

COUNTING HYPERGRAPH COLOURINGS IN THE LOCAL LEMMA REGIME

Heng Guo (University of Edinburgh)

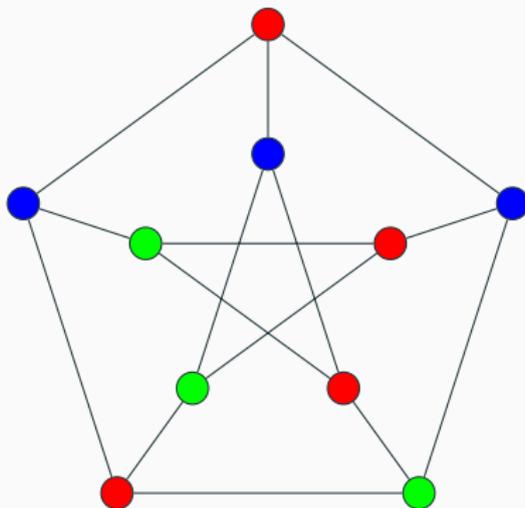
Joint with **Chao Liao** (SJTU), **Pinyan Lu** (SHUFE), and **Chihao Zhang** (SJTU)

Birmingham, Jan 31 2019

COLOURINGS



GRAPH (PROPER) COLOURING



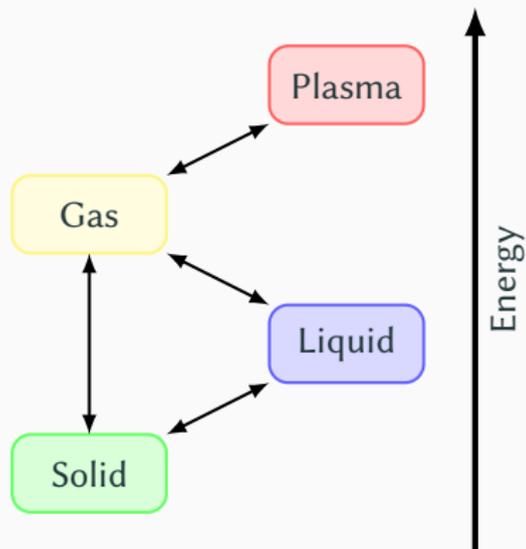
3-colouring of the Petersen graph

PHASE TRANSITIONS

Phase transitions:

as some parameter changes, macroscopic behaviours of the whole system change drastically.

E.g. ice \rightarrow water \rightarrow water vapor



COMPUTATIONAL PHASE TRANSITIONS

As parameters change, the computational complexity of a problem may change drastically.

Determine whether a graph is q -colourable (or find one if it exists):

- $q = 1, 2$: trivial;
- $q \geq 3$: **NP**-hard.

What about graphs with maximum degree Δ ?

- $q \geq \Delta + 1$: colourable by simple greedy algorithm;
- $q \geq \Delta - k_\Delta + 1$: polynomial-time (Molloy, Reed '01 '14);
- $q \leq \Delta - k_\Delta$: **NP**-hard (Embden-Weinert, Hougardy,
($k_\Delta \approx \sqrt{\Delta} - 2$) and Kreuter '98).

COMPUTATIONAL PHASE TRANSITIONS

As parameters change, the computational complexity of a problem may change drastically.

Determine whether a graph is q -colourable (or find one if it exists):

- $q = 1, 2$: trivial;
- $q \geq 3$: **NP**-hard.

What about graphs with maximum degree Δ ?

- $q \geq \Delta + 1$: colourable by simple greedy algorithm;
- $q \geq \Delta - k_\Delta + 1$: polynomial-time (Molloy, Reed '01 '14);
- $q \leq \Delta - k_\Delta$: **NP**-hard (Embden-Weinert, Hougardy,
($k_\Delta \approx \sqrt{\Delta} - 2$) and Kreuter '98).

COMPUTATIONAL PHASE TRANSITIONS

As parameters change, the computational complexity of a problem may change drastically.

Determine whether a graph is q -colourable (or find one if it exists):

- $q = 1, 2$: trivial;
- $q \geq 3$: **NP**-hard.

What about graphs with maximum degree Δ ?

- $q \geq \Delta + 1$: colourable by simple greedy algorithm;
- $q \geq \Delta - k_\Delta + 1$: polynomial-time (Molloy, Reed '01 '14);
- $q \leq \Delta - k_\Delta$: **NP**-hard (Embden-Weinert, Hougardy,
($k_\Delta \approx \sqrt{\Delta} - 2$) and Kreuter '98).

Threshold phenomena are most common, but things can be more complicated!

Determine or find q -colourings for a planar graph:

- $q = 2$: easy;
- $q = 3$: NP-hard (Dailey '80);
- $q = 4$: quadratic time (Four colour theorem)
by Robertson, Sanders, Seymour, and Thomas (1996);
- $q \geq 5$: linear time (much simpler proof) (RSST '96).

Threshold phenomena are most common, but things can be more complicated!

Determine or find q -colourings for a planar graph:

- $q = 2$: easy;
- $q = 3$: NP-hard (Dailey '80);
- $q = 4$: quadratic time (Four colour theorem)
by Robertson, Sanders, Seymour, and Thomas (1996);
- $q \geq 5$: linear time (much simpler proof) (RSST '96).

Threshold phenomena are most common, but things can be more complicated!

Determine or find q -colourings for a planar graph:

- $q = 2$: easy;
- $q = 3$: **NP**-hard (Dailey '80);
- $q = 4$: quadratic time (Four colour theorem)
by Robertson, Sanders, Seymour, and Thomas (1996);
- $q \geq 5$: linear time (much simpler proof) (RSST '96).

Threshold phenomena are most common, but things can be more complicated!

Determine or find q -colourings for a planar graph:

- $q = 2$: easy;
- $q = 3$: **NP**-hard (Dailey '80);
- $q = 4$: quadratic time (Four colour theorem)
by Robertson, Sanders, Seymour, and Thomas (1996);
- $q \geq 5$: linear time (much simpler proof) (RSST '96).

Threshold phenomena are most common, but things can be more complicated!

Determine or find q -colourings for a planar graph:

- $q = 2$: easy;
- $q = 3$: **NP**-hard (Dailey '80);
- $q = 4$: quadratic time (Four colour theorem)
by Robertson, Sanders, Seymour, and Thomas (1996);
- $q \geq 5$: linear time (much simpler proof) (RSST '96).

How about generating a **uniform** proper colouring **at random**?

(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

RANDOMLY COLOUR A GRAPH

How about generating a **uniform** proper colouring **at random**?

(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

RANDOMLY COLOUR A GRAPH

How about generating a **uniform** proper colouring **at random**?

(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

RANDOMLY COLOUR A GRAPH

How about generating a **uniform** proper colouring **at random**?

(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

RANDOMLY COLOUR A GRAPH

How about generating a **uniform** proper colouring **at random**?

(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

RANDOMLY COLOUR A GRAPH

How about generating a **uniform** proper colouring **at random**?

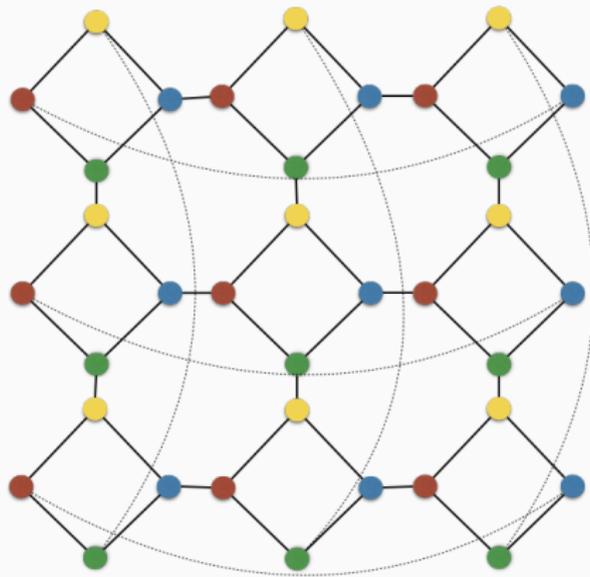
(closely related to approximately count the number of colourings)

- $q > 2\Delta$: rapid mixing of Glauber dynamics by [Jerrum \(1995\)](#); [Salas and Sokal \(1997\)](#);
- $q > \frac{11}{6}\Delta$: rapid mixing of WSK dynamics by [Vigoda \(2000\)](#);
improved by [Chen and Moitra \(2019\)](#); [Delcourt, Perarnau, and Postle \(2019\)](#) to $q > (\frac{11}{6} - \epsilon)\Delta$ for a small ϵ ;
- $q < \Delta$: **NP**-hard by [Galanis, Štefankovič, and Vigoda \(2015\)](#);
(even q)

It is conjectured that there is a threshold and $q_c = \Delta + 1$. This is the uniqueness threshold of Gibbs measures in an infinite Δ -regular tree (namely a Bethe lattice), by [Jonasson \(2002\)](#).

