

GAV-sound with conjunctive queries

- Source and global schema as before:
 - source $R_1(A, B), R_2(B, C)$
 - Global schema: $T_1(A, C), T_2(B, C)$
- GAV mappings become sound:
 - $T_1 \supseteq \{x, y, z \mid R_1(x, y) \wedge R_2(y, z)\}$
 - $T_2 \supseteq R_2$
- Let D_{exact} be the unique database that arises from the *exact* setting (with \supseteq replaced by $=$)
- Then every database D_{sound} that satisfies the sound setting also satisfies

$$D_{exact} \subseteq D_{sound}$$

GAV-sound with conjunctive queries cont'd

- Conjunctive queries are monotone:

$$D_1 \subseteq D_2 \quad \Rightarrow \quad Q(D_1) \subseteq Q(D_2)$$

- Exact solution is a sound solution too, and is contained in every sound solution.
- Hence certain answers for each conjunctive query

$$\text{certain}(D, Q) = \bigcap_{D_{\text{sound}}} Q(D_{\text{sound}}) = Q(D_{\text{exact}})$$

- The solution for GAV-exact gives us certain answers for GAV-sound, for conjunctive (and more generally, monotone) queries.

Query answering using views

- General setting: database relations R_1, \dots, R_n .
- Several views V_1, \dots, V_k are defined as results of queries over the R_i 's.
- We have a query Q over R_1, \dots, R_n .
- **Question:** Can Q be answered in terms of the views?
 - In other words, can Q be reformulated so it only refers to the data in V_1, \dots, V_k ?

Query answering using views in data integration

- LAV:
 - R_1, \dots, R_n are global schema relations; Q is the global schema query
 - V_i 's are the sources defined over the global schema
 - We must answer Q based on the sources (virtual integration)
- GAV:
 - R_1, \dots, R_n are the sources that are not fully available.
 - Q is a query in terms of the source (or a query that was reformulated in terms of the sources)
 - Must see if it is answerable from the available views V_1, \dots, V_k .
- We know the problem is impossible to solve for full relational algebra, hence we concentrate on **conjunctive queries**.

Conjunctive queries: rule-based notation

- We often write conjunctive queries as logical statements:

$$\{t, y, r \mid \exists d (\text{Movie}(t, d, y) \wedge \text{RV}(t, r) \wedge y > 2000)\}$$

- Rule-based:

$$Q(t, y, r) \text{ :- Movie}(t, d, y), \text{RV}(t, r), y > 2000$$

- $Q(t, y, r)$ is the **head** of the rule
- $\text{Movie}(t, d, y), \text{RV}(t, r), y > 2000$ is its **body**
- conjunctions are replaced by commas
- variables that occur in the body but not in the head (d) are assumed to be existentially quantified
- essentially logic programming notation (without functions)

Query answering using views: example

- Two relations in the database: $\text{Cites}(A,B)$ (if A cites B), and $\text{SameTopic}(A,B)$ (if A, B work on the same topic)
- Query $Q(x, y) :- \text{SameTopic}(x, y), \text{Cites}(x, y), \text{Cites}(y, x)$
- Two views are given:
 - $V_1(x, y) :- \text{Cites}(x, y), \text{Cites}(y, x)$
 - $V_2(x, y) :- \text{SameTopic}(x, y), \text{Cites}(x, x'), \text{Cites}(y, y')$
- Suggested rewriting: $Q'(x, y) :- V_1(x, y), V_2(x, y)$
- Why? Unfold using the definitions:
 $Q'(x, y) :- \text{Cites}(x, y), \text{Cites}(y, x), \text{SameTopic}(x, y), \text{Cites}(x, x'), \text{Cites}(y, y')$
- Equivalent to Q

Query answering using views

- Need a formal technique (algorithm): cannot rely on the semantics.

- Query Q :

```
SELECT R1.A
FROM R R1, R R2, S S1, S S2
WHERE R1.A=R2.A AND S1.A=S2.A AND R1.A=S1.A
      AND R1.B=1 and S2.B=1
```

- $Q(x) :- R(x, y), R(x, 1), S(x, z), S(x, 1)$

- Equivalent to $Q(x) :- R(x, 1), S(x, 1)$

- So if we have a view

- $V(x, y) :- R(x, y), S(x, y)$ (i.e. $V = R \cap S$), then
- $Q = \pi_A(\sigma_{B=1}(V))$
- Q can be rewritten (as a conjunctive query) in terms of V

