- ▶ Decision question: given $v = u$, does it have a solution ?
- ▶ Order is max order of the x_i s
- ▶ Undecidable (even at order 2) [Huet 1972; Goldfarb 1981]

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- ▶ Higher-order matching
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- ▶ Decidable for all orders [Stirling 2006; 2009]

Matching is essentially monadic

- ▶ Given $v = u$ with $x_1 : A_1, \dots, x_n : A_n$ in v
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where $x : ((A_1, \dots, A_n, \mathbf{0}), \mathbf{0})$
- ▶ Conceptually simpler problem: just one free variable
- ▶ Called "interpolation": $x w_1 \dots w_k = u$
where $x : (B_1, \dots, B_k, \mathbf{0}), w_i : B_i, u : \mathbf{0}$ in Inf.
- ▶ Solution t in Inf such that $tw_1 \dots w_k \rightarrow_{\beta}^* u$

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- ▶ Canonical solution $\lambda z. z t_1 \dots t_n$ where t_j s are closed
Consequently $v\{t_1/x_1, \dots, t_n/x_n\} \rightarrow_{\beta}^* u$
So, $\theta = \{t_1/x_1, \dots, t_n/x_n\}$ solves $v = u$
Reduces matching to interpolation

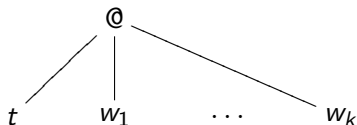
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- ▶ Restrict constants in solution terms to be those in u plus fresh
 $b : \mathbf{0}$ Restricts to finitely many constants

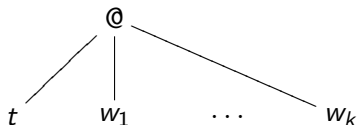
Interpolation trees

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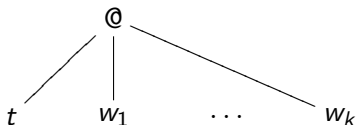
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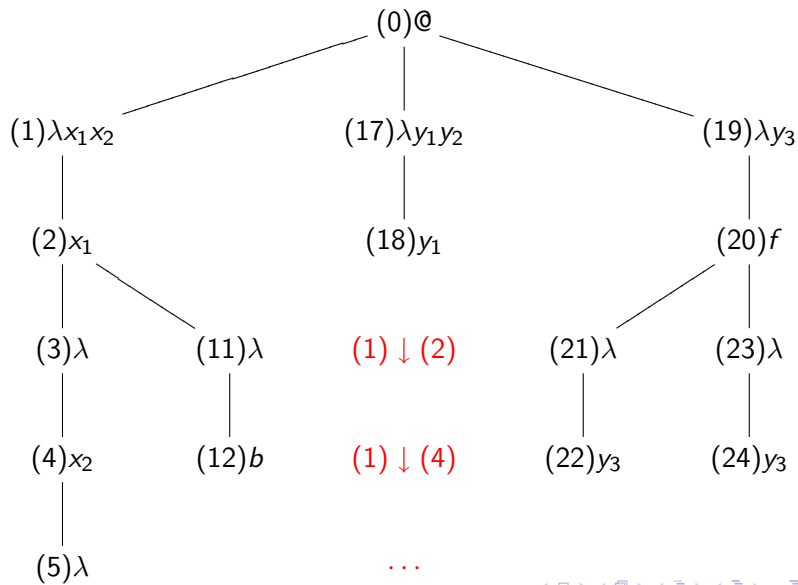
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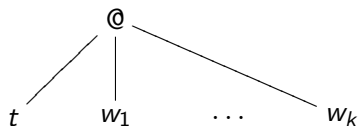


- ▶ Goal: understand the reduction of $tw_1 \dots w_k$ to normal form by only examining the interpolation tree
- ▶ t, w_1, \dots, w_k binding trees with dummy lambdas and binding relation \downarrow between nodes
- ▶ $n \downarrow m$ if n labelled $\lambda \bar{y}$ binds y_j , label at m

Example: $x(\lambda y_1 y_2 . y_1)(\lambda y_3 . f y_3 y_3) = faa$

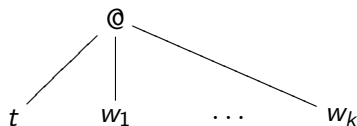


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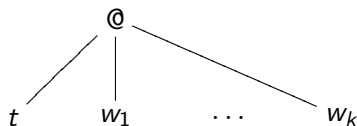
► Tree automaton

Finite sets: states Q , alphabet Σ , final states $F \subseteq Q$,

transitions Δ of form $sq_1 \dots q_k \Rightarrow q$,

$k \geq 0$, $s \in \Sigma$, $\text{arity}(s) = k$ and $q, q_i \in Q$

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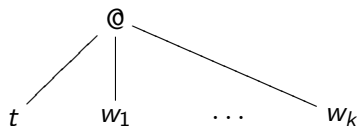
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- ▶ Using transitions label tree bottom-up with states
 - Automaton accepts tree iff root can be labelled with a final state
- ▶ Non-emptiness decidable; sets recognised are regular

Tree automata for 4th-order [Comon, Jurski 97]

- ▶ 4th-order E , $xw_1 \dots w_k = u$ and C_E constants in u plus b
- ▶ For finite alphabet Σ consider a potential solution term
 $t = \lambda x_1 \dots x_k . s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C_E, m \geq 0$$
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- ▶ Guarantees finite alphabet for accessible nodes: reuse variables

Tree automata for 4th-order [Comon, Jurski 97] II

► **Finite states:**

inaccessible nodes: – for “dont care”

accessible nodes: U is subterms of u closed under replacement of subtrees with finitely many $z_j^i : \mathbf{0}$

$$\{[e], [\lambda e], [\lambda z_1^n \dots z_m^n e], [\lambda x_1 \dots x_k u] \mid e \in U \cup \{-\}\}$$