Sometimes you just cannot let it go.

$$q = \Delta + 1 = 4$$

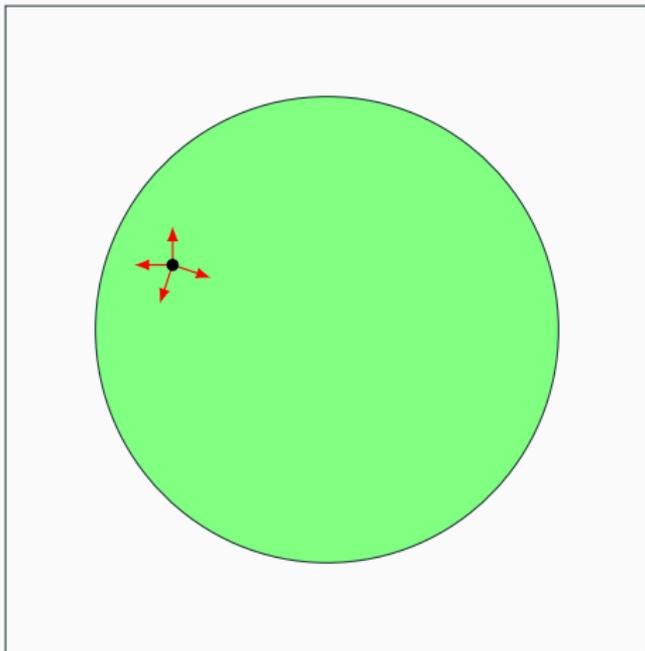


credit: Chihao Zhang

DISCONNECTED STATE SPACE

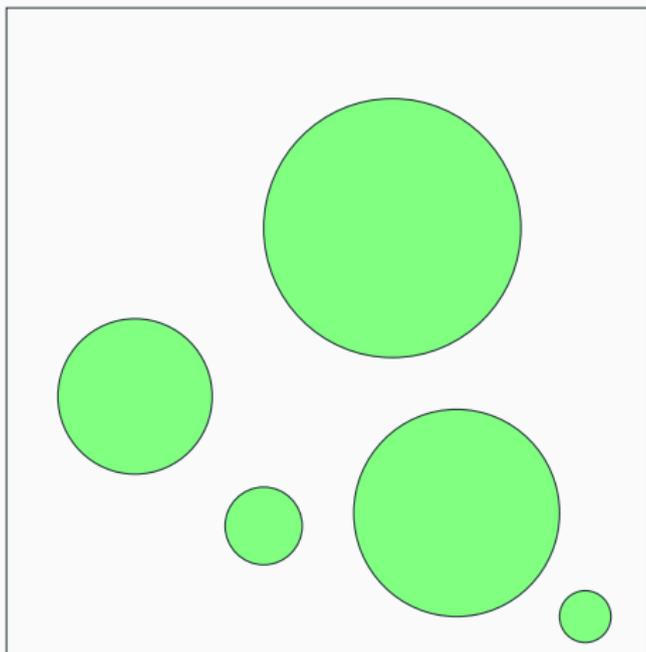
Markov chain is a random walk in the solution space.

(The solution space has to be connected!)



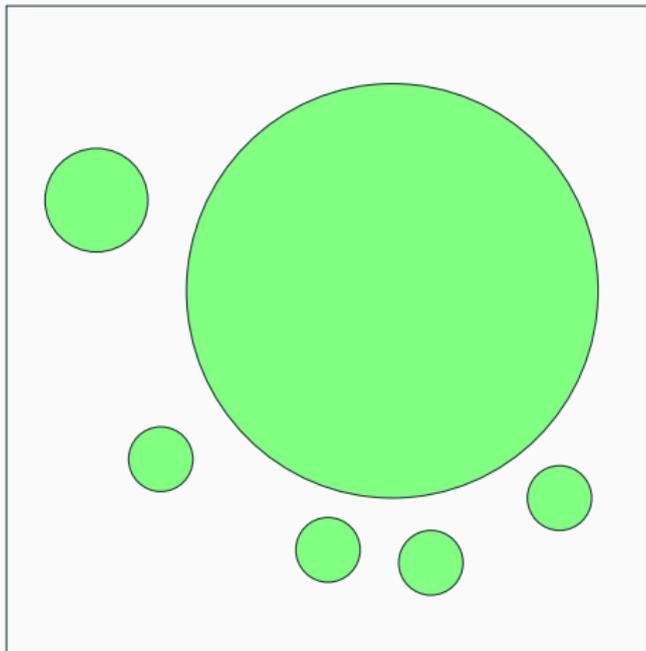
DISCONNECTED STATE SPACE

A disconnected state space is not good.



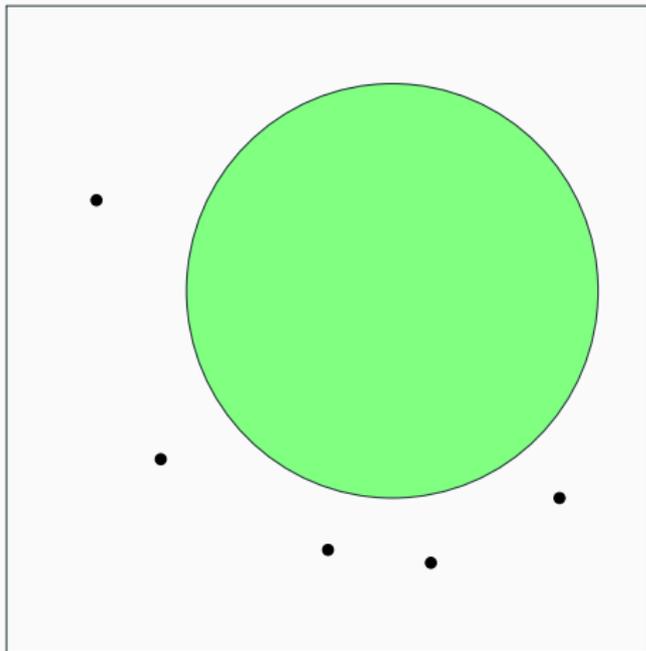
DISCONNECTED STATE SPACE

There's still hope if one **giant** component dominates.



DISCONNECTED STATE SPACE

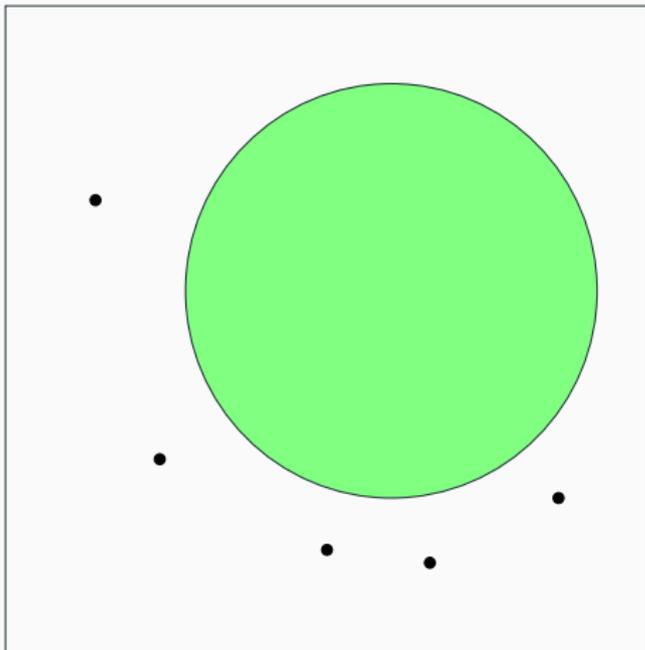
There's still hope if one **giant** component dominates.
If $q = \Delta + 1$, then all other components are isolated vertices ...
(Feghali, Johnson, and Paulusma 2016)



DISCONNECTED STATE SPACE

There's still hope if one **giant** component dominates.
... and the number of isolated vertices is exponentially small.

(Bonamy, Bousquet, and Perarnau 2018)

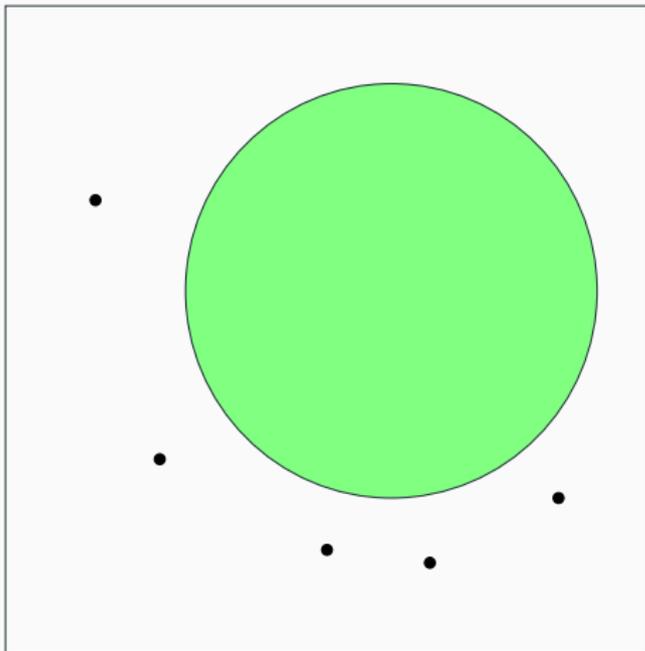


DISCONNECTED STATE SPACE

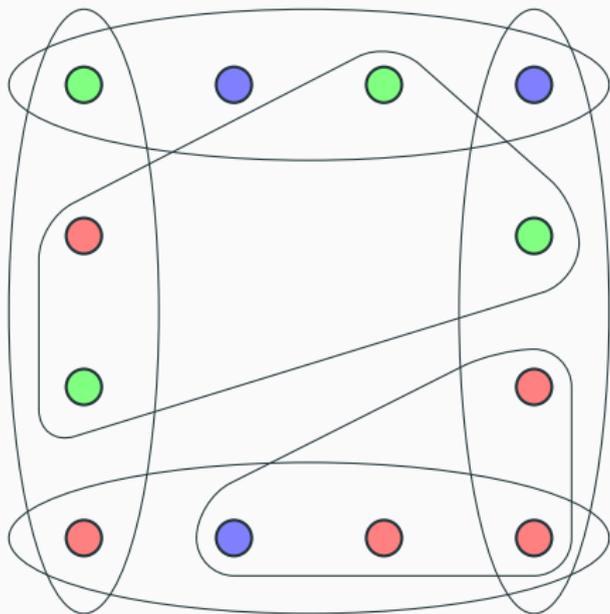
There's still hope if one **giant** component dominates.