Query rewriting

- Setting:
 - Queries V_1, \dots, V_k over the same schema σ (assume to be conjunctive; they define the views)
 - Each Q_i is of arity n_i
 - A schema ω with relations of arities n_1, \dots, n_k
- Given:
 - a query Q over σ
 - a query Q' over ω
- Q' is a **rewriting** of Q if for every σ -database D ,

$$Q(D) = Q'(V_1(D), \dots, V_k(D))$$

Maximal rewriting

- Sometimes exact rewritings cannot be obtained
- Q' is a **maximally-contained** rewriting if:
 - it is contained in Q :

$$Q'(V_1(D), \dots, V_k(D)) \subseteq Q(D)$$

for all D

- it is maximal such: if

$$Q''(V_1(D), \dots, V_k(D)) \subseteq Q(D)$$

for all D , then

$$Q'' \subseteq Q'$$

Side remark: query rewriting and certain answers

- If we have sources $\mathbf{R} = (R_1, \dots, R_k)$, we can view conditions

$$V_1(D) = R_1, \dots, V_k(D) = R_k$$

as an incomplete specification of a database D

- To answer Q over D , given R_1, \dots, R_k , we want to compute certain answers:

$$\text{certain}(Q, \mathbf{R}) = \bigcap \{Q(D) \mid V_1(D) = R_1, \dots, V_k(D) = R_k\}$$

- If for every such D we have $Q(D) = Q'(V_1(D), \dots, V_k(D))$, then $\text{certain}(Q, \mathbf{R}) = Q'$.
- But we may even look at a more general way of query answering by finding a rewriting Q' so that

$$\text{certain}(Q, \mathbf{R}) = Q'(\mathbf{R})$$

Query rewriting: a naive algorithm

- Given:
 - conjunctive queries V_1, \dots, V_k over schema σ
 - a query Q over σ
- Algorithm:
 - guess a query Q' over the views
 - Unfold Q' in terms of the views
 - Check if the unfolding is contained in Q
- If one unfolding is equivalent to Q , then Q' is a rewriting
- Otherwise take the union of all unfoldings contained in Q
 - it is a maximally contained rewriting

Why is it not an algorithm yet?

- **Problem 1:** we do not yet know how to test containment and equivalence.
 - But we shall learn soon
- **Problem 2:** the guess stage.
 - There are infinitely many conjunctive queries.
 - We cannot check them all.
 - Solution: we only need to check a few.

Guessing rewritings

- A **basic fact**:
 - If there is a rewriting of Q using V_1, \dots, V_k , then there is a rewriting with no more conjuncts than in Q .
 - E.g., if $Q(x) :- R(x, y), R(x, 1), S(x, z), S(x, 1)$, we only need to check conjunctive queries over V with at most 4 conjuncts.
- Moreover, maximally contained rewriting is obtained as the union of all conjunctive rewritings of length of Q or less.
- Complexity: enumerate all candidates (exponentially many); for each an NP (or exponential) algorithm. Hence exponential time is required.
- Cannot lower this due to NP-completeness.

Containment and optimization of conjunctive queries

- Reminder:

- conjunctive queries
 - = SPJ queries
 - = rule-based queries
 - = simple SELECT-FROM-WHERE SQL queries
(only AND and equality in the WHERE clause)

- Extremely common, and thus special optimization techniques have been developed
- Reminder: for two relational algebra expressions e_1, e_2 , $e_1 = e_2$ is undecidable.
- But for conjunctive queries, even $e_1 \subseteq e_2$ is decidable.
- Main goal of optimizing conjunctive queries: reduce the number of joins.

Optimization of conjunctive queries: an example

- Given a relation R with two attributes A, B

- Two SQL queries:

Q1

```
SELECT R1.B, R1.A
FROM R R1, R R2
WHERE R2.A=R1.B
```

Q2

```
SELECT R3.A, R1.A
FROM R R1, R R2, R R3
WHERE R1.B=R2.B AND R2.B=R3.A
```

- Are they equivalent?
- If they are, we saved one join operation.
- In relational algebra:

$$Q_1 = \pi_{2,1}(\sigma_{2=3}(R \times R))$$

$$Q_2 = \pi_{5,1}(\sigma_{2=4 \wedge 4=5}(R \times R \times R))$$

Optimization of conjunctive queries cont'd

- Are Q_1 and Q_2 equivalent?
- If they are, we cannot show it by using equivalences for relational algebra expression.
- Because: they don't decrease the number of \bowtie or \times operators, but Q_1 has 1 join, and Q_2 has 2.
- But Q_1 and Q_2 are equivalent. How can we show this?
- But representing queries as databases. This representation is very close to rule-based queries.

