
An Approach to the Analysis and Design of Multiagent Systems based on Interaction Frames

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Overview

- ▶ Motivation
- ▶ Interaction Frames & Framing
- ▶ InFFrA
- ▶ Example
- ▶ Conclusions

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Motivation

- ▶ Open systems on the Internet
 - virtual enterprises
 - supply chain management
 - electronic marketplaces
 - ubiquitous information access

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- ▶ New research issues
- ▶ Something amiss?

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- ▶ Architectures to design and analyse such agents are missing.
- ▶ ***InFFrA is a possible solution!***

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- ▶ Introduction to InFFrA

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- ▶ Application to Multiagent Learning System

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- ▶ Introduction to InFFrA
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- ▶ Discussion & Outlook

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Interaction Frames & Framing

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 - roles & relationships,
 - courses of interaction (trajectories),
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- ▶ Local vs. shared knowledge
 - ➔ common vs. private attributes
- ▶ Interactions are not subject to direct agent control!

Interaction Frames & Framing

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- ▶ Socio-centric view with individualist “touch”
- ▶ Frame & Framing concepts grounded in Goffman’s sociological theory

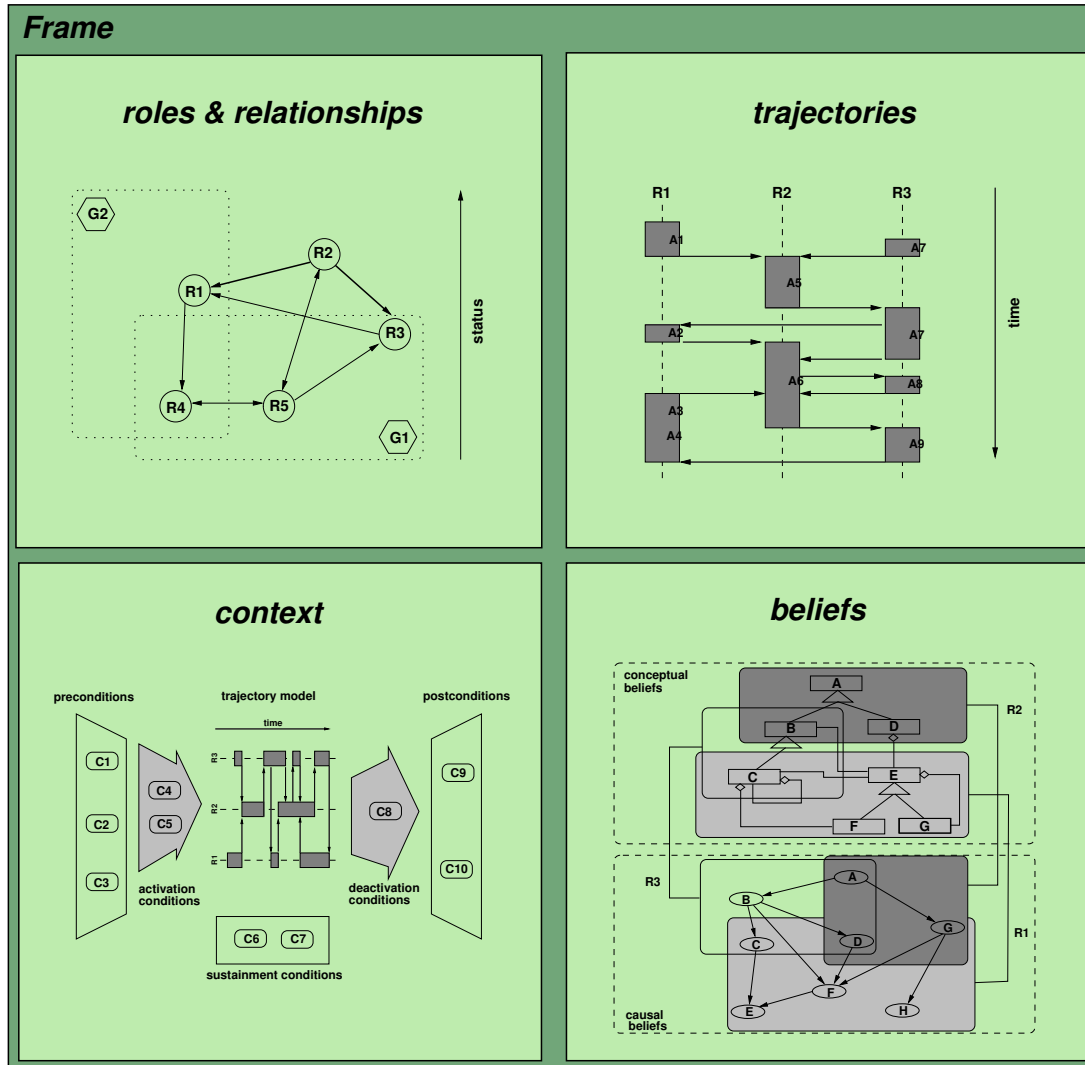
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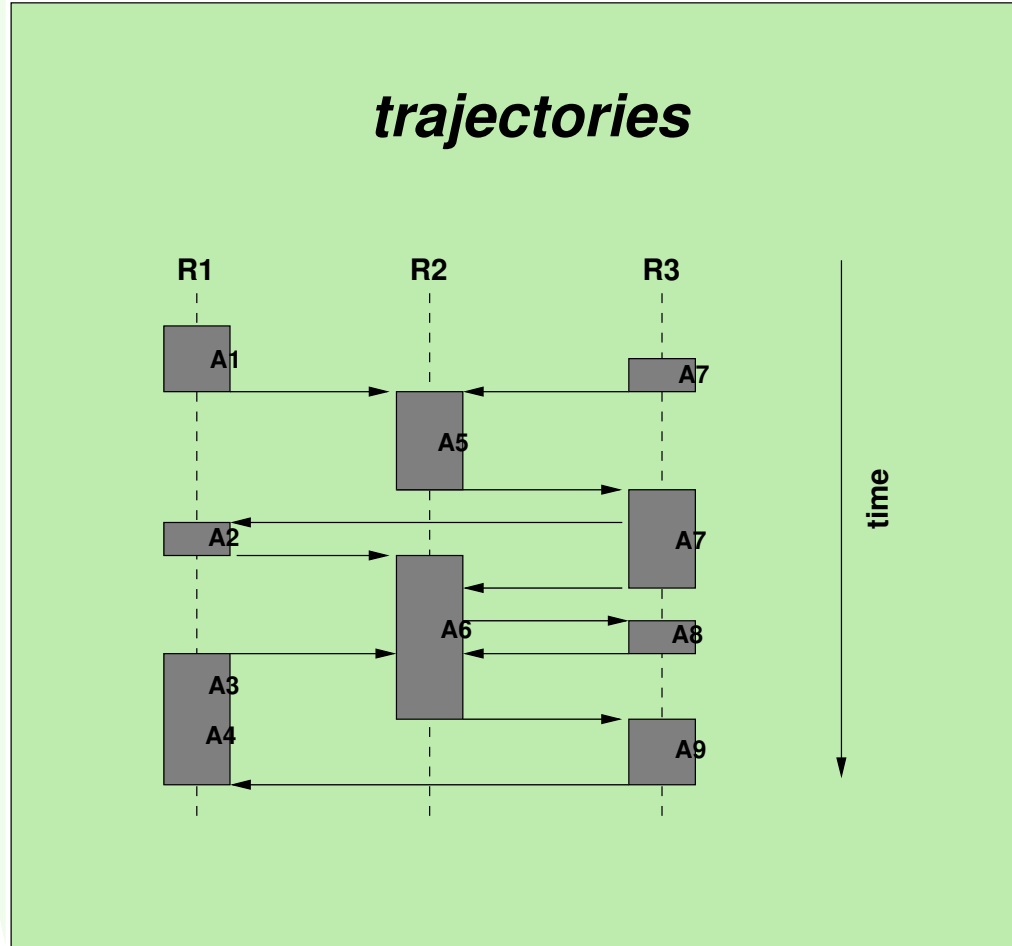
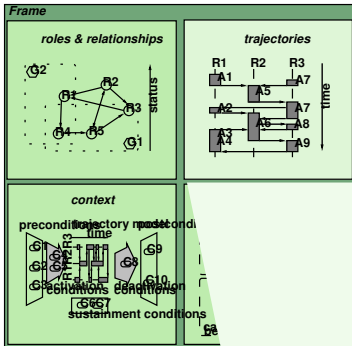
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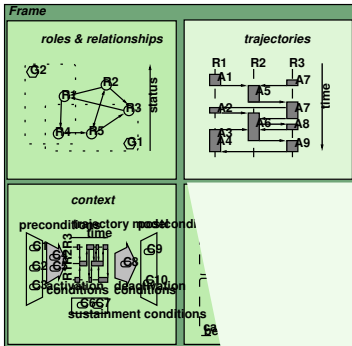
InFFrA – Frames



