

# A SIMPLE FPRAS FOR BI-DIRECTED REACHABILITY

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Joint with **Mark Jerrum** (Queen Mary, University of London)

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# COUNTING



# THE COMPLEXITY OF COMPUTING QUANTITIES

Complexity class **#P** by Valiant (1979):

a counting analogue of **NP**.

Evaluation of probabilities;

Multivariate integration;

Counting discrete structures ...

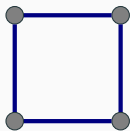


# NETWORK RELIABILITY

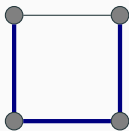
**RELIABILITY:** in a graph (or network)  $G = (V, E)$ , suppose each edge fails with probability  $p$ . What's the probability that the remaining graph is connected?

In other words, we want to compute

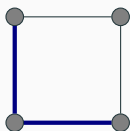
$$Z_{\text{rel}}(G, p) := \sum_{R \subseteq E: (V, R) \text{ is connected}} p^{|E \setminus R|} (1-p)^{|R|}.$$



$$(1-p)^4$$



$$p(1-p)^3$$



Disconnected!

# COMPUTATIONAL COMPLEXITY OF RELIABILITY

The unweighted case (namely,  $p = 0.5$ ) is among the original 17 **#P**-complete problem in [Valiant '79].

Exact evaluation is **#P**-complete [Jerrum '81] [Provan, Ball '83].

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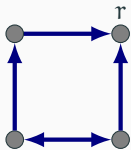
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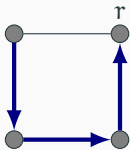
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# REACHABILITY

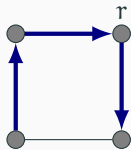
We say a directed graph  $G$  with root  $r$  is *root-connected* if all vertices can reach  $r$ .



Root-connected



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Not connected!

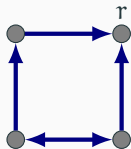
Ball and Provan (1983) defined **REACHABILITY**: in a directed graph with root  $r$ , suppose each arc fails with probability  $p$ , what's the probability that the remaining graph is root-connected?

$$Z_{\text{reach}}(G, p) := \sum_{R \subseteq E: (V, R) \text{ is root-connected}} p^{|E \setminus R|} (1 - p)^{|R|}.$$

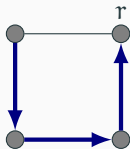


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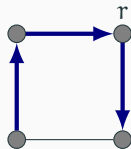
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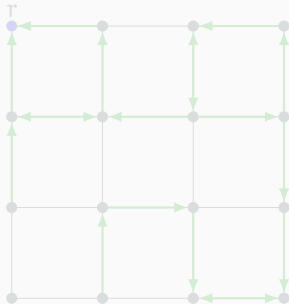
# CLUSTER POPPING

If  $G$  is **bi-directed**, approximating  $Z_{\text{reach}}(G, p)$  can be reduced to sampling root-connected subgraphs [Gorodezky, Pak 14].

Cluster: no edge going out.

Cluster popping [Gorodezky, Pak 14]:  
randomize edges and repeatedly pop minimal clusters.

[G., Jerrum 17]: the expected number of rounds in a bi-directed graph is  $O\left(\frac{m}{1-p}\right)$ .



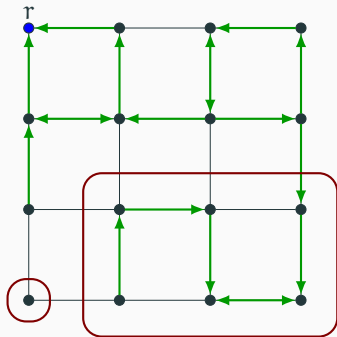
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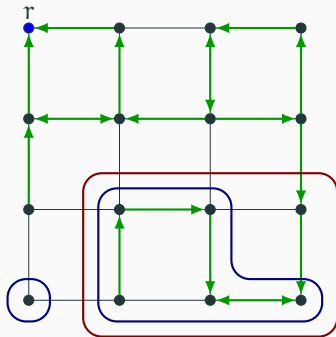
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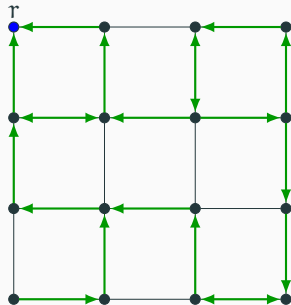
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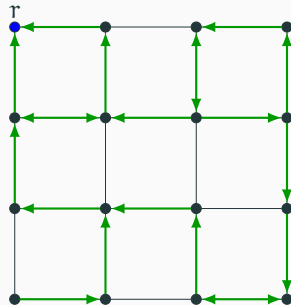
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# PARTIAL REJECTION SAMPLING

(WHY IS CLUSTER-POPPING CORRECT AND EFFICIENT?)