$$Q_1(x, y) \text{ :- } R(y, x), R(x, z)$$

$$Q_2(x, y) \text{ :- } R(y, x), R(w, x), R(x, u)$$

Conjunctive queries into tableaux

- Tableau: representing of a conjunctive query as a database
- We first consider queries over a single relation
- $Q_1(x, y) :- R(y, x), R(x, z)$
- $Q_2(x, y) :- R(y, x), R(w, x), R(x, u)$
- Tableaux:

A	B
y	x
x	z
x	y

← answer line

A	B
y	x
w	x
x	u
x	y

← answer line

- Variables in the answer line are called distinguished

Tableau homomorphisms

- A homomorphism of two tableaux $f : T_1 \rightarrow T_2$ is a mapping

$$f : \{\text{variables of } T_1\} \rightarrow \{\text{variables of } T_2\} \cup \{\text{constants}\}$$

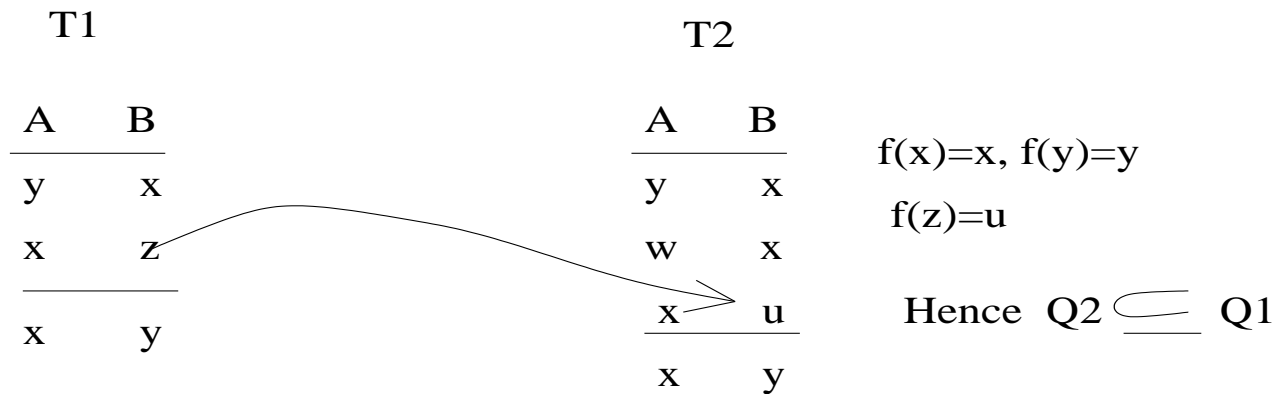
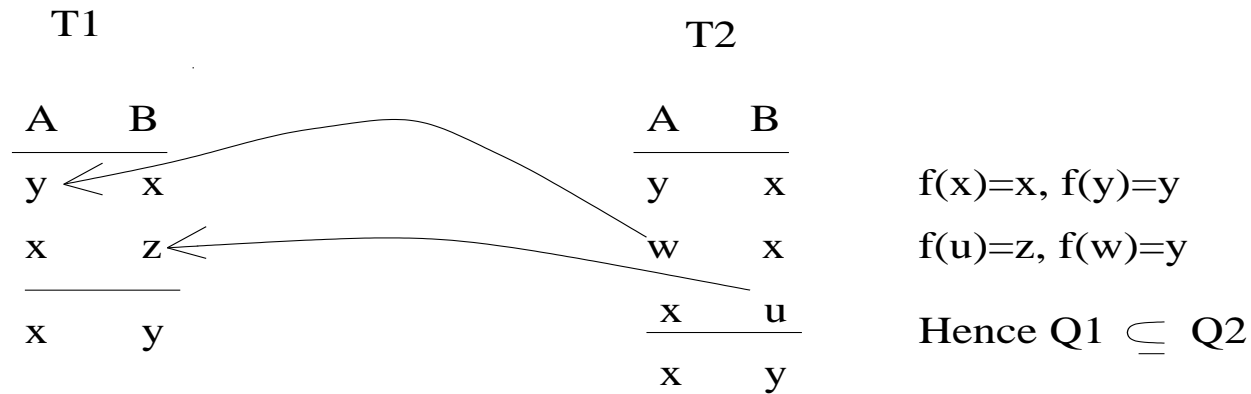
- For every distinguished x , $f(x) = x$
- For every row x_1, \dots, x_k in T_1 , $f(x_1), \dots, f(x_k)$ is a row of T_2
- Query containment: $Q \subseteq Q'$ if $Q(D) \subseteq Q'(D)$ for every database D
- **Homomorphism Theorem:** Let Q, Q' be two conjunctive queries, and T, T' their tableaux. Then