FPTAS for counting 4-colourings in cubic graphs.

(Lu, Yang, Zhang, and Zhu 2017) (Not via Markov chains!)



WHAT ABOUT HYPERGRAPHS?



A proper hypergraph colouring is one where **no** edge is **monochromatic**.

PREVIOUS RESULTS

For k -uniform hypergraphs, [Bordewich, Dyer, and Karpinski \(2006\)](#) show that Glauber dynamics is rapidly mixing if

$$k \geq 4 \text{ and } q > \Delta \quad \text{or} \quad k = 3 \text{ and } q > 1.5\Delta.$$

However, Lovász local lemma implies that there exists a proper colouring if $q > 2e\Delta^{1/(k-1)}$.

[Frieze and Melsted \(2011\)](#) showed that if $q \ll \Delta$, then there exists a colouring so that no move is possible (“frozen”).

[Frieze and Anastos \(2017\)](#) showed that Glauber dynamics still converges rapidly if the hypergraph is **simple** and $q > \max\{C_k \log n, 500k^3 \Delta^{1/(k-1)}\}$.

(**Simple**: every two hyperedges intersect in at most one vertex.)

PREVIOUS RESULTS

For k -uniform hypergraphs, [Bordewich, Dyer, and Karpinski \(2006\)](#) show that Glauber dynamics is rapidly mixing if

$$k \geq 4 \text{ and } q > \Delta \quad \text{or} \quad k = 3 \text{ and } q > 1.5\Delta.$$

However, Lovász local lemma implies that there exists a proper colouring if $q > 2e\Delta^{1/(k-1)}$.

[Frieze and Melsted \(2011\)](#) showed that if $q \ll \Delta$, then there exists a colouring so that no move is possible (“frozen”).

[Frieze and Anastos \(2017\)](#) showed that Glauber dynamics still converges rapidly if the hypergraph is **simple** and $q > \max\{C_k \log n, 500k^3 \Delta^{1/(k-1)}\}$.

(**Simple**: every two hyperedges intersect in at most one vertex.)

PREVIOUS RESULTS

For k -uniform hypergraphs, [Bordewich, Dyer, and Karpinski \(2006\)](#) show that Glauber dynamics is rapidly mixing if

$$k \geq 4 \text{ and } q > \Delta \quad \text{or} \quad k = 3 \text{ and } q > 1.5\Delta.$$

However, Lovász local lemma implies that there exists a proper colouring if $q > 2e\Delta^{1/(k-1)}$.

[Frieze and Melsted \(2011\)](#) showed that if $q \ll \Delta$, then there exists a colouring so that no move is possible (“frozen”).

[Frieze and Anastos \(2017\)](#) showed that Glauber dynamics still converges rapidly if the hypergraph is **simple** and $q > \max\{C_k \log n, 500k^3 \Delta^{1/(k-1)}\}$.

(**Simple**: every two hyperedges intersect in at most one vertex.)

PREVIOUS RESULTS

For k -uniform hypergraphs, [Bordewich, Dyer, and Karpinski \(2006\)](#) show that Glauber dynamics is rapidly mixing if

$$k \geq 4 \text{ and } q > \Delta \quad \text{or} \quad k = 3 \text{ and } q > 1.5\Delta.$$

However, Lovász local lemma implies that there exists a proper colouring if $q > 2e\Delta^{1/(k-1)}$.

[Frieze and Melsted \(2011\)](#) showed that if $q \ll \Delta$, then there exists a colouring so that no move is possible (“frozen”).

[Frieze and Anastos \(2017\)](#) showed that Glauber dynamics still converges rapidly if the hypergraph is **simple** and $q > \max\{C_k \log n, 500k^3 \Delta^{1/(k-1)}\}$.

(**Simple**: every two hyperedges intersect in at most one vertex.)

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 315\Delta^{\frac{14}{k-14}}$, there is an FPTAS for the number of q -colourings in k -uniform hypergraphs with maximum degree Δ .

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 798\Delta^{\frac{16}{k-16/3}}$, there is also an almost-uniform polynomial-time sampler.

Our approach is a modified version of [Moitra \(2017\)](#) based on the Lovász local lemma. His original approach in this setting would require an extra condition of the form $k > C \log \Delta$.

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 315\Delta^{\frac{14}{k-14}}$, there is an FPTAS for the number of q -colourings in k -uniform hypergraphs with maximum degree Δ .

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 798\Delta^{\frac{16}{k-16/3}}$, there is also an almost-uniform polynomial-time sampler.

Our approach is a modified version of [Moitra \(2017\)](#) based on the Lovász local lemma. His original approach in this setting would require an extra condition of the form $k > C \log \Delta$.

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 315\Delta^{\frac{14}{k-14}}$, there is an FPTAS for the number of q -colourings in k -uniform hypergraphs with maximum degree Δ .

Theorem

For $\Delta \geq 2$, $k \geq 28$, and $q > 798\Delta^{\frac{16}{k-16/3}}$, there is also an almost-uniform polynomial-time sampler.

Our approach is a modified version of [Moitra \(2017\)](#) based on the Lovász local lemma. His original approach in this setting would require an extra condition of the form $k > C \log \Delta$.

LOVÁSZ LOCAL LEMMA

(AND HOW IT HELPS WITH APPROXIMATE COUNTING)



LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

LOVÁSZ LOCAL LEMMA

The original local lemma (Erdős and Lovász 75) was introduced to show the existence of 3-colourings in hypergraphs.

Let $H = (V, \mathcal{E})$ be the hypergraph, and $\Gamma(e)$ be the set of hyperedges intersecting $e \in \mathcal{E}$. Then $|\Gamma(e)| \leq (\Delta - 1)k$.

Theorem (Lovász '77)

If there exists an assignment $x : \mathcal{E} \rightarrow (0, 1)$ such that for every $e \in \mathcal{E}$ we have

$$\Pr(e \text{ is monochromatic}) \leq x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')), \quad (1)$$

then a proper colouring exists.

Typically we set $x(e) = \frac{1}{k\Delta}$. It gives

$$x(e) \prod_{e' \in \Gamma(e)} (1 - x(e')) \geq \frac{1}{k\Delta} \left(1 - \frac{1}{k\Delta}\right)^{k(\Delta-1)} \geq \frac{1}{ek\Delta}. \quad (2)$$

Notice that $\Pr(e \text{ is monochromatic}) = \frac{q}{q^k} = \frac{1}{q^{k-1}}$.

Thus $q^{k-1} \geq ek\Delta$, or equivalently $q \geq (ek\Delta)^{\frac{1}{k-1}}$ suffices.

Let \mathcal{C} be the set of all proper colourings.

Let $\mu(\cdot)$ be the Gibbs (uniform) distribution on all proper colourings, (namely the product distribution conditioned on no monochromatic edge).

The local lemma also gives an upper bound for any event under $\mu(\cdot)$.

Theorem (Haeupler, Saha, and Srinivasan '11)

If (1) holds for every $e \in \mathcal{E}$, then for any event B , it holds that

$$\mu(B) \leq \Pr(B) \prod_{e \in \Gamma(B)} (1 - x(e))^{-1}.$$

Let \mathcal{C} be the set of all proper colourings.

Let $\mu(\cdot)$ be the Gibbs (uniform) distribution on all proper colourings, (namely the product distribution conditioned on no monochromatic edge).

The local lemma also gives an upper bound for any event under $\mu(\cdot)$.

Theorem (Haeupler, Saha, and Srinivasan '11)

If (1) holds for every $e \in \mathcal{E}$, then for any event B , it holds that

$$\mu(B) \leq \Pr(B) \prod_{e \in \Gamma(B)} (1 - x(e))^{-1}.$$

REDUCING TO COMPUTING MARGINAL PROBABILITIES

For approximate counting, we use the (algorithmic) local lemma to find a partial colouring τ so that every hyperedge is satisfied by the first k_1 vertices.