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$$\begin{array}{l} z \Rightarrow [z] \quad z \Rightarrow [-] \quad a \Rightarrow [a] \quad c \Rightarrow [-] \\ \lambda x_1 [ga] \Rightarrow [\lambda x_1 ga] \quad x_1 [\lambda -][\lambda gz] \Rightarrow [gz] \\ \dots \end{array}$$

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- ▶ **Theorem** The tree automaton associated with a 4th-order $xw_1 \dots w_k = u$ accepts t iff t solves $xw_1 \dots w_k = u$

Tree automata for 5th-order: PROBLEMS

- ▶ **Finite alphabet ?** can stack 2nd-order variables

$\lambda xy.x(\lambda z_1.x(\lambda z_2.\dots(\lambda z_n.z_n(z_{n-1}(\dots z_1(y))\dots))\dots))$

Need an infinite alphabet

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Number of evaluations can be infinite

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↓ from the first node labelled λz to the last node labelled z ,
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Fact For all A and finite C , there is a finite Σ such that every $t \in T_A(C)$ up to α -equivalence is a binding Σ -tree.

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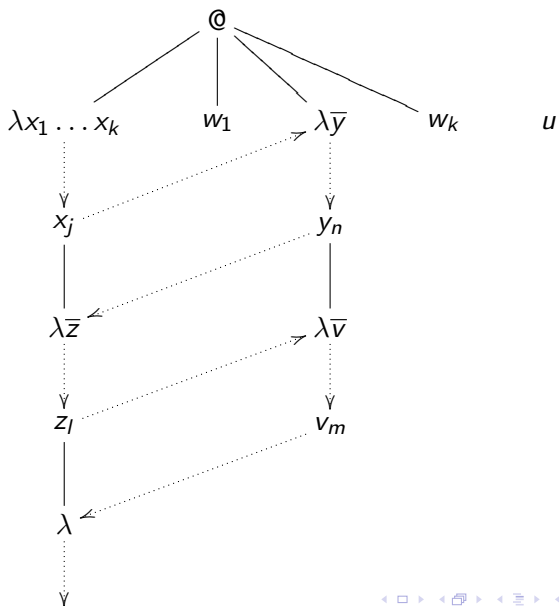
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- ▶ **Second problem ?** need finer analysis than evaluation of an accessible node

