Query Processing and Optimization

- *Query optimization*: finding a good way to evaluate a query
- Queries are declarative, and can be translated into procedural languages in more than one way
- Hence one has to choose the best (or at least good) procedural query
- This happens in the context of *query processing*
- A query processor turns queries and updates into sequences of of operations on the database

Query processing and optimization stages

- Which relational algebra expression, equivalent to a given declarative query, will lead to the most efficient algorithm?
- For each algebraic operator, what algorithm do we use to compute that operator?
- How do operations pass data (main memory buffer, disk buffer?)

- We first concentrate the first step: finding efficient relational algebra expressions
- For the second step, we need to know how data is stored, and how it is accessed

Overview of query processing

• Start with a declarative query:

```
SELECT R.A, S.B, T.E
FROM R,S,T
WHERE R.C=S.C AND S.D=T.D AND R.A>5 AND S.B<3 AND T.D=T.E
```

• Translate into an algebra expression:

 $\pi_{R.A,S.B,T.E}(\sigma_{R.A>5\land S.B<3\land T.D=T.E}(R\bowtie S\bowtie T))$

• Optimization step: rewrite to an equivalent but more efficient expression:

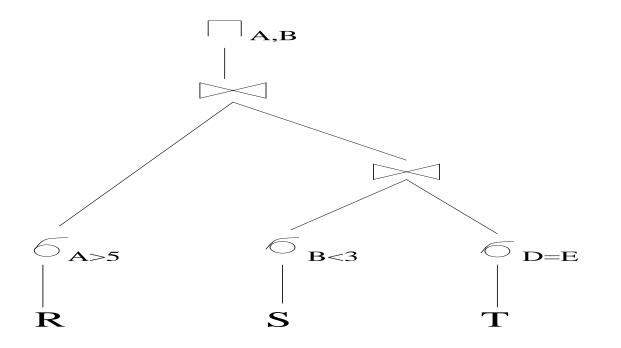
 $\pi_{R.A,S.B,T.E}(\sigma_{A>5}(R) \bowtie \sigma_{B<3}(S) \bowtie \sigma_{D=E}(T)))$

• Why is it more efficient?

Because selections are evaluated early, and joined relations are not as large as R,S,T.

Overview of query processing cont'd

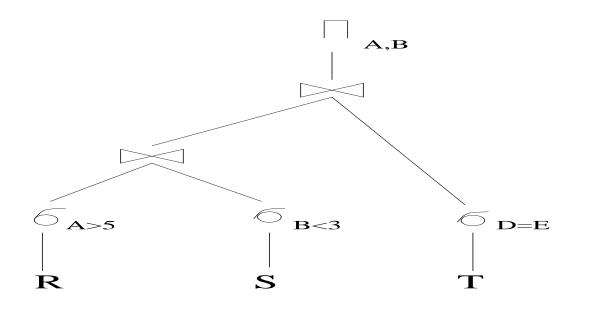
- Evaluating the optimized expression. Choices to make: order of joins.
- Two possible *query plans*:



first joins S, T, and then joins the result with R.

Overview of query processing cont'd

• Another query plan:



It first joins S, T, and then joins the result with R.

- Both query plans produce the same result.
- How to choose one?

Optimization by algebraic manipulations

- Given a relational algebra expression e, find another expression e' equivalent to e that is easier (faster) to evaluate.
- Basic question: Given two relational algebra expressions e_1, e_2 , are they equivalent?
- This is the same as asking if an expression *e* always produces the empty answer:

$$e_1 = e_2 \quad \Leftrightarrow \quad e_1 - e_2 = \emptyset \text{ and } e_2 - e_1 = \emptyset$$

- Problem: testing $e = \emptyset$ is undecidable for relational algebra expressions.
- Good news:

We can still list some useful equalities, and

It is decidable for very important classes of queries (SPJ queries)

Optimization by algebraic manipulations

• Join and Cartesian product are commutative and associative, hence they can be applied in any order:

$$\begin{split} R\times S \ &=\ S\times R\\ R\times (S\times T) \ &=\ (R\times S)\times T\\ R\bowtie S \ &=\ S\bowtie R\\ R\bowtie (S\bowtie T) \ &=\ (R\bowtie S)\bowtie T \end{split}$$

• Cascade of projections. Assume that attributes A_1, \ldots, A_n are among B_1, \ldots, B_m . Then

$$\pi_{A_1,...,A_n}(\pi_{B_1,...,B_m}(E)) = \pi_{A_1,...,A_n}(E)$$

• Cascade of selections:

$$\sigma_{c_1}(\sigma_{c_2}(E)) = \sigma_{c_1 \wedge c_2}(E)$$

Optimization by algebraic manipulations

• Commuting selections and projections. Assume that condition c involves attributes $A_1, \ldots, A_n, B_1, \ldots, B_m$. Then

$$\pi_{A_1,...,A_n}(\sigma_c(E)) = \pi_{A_1,...,A_n}(\sigma_c(\pi_{A_1,...,A_n}, B_1,...,B_m(E)))$$