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# A RANDOM WALK SAT-SOLVER

The prototypical NP-complete problem:

given a CNF formula, does it have a satisfying assignment?

$$(x_1 \vee \bar{x}_3 \vee x_5) \wedge (x_2 \vee x_3) \wedge (\bar{x}_3 \vee \bar{x}_4) \wedge (x_1 \vee \bar{x}_5 \vee x_6 \vee x_7) \dots$$

*Rejection sampling*: assign each variable uniformly at random and independently. If not satisfying, reject and repeat.

Walk-SAT: while there is a violated clause, re-randomize all its variables.

It is optimal in a very general setting! [Moser, Tardos 10]



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# VARIABLE FRAMEWORK OF THE LOVÁSZ LOCAL LEMMA

Find a “perfect” assignment of the variables **avoiding** all “bad” events.

Variables  $X_1, \dots, X_n$

“Bad” events  $A_1, \dots, A_m$

Dependency graph:  $A_i$  and  $A_j$  are adjacent if  $\text{var}(A_i) \cap \text{var}(A_j) \neq \emptyset$ .

Erdős and Lovász (1975):  $4p\Delta \leq 1 \Rightarrow$  existence of a perfect assignment.

$p$ : max probability of  $A_i$

$\Delta$ : max degree of the dependency graph

Lovász (1977) improved the condition to  $ep(\Delta + 1) \leq 1$ .

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LLL only guarantees an **exponentially** small probability.

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Beck (1991) showed that an algorithmic version is possible, starting a long line of research.

Moser and Tardos (2010) found a very elegant algorithm:

1. Initialize all variables randomly.
2. While there exists an occurring bad event:  
    pick one (various rules) and **resample** all its variables.

Many developments since then:

[Haeupler, Saha, Srinivasan 11], [Kolipaka, Szegedy 11], [Harris, Srinivasan 13], [Achlioptas, Iliopoulos 16], [Harvey, Vondrak 15], [He, Li, Liu, Wang, Xia 17].

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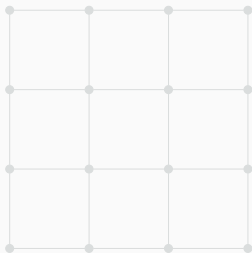
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# SAMPLING INDEPENDENT SETS?

Target distribution: uniform on independent sets.

Adapting Moser-Tardos:

1. Randomize each vertex.
2. Resample all connected component of size at least 2, until there is none.



This does *not* draw from the target distribution:

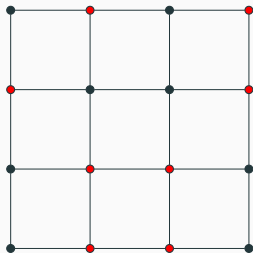
- Once a vertex is resampled, it will stay unoccupied and fill the grid. The process will be highly biased.
- The process converges too fast. However uniformly sampling independent sets is given approximately.

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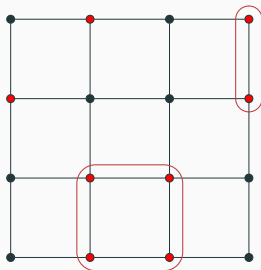
- Once a vertex is unoccupied, it will stay unoccupied till the end. Hence the empty set is overly favored.
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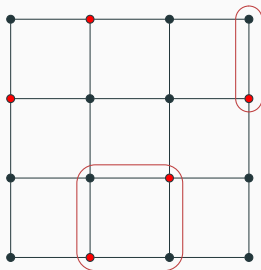