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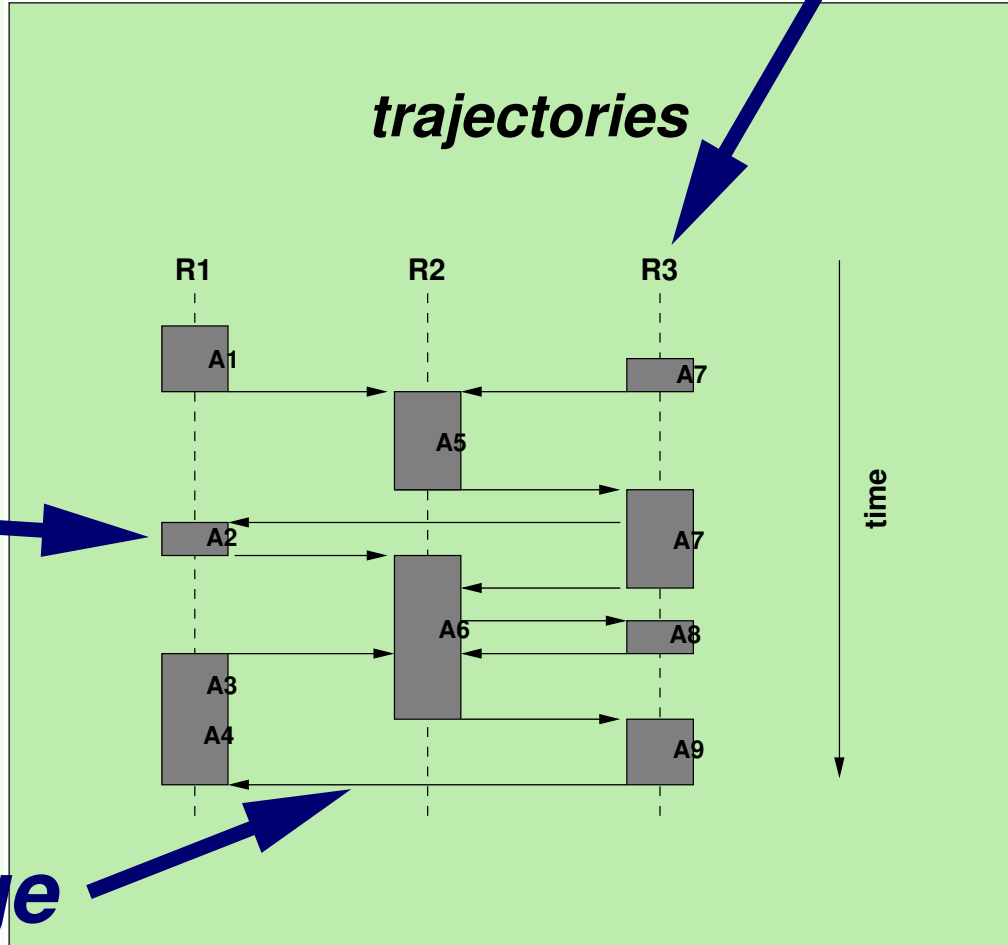


actor role

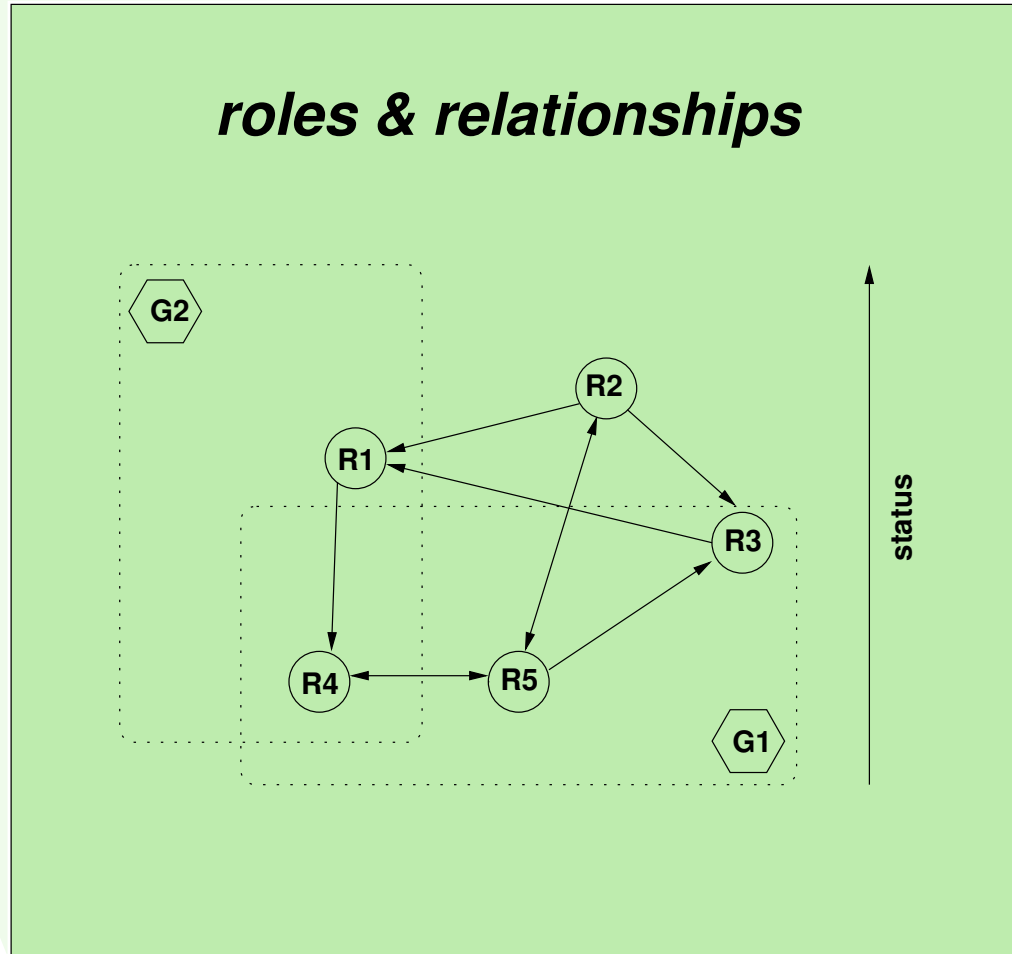
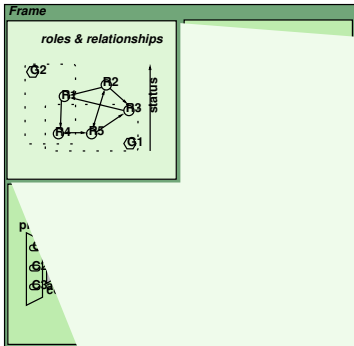
trajectories