(This will succeed as long as $q > (ek_1\Delta)^{\frac{1}{k_1-1}}$. k_1 will eventually be set to $\frac{k}{14}$.)

Then we compute the probability of τ by “pinning” vertices one by one.

Let $U = \{u_1, \dots, u_r\}$ be the support of τ .

$$\frac{q^{n-r}}{|C|} = \Pr_{\sigma \sim \mu}(\sigma \models \tau)$$

REDUCING TO COMPUTING MARGINAL PROBABILITIES

For approximate counting, we use the (algorithmic) local lemma to find a partial colouring τ so that every hyperedge is satisfied by the first k_1 vertices.

(This will succeed as long as $q > (ek_1\Delta)^{\frac{1}{k_1-1}}$. k_1 will eventually be set to $\frac{k}{14}$.)

Then we compute the probability of τ by “pinning” vertices one by one.

Let $\mathcal{U} = \{u_1, \dots, u_r\}$ be the support of τ .

$$\begin{aligned} \frac{q^{n-r}}{|\mathcal{C}|} &= \Pr_{\sigma \sim \mu} (\sigma \models \tau) \\ &= \Pr_{\sigma \sim \mu} (\forall u \in \mathcal{U}, \sigma(u) = \tau(u)) \end{aligned}$$

REDUCING TO COMPUTING MARGINAL PROBABILITIES

For approximate counting, we use the (algorithmic) local lemma to find a partial colouring τ so that every hyperedge is satisfied by the first k_1 vertices.

(This will succeed as long as $q > (ek_1\Delta)^{\frac{1}{k_1-1}}$. k_1 will eventually be set to $\frac{k}{14}$.)

Then we compute the probability of τ by “pinning” vertices one by one.

Let $\mathcal{U} = \{u_1, \dots, u_r\}$ be the support of τ .

$$\begin{aligned}\frac{q^{n-r}}{|\mathcal{C}|} &= \Pr_{\sigma \sim \mu} (\sigma \models \tau) \\ &= \Pr_{\sigma \sim \mu} (\forall u \in \mathcal{U}, \sigma(u) = \tau(u)) \\ &= \Pr_{\sigma \sim \mu} (\sigma(u_1) = \tau(u_1)) \cdot \Pr_{\sigma \sim \mu} (\forall u \in \mathcal{U}, \sigma(u) = \tau(u) \mid \sigma(u_1) = \tau(u_1))\end{aligned}$$

REDUCING TO COMPUTING MARGINAL PROBABILITIES

For approximate counting, we use the (algorithmic) local lemma to find a partial colouring τ so that every hyperedge is satisfied by the first k_1 vertices.

(This will succeed as long as $q > (ek_1\Delta)^{\frac{1}{k_1-1}}$. k_1 will eventually be set to $\frac{k}{14}$.)

Then we compute the probability of τ by “pinning” vertices one by one.

Let $U = \{u_1, \dots, u_r\}$ be the support of τ .

$$\begin{aligned}\frac{q^{n-r}}{|C|} &= \Pr_{\sigma \sim \mu} (\sigma \models \tau) \\ &= \Pr_{\sigma \sim \mu} (\forall u \in U, \sigma(u) = \tau(u)) \\ &= \Pr_{\sigma \sim \mu} (\sigma(u_1) = \tau(u_1)) \cdot \Pr_{\sigma \sim \mu} (\forall u \in U, \sigma(u) = \tau(u) \mid \sigma(u_1) = \tau(u_1)) \\ &= \Pr_{\sigma \sim \mu} (\sigma(u_1) = \tau(u_1)) \cdot \Pr_{\sigma \sim \mu} (\sigma(u_2) = \tau(u_2) \mid \sigma(u_1) = \tau(u_1)) \\ &\quad \cdot \Pr_{\sigma \sim \mu} (\forall u \in U, \sigma(u) = \tau(u) \mid \sigma(u_1) = \tau(u_1), \sigma(u_2) = \tau(u_2))\end{aligned}$$

REDUCING TO COMPUTING MARGINAL PROBABILITIES

For approximate counting, we use the (algorithmic) local lemma to find a partial colouring τ so that every hyperedge is satisfied by the first k_1 vertices.

(This will succeed as long as $q > (ek_1\Delta)^{\frac{1}{k_1-1}}$. k_1 will eventually be set to $\frac{k}{14}$.)

Then we compute the probability of τ by “pinning” vertices one by one.

Let $\mathcal{U} = \{u_1, \dots, u_r\}$ be the support of τ .

$$\begin{aligned}\frac{q^{n-r}}{|\mathcal{C}|} &= \Pr_{\sigma \sim \mu}(\sigma \models \tau) \\ &= \Pr_{\sigma \sim \mu}(\forall u \in \mathcal{U}, \sigma(u) = \tau(u)) \\ &= \Pr_{\sigma \sim \mu}(\sigma(u_1) = \tau(u_1)) \cdot \Pr_{\sigma \sim \mu}(\forall u \in \mathcal{U}, \sigma(u) = \tau(u) \mid \sigma(u_1) = \tau(u_1)) \\ &= \Pr_{\sigma \sim \mu}(\sigma(u_1) = \tau(u_1)) \cdot \Pr_{\sigma \sim \mu}(\sigma(u_2) = \tau(u_2) \mid \sigma(u_1) = \tau(u_1)) \\ &\quad \cdot \Pr_{\sigma \sim \mu}(\forall u \in \mathcal{U}, \sigma(u) = \tau(u) \mid \sigma(u_1) = \tau(u_1), \sigma(u_2) = \tau(u_2))\end{aligned}$$

Thus the key is to estimate marginal probabilities under partial colourings (up to $1 \pm \frac{\epsilon}{n}$ error), where at least $k - k_1$ vertices are uncoloured in every edge.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

The upper bound comes from a direct application of the fine-tuned version.

The lower bound is obtained by giving upper bounds for “blocking cases”.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

The upper bound comes from a direct application of the fine-tuned version.

The lower bound is obtained by giving upper bounds for “blocking cases”.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

We use this lemma with $t \approx \Delta^C$ at various places with various C . Recall that our assumption is of the form $q \geq C' \Delta^{\frac{C''}{k}}$.

Under μ , all vertices are **very close** to uniform.

We use this lemma when some vertices are **already** coloured, namely for μ conditioned on a partial colouring.

The quantity k' is the minimum number of uncoloured vertices among all unsatisfied hyperedges (namely $k' = k - k_1$).

A good start, but not enough. The goal is $\frac{\epsilon}{n}$ -approximation of the marginals.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

We use this lemma with $t \approx \Delta^C$ at various places with various C . Recall that our assumption is of the form $q \geq C' \Delta^{\frac{C''}{k}}$.

Under μ , all vertices are **very close to** uniform.

We use this lemma when some vertices are **already** coloured, namely for μ conditioned on a partial colouring.

The quantity k' is the minimum number of uncoloured vertices among all unsatisfied hyperedges (namely $k' = k - k_1$).

A good start, but not enough. The goal is $\frac{\epsilon}{n}$ -approximation of the marginals.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

We use this lemma with $t \approx \Delta^C$ at various places with various C . Recall that our assumption is of the form $q \geq C' \Delta^{\frac{C''}{k}}$.

Under μ , all vertices are ~~very close to~~ uniform.

We use this lemma when some vertices are **already** coloured, namely for μ conditioned on a partial colouring.

The quantity k' is the minimum number of uncoloured vertices among all unsatisfied hyperedges (namely $k' = k - k_1$).

A good start, but not enough. The goal is $\frac{\epsilon}{n}$ -approximation of the marginals.

LOCAL UNIFORMITY

Lemma

If $\forall e \in \mathcal{E}$, $k' \leq |e| \leq k$, $t \geq k$ and $q \geq (et\Delta)^{\frac{1}{k'-1}}$, then for any $v \in V$ and any colour $c \in [q]$,

$$\frac{1}{q} \left(1 - \frac{1}{t}\right) \leq \Pr_{\sigma \sim \mu}(\sigma(v) = c) \leq \frac{1}{q} \left(1 + \frac{4}{t}\right).$$

We use this lemma with $t \approx \Delta^C$ at various places with various C . Recall that our assumption is of the form $q \geq C' \Delta^{\frac{C''}{k}}$.

Under μ , all vertices are ~~very close to~~ uniform.

We use this lemma when some vertices are **already** coloured, namely for μ conditioned on a partial colouring.

The quantity k' is the minimum number of uncoloured vertices among all unsatisfied hyperedges (namely $k' = k - k_1$).

A good start, but not enough. The goal is $\frac{\epsilon}{n}$ -approximation of the marginals.

COUPLING

Say we want to compute the marginal probability of v .

Let \mathcal{C}_i be the set of colourings where v is coloured i , and μ_i be uniform over \mathcal{C}_i . We want to couple μ_1 and μ_2 .

Start: $V_1 = \{v\}$, $V_{\text{col}} = \{v\}$. Maintain $V_2 = V \setminus V_1$.

Body:

1. For any hyperedge e intersecting both V_1 and V_2 , let u be its first vertex. Couple u maximally **assuming** its marginal probabilities are known.
2. Remove all hyperedges that are satisfied in **both** copies.
3. If an edge has k_2 vertices coloured, put all remaining vertices in V_1 (**failed**) and remove the edge.