• A useful special case: if c only involves attributes A_1, \ldots, A_n , then

$$\pi_{A_1,\ldots,A_n}(\sigma_c(E)) = \sigma_c(\pi_{A_1,\ldots,A_n}(E))$$

 \bullet Commuting selection with join. If c only involves attributes from $E_1,$ then

$$\sigma_c(E_1 \bowtie E_2) = \sigma_c(E_1) \bowtie E_2$$

Optimization by algebraic manipulations cont'd

• Let c_1 only mention attributes of E_1 and c_2 only mention attributes of E_2 . Then

$$\sigma_{c_1 \wedge c_2}(E_1 \bowtie E_2) = \sigma_{c_1}(E_1) \bowtie \sigma_{c_2}(E_2)$$

• Because:

$$\sigma_{c_1 \wedge c_2}(E_1 \bowtie E_2)$$

= $\sigma_{c_1}(\sigma_{c_2}(E_1 \bowtie E_2))$
= $\sigma_{c_1}(E_1 \bowtie \sigma_{c_2}(E_2))$
= $\sigma_{c_1}(E_1) \bowtie \sigma_{c_2}(E_2)$

• Another useful rule: If c only mentions attributes present in both E_1 and E_2 , then

$$\sigma_c(E_1 \bowtie E_2) = \sigma_c(E_1) \bowtie \sigma_c(E_2)$$

Optimization by algebraic manipulations cont'd

- \bullet Rules combining σ,π with \cup and -
- Commuting selection and union:

$$\sigma_c(E_1 \cup E_2) = \sigma_c(E_1) \cup \sigma_c(E_2)$$

• Commuting selection and difference:

$$\sigma_c(E_1 - E_2) = \sigma_c(E_1) - \sigma_c(E_2)$$

• Commuting projection and union:

$$\pi_{A_1,\dots,A_n}(E_1 \cup E_2) = \pi_{A_1,\dots,A_n}(E_1) \cup \pi_{A_1,\dots,A_n}(E_2)$$

• Question: what about projection and difference? Is $\pi_A(E_1 - E_2)$ equal to $\pi_A(E_1) - \pi_A(E_2)$? Optimization by algebraic manipulations: example

• Recall

 $\pi_{R.A,S.B,T.E}(\sigma_{R.A>5\land S.B<3\land T.D=T.E}(R\bowtie S\bowtie T))$

• Optimization: pushing selections

 $\pi_{R.A,S.B,T.E}(\sigma_{R.A>5\land S.B<3\land T.D=T.E}(R\bowtie S\bowtie T))$

$$= \pi_{R.A,S.B,T.E}(\sigma_{R.A>5}(\sigma_{S.B<3}(\sigma_{T.D=T.E}(R \bowtie S \bowtie T))))$$

$$= \pi_{R.A,S.B,T.E}(\sigma_{R.A>5}(\sigma_{S.B<3}(R \bowtie S \bowtie (\sigma_{T.D=T.E}(T)))))$$

 $= \pi_{R.A,S.B,T.E}(\sigma_{R.A>5}(R \bowtie \sigma_{S.B<3}(S) \bowtie (\sigma_{T.D=T.E}(T))))$

$$= \pi_{R.A,S.B,T.E}(\sigma_{A>5}(R) \bowtie \sigma_{B<3}(S) \bowtie \sigma_{D=E}(T)))$$

Implementation of individual operations

- Depends on access method and file organization
- Suppose EmplId is a key; how long does it take to answer:

```
\sigma_{\mathsf{EmplId}=1234567}(\mathsf{Employee})?
```

- Time is linear in the worst case
- But one can perform the selection much faster if there is an *index* on attribute EmplId
- Index: auxiliary structure that provides fast access to tuples in a table based on a given key value
- Most common example: B-trees
- With B-trees, the above selection takes $O(\log n)$

Note on indices and SQL

- SQL allows one to create an index on a given attribute or a sequence of attributes
- Once an index is created, the table can be accessed fast if the values of index attributes are known
- SQL always creates an index for attributes declared as a primary key of a table
- Syntax:

```
CREATE INDEX <Index_Name> ON
<Table_Name>(<attr1>,...,<attrN>)
```

• Example:

CREATE INDEX EmplIndex ON Employee(EmplId)