Games: automaton moving around interpolation tree



Game/automaton $G(t, E)$

- ▶ Play: sequence $n_1q_1\theta_1, \dots, n_lq_l\theta_l$
 - ▶ n_i is a node of the interpolation tree,
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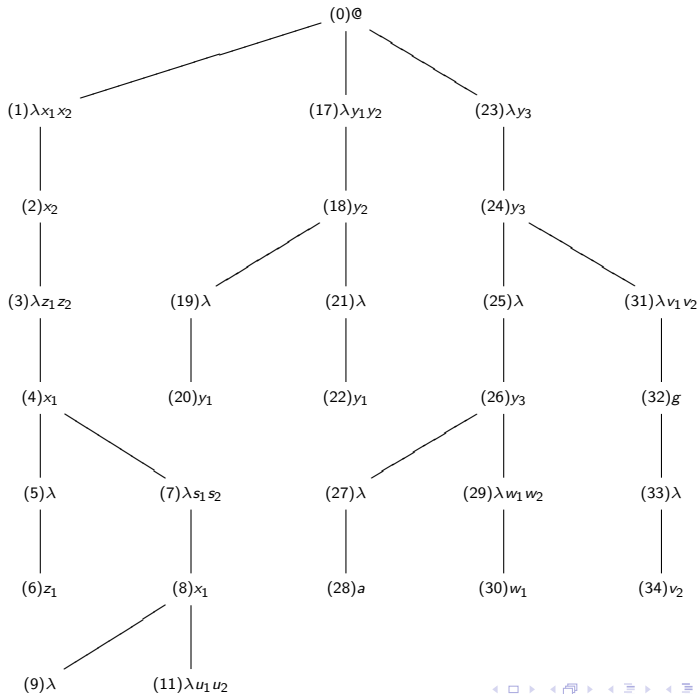
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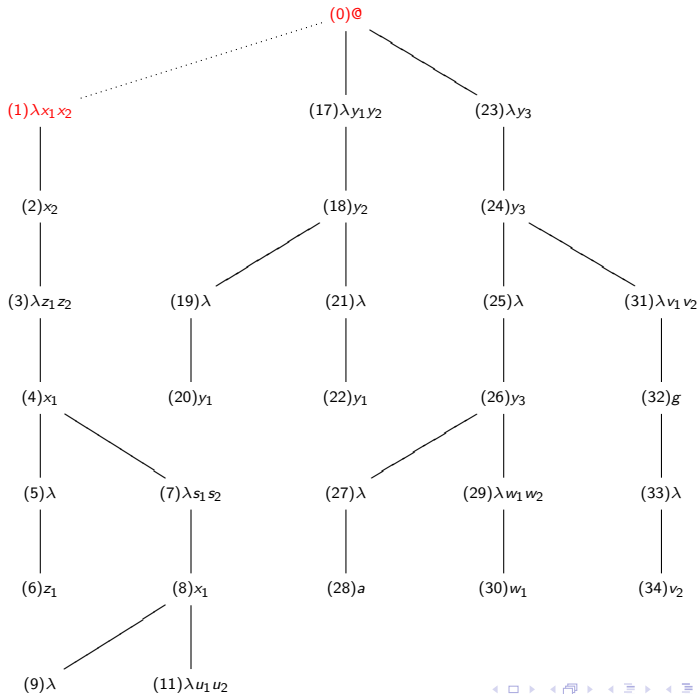
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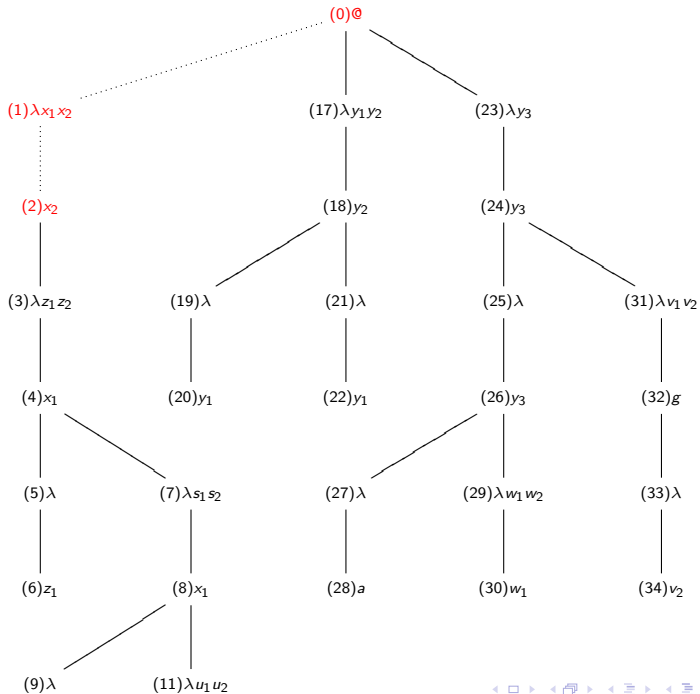
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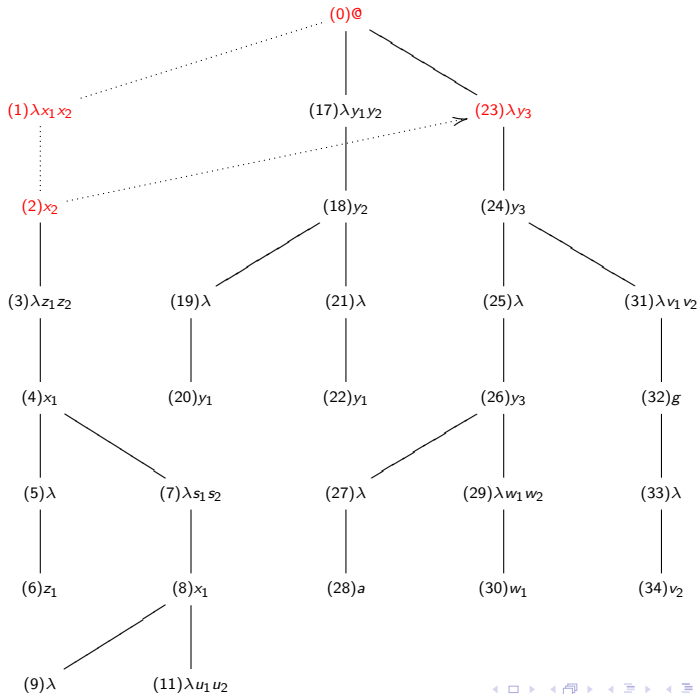
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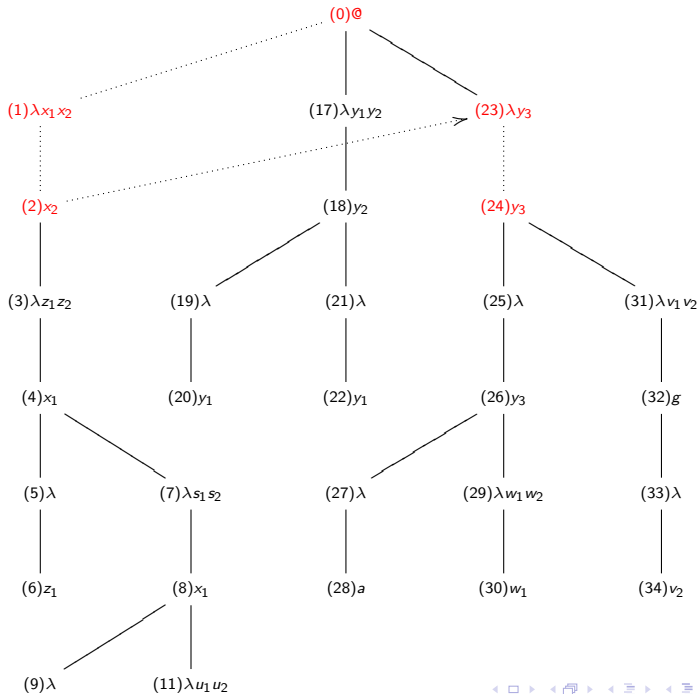
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- ▶ Player \forall loses every play in $G(t, E)$ iff t solves E