action

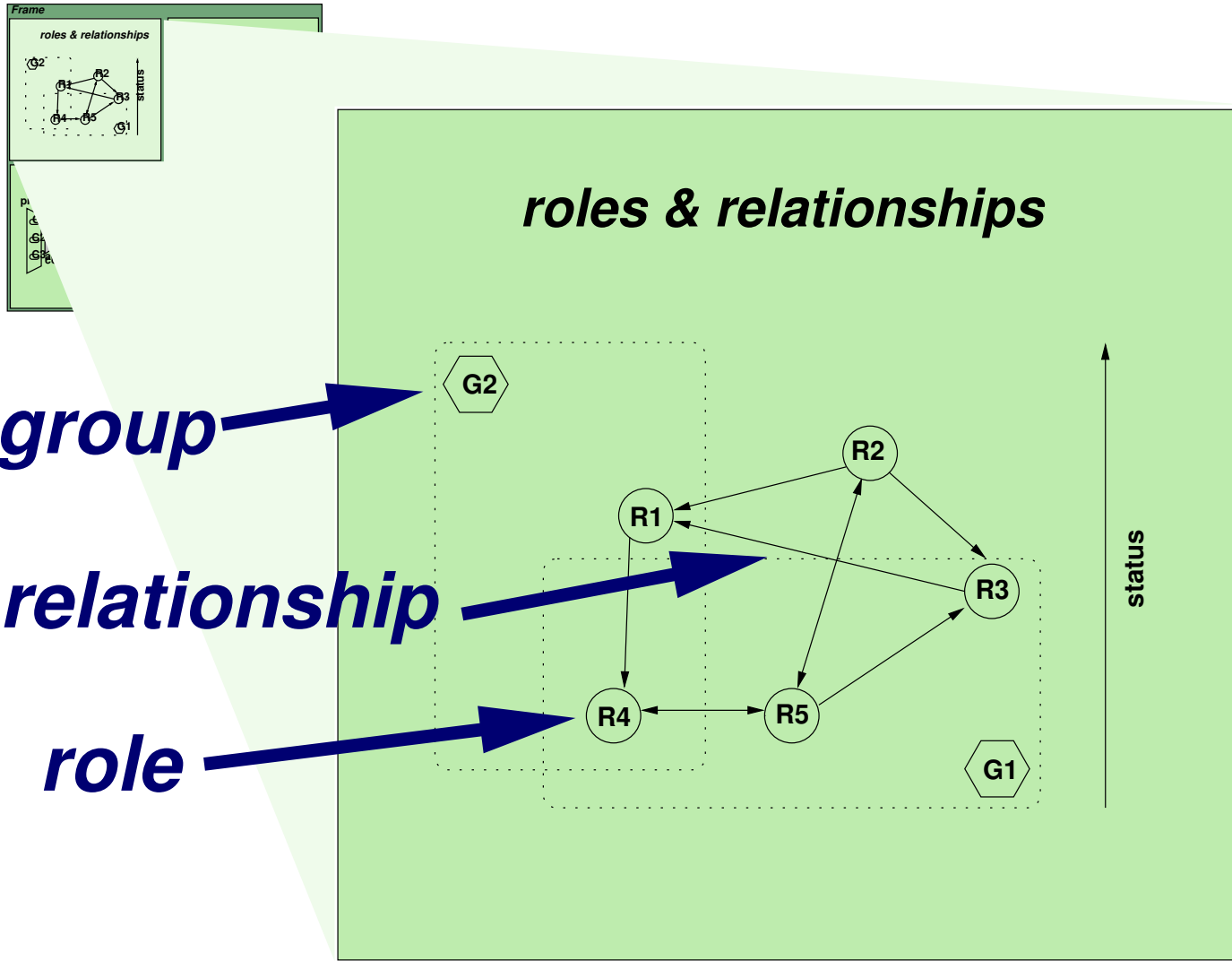
message



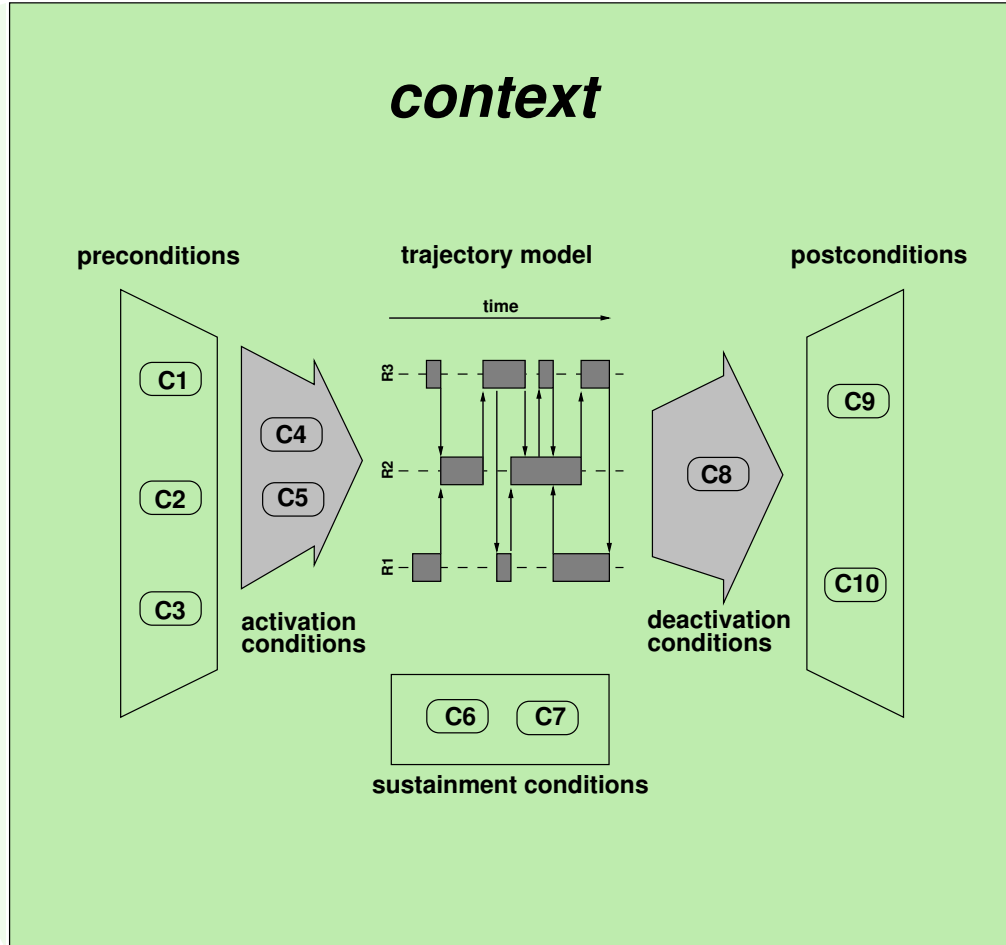
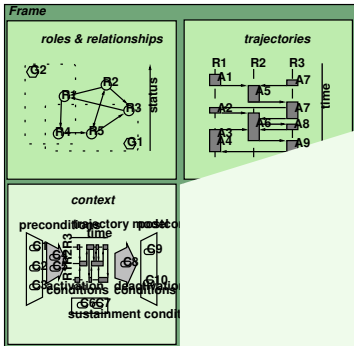
InFFrA – Frames



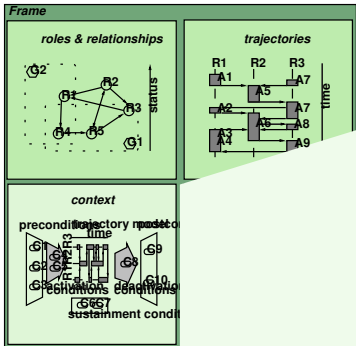