Stop: all hyperedges intersecting V_1 are removed.

(The constant k_2 is eventually set to $\frac{3k}{7}$ for approximate counting and $\frac{3k}{8}$ for sampling.)

COUPLING

Say we want to compute the marginal probability of v .

Let \mathcal{C}_i be the set of colourings where v is coloured i , and μ_i be uniform over \mathcal{C}_i . We want to couple μ_1 and μ_2 .

Start: $V_1 = \{v\}$, $V_{\text{col}} = \{v\}$. Maintain $V_2 = V \setminus V_1$.

Body:

1. For any hyperedge e intersecting both V_1 and V_2 , let u be its first vertex. Couple u maximally **assuming** its marginal probabilities are known.
2. Remove all hyperedges that are satisfied in **both** copies.
3. If an edge has k_2 vertices coloured, put all remaining vertices in V_1 (**failed**) and remove the edge.

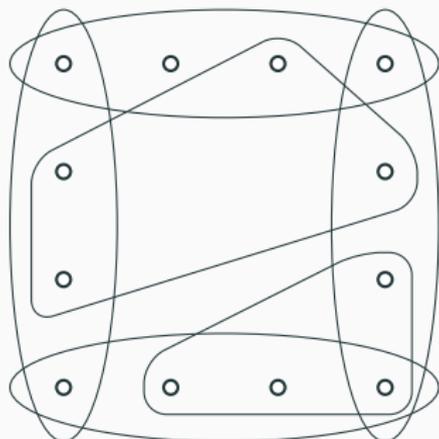
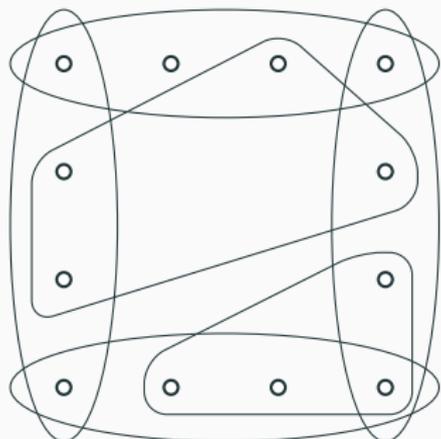
Stop: all hyperedges intersecting V_1 are removed.

(The constant k_2 is eventually set to $\frac{3k}{7}$ for approximate counting and $\frac{3k}{8}$ for sampling.)

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

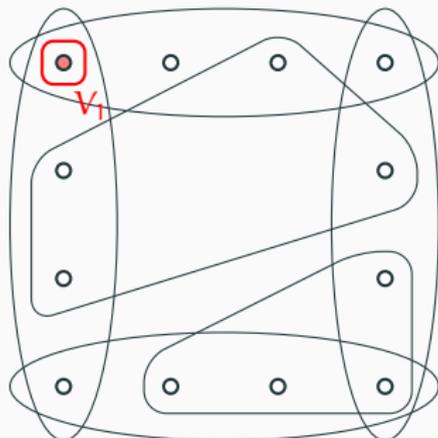
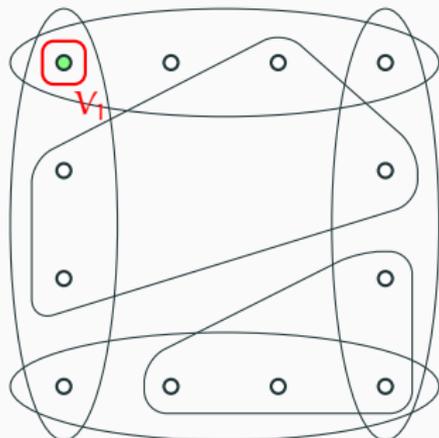
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

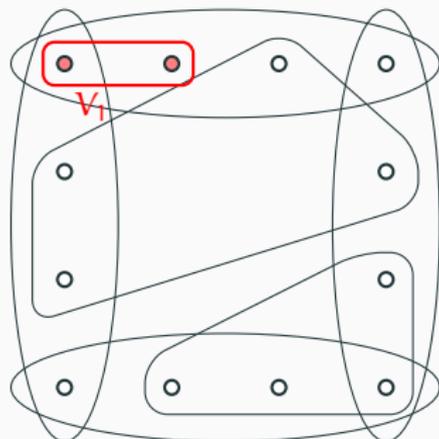
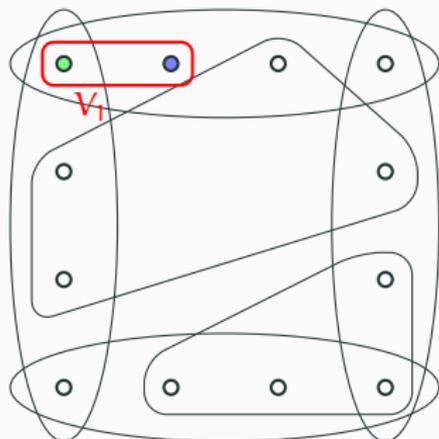
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

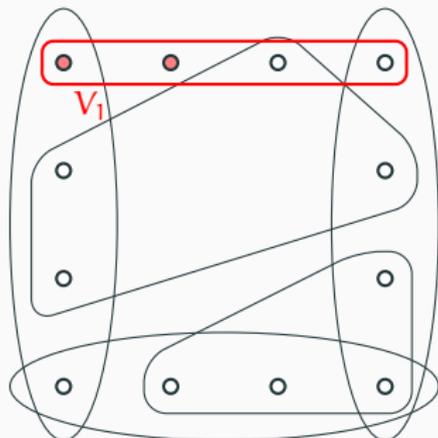
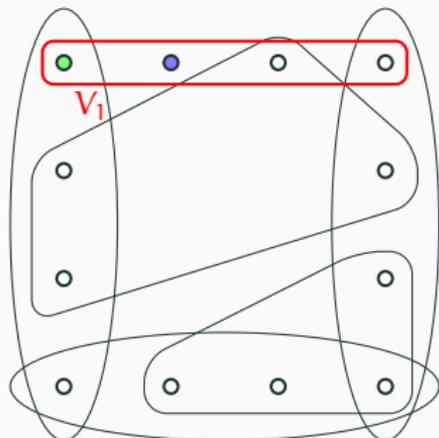
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O(\frac{1}{n^\epsilon})$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

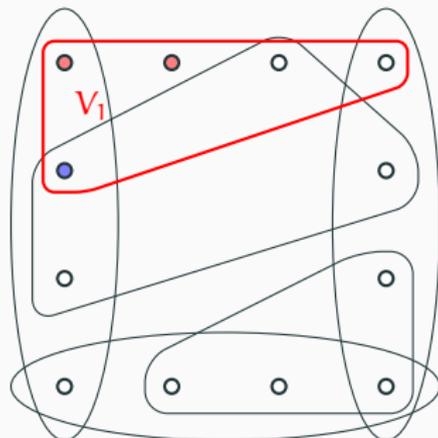
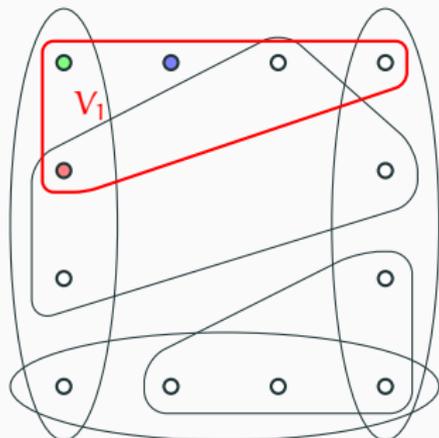
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

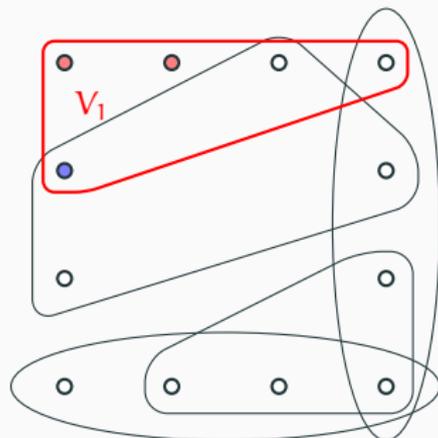
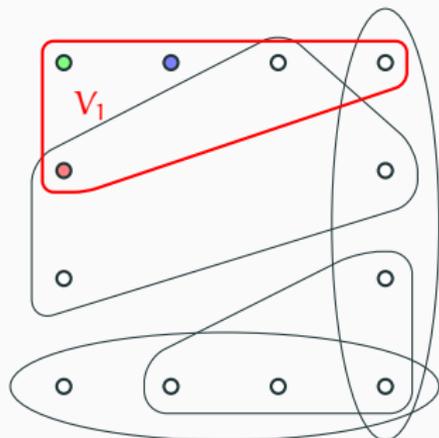
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