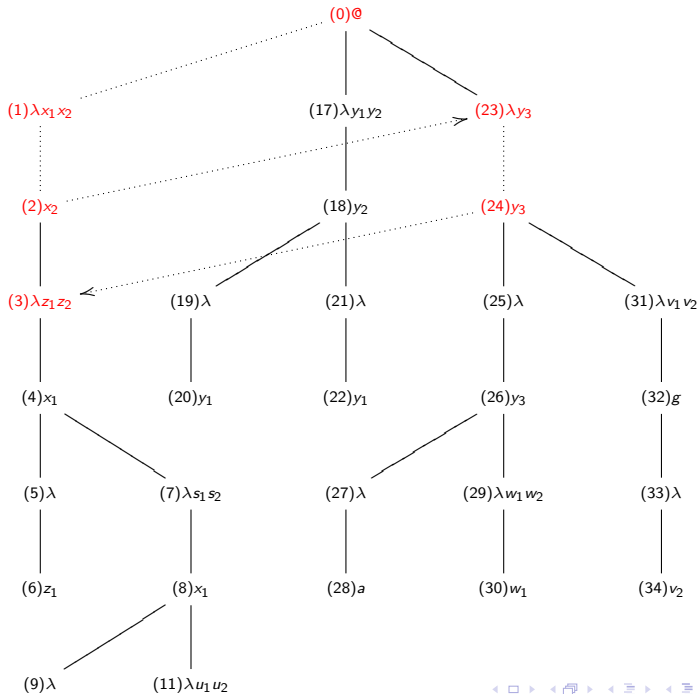


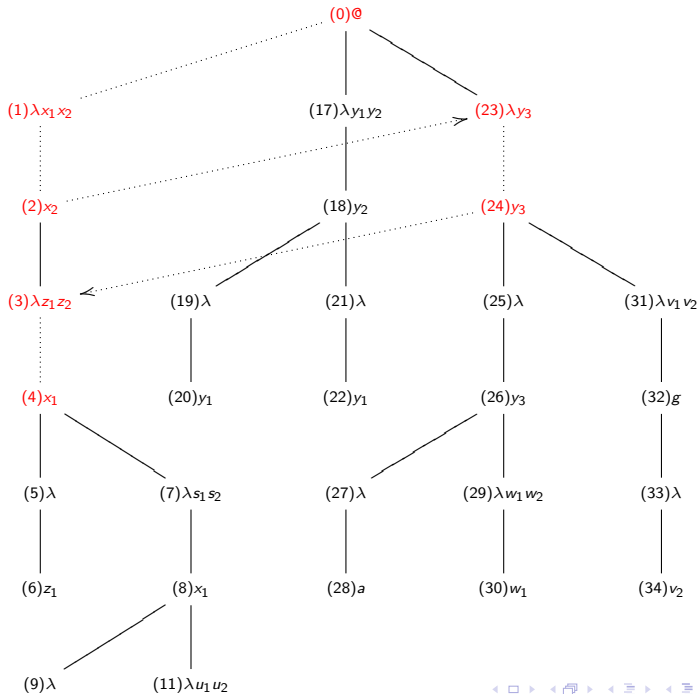


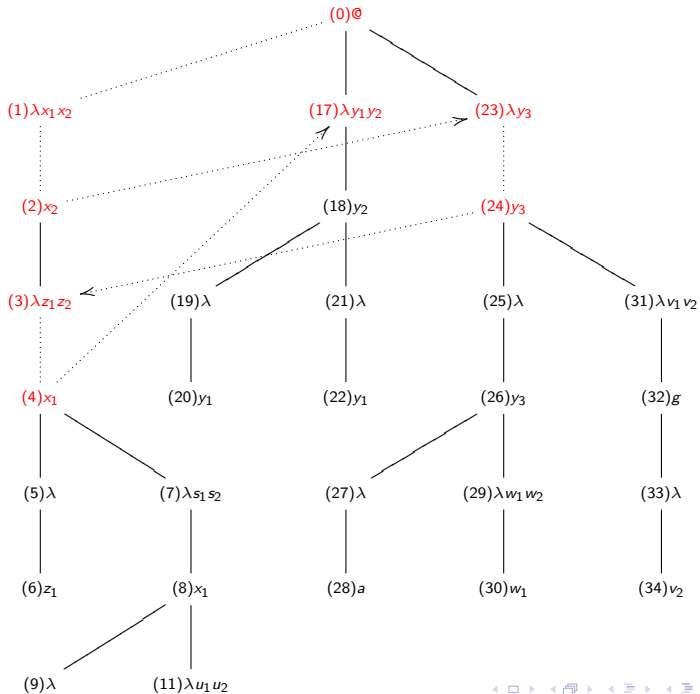


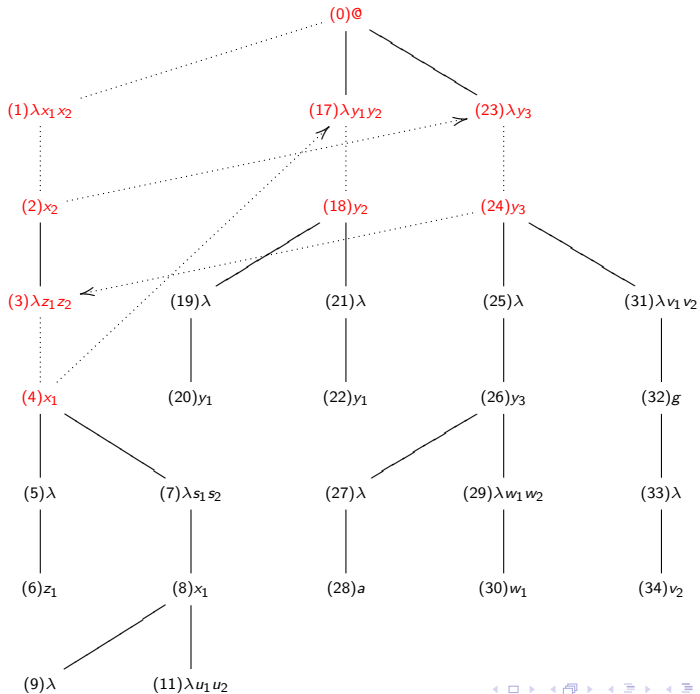


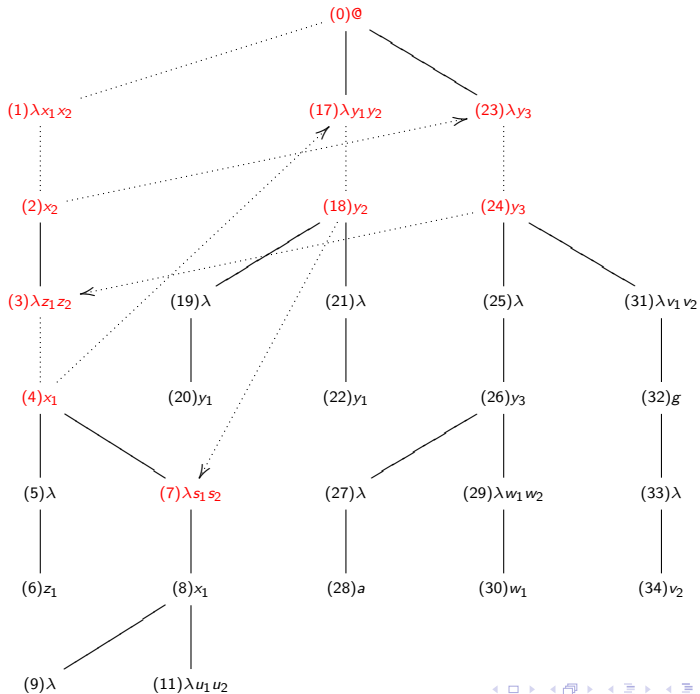


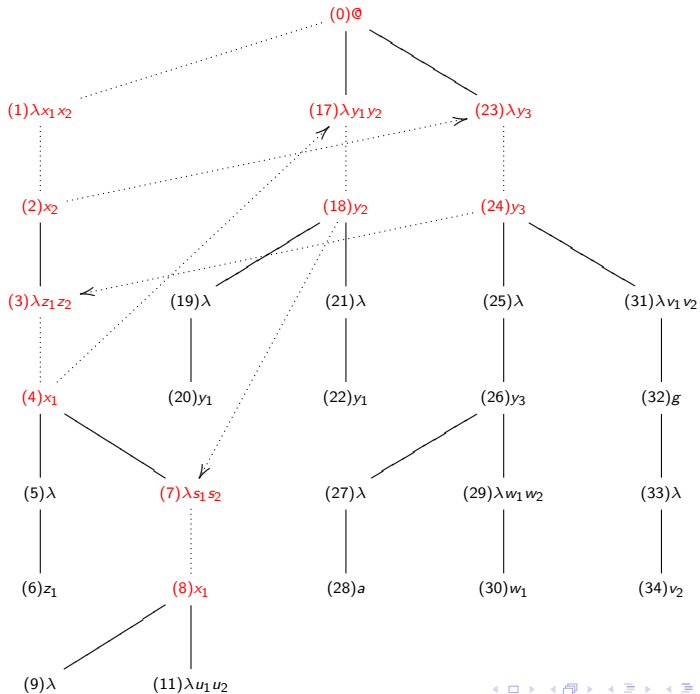


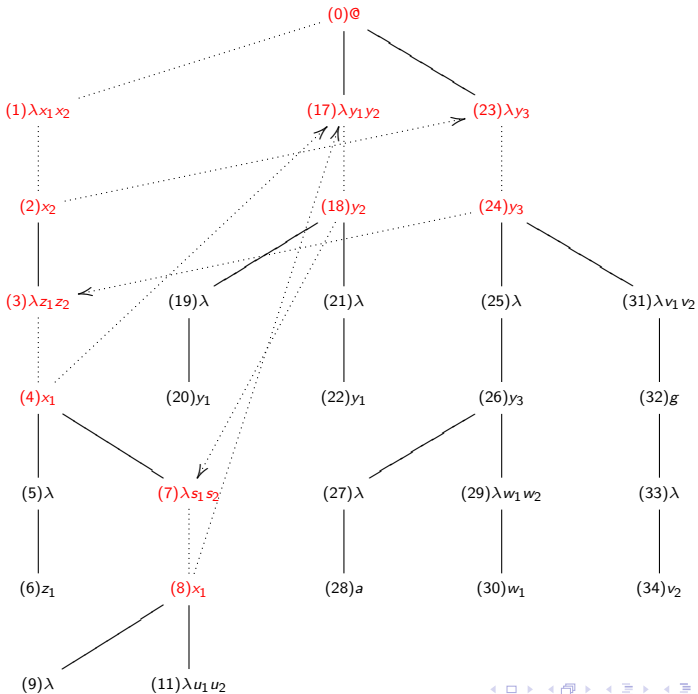


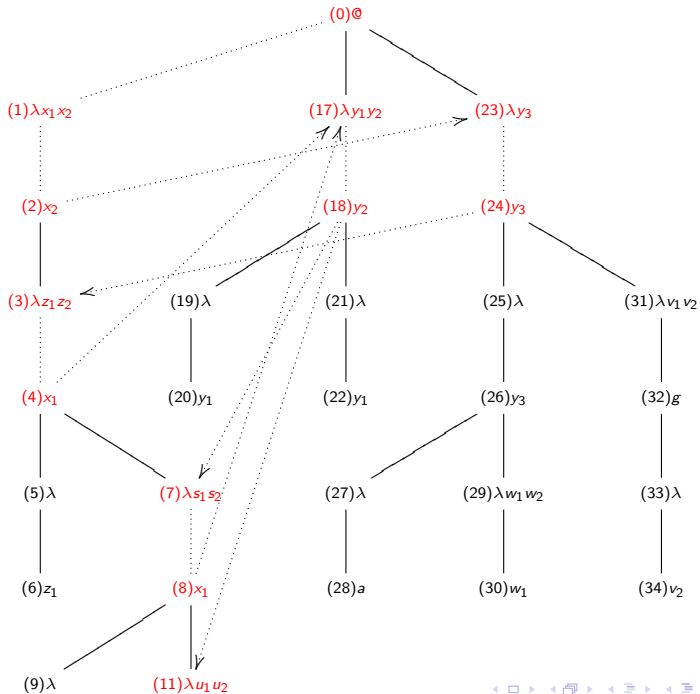












Application of games to define tree automata

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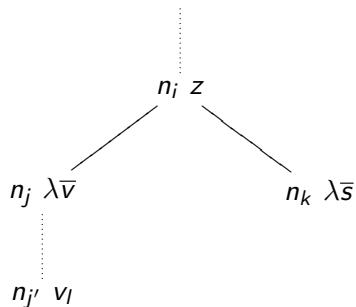
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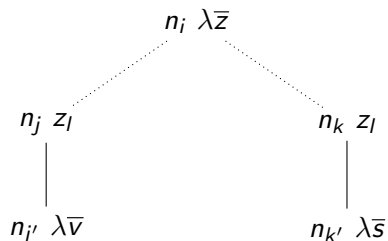
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Uniformity properties of game playing I