$$Q \subseteq Q'$$

if and only if

there exists a homomorphism $f : T' \rightarrow T$

Applying the Homomorphism Theorem: $Q_1 = Q_2$



Applying the Homomorphism Theorem: Complexity

- Given two conjunctive queries, how hard is it to test if $Q_1 = Q_2$?
- it is easy to transform them into tableaux, from either SPJ relational algebra queries, or SQL queries, or rule-based queries
- But testing the existence of a homomorphism between two tableaux is hard: NP-complete. Thus, a polynomial algorithm is unlikely to exist.
- However, queries are small, and conjunctive query optimization is possible in practice.

Minimizing conjunctive queries

- Goal: given a conjunctive query Q , find an equivalent conjunctive query Q' with the minimum number of joins.

- Assume Q is

$$Q(\vec{x}) \text{ :- } R_1(\vec{u}_1), \dots, R_k(\vec{u}_k)$$

- Assume that there is an equivalent conjunctive query Q' of the form

$$Q'(\vec{x}) \text{ :- } S_1(\vec{v}_1), \dots, S_l(\vec{v}_l)$$

with $l < k$

- Then Q is equivalent to a query of the form

$$Q'(\vec{x}) \text{ :- } R_{i_1}(\vec{u}_{i_1}), \dots, R_l(\vec{u}_{i_l})$$

- In other words, to minimize a conjunctive query, one has to delete some subqueries on the right of :-

Minimizing conjunctive queries cont'd

- Given a conjunctive query Q , transform it into a tableau T
- Let Q' be a minimal conjunctive query equivalent to Q . Then its tableau T' is a subset of T .
- Minimization algorithm:
 $T' := T$
repeat until no change
 choose a row t in T'
 if there is a homomorphism $f : T' \rightarrow T' - \{t\}$
 then $T' := T' - \{t\}$
end
- Note: if there exists a homomorphism $T' \rightarrow T' - \{t\}$, then the queries defined by T' and $T' - \{t\}$ are equivalent. Because: there is always a homomorphism from $T' - \{t\}$ to T' . (Why?)

Minimizing SPJ/conjunctive queries: example

- R with three attributes A, B, C

- SPJ query

$$Q = \pi_{AB}(\sigma_{B=4}(R)) \bowtie \pi_{BC}(\pi_{AB}(R) \bowtie \pi_{AC}(\sigma_{B=4}(R)))$$

- Equivalently, a SQL query:

```
SELECT R1.A, R2.B, R3.C
FROM R R1, R R2, R R3
WHERE R1.B=4 AND R2.A=R3.A AND
      R3.B=4 AND R2.B=R1.B
```

- Translate into a conjunctive query:

$$\exists x_1, z_1, z_2 (R(x, 4, z_1) \wedge R(x_1, 4, z_2) \wedge R(x_1, 4, z) \wedge y = 4)$$

- Rule-based:

$$Q(x, y, z) :- R(x, 4, z_1), R(x_1, 4, z_2), R(x_1, 4, z), y = 4$$

Minimizing SPJ/conjunctive queries cont'd

- Tableau T :

A	B	C
x	4	z_1
x_1	4	z_2
x_1	4	z
x	4	z

- Minimization, step 1: is there a homomorphism from T to

A	B	C
x_1	4	z_2
x_1	4	z
x	4	z

- Answer: No. For any homomorphism f , $f(x) = x$ (why?), thus the image of the first row is not in the small tableau.

Minimizing SPJ/conjunctive queries cont'd

- Step 2: Is T equivalent to

A	B	C
x	4	z_1
x_1	4	z
x	4	z
- Answer: Yes. Homomorphism $f: f(z_2) = z$, all other variables stay the same.
- The new tableau is not equivalent to

A	B	C
x	4	z_1
x	4	z

 or

A	B	C
x_1	4	z
x	4	z
- Because $f(x) = x$, $f(z) = z$, and the image of one of the rows is not present.