InFFrA – Frames



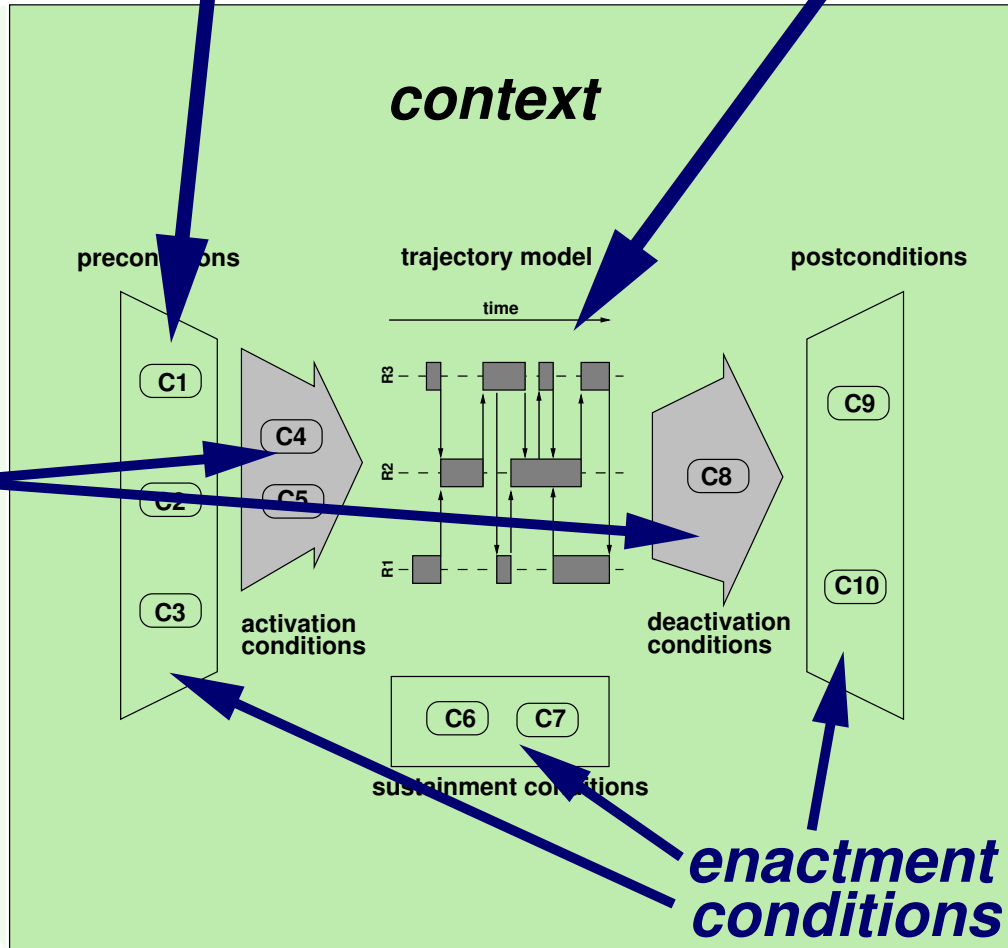
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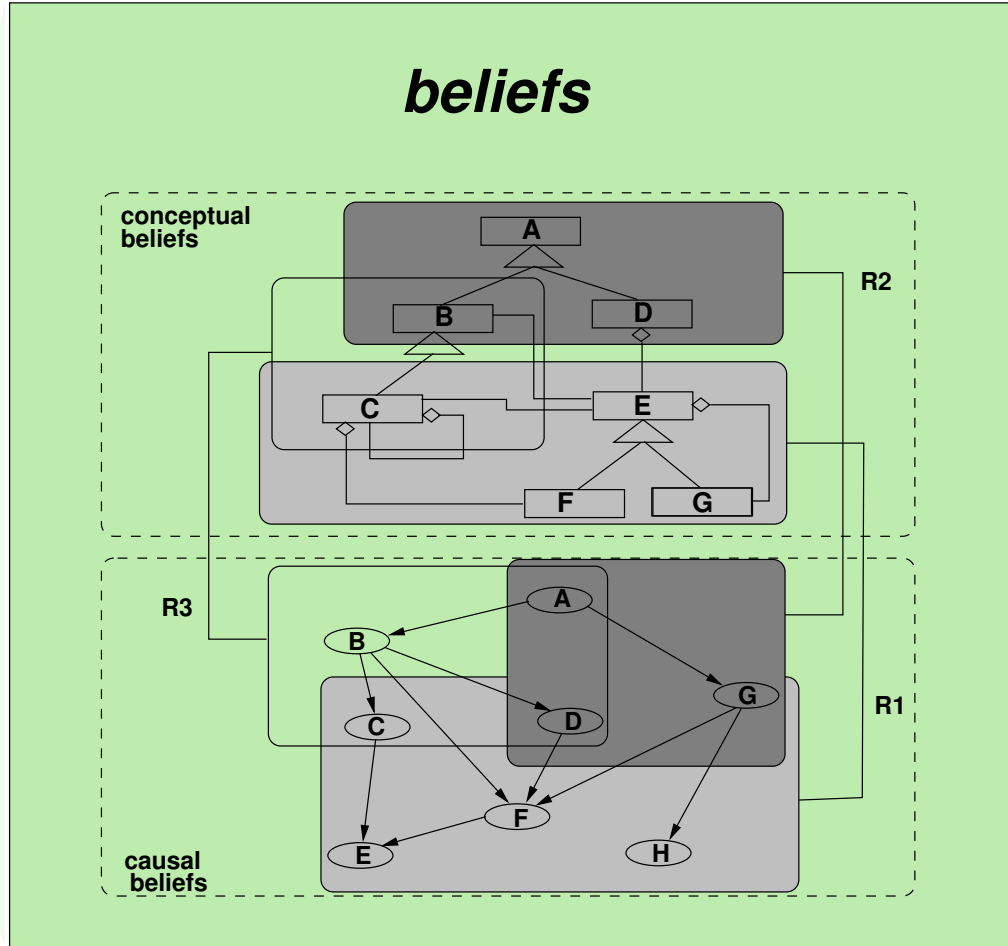
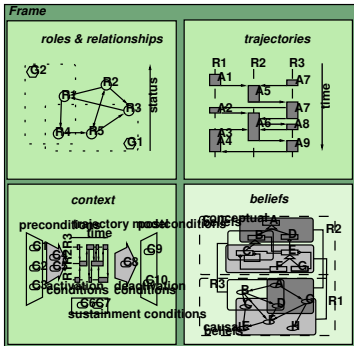
condition *trajectory*