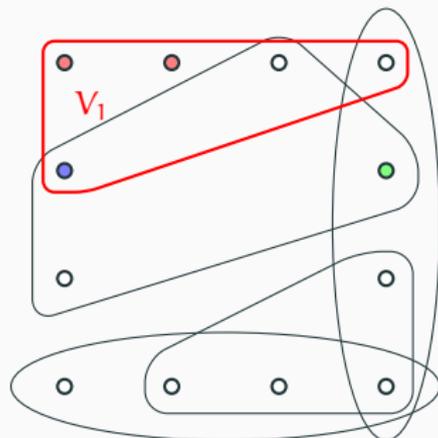
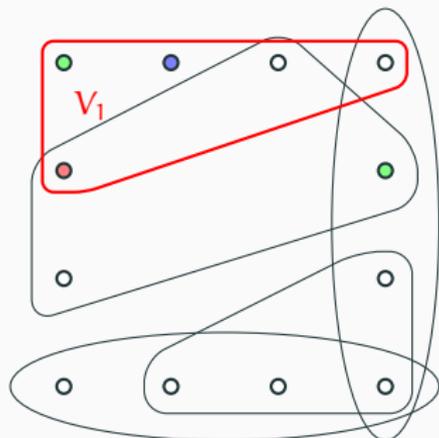
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

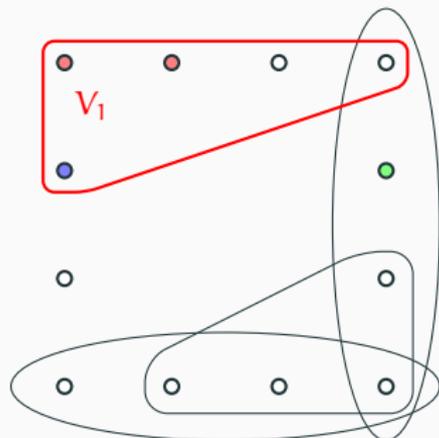
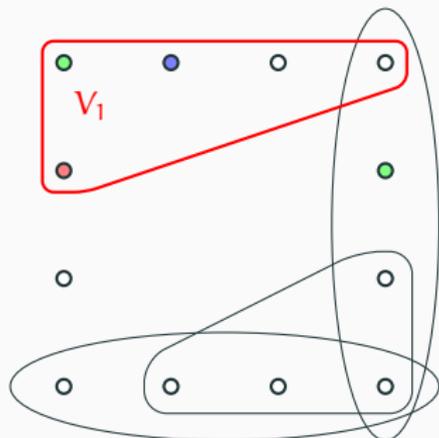
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

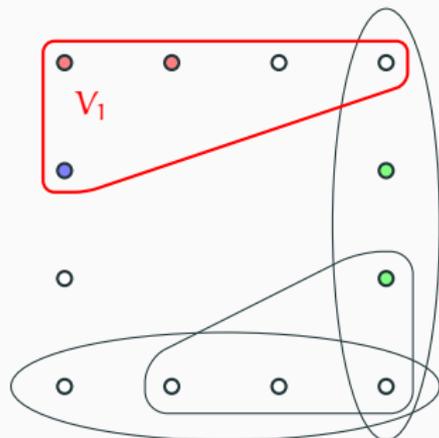
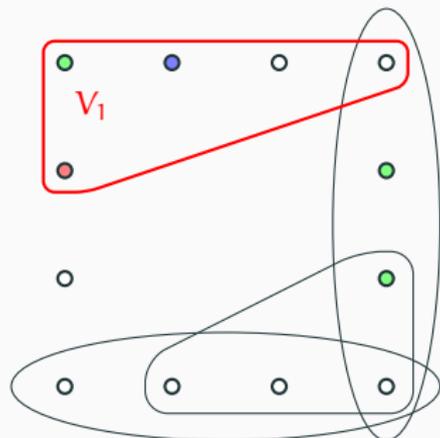
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

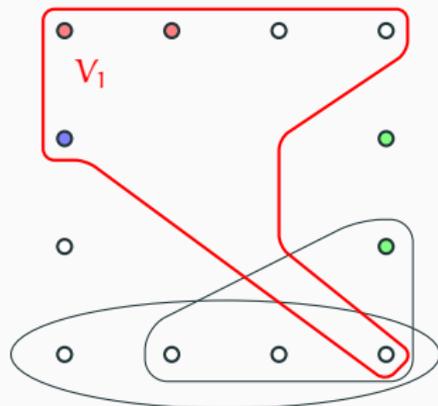
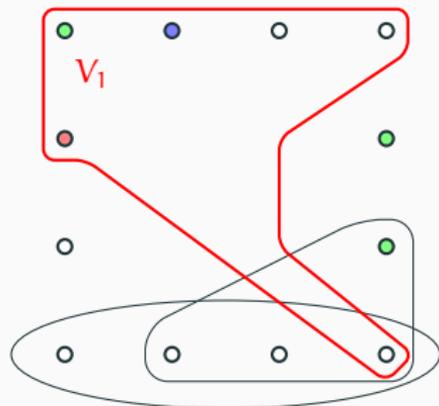
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

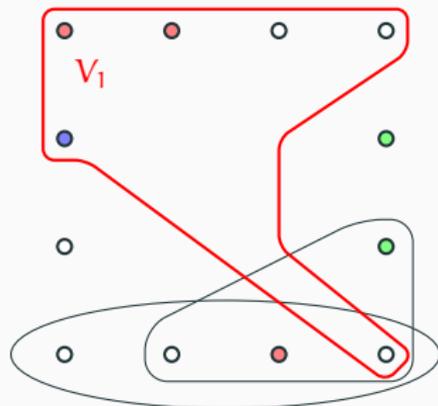
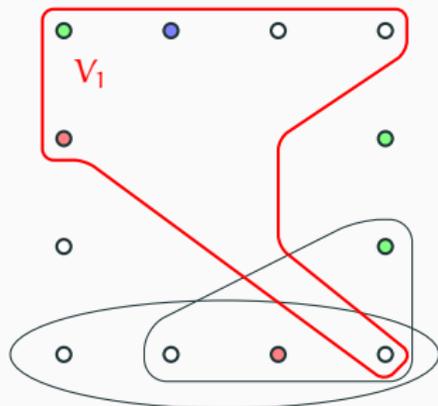
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

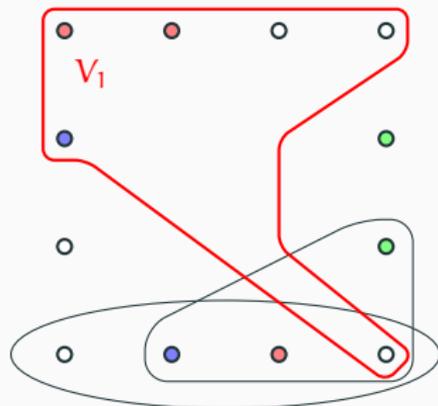
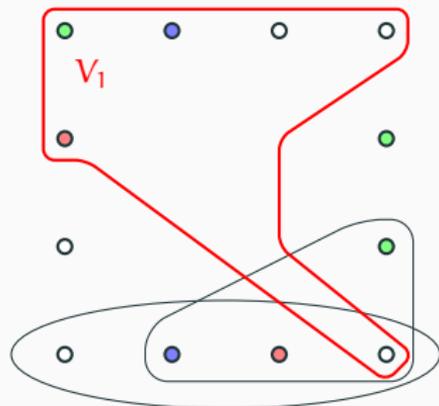
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

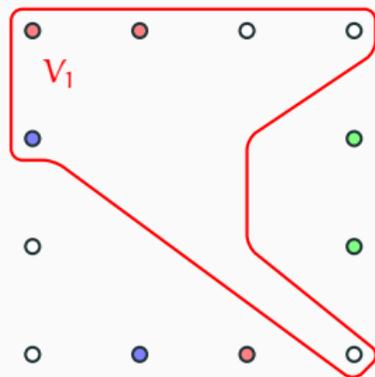
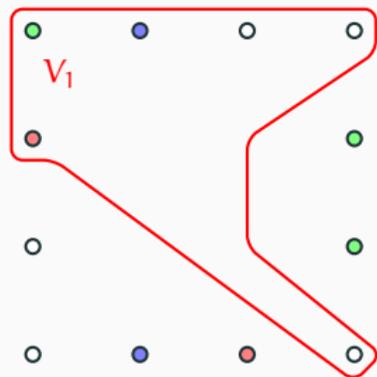
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

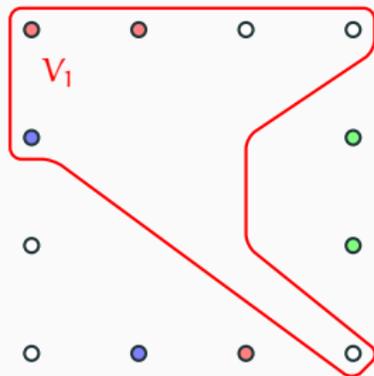
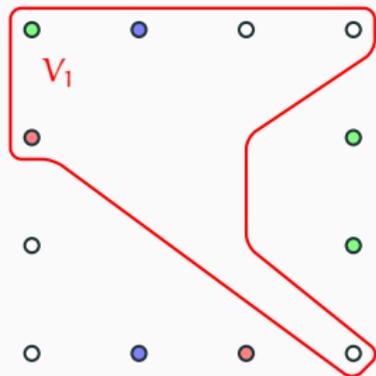
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^\epsilon}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.