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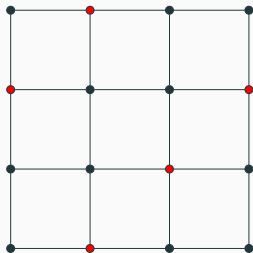
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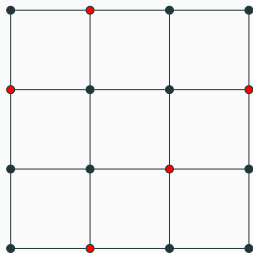
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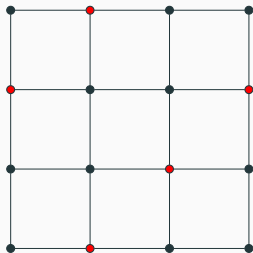
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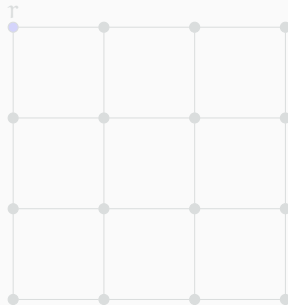
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Goal: sample a uniform spanning tree with root  $r$ .

1. For each  $v \neq r$ , assign a random arrow from  $v$  to one of its neighbours.
2. While there is a (directed) cycle in the current graph, resample all arrows along all cycles.
3. Output.

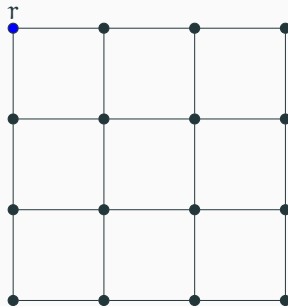


No cycle +  $n - 1$  edges  $\Rightarrow$  Spanning Tree

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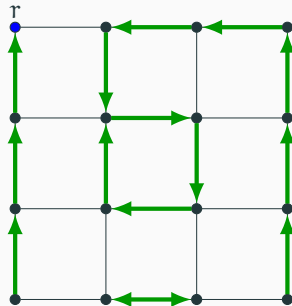


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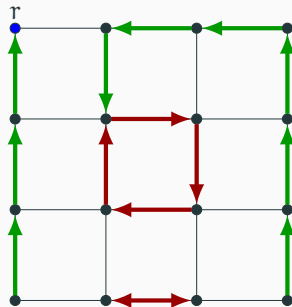


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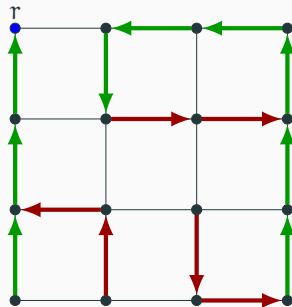
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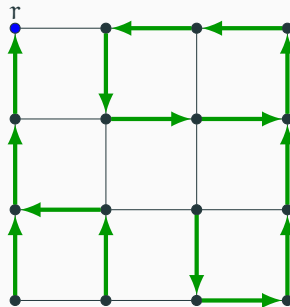


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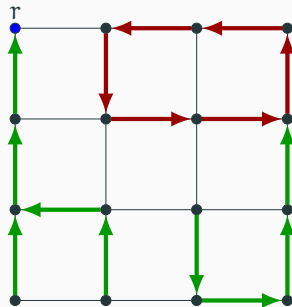


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Goal: sample a uniform spanning tree with root  $r$ .

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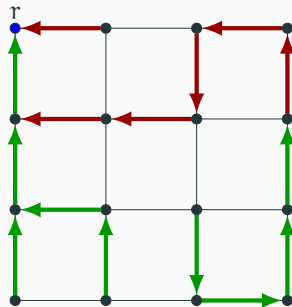


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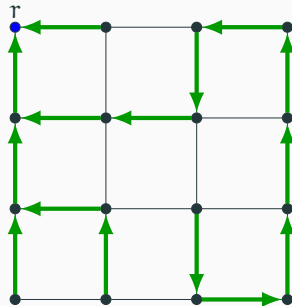


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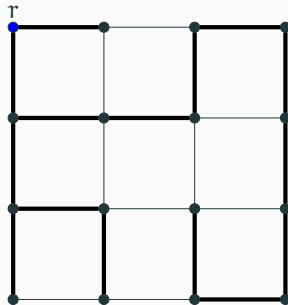


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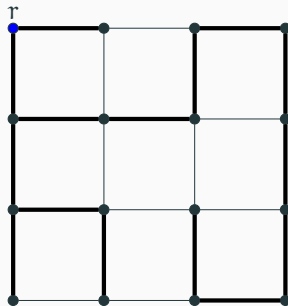


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Cycle-popping is a special case of Moser-Tardos:

Arrows are variables.