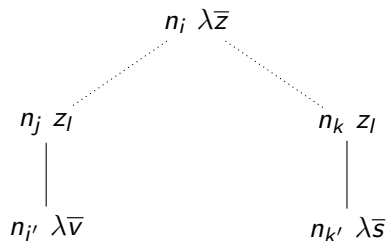
- ▶ If play is at n_i then at n_j and then later at n_k then inbetween there must have been a position at an $n_{j'}$ bound by n_j

Uniformity properties of game playing II



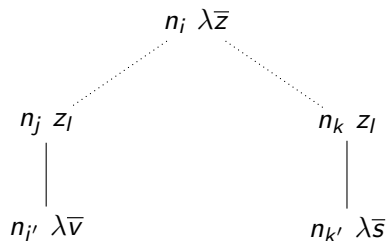
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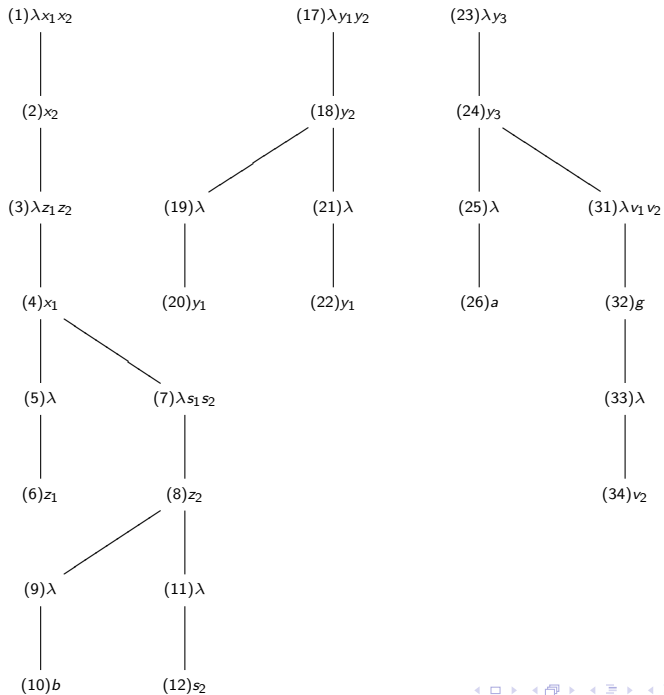
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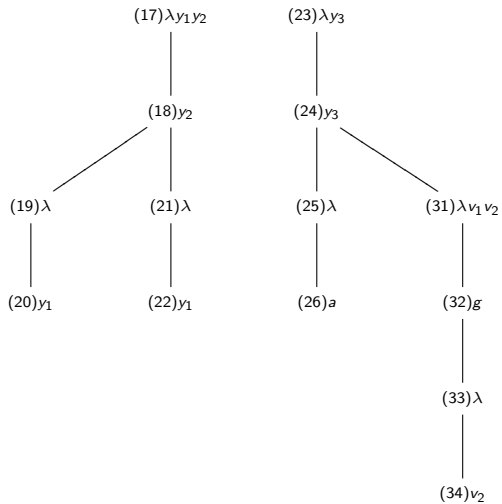
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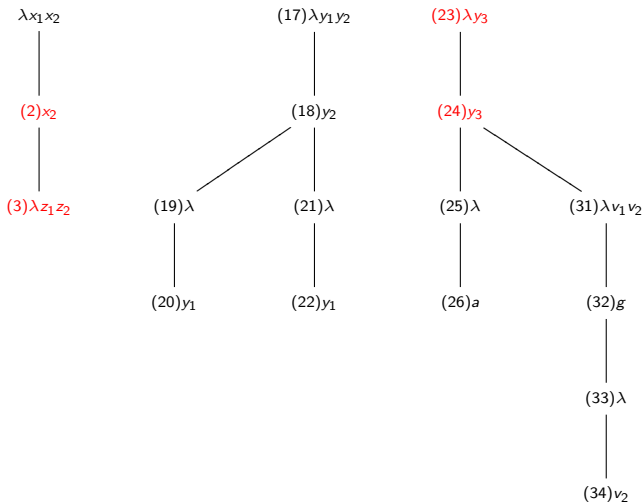
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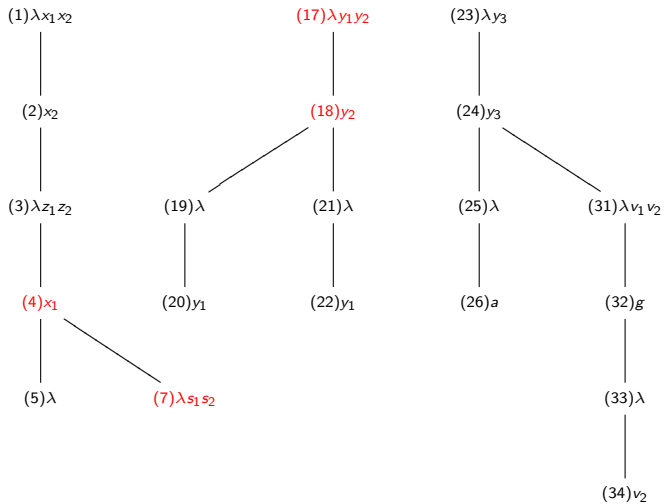
$$x(\lambda y_1 y_2 . y_2 y_1 y_1)(\lambda y_3 . y_3 a(\lambda v_1 v_2 . g v_2)) = ga$$