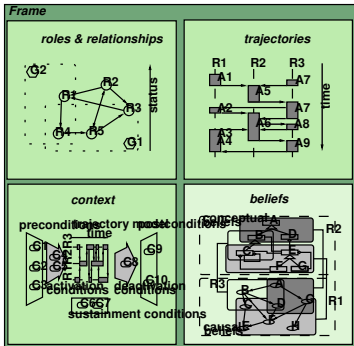
activation conditions

enactment conditions

InFFrA – Frames



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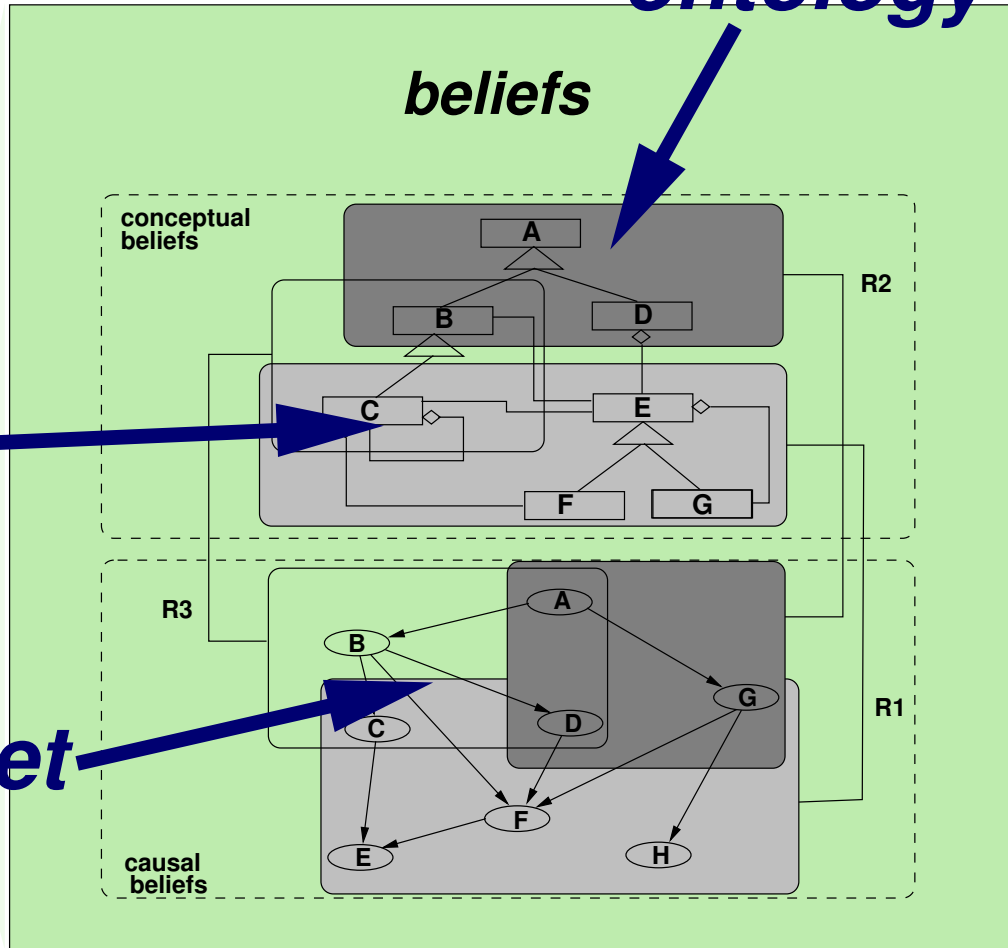