Processing individual operators: join

- Join is the costliest operator of relational algebra
- Query: $R \bowtie S = \sigma_{R.A=S.A}(R \times S)$
- SELECT R.A, R.B, S.C FROM R, S WHERE R.A=S.A
- Naive implementation:

```
for every tuple t1 in R do
for every tuple t2 in S do
if t1.A=t2.A then output (t1.A,t1.B,t2.C)
end
end
```

• Time complexity: $O(n^2)$

Join processing

- Assumption: R.A is the primary key of R.
- New $O(n \log n)$ algorithm:

```
Sort R and S on attribute A;
scanS := first tuple in S;
for each tuple t1 in R do
scan S starting from scanS until a tuple
t2 with t2.A \geq t1.A is found;
if t2.A=t1.A then
while t2.A=t1.A do
if t1.A=t2.A then output (t1.A,t1.B,t2.C);
move to the next tuple t2 of S
end
set scanS := current tuple t2
end
```

Join processing cont'd

- \bullet Previous algorithm can be extended to the case when the common attributes of R and S do not form a key in either relation
- One uses two pointers then to scan the relations
- Name: Sort-Merge join
- Both algorithms would be implemented differently in practice
- No need to do a new disk read to get each tuple; instead, read one block at a time
- Complexity of sort-merge join: If the relations are sorted, it requires $B_R + B_S$ disk reads, where B_R, B_S are the numbers of disk blocks in R, S.

Join processing: hash join

- Reminder: hashing.
- Bucket a unit of storage that can store one or more tuples. Typically several disk blocks
- K a set of search-key values; B a set of buckets
- Hash function $h: K \to B$
- Good properties: uniform, random distribution
- Example of hashing: first two digits of the student # (assumes 100 buckets)
- Example of bad hashing: (account balance mod 100 000) div 10 000
- Overflows. Reason: bad distribution, insufficient buckets.
- Handling of overflows: a linked list of overflow buckets

Join processing: hash join of ${\cal R}$ and ${\cal S}$

- $\bullet\ X$ the set of common attributes
- \bullet Step 1: Select M, the number of buckets
- Step 2: Select a hash function h on attributes from X: $h : {tuples over X} \rightarrow {1, ..., M}$
- Step 3: Partition R and S:
 - $\begin{array}{ll} \mbox{for each t in R do} & \mbox{for each t in S do} \\ i := h(t.X) & \mbox{i} := h(t.X) \\ H_i^R := H_i^R \cup \{t\} & \mbox{H}_i^S := H_i^S \cup \{t\} \\ \mbox{end} & \mbox{end} \end{array}$
- If there are no overflows, this requires $O(B_R + B_S)$ I/O operations (read the relations, and write them back)
- With overflows, one uses recursive partitioning, and then complexity becomes $O(n \log n)$, where $n = B_R + B_S$.

Join processing: hash join of R and S

- Assume that the relations are partitioned
- Algorithm:

for
$$i=1$$
 to M do read H^R_i read H^S_i add $H^R_i \bowtie H^S_i$ to the output end

- Why does it work? If two tuples $t_1 \in R$, $t_2 \in S$ match, $t_1.X = t_2.X$ and $h(t_1) = h(t_2)$; hence they are in the same partition class
 - Improvements: how does one compute $H_i^R \bowtie H_i^S$? One possibility: use another hash function. If it doesn't create overflows, the time for the algorithm is $O(B_R + B_S)$

Using hash functions for Boolean operations

• Observe:

$$R \cap S = (H_1^R \cap H_1^S) \cup \ldots \cup (H_M^R \cap H_M^S)$$

 \bullet Because: if $t \in R \cap S$ and $t \in H^R_i$, then $t \in H^S_i$

- \bullet Advantage: each tuple $t \in R$ must only be compared with $H^S_{h(t)}\text{,}$ and not with the whole relation S
- Using hash functions for difference:

```
for each t in R do i:=h(t) if t\not\in H_i^S, include t in the output end
```

Other operations

- \bullet Set union $R \cup S$: if no index is needed on the result, just append S to R
- If index is needed, then do as above, and then build a new index
- Duplicate elimination: On a sorted relation, it takes linear time. Thus, sort relation R first, based on any attribute(s), and then do one pass and eliminate duplicate
- Complexity: $O(n \log n)$.
- Aggregation with GROUP BY: similarly, sort on the group by attributes, before computing aggregate functions.