Cycles are "bad" events.

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# EXTREMAL INSTANCES

We call an instance **extremal**:

if any two “bad” events  $A_i$  and  $A_j$  are either **independent** or **disjoint**.

- Extremal instances **minimize** the probability of solutions (in some precise sense) [Shearer 85].
- **Moser-Tardos** runs slowest in extremal instances.
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Wilson's setup is extremal:

If two cycles share a vertex (**dependent**) and they both occur (**overlapping**), then these two cycles must be identical by following the arrow!

Other extremal instances:

- "Cluster-popping" [Gorodezky, Pak 14]
- Sink-free orientations [Bubley, Dyer 97] [Cohn, Pemantle, Propp 02]  
Reintroduced to show distributed LLL lower bound  
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Associate an infinite stack  $X_{i,0}, X_{i,1}, \dots$  to each random variable  $X_i$ .  
When we need to resample, draw the next value in the stack.

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## CHANGE THE FUTURE, NOT THE PAST

For **extremal** instances, replacing a **perfect** assignment with another one will not change the resampling history!

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For any output  $\sigma$  and  $\tau$ , there is a **bijection** between trajectories leading to  $\sigma$  and  $\tau$ .

# RUNNING TIME ON EXTREMAL INSTANCES

## Theorem (G., Jerrum, Liu 17)

Under Shearer's condition, for *extremal* instances,

$$\mathbb{E} T = \sum_{i=1}^m \frac{q_i}{q_\emptyset} = \frac{\# \text{ near-perfect assignments}}{\# \text{ perfect assignments}}.$$

(Shearer's condition:  $q_S \geq 0$  for all  $S \subseteq V$ , where  $q_S$  is the independence polynomial on  $G \setminus \Gamma^+(S)$  with weight  $-p_j$  on vertex  $j$ .)

In general (non-extremal),  $\mathbb{E} T \leq \sum_{i=1}^m \frac{q_i}{q_\emptyset}$  [Kolipaka, Szegedy 11].

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## BACK TO CLUSTER-POPPING

Cluster-popping: repeatedly resample minimal clusters.

Let  $\Omega_k$  be the set of subgraphs with  $k$  minimal clusters.

$$Z_k := \sum_{S \in \Omega_k} p^{|\mathcal{E} \setminus S|} (1-p)^{|S|} \quad \mathbb{E} T = \frac{Z_1}{Z_0}$$

[G., Jerrum 17]: for **bi-directed** graphs,  $Z_1 \leq \frac{mn}{1-p} Z_0$ .

We show this by designing an injective mapping  $\Omega_1 \rightarrow \Omega_0 \times V \times E$ .

### Theorem

*There is an FPRAS for REACHABILITY in bi-directed graphs. The running time is  $O(\epsilon^{-2} p (1-p)^{-3} m^2 n^3)$  for an  $(1 \pm \epsilon)$ -approximation.*

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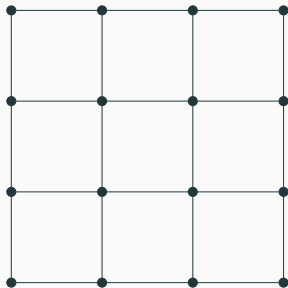
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# A CORRECT ALGORITHM FOR SAMPLING INDEPENDENT SETS

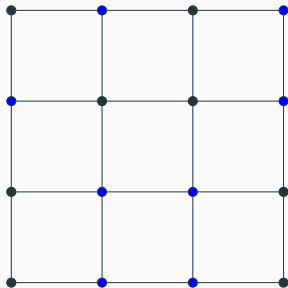
1. Randomize each vertex.
2. Let **Bad** be the set of vertices whose connected component has size  $\geq 2$ .
3. **Res** = **Bad**  $\cup$   $\partial$ **Bad**.
4. Resample **Res**.  
Check independence.