Minimizing SPJ/conjunctive queries cont'd

- Minimal tableau:

A	B	C
x	4	z_1
x_1	4	z
x	4	z

- Back to conjunctive query:

$$Q'(x, y, z) :- R(x, y, z_1), R(x_1, y, z), y = 4$$

- An SPJ query:

$$\pi_{AB}(\sigma_{B=4}(R)) \bowtie \pi_{BC}(\sigma_{B=4}(R))$$

- SELECT R1.A, R1.B, R2.C
FROM R R1, R R2
WHERE R1.B=R2.B AND R1.B=4

Review of the journey

- We started with

$$\pi_{AB}(\sigma_{B=4}(R)) \bowtie \pi_{BC}(\pi_{AB}(R) \bowtie \pi_{AC}(\sigma_{B=4}(R)))$$

- Translated into a conjunctive query
- Built a tableau and minimized it
- Translated back into conjunctive query and SPJ query
- Applied algebraic equivalences and obtained

$$\pi_{AB}(\sigma_{B=4}(R)) \bowtie \pi_{BC}(\sigma_{B=4}(R))$$

- Savings: one join.

All minimizations are equivalent

- Let Q be a conjunctive query, and Q_1, Q_2 two conjunctive queries equivalent to Q
- Assume that Q_1 and Q_2 are both minimal, and let T_1 and T_2 be their tableaux.
- Then T_1 and T_2 are isomorphic; that is, T_2 can be obtained from T_1 by renaming of variables.
- That is, all minimizations are equivalent.
- In particular, in the minimization algorithm, the order in which rows are considered, is irrelevant.

Equivalence of conjunctive queries: the general case

- So far we assumed that there is only one relation R , but what if there are many?
- Construct tableaux as before:

$$Q(x, y): -B(x, y), R(y, z), R(y, w), R(w, y)$$

- Tableau:

		A	B
B:	$\frac{A \quad B}{x \quad y}$	R:	$\frac{A \quad B}{y \quad z}$
			$y \quad w$
			$w \quad y$
<hr/>			
	x		y

- Formally, a tableau is just a database where variables can appear in tuples, plus a set of distinguished variables.

Tableaux and multiple relations

- Given two tableaux T_1 and T_2 over the same set of relations, and the same distinguished variables, a homomorphism $h : T_1 \rightarrow T_2$ is a mapping

$$f : \{\text{variables of } T_1\} \rightarrow \{\text{variables of } T_2\}$$

such that

- $f(x) = x$ for every distinguished variable, and
 - for each row \vec{t} in R in T_1 , $f(\vec{t})$ is in R in T_2 .
- **Homomorphism theorem:** let Q_1 and Q_2 be conjunctive queries, and T_1, T_2 their tableaux. Then

$$Q_2 \subseteq Q_1$$

if and only if

there exists a homomorphism $f : T_1 \rightarrow T_2$

Query rewriting

- Recall the algorithm, for a given Q and view definitions V_1, \dots, V_k :
 - Look at all rewritings that have as at most as many joins as Q
 - check if they are contained in Q
 - take the union of those that are
- This is the maximally contained rewriting
- There are algorithms that prune the search space and make looking for rewritings contained in Q more efficient
 - the bucket algorithm
 - MiniCon

How hard is it to answer queries using views?

- Setting: we now have an actual **content** of the views.
- As before, a query is Q posed against D , but must be answered using information in the views.
- Suppose I_1, \dots, I_k are view instances. Two possibilities:
 - Exact mappings: $I_j = V_j(D)$
 - Sound mappings: $I_j \subseteq V_j(D)$
- We need certain answers for given $\mathcal{I} = (I_1, \dots, I_k)$:

$$\text{certain}_{\text{exact}}(Q, \mathcal{I}) = \bigcap_{D: I_j = V_j(D) \text{ for all } j} Q(D)$$

$$\text{certain}_{\text{sound}}(Q, \mathcal{I}) = \bigcap_{D: I_j \subseteq V_j(D) \text{ for all } j} Q(D)$$

How hard is it to answer queries using views?

- If certain_{exact}(Q, \mathcal{I}) or certain_{sound}(Q, \mathcal{I}) are impossible to obtain, we want **maximally contained rewritings**:
 - $Q'(\mathcal{I}) \subseteq \text{certain}_{\text{exact}}(Q, \mathcal{I})$, and
 - if $Q''(\mathcal{I}) \subseteq \text{certain}_{\text{exact}}(Q, \mathcal{I})$ then $Q''(\mathcal{I}) \subseteq Q'(\mathcal{I})$
 - (and likewise for *sound*)
- How hard is it to compute this from \mathcal{I} ?
- In databases, we reason about complexity in two ways:
 - The big-O notation ($O(n \log n)$ vs $O(n^2)$ vs $O(2^n)$)
 - Complexity-theoretic notions: PTIME, NP, DLOGSPACE, etc
- Advantage of complexity-theoretic notions: if you have a $O(2^n)$ algorithm, is it because the problem is inherently hard, or because we are not smart enough to come up with a better algorithm (or both)?