• Find names of theaters that play movies featuring Nicholson

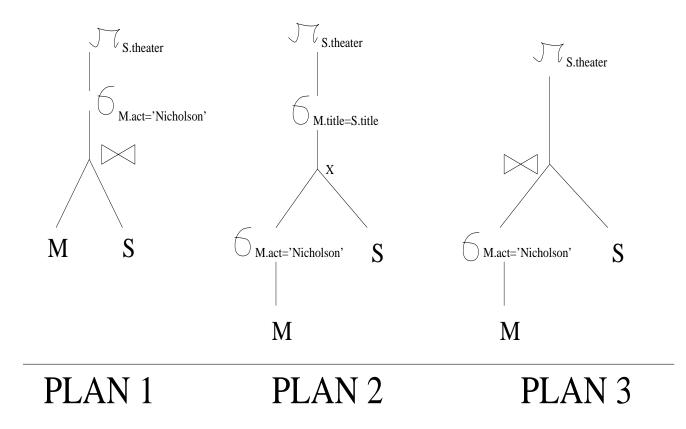
```
SELECT S.theater
FROM Movies M, Schedule S
WHERE M.title=S.title AND M.actor='Nicholson'
```

• Translate into algebra:

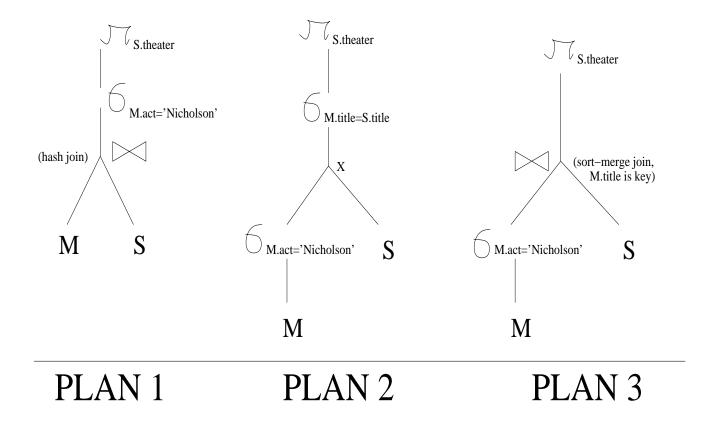
$$\pi_{\text{theater}}(\sigma_{\text{actor}='\text{Nicholson'}}(M \bowtie S))$$

- Next step: choose a query plan
- To do so, use algebraic rewritings to create several equivalent expressions, and then choose algorithms for performing individual operators.

Step 1







- Choosing the best plan: cost-based optimization
- Query optimizer estimates the cost of evaluating each plan
- Particularly important: selectivity estimation (how many tuples in $\sigma_c(E)$?) and join size estimation
- Techniques used: statistics. Sometimes a sampling is done before a query is processed.
- Problem with cost-based optimization: the set of all query plans is extremely large; the optimizer cannot try them all
- Another problem: how long can the optimizer run? Hopefully not as long as the savings it provides.

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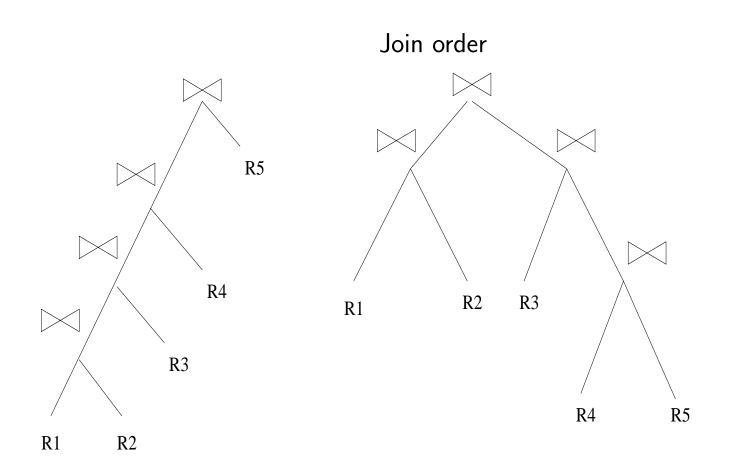
Join order

- We know that join is commutative and associative.
- How does one evaluate

 $R_1 \bowtie R_2 \bowtie R_3 \bowtie R_4 \bowtie R_5?$

• Possibilities:

 $(((R_1 \bowtie R_2) \bowtie R_3) \bowtie R_4) \bowtie R_5$ $(R_1 \bowtie R_2) \bowtie (R_3 \bowtie (R_4 \bowtie R_5))$ $(R_1 \bowtie (R_3 \bowtie R_5)) \bowtie (R_4 \bowtie R_2)$



- DB2 optimizer only considers deep join orders like the one on the left.
- In general, choosing an optimal join order is computationally hard (usually NP-complete for reasonable cost measures)

SQL and query optimization

- Query optimizer helps turn your query into a more efficient one, but you can help the query optimizer do its job better.
- The search space of all possible query plans is extremely large, and optimizers only run for a short time, and thus may fail to find a good plan.
- There are several rules that usually ensure a better query plan; however, a lot depends on a particular system, version, and its optimizers, and these rules may not be universally applicable. Still, if your query isn't running fast enough, it's worth giving them a try.