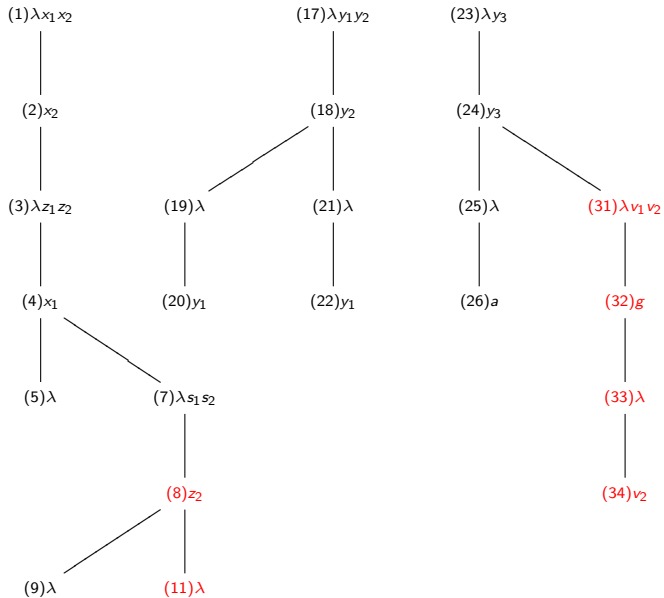


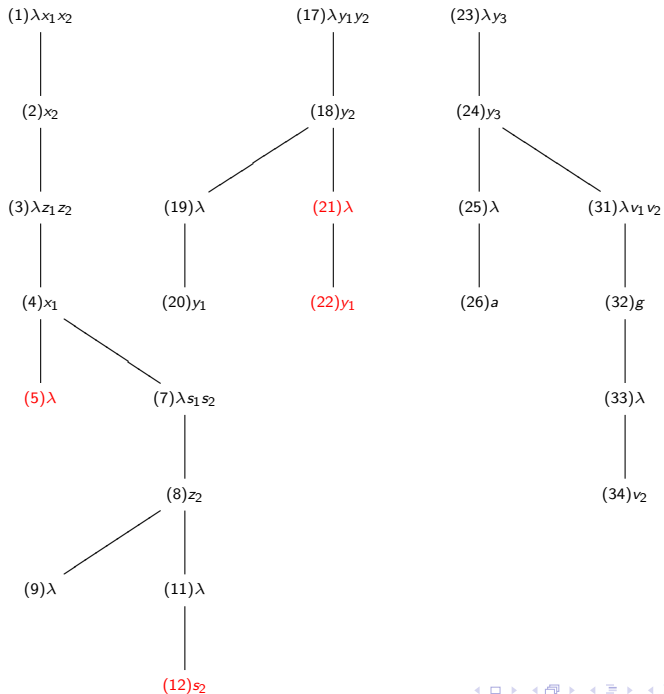
(1) $\lambda_{x_1 x_2}$

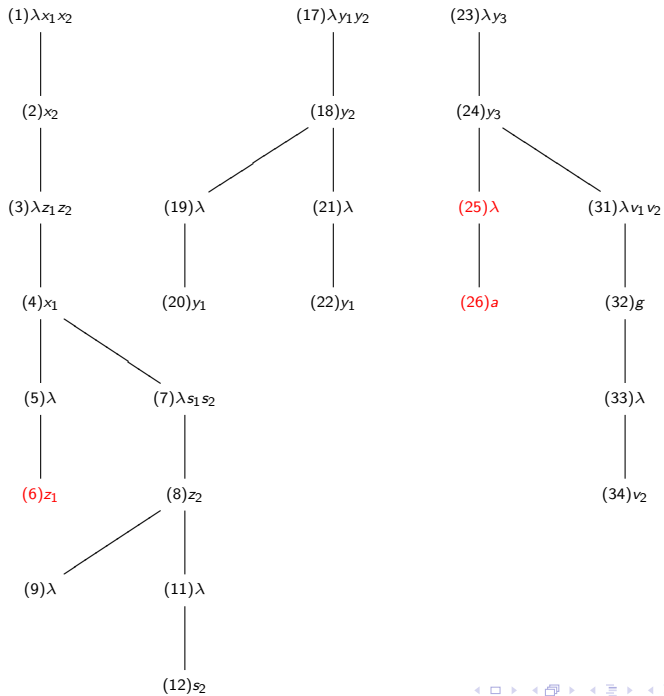












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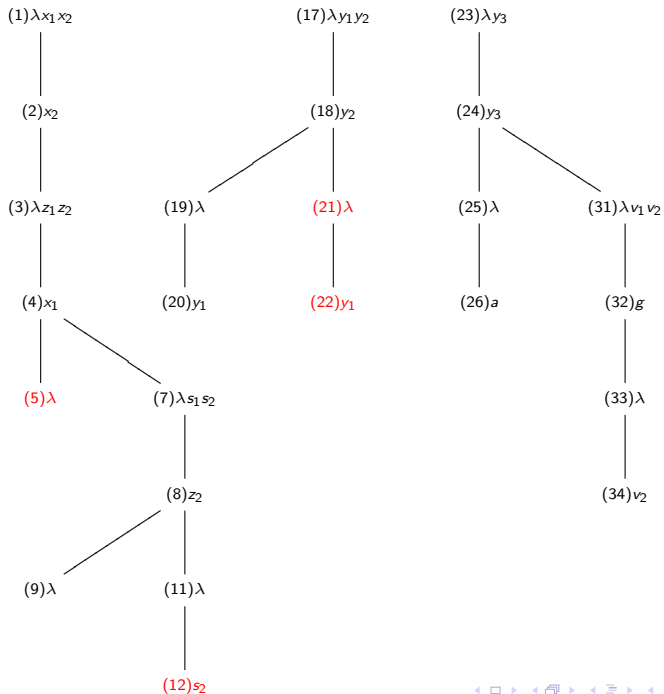
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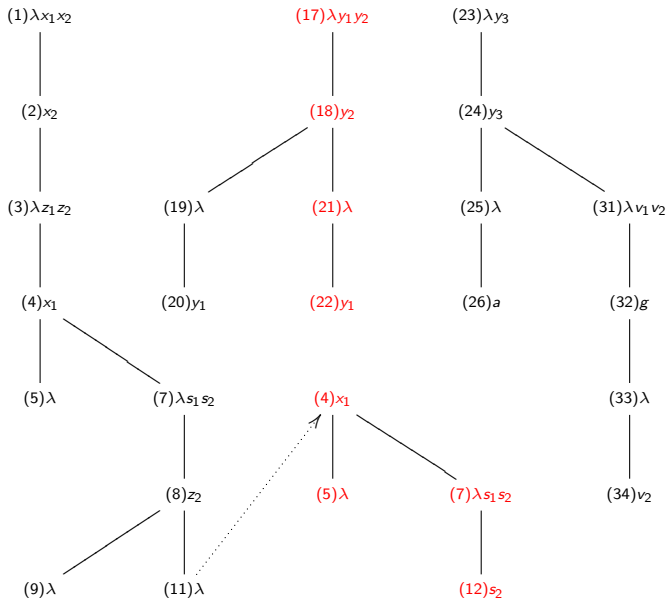
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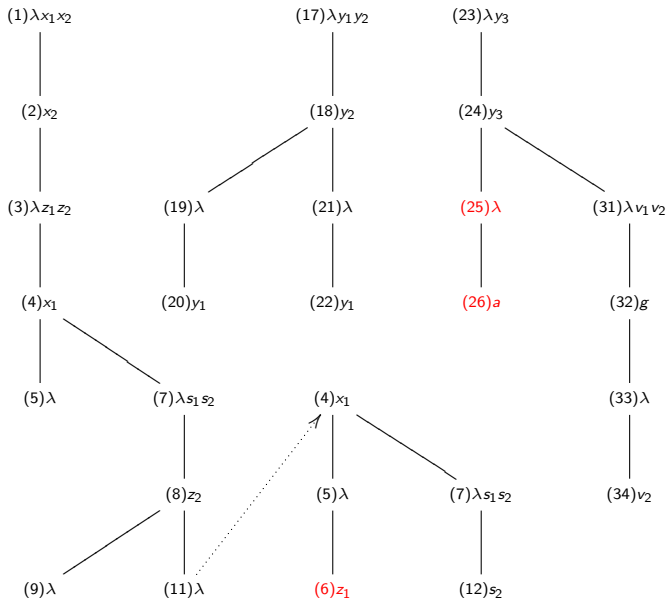
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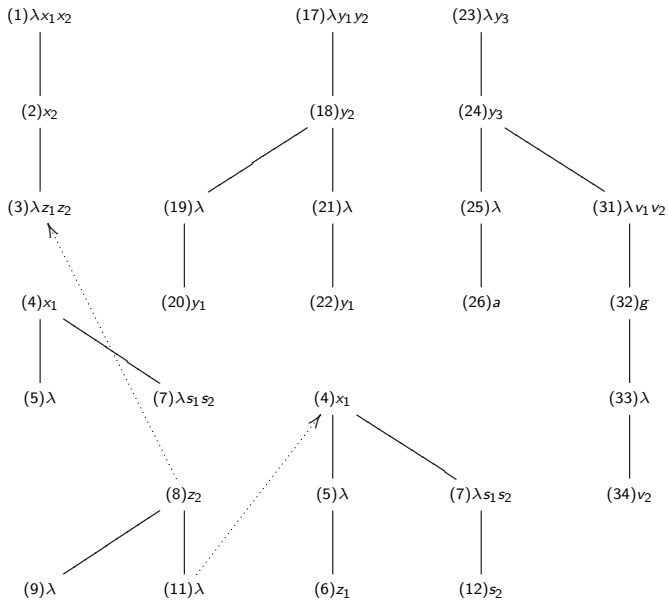
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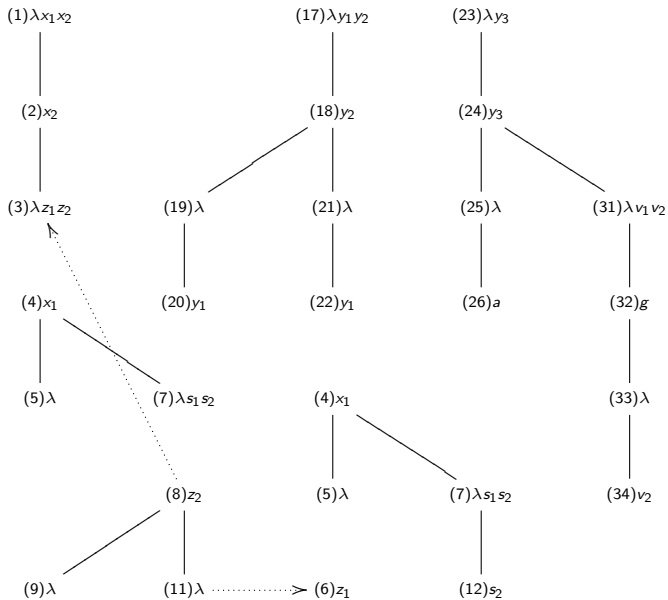
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Application of games to decidability of matching

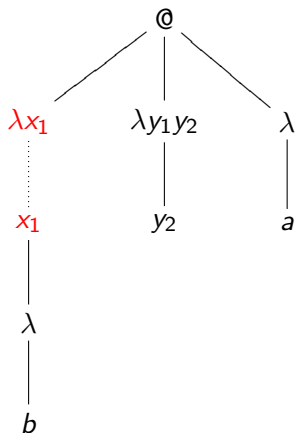
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- ▶ Theorem If $x : A$ and A has order $2n + 2$ or $2n + 3$ and arity m then $xw_1 \dots w_k = u$ has a (canonical) solution iff it has a (canonical) solution of depth at most $2(m + 1)^n \times |u|$

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- ▶ THE END

Games only work for long normal forms

- ▶ $x : ((\mathbf{0}, \mathbf{0}, \mathbf{0}), \mathbf{0}, \mathbf{0})$ β -interpolation problem $x(\lambda y_1 y_2 . y_2) a = a$



- ▶ $\lambda x_1 . x_1 b (\lambda y_1 y_2 . y_2) a \rightarrow_{\beta}^* a$
- ▶ No natural game?