role

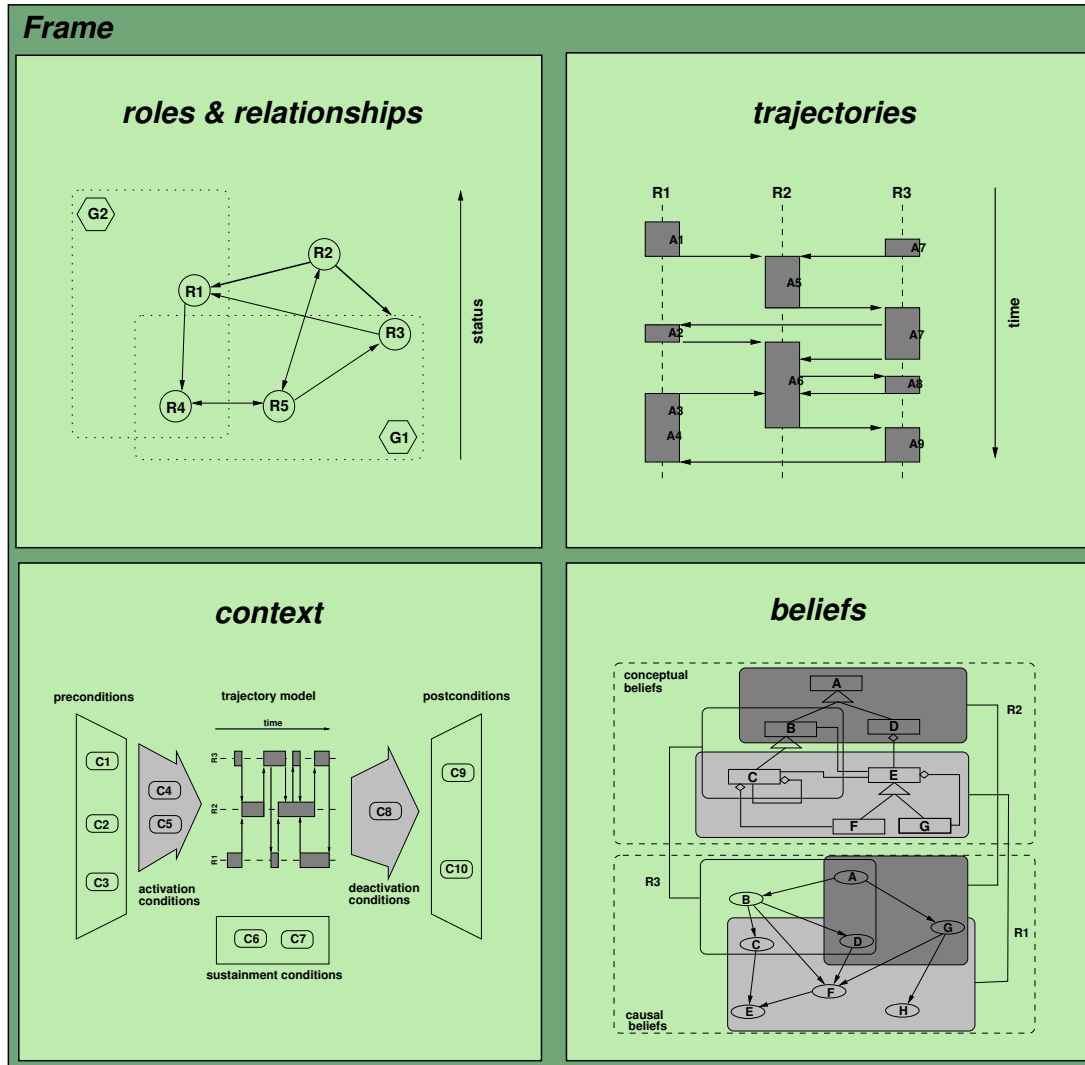
belief net

ontology

beliefs



InFFrA – Frames



Further Features

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 - Links (“alternative”, “variant”, etc.)
 - History (of frame evolution)

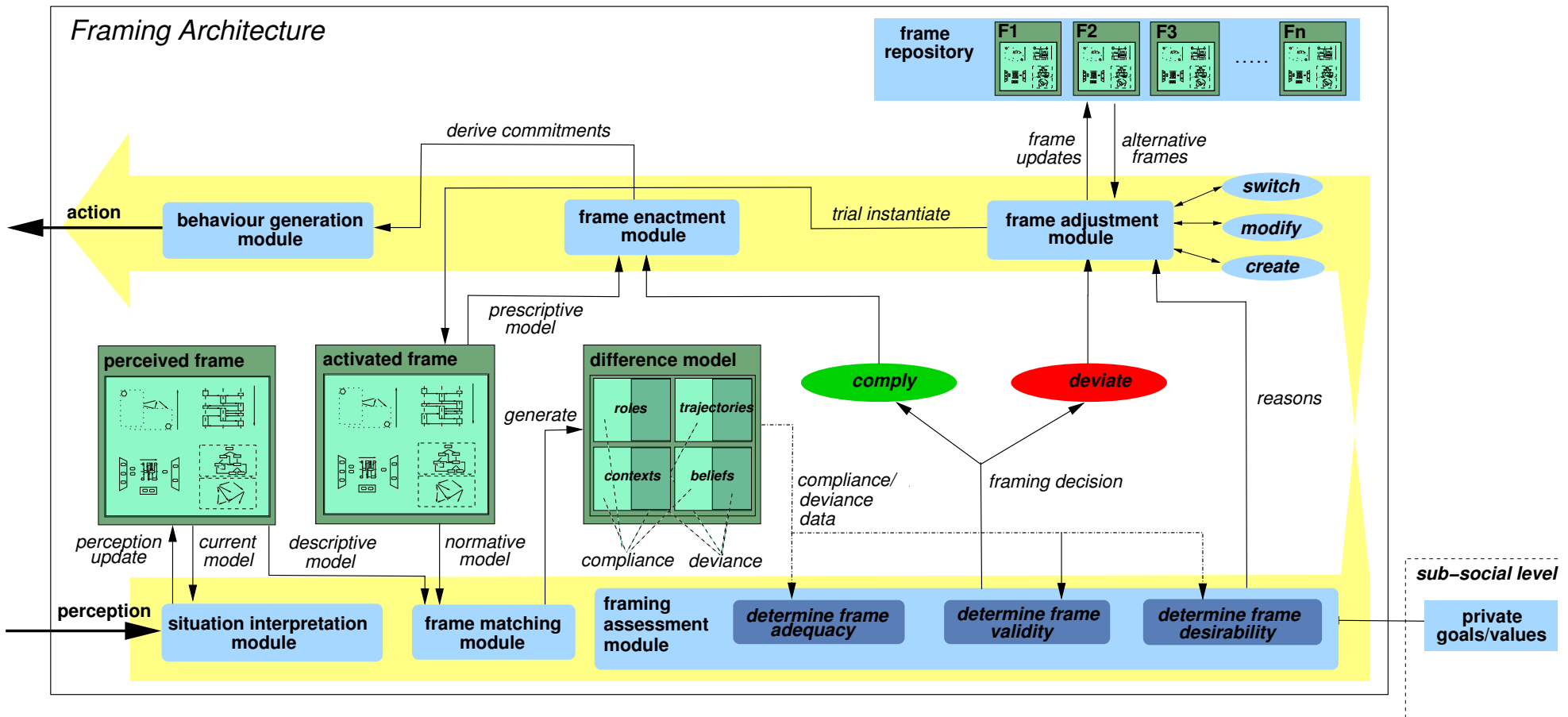
InFFrA – Framing

- ▶ Data structures:
 - Perceived frame
 - Active frame
 - Difference model
 - Trial frame
 - Frame repository

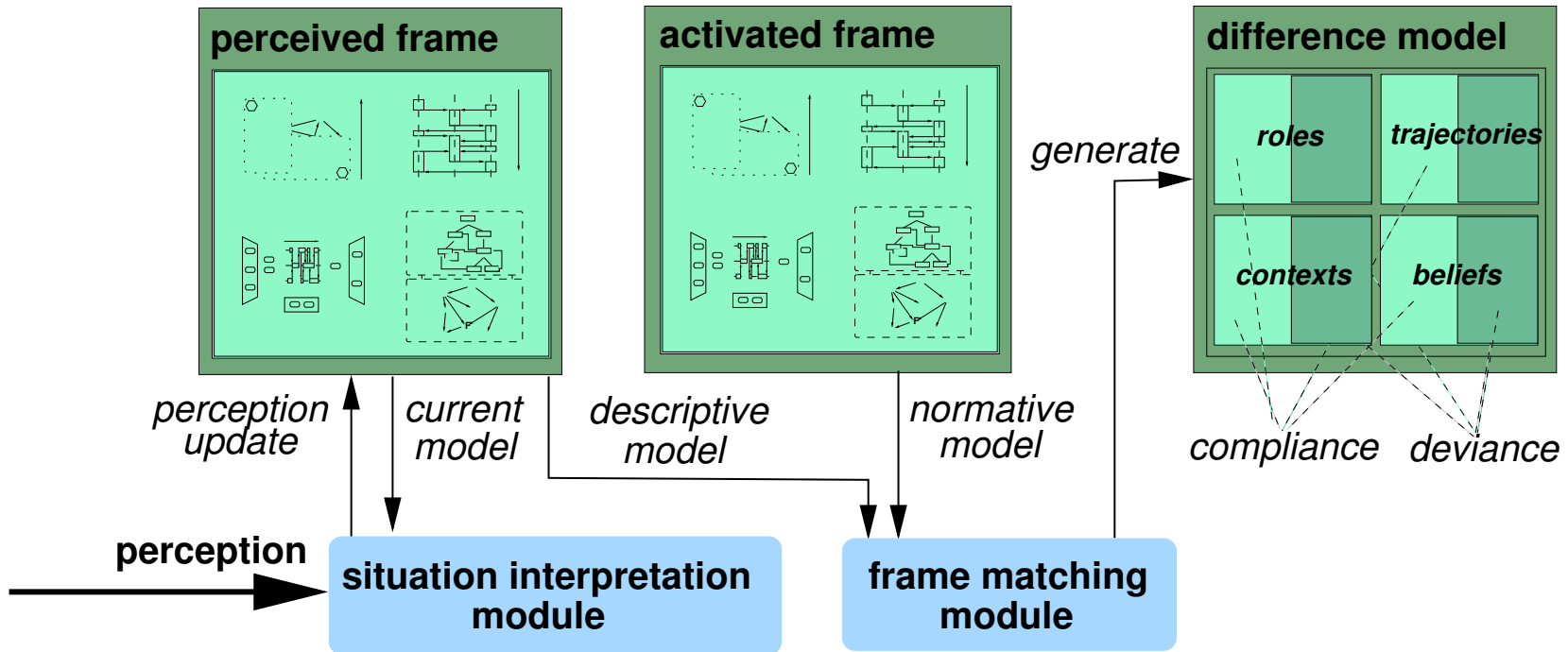
InFFrA – Framing

- ▶ Inference steps:
 - Situation interpretation
 - Matching
 - Assessment
 - Framing decision
 - Adjustment/re-framing
 - Enactment
 - Behaviour generation