Order does matter!

```
SELECT * SELECT *

FROM Students is better than HERE grade='A' AND sex='female' AND grade='A'
```

- Because usually there are fewer A students than female students.
- Using orders instead of <>

```
SELECT *
FROM Movies
WHERE Length > 120
OR Length < 120</pre>
SELECT *
SELECT *
FROM Movies
WHERE Length <> 120
WHERE Length <> 120
```

- Because the ordered version forces SQL to use an index on Length, if there is one
- Without such an index, the version with OR runs longer

Provide more JOIN information

SELECT *
FROM T1, T2, T3
WHERE T1.common = T3.common AND T1.common=T2.common
SELECT *
FROM T1, T2, T3
WHERE T1.common = T3.common AND T3.common=T2.common
These may not be as good as
SELECT *

```
FROM T1, T2, T3
WHERE T1.common = T2.common
AND T2.common = T3.common
AND T3.common = T1.common
```

Avoid unions if OR is sufficient

SELECT *
FROM Personnel
WHERE location='Edinburgh'
UNION
SELECT *
FROM Personnel
WHERE location='Glasgow'
is not as good as

```
SELECT DISTINCT*
FROM Personnel
WHERE location='Edinburgh'
OR location='Glasgow'
```

The optimizer normally works within a single SELECT-FROM-WHERE.

Joins are better than nested queries

```
SELECT S.Theater
FROM Schedule S
WHERE S.Title IN (SELECT M.Title
FROM Movies M
WHERE M.director='Spielberg')
```

is likely to run slower than

```
SELECT S.Theater
FROM Schedule S, Movies M
WHERE S.Title = M.Title
AND M.director='Spielberg'
```

Transactions and Concurrency Control

- Transaction: a unit of program execution that accesses and possibly updates some data items.
- A transaction is a collection of operations that logically form a single unit.
- Executing a transaction: either all operations are executed, or none are.
- \bullet Each transactions may consist of several steps, some involving I/O activity, and some CPU activity.
- Moreover, typically several transactions are running on a system; some are long, some are short.
- This creates an opportunity for concurrent execution. Problem: how to ensure consistency?

Transaction model

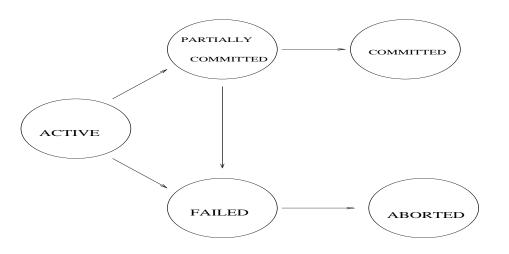
- \bullet Operation $\mathbf{read}(X)$ transfers the data item X from the database to a local buffer belonging to the transaction
- \bullet Operation $\mathbf{write}(X)$ transfers the data item X from the local buffer back to the database
- Example: transfer \$100 from account A to account B read(A);
 A := A 100;
 write(A);
 read(B);
 B := B + 100;
 write(B)
- It executes as a single unit: at no point between read(A) and write(B) can a user query the database, as it might be in an inconsistent state.

ACID properties

- Atomicity: either all operations of a transaction are reflected properly in the database, or none are.
- **Consistency**: execution of a transaction in isolation preserves the consistency of the database.
- Isolation: even though many transactions may run concurrently, the DBMS ensures that for any two transactions T, T', it appears to T that either T' finished before T started, or T' started execution after T finished.
- **Durability**: after a transaction completes successfully, the changes it has made persist.

States of a transaction

- Active: it stays in this state while it is executing
- *Partially committed*: after the final statement has been executed.
- *Failed*: after the discovery that normal execution cannot proceed.
- *Aborted*: after it has been rolled back, and the database state restored to the one prior to the start of the execution.
- *Committed*: after successful completion.