When the algorithm stops, it draws from the desired distribution.

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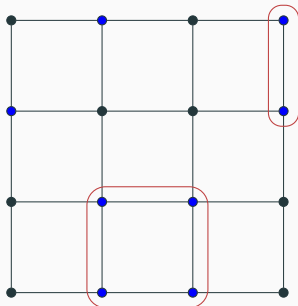
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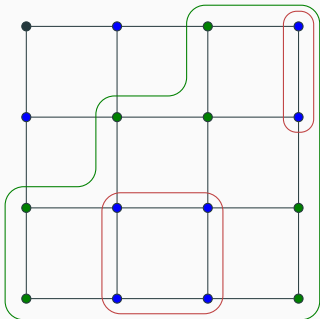
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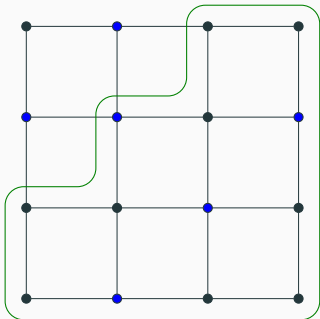
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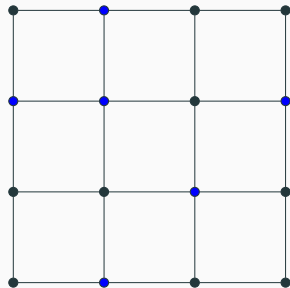
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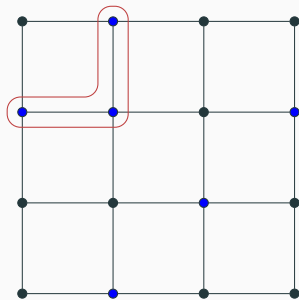


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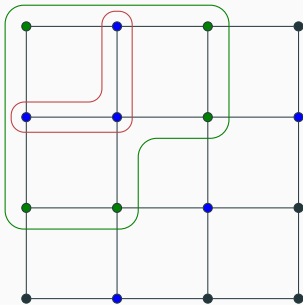
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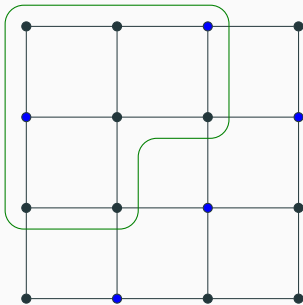
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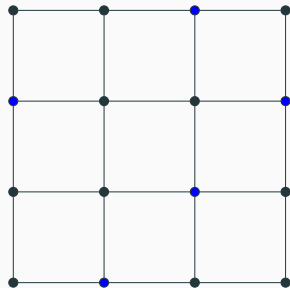
1. Randomize each vertex.
2. Let **Bad** be the set of vertices whose connected component has size  $\geq 2$ .
3. **Res** = **Bad**  $\cup$   $\partial$ **Bad**.
- 4. Resample **Res**.  
Check independence.



When the algorithm stops, it draws from the desired distribution.

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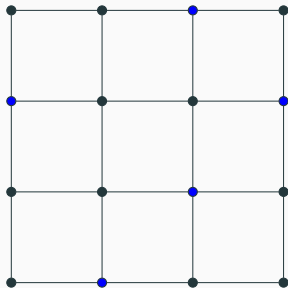
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## BEYOND EXTREMAL CASES

We also gave a general algorithm, and is optimal in certain restricted cases, up to constants [G., Jerrum, Liu 17].

But it falls short in general. My conjecture is that there is an efficient algorithm whenever  $p\Delta^2 \leq C$  for some constant  $C$ .

On the other hand, there is a constant  $C'$  such that if  $p\Delta^2 \geq C'$ , then sampling is **NP**-hard [Bezáková, Galanis, Goldberg, G., Štefankovič 16].

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## **CONCLUDING REMARKS**

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# OPEN PROBLEMS

- How to sample connected subgraphs (or approximate *reliability*)?
- What is the optimal sampling algorithm in the local lemma setting in general?
- Can we do this for perfect matchings - resampling **permutations**???

A professor is one who can speak on any subject for precisely fifty minutes.

— Norbert Wiener

**THANK YOU!**

arXiv:1611.01647

arXiv:1709.08561