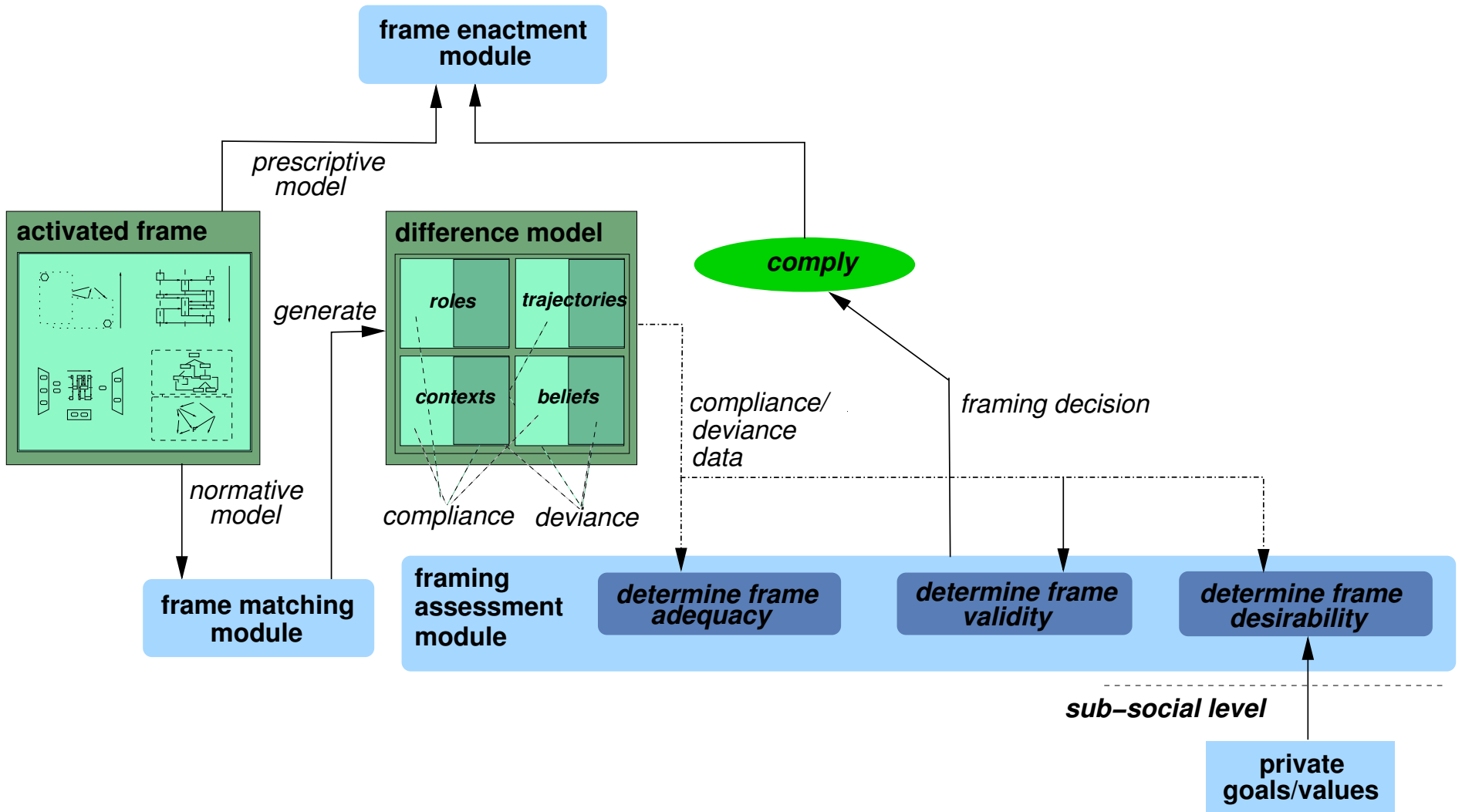
Framing



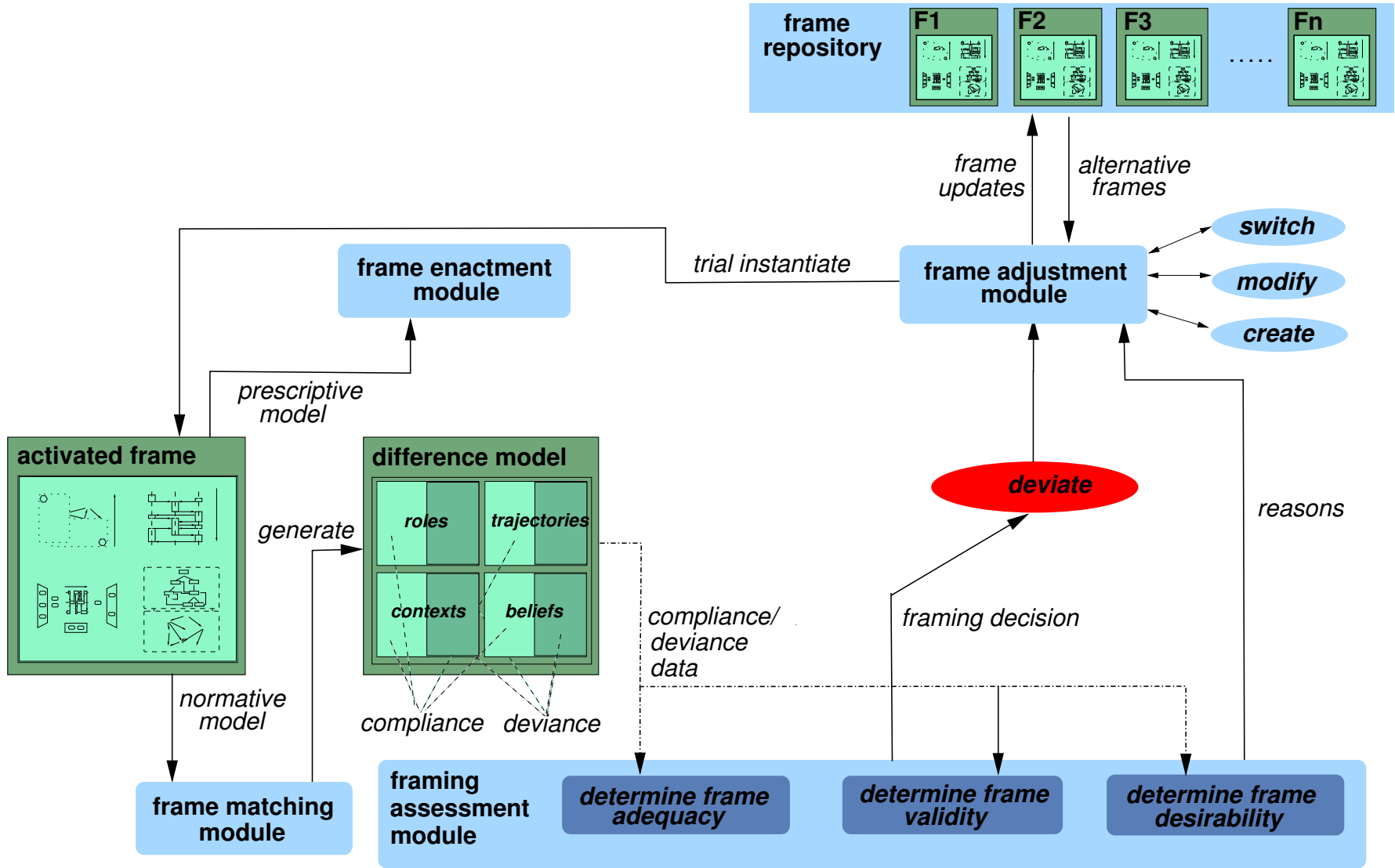
Interpretation & Matching



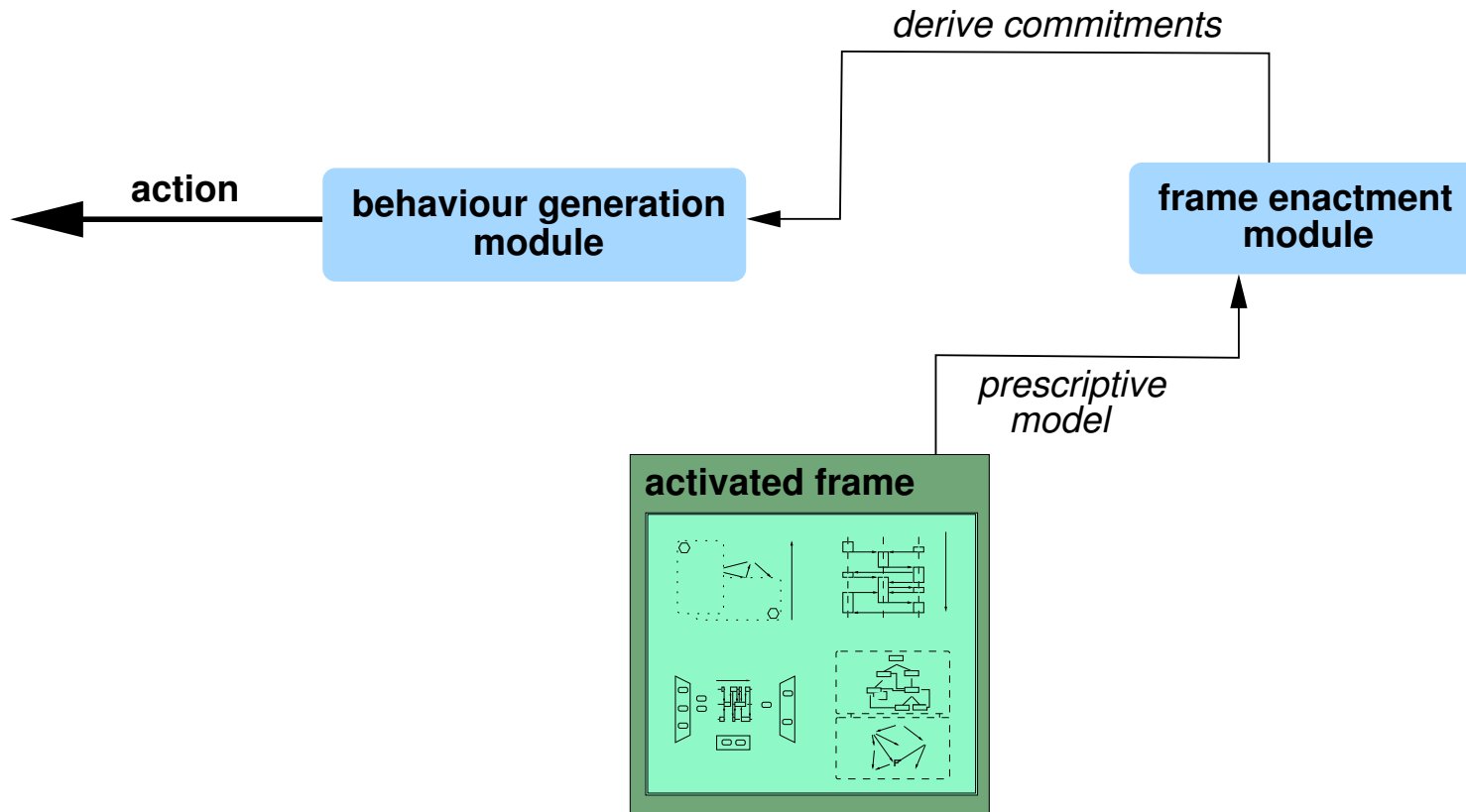
Assessment: “Comply Case