At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

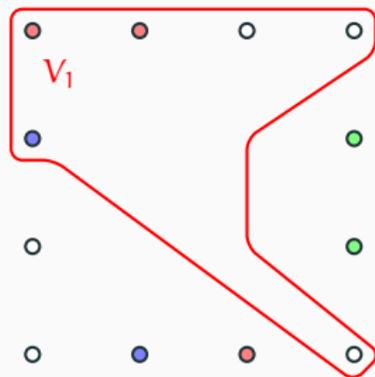
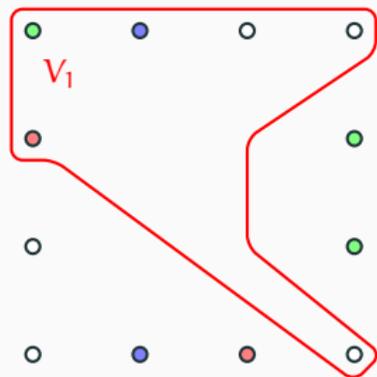
If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^c}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING - AN EXAMPLE

V_1 : discrepancy. V_{col} : coloured. $V_2 := V \setminus V_1$.

Stop: all hyperedges intersecting V_1 are removed.

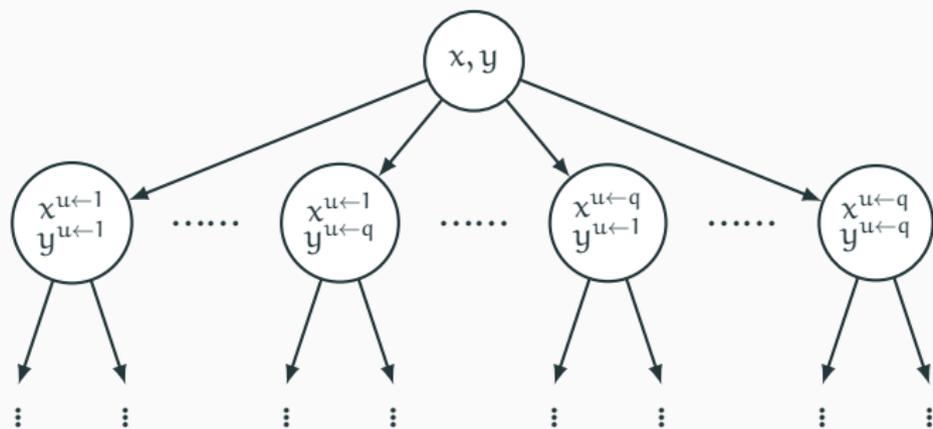


At any time, there are at least $k' - k_2$ empty vertices in any hyperedge.

If $q > C\Delta^{\frac{3}{k' - k_2}}$, then the coupling stops in $O(\log n)$ steps with probability $1 - O\left(\frac{1}{n^c}\right)$.

Moitra (2017) marks what vertices to couple in advance, whereas our coupling is **adaptive**.

COUPLING TREE



Coupling tree \mathcal{T} : each node is a pair of partial colourings (x, y) .

The children of (x, y) are all q^2 ways to extend them to the next vertex.

We cannot really run the coupling. Instead, we set up a linear program. The variables are to mimic:

$$p_{x,y}^x = \frac{|\mathcal{C}_1|}{|\mathcal{C}_x|} \cdot \mu_{cp}(x, y),$$
$$p_{x,y}^y = \frac{|\mathcal{C}_2|}{|\mathcal{C}_y|} \cdot \mu_{cp}(x, y),$$

where \mathcal{C}_i is the set of colourings s.t. $v \leftarrow i$ for $i = 1, 2$, and \mathcal{C}_x (or \mathcal{C}_y) is the set of colourings consistent with x (or y).

Note that $0 \leq p_{x,y}^x, p_{x,y}^y \leq 1$ as $\sum_y p_{x,y}^x = 1$.

We can write down linear constraints for these variables.

We cannot really run the coupling. Instead, we set up a linear program. The variables are to mimic:

$$p_{x,y}^x = \frac{|\mathcal{C}_1|}{|\mathcal{C}_x|} \cdot \mu_{cp}(x, y),$$
$$p_{x,y}^y = \frac{|\mathcal{C}_2|}{|\mathcal{C}_y|} \cdot \mu_{cp}(x, y),$$

where \mathcal{C}_i is the set of colourings s.t. $v \leftarrow i$ for $i = 1, 2$, and \mathcal{C}_x (or \mathcal{C}_y) is the set of colourings consistent with x (or y).

Note that $0 \leq p_{x,y}^x, p_{x,y}^y \leq 1$ as $\sum_y p_{x,y}^x = 1$.

We can write down linear constraints for these variables.

We cannot really run the coupling. Instead, we set up a linear program. The variables are to mimic:

$$p_{x,y}^x = \frac{|\mathcal{C}_1|}{|\mathcal{C}_x|} \cdot \mu_{cp}(x, y),$$
$$p_{x,y}^y = \frac{|\mathcal{C}_2|}{|\mathcal{C}_y|} \cdot \mu_{cp}(x, y),$$

where \mathcal{C}_i is the set of colourings s.t. $v \leftarrow i$ for $i = 1, 2$, and \mathcal{C}_x (or \mathcal{C}_y) is the set of colourings consistent with x (or y).

Note that $0 \leq p_{x,y}^x, p_{x,y}^y \leq 1$ as $\sum_y p_{x,y}^x = 1$.

We can write down linear constraints for these variables.

CONSTRAINTS 1

From the definition: $\frac{|c_1|}{|c_2|} = \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|}$.

If (x, y) is a leaf in \mathcal{T} , then we can compute $\frac{|c_x|}{|c_y|}$ in time $\exp(|V_1 \setminus V_{col}|)$.

Constraints 1: For every leaf (x, y) , we have the constraints:

$$\underline{r} \leq \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|} \leq \bar{r}.$$

Here \underline{r} and \bar{r} are our guessed lower and upper bounds for $\frac{|c_1|}{|c_2|}$.

CONSTRAINTS 1

From the definition: $\frac{|c_1|}{|c_2|} = \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|}$.

If (x, y) is a leaf in \mathcal{T} , then we can compute $\frac{|c_x|}{|c_y|}$ in time $\exp(|V_1 \setminus V_{col}|)$.

Constraints 1: For every leaf (x, y) , we have the constraints:

$$\underline{r} \leq \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|} \leq \bar{r}.$$

Here \underline{r} and \bar{r} are our guessed lower and upper bounds for $\frac{|c_1|}{|c_2|}$.

CONSTRAINTS 1

From the definition: $\frac{|c_1|}{|c_2|} = \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|}$.

If (x, y) is a leaf in \mathcal{T} , then we can compute $\frac{|c_x|}{|c_y|}$ in time $\exp(|V_1 \setminus V_{col}|)$.

Constraints 1: For every leaf (x, y) , we have the constraints:

$$\underline{r} \leq \frac{p_{x,y}^x}{p_{x,y}^y} \cdot \frac{|c_x|}{|c_y|} \leq \bar{r}.$$

Here \underline{r} and \bar{r} are our guessed lower and upper bounds for $\frac{|c_1|}{|c_2|}$.

CONSTRAINTS 2

Constraints 2: For the root $(x_0, y_0) \in \mathcal{T}$, we have

$$p_{x_0, y_0}^{x_0} = p_{x_0, y_0}^{y_0} = 1.$$

Moreover, for every non-leaf $(x, y) \in \mathcal{T}$, let u be the next vertex to couple.

For every $c \in [q]$,

$$\sum_{c' \in [q]} p_{x^{u \leftarrow c}, y^{u \leftarrow c'}}^{x^{u \leftarrow c}} = \frac{|\mathcal{C}_1|}{|\mathcal{C}_{x^{u \leftarrow c}}|} \cdot \frac{|\mathcal{C}_{x^{u \leftarrow c}}|}{|\mathcal{C}_x|} \cdot \mu_{cp}(x, y) = p_{x, y}^x;$$

$$\sum_{c' \in [q]} p_{x^{u \leftarrow c'}, y^{u \leftarrow c}}^{y^{u \leftarrow c}} = \frac{|\mathcal{C}_2|}{|\mathcal{C}_{y^{u \leftarrow c}}|} \cdot \frac{|\mathcal{C}_{y^{u \leftarrow c}}|}{|\mathcal{C}_y|} \cdot \mu_{cp}(x, y) = p_{x, y}^y.$$

RECOVER THE MARGINALS

Due to **Constraints 2**, a simple induction shows that for every $\sigma \in \mathcal{C}_1$,

$$\sum_{(x,y) \in \mathcal{L}(\mathcal{T}): \sigma \models x} p_{x,y}^x = 1.$$

Rewrite $|\mathcal{C}_1|$:

$$\begin{aligned} |\mathcal{C}_1| &= \sum_{\sigma \in \mathcal{C}_1} 1 = \sum_{\sigma \in \mathcal{C}_1} \sum_{(x,y) \in \mathcal{L}(\mathcal{T}): \sigma \models x} p_{x,y}^x \\ &= \sum_{(x,y) \in \mathcal{L}(\mathcal{T})} \sum_{\sigma \models x} p_{x,y}^x \\ &= \sum_{(x,y) \in \mathcal{L}(\mathcal{T})} p_{x,y}^x |\mathcal{C}_x|. \end{aligned}$$