Complexity classes: what you always wanted to know but never dared to ask

- Or a 5/5-introduction: a five minute review that tells you what are likely to remember 5 years after taking a complexity theory course.
- The **big divide**: **PTIME** (computable in polynomial time, i.e. $O(n^k)$ for some fixed k)
- Inside **PTIME**: tractable queries (although high-degree polynomial are intractable)
- Outside **PTIME**: intractable queries (efficient algorithms are unlikely)
- Way outside **PTIME**: provably intractable queries (efficient algorithms do not exist)
 - EXPTIME: c^n -algorithms for a constant c . Could still be ok for not very large inputs
 - Even further – 2-EXPTIME: c^{c^n} . Cannot be ok even for small inputs (compare 2^{10} and $2^{2^{10}}$).

Inside PTIME

$$AC^0 \subsetneq TC^0 \subseteq NC^1 \subseteq DLOG \subseteq NLOG \subseteq PTIME$$

- AC^0 : very efficient parallel algorithms (constant time, simple circuits)
 - relational calculus
- TC^0 : very efficient parallel algorithms in a more powerful computational model with counting gates
 - basic SQL (relational calculus/grouping/aggregation)
- NC^1 : efficient parallel algorithms
 - regular languages
- $DLOG$: very little – $O(\log n)$ – space is required
 - SQL + (restricted) transitive closure
- $NLOG$: $O(\log n)$ space is required if nondeterminism is allowed
 - SQL + transitive closure (as in the SQL3 standard)

Beyond PTIME

$$\text{PTIME} \subseteq \left\{ \begin{array}{c} \text{NP} \\ \text{coNP} \end{array} \right\} \subseteq \text{PSPACE}$$

- **PTIME**: can solve a problem in polynomial time
- **NP**: can check a given candidate solution in polynomial time
 - another way of looking at it: guess a solution, and then verify if you guessed it right in polynomial time
- **coNP**: complement of NP – verify that all “reasonable” candidates are solutions to a given problem.
 - Appears to be harder than NP but the precise relationship isn’t known
- **PSPACE**: can be solved using memory of polynomial size (but perhaps an exponential-time algorithm)

Complete problems

- These are the hardest problems in a class.
- If our problem is as hard as a complete problem, it is very unlikely it can be done with lower complexity.
- For NP:
 - SAT (satisfiability of Boolean formulae)
 - many graph problems (e.g. 3-colourability)
 - Integer linear programming etc
- For PSPACE:
 - Quantified SAT
 - Two XML DTDs are equivalent

Complexity of query answering

- We want the complexity of finding

$$\text{certain}_{\text{exact}}(Q, \mathcal{I}) \quad \text{or} \quad \text{certain}_{\text{sound}}(Q, \mathcal{I})$$

in terms of the size of \mathcal{I}

- If all view definitions are conjunctive queries and Q is a relational algebra or a SQL query, then the complexity is **coNP**.
- (blackboard)
- This is too high!
- If all view definitions are conjunctive queries and Q is a conjunctive query, then the complexity is **PTIME**.
 - Because: the maximally contained rewriting computes certain answers!

Complexity of query answering

view language	query language		
	CQ	CQ [≠]	relational calculus
CQ	ptime	coNP	undecidable
CQ [≠]	ptime	coNP	undecidable
relational calculus	undecidable	undecidable	undecidable

CQ – conjunctive queries

CQ[≠] – conjunctive queries with **inequalities**
 (for example, $Q(x) :- R(x, y), S(y, z), x \neq z$)

Complexity of query answering: coNP-completeness idea

- Start with a graph G – this is our instance
- D is G together with a colouring, with 3 colours; each node is assigned one colour.
- Q asks if we have an edge (a, b) with $a \neq b$ and a, b of the same colour.
- If G is not 3-colourable, then **every** instance D would satisfy Q
- Otherwise, if G is 3-colourable, we can find extensions that are and that are not 3-colourable – hence certain answers are empty.
- Thus if we can compute certain answers, we can test **non-3-colourability**
 \Rightarrow coNP-completeness.