Two transactions

- $\bullet~T$ takes \$100 from account A to account B.
- T' takes 10% of account A to account B.
- Property of T and T': they don't change A+B. Money isn't created, and doesn't disappear.

$$T: read(A);$$

$$A := A - 100;$$
write(A);
read(B);

$$B = B+100;$$
write(B)
$$T': read(A);$$

$$tmp := A*0.1;$$

$$A := A - tmp;$$
write(A);
read(B);

$$B = B+tmp;$$
write(B)

Two serial executions: T;T' and T';T

T	T'	T'	$\mid T$
read(A);		read(A);	
A := A - 100;		tmp := A*0.1;	
write(A);		A := A - tmp;	
read(B);		write(A);	
B = B + 100;		read(B);	
write(B);		B=B+tmp;	
	read(A);	write(B);	
	tmp := A*0.1;		read(A);
	A := A - tmp;		A := A - 100;
	write(A);		write(A);
	read(B);		read(B);
	B = B + tmp;		B = B + 100;
	write(B);		write(B);

Transaction invariant

- A+B doesn't change after T and T' execute.
- Assume that both A and B have \$1,000.
- Evaluating T; T': after T: A=900, B=1100.
 after T': A=810, B=1190.
 A+B=2000.
- Evaluating T'; T: after T': A=900, B=1100 after T: A=800, B=1200. A+B=2000.

Concurrent execution I

T	T'	
read(A);		
A := A - 100;		
write(A);		
	read(A);	
	tmp := A*0.1;	Result:
	A := A - tmp;	A=810
	write(A);	B=1190
read(B);		A+B=2000
B = B + 100;		
write(B);		
	read(B);	
	B = B + tmp;	
	write(B);	

Concurrent execution II

T	T'		
read(A);		-	
A := A - 100;			
$\mathbf{write}(A);$ $\mathbf{read}(B);$ B = B+100; $\mathbf{write}(B);$	<pre>read(A); tmp := A*0.1; A := A - tmp; write(A);</pre>		Result: A=900 B=1200 A+B=2100 We created \$100!
	read(B);		
	B = B + tmp; $\mathbf{write}(B);$		

Serializability

- Why is schedule I good and schedule II bad?
- \bullet Because schedule I is equivalent to a serial execution of T and $T^\prime\text{,}$ and schedule II is not.
- We formalize this via *conflict serializability*.
- Transaction scheduling in DBMSs always ensures serializability.

Simplified representation of transactions

- For scheduling, the only important operations are read and write. What operations are performed on each data item does not affect the schedule.
- We thus represent transactions by a sequence of read-write operations, assuming that between each read(A) and write(A) some computation is done on A.

Simplified representation of transactions cont'd

• Examples of two concurrent executions in the new model:

Scl	hedu	le l
00		

Schedule II

T	T'	T	T'
read(A);		read(A);	
write(A);			read(A); write(A);
	read(A);		write(A);
	write(Á);	write(A);	
read(B);		read(B);	
write(B);		write(B);	
	read(B);		read(B);
	read(B); write(B);		read(B); write(B);

Analyzing conflicts

- Let Op_1 and Op_2 be two consecutive operations in a schedule.
- Conflict the order matters:

 $\mathsf{Op}_1;\mathsf{Op}_2$ and $\mathsf{Op}_2;\mathsf{Op}_1$

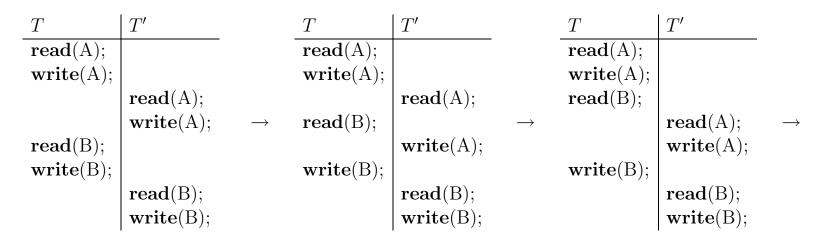
may give us different results.

- If there is no conflict, Op_1 and Op_2 can be swapped.
- If Op₁ and Op₂ refer to different data items, they do not cause a conflict, and can be swapped.
- If they are both operations on the same data item X, then: if both are read(X), the order does not matter; if Op₁ =read(X), Op₂ =write(X), the order matters. if Op₁ =write(X), Op₂ =read(X), the order matters. if Op₁ =write(X), Op₂ =write(X), the order matters.

Conflict serializability

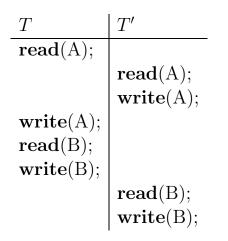
- Swapping a pair of operations in a schedule is allowed when: they refer to different data items, or, they refer to the same data item and are both read operations.
- A schedule is called **conflict** serializable if it can be transformed into a serial schedule by a sequence of such swap operations.

Schedule I is conflict serializable



T	T'		T	T'
read(A);			read(A);	
write(A);			write(A);	
read(B);			read(B);	
	read(A);	\rightarrow	write(B);	
write(B);				read(A);
	write(A);			write(A);
	read(B); write(B);			read(B);
	write(B);			<pre>read(A); write(A); read(B); write(B);</pre>

Schedule II is not conflict serializable



• In a serial schedule, either:

write(A) by T precedes read(A) by T', or write(A) by T' precedes read(A) by T

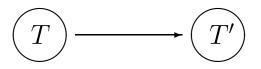
• But:

write(A) by T cannot be swapped with write(A) by T', and write(A) by T' cannot be swapped with read(A) by T

• Hence the schedule is not serializable.

Testing conflict serializability

- \bullet Construct the precedence graph of a schedule S
- Nodes: transactions in the system
- Edges: there is an edge



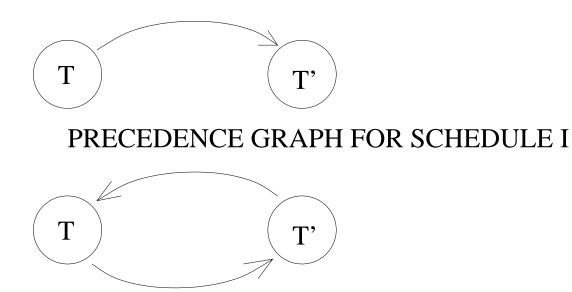
if T executes an operation Op_1 before T' executes an operation Op_2 such that Op_1 and Op_2 cannot be swapped.

- That is, one of these conditions holds:
 - T executes write(X) before T' executes read(X)
 - T executes read(X) before T' executes write(X)
 - T executes write(X) before T' executes write(X)

Testing conflict serializability

- \bullet Given a schedule S, construct its precedence graph
- If there is an edge $T \to T'$, then in any serial schedule S' equivalent to S, the transaction T must appear before T'.
- \bullet A schedule S is conflict serializable if and only if its precedence graph contains no cycles.
- Testing serializability:
 - Construct the conflict graph
 - Check if it has cycles
 - If it doesn't have cycles, do topological sort
- The result of the topological sort gives an equivalent serial schedule.
- Reminder: a topological sort of an acyclic graph G produces an order \prec on its nodes consistent with G if there is an edge from x to y, then $x \prec y$.

Testing conflict serializability: examples



PRECEDENCE GRAPH FOR SCHEDULE 2

• Thus, schedule I is conflict serializable, and schedule II is not.

Concurrency control: lock-based protocols

- Main goal of concurrency control: to ensure the isolation property for concurrently running transactions
- Typically achieved via locks
- Each data item is locked by at most one transaction; while it is locked, no other transaction has access to it.
- Two new primitives: lock(A) and unlock(A)
- A typical transaction:

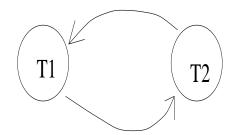
Locking and serializability

- A new abstract view of transaction: only the order of lock and unlock operations matters
- If data item A is locked by transaction T, and transaction T' issues a lock(A) command, it must wait until T executes unlock(A).
- New representation of schedules: Schedule S_1 Schedule S_2 T_2 : lock(A) T_1 : lock(A) T_2 : unlock(A) T_2 : lock(B) T_3 : lock(A) T_2 : unlock(B) T_3 : unlock(A) T_1 : lock(B) T_1 : lock(B) T_1 : unlock(B) T_1 : unlock(B) T_2 : lock(A) T_2 : lock(A) T_2 : unlock(A) T_2 : lock(B) T_2 : unlock(A) T_2 : unlock(B) T_2 : unlock(A)

Locking and serializability

- Precedence graph: for each operation T_i : unlock(A), locate the following T_i : lock(A) statement, and put an edge from T_i to T_i
- Conflict-serializability with locking: a schedule is conflict-serializable if the precedence graph does not have cycles.
- Precedence graphs:

$$\begin{array}{c} T1 \longrightarrow T2 \longrightarrow T3 \end{array} \quad FOR \ S1 \end{array}$$

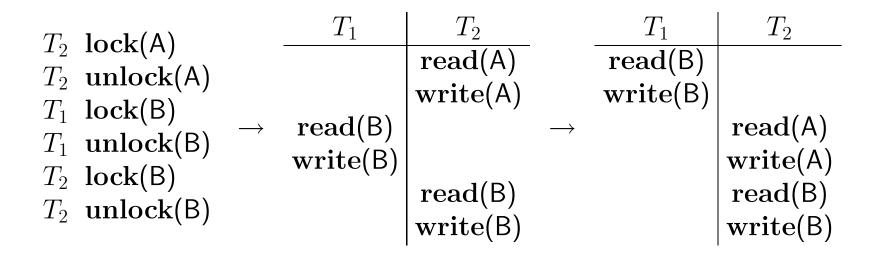


FOR S2

• Hence S_1 is conflict-serializable, S_2 is not.

Locking and serializability cont'd

• A conflict-serializable schedule of lock-unlock operations ensures a conflict-serializable schedule of read-write operations:



Two-phase locking

- A protocol which guarantees conflict-serializable schedule
- Used in most commercial DBMSs
- Each transaction has two phases:
- *Growing phase*: a transaction may request new locks, but may not release any locks
- *Shrinking phase*: a transaction may release locks, but may not request any locks
- That is, after transaction released a lock, it may not request any new locks
- Main property of two-phase locking:

A schedule ${\cal S}$ in which every transaction satisfies the two-phase locking protocol is conflict-serializable

Two-phase locking and serializability: proof

Assume that every transaction conforms to the two-phase locking protocol (or: is a 2PL transaction)

Assume S is not serializable, and the precedence graph contains a cycle:

$$T_1 \to T_2 \to T_3 \to \ldots \to T_k \to T_1$$

Trace the cycle:

- T_1 locks and unlocks something
- T_2 locks and unlocks something
- ...
- T_k locks and unlocks something
- T_1 locks and unlocks something

Then T_1 locks some data item after it released a lock, and hence it is not 2PL.

Two-phase locking and serializability cont'd

- \bullet The result is best possible
- For any non-2PL transaction T, there is a 2PL transaction T' and a schedule S for T, T' that is not serializable.

• Idea: $\frac{T}{Iock(A)} = \frac{T'}{Iock(A)}$ unlock(A) Iock(B) unlock(B) = unlock(A) unlock(B) = unlock(B)
Schedule:

 $T \quad lock(A), unlock(A)$ $T' \quad all operations$

- T lock(B), unlock(B)
- This schedule is not serializable.

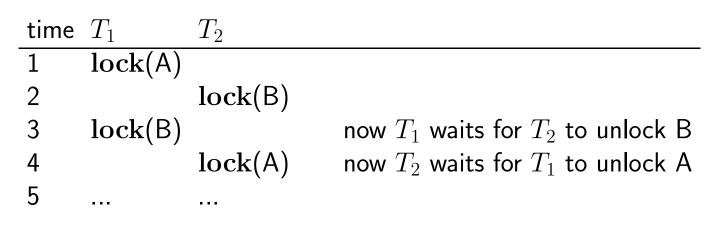
2PL in practice

- Majority of commercial DBMSs implement some form of 2PL
- Rigorous 2PL: all locks must be held until the transaction commits
- Two types of locks:

Exclusive: the transaction can both read and write the data item Shared: the transaction can only read the data item

- At most one transaction can possess an exclusive lock for a data item at any given time, but several transactions can possess a shared lock
- Strict 2PL: all exclusive locks taken by the transaction must be held until it commits
- Strict and rigorous 2PL are the most common concurrency control mechanisms

Deadlocks



- Deadlock: T_1 waits for T_2 , T_2 waits for T_1
- In general, there is a set of transactions T_1, \ldots, T_k such that:
 - T_1 waits for T_2
 - T_2 waits for T_3
 - ...
 - T_k waits for T_1

Dealing with deadlocks

- Two main mechanisms: prevention and detection
- Prevention: find a concurrency control mechanism which ensures that there is no "waits-for" cycle
- Simple deadlock prevention: each transaction locks *all* data items before it starts execution. Such a locking constitutes *one* step.
- Disadvantage: data utilization is very low
- Another approach: use preemption. If T_1 has a lock on A, and T_2 requests it, then the system has three choices:
 - let T_2 wait, or
 - roll back T_1 and grant the lock to T_2 , or
 - roll back T_2

Deadlock prevention cont'd

- The decision is based on *timestamps*, that say how old transactions are.
- Timestamp: the time when transaction started its execution. The larger the timestamp, the younger the transaction.
- Example: the *wound-wait* scheme. If T_1 requests a lock held by T_2 , then T_1 waits if T_1 is younger than T_2 . Otherwise T_2 is rolled back.
- The *wait-die* scheme. If T_1 requests a lock held by T_2 , then T_1 waits if T_1 is older than T_2 . Otherwise T_1 is rolled back.
- Issue: starvation may occur. Some transactions may never commit, as they keep being rolled back.

Deadlock detection and recovery

- The *wait-for* graph. Nodes are transactions. There is an edge from T to T' if T' waits for T to release a lock.
- There is a deadlock if there is a cycle in the wait-for graph.
- Deadlock recovery: identify a minimal set of transactions such that rolling them back will make the wait-for graph cycle-free.