Similar equalities hold on the y side, implying:

$$\frac{|\mathcal{C}_1|}{|\mathcal{C}_2|} = \frac{\sum_{(x,y) \in \mathcal{L}(\mathcal{T})} p_{x,y}^x |\mathcal{C}_x|}{\sum_{(x,y) \in \mathcal{L}(\mathcal{T})} p_{x,y}^y |\mathcal{C}_y|}.$$

RECOVER THE MARGINALS (CONT.)

$$\frac{|c_1|}{|c_2|} = \frac{\sum_{(x,y) \in \mathcal{L}(\mathcal{T})} p_{x,y}^x |C_x|}{\sum_{(x,y) \in \mathcal{L}(\mathcal{T})} p_{x,y}^y |C_y|}$$

Recall **Constraints 1**. For any $(x, y) \in \mathcal{L}(\mathcal{T})$,

$$\underline{r} \leq \frac{p_{x,y}^x |C_x|}{p_{x,y}^y |C_y|} \leq \bar{r}.$$

It implies that

$$\underline{r} \leq \frac{|c_1|}{|c_2|} \leq \bar{r}.$$

CONSTRAINTS 3

Unfortunately, the whole linear program is exponentially large. The saving grace is that the coupling stops at $O(\log n)$ size whp.

If we truncate at $O(\log n)$ levels, the error should be small, due to local uniformity.

Constraints 3: For every $c, c' \in [q]$ that $c \neq c'$:

$$p_{x^{u+c}, y^{u+c'}}^{x^{u+c}} \leq \frac{5}{t} \cdot p_{x,y}^x;$$

$$p_{x^{u+c}, y^{u+c'}}^{y^{u+c'}} \leq \frac{5}{t} \cdot p_{x,y}^y.$$

The quantity t will eventually be set as $C(k\Delta)^6$.

CONSTRAINTS 3

Unfortunately, the whole linear program is exponentially large. The saving grace is that the coupling stops at $O(\log n)$ size whp.

If we truncate at $O(\log n)$ levels, the error should be small, due to local uniformity.

Constraints 3: For every $c, c' \in [q]$ that $c \neq c'$:

$$p_{x^{u \leftarrow c}, y^{u \leftarrow c'}}^{x^{u \leftarrow c}} \leq \frac{5}{t} \cdot p_{x,y}^x;$$

$$p_{x^{u \leftarrow c}, y^{u \leftarrow c'}}^{y^{u \leftarrow c'}} \leq \frac{5}{t} \cdot p_{x,y}^y.$$

The quantity t will eventually be set as $C(k\Delta)^6$.

TRUNCATION ERROR

Recall that

$$|\mathcal{C}_1| = \sum_{\sigma \in \mathcal{C}_1} \sum_{(x,y) \in \mathcal{L}(\mathcal{T}): \sigma \models x} p_{x,y}^x.$$

The truncation error from a particular $\sigma \in \mathcal{C}_1$ comes from conditioned on outputting σ , the coupling lasts too long.

Such “bad” colourings do exist (all early vertices are monochromatic).

We prove two things:

1. The fraction of “bad” colourings is small;
2. For every “good” colouring, the truncation error is small because of **Constraints 3**.

Recall that

$$|\mathcal{C}_1| = \sum_{\sigma \in \mathcal{C}_1} \sum_{(x,y) \in \mathcal{L}(\mathcal{T}): \sigma \models x} p_{x,y}^x.$$

The truncation error from a particular $\sigma \in \mathcal{C}_1$ comes from conditioned on outputting σ , the coupling lasts too long.

Such “bad” colourings do exist (all early vertices are monochromatic).

We prove two things:

1. The fraction of “bad” colourings is small;
2. For every “good” colouring, the truncation error is small because of **Constraints 3**.

Recall that

$$|\mathcal{C}_1| = \sum_{\sigma \in \mathcal{C}_1} \sum_{(x,y) \in \mathcal{L}(\mathcal{T}): \sigma \models x} p_{x,y}^x.$$

The truncation error from a particular $\sigma \in \mathcal{C}_1$ comes from conditioned on outputting σ , the coupling lasts too long.

Such “bad” colourings do exist (all early vertices are monochromatic).

We prove two things:

1. The fraction of “bad” colourings is small;
2. For every “good” colouring, the truncation error is small because of **Constraints 3**.

BOUND THE ERROR

A “bad” colouring must fail many hyperedges during the coupling, but we couple k_2 vertices of every hyperedge.

Thus its fraction is small if k_2 is sufficiently large.

The error allowed by **Constraints 3** is controlled by the number of uncoloured vertices in the coupling process, namely the quantity $k' - k_2$.

The larger $k' - k_2$, the more uniform all vertices are and the smaller coupling errors.

We solve an optimization problem to get the best k_2 balancing the two points above.

BOUND THE ERROR

A “bad” colouring must fail many hyperedges during the coupling, but we couple k_2 vertices of every hyperedge.

Thus its fraction is small if k_2 is sufficiently large.

The error allowed by **Constraints 3** is controlled by the number of uncoloured vertices in the coupling process, namely the quantity $k' - k_2$.

The larger $k' - k_2$, the more uniform all vertices are and the smaller coupling errors.

We solve an optimization problem to get the best k_2 balancing the two points above.

BOUND THE ERROR

A “bad” colouring must fail many hyperedges during the coupling, but we couple k_2 vertices of every hyperedge.

Thus its fraction is small if k_2 is sufficiently large.

The error allowed by **Constraints 3** is controlled by the number of uncoloured vertices in the coupling process, namely the quantity $k' - k_2$.

The larger $k' - k_2$, the more uniform all vertices are and the smaller coupling errors.

We solve an optimization problem to get the best k_2 balancing the two points above.

So far we are calculating the marginal probability, which requires that there are **sufficiently** many uncoloured vertices in **all** hyperedges.

- For approximate counting, we use the local lemma to find a partial colouring so that every hyperedge is satisfied by its first $\frac{k}{14}$ vertices. Then we compute the marginal probability of this partial colouring by pinning vertices one by one.
- For sampling, we use the marginal to colour vertices, similar to the coupling process. We colour $\frac{3k}{16}$ vertices of every hyperedge. With high probability, every remaining connected component has size $O(\log n)$.

So far we are calculating the marginal probability, which requires that there are **sufficiently** many uncoloured vertices in **all** hyperedges.

- For approximate counting, we use the local lemma to find a partial colouring so that every hyperedge is satisfied by its first $\frac{k}{14}$ vertices. Then we compute the marginal probability of this partial colouring by pinning vertices one by one.
- For sampling, we use the marginal to colour vertices, similar to the coupling process. We colour $\frac{3k}{16}$ vertices of every hyperedge. With high probability, every remaining connected component has size $O(\log n)$.

So far we are calculating the marginal probability, which requires that there are **sufficiently** many uncoloured vertices in **all** hyperedges.

- For approximate counting, we use the local lemma to find a partial colouring so that every hyperedge is satisfied by its first $\frac{k}{14}$ vertices. Then we compute the marginal probability of this partial colouring by pinning vertices one by one.
- For sampling, we use the marginal to colour vertices, similar to the coupling process. We colour $\frac{3k}{16}$ vertices of every hyperedge. With high probability, every remaining connected component has size $O(\log n)$.

CONCLUDING REMARKS

- What is the correct threshold for hypergraph colouring?
 - Is it $q \asymp \Delta^{\frac{2}{k}}$?
- What about **NP**-hardness of sampling hypergraph colourings?
- Does this method work for general LLL?
- What is the relationship between this method and traditional ones (Markov chains, spatial mixing, etc.)?

- What is the correct threshold for hypergraph colouring?
 - Is it $q \asymp \Delta^{\frac{2}{k}}$?
- What about NP-hardness of sampling hypergraph colourings?
- Does this method work for general LLL?
- What is the relationship between this method and traditional ones (Markov chains, spatial mixing, etc.)?

- What is the correct threshold for hypergraph colouring?
 - Is it $q \asymp \Delta^{\frac{2}{k}}$?
- What about **NP**-hardness of sampling hypergraph colourings?
- Does this method work for general LLL?
- What is the relationship between this method and traditional ones (Markov chains, spatial mixing, etc.)?

- What is the correct threshold for hypergraph colouring?
 - Is it $q \asymp \Delta^{\frac{2}{k}}$?
- What about **NP**-hardness of sampling hypergraph colourings?
- Does this method work for general LLL?
- What is the relationship between this method and traditional ones (Markov chains, spatial mixing, etc.)?

- What is the correct threshold for hypergraph colouring?
 - Is it $q \asymp \Delta^{\frac{2}{k}}$?
- What about **NP**-hardness of sampling hypergraph colourings?
- Does this method work for general LLL?
- What is the relationship between this method and traditional ones (Markov chains, spatial mixing, etc.)?

THANK YOU!

arXiv:1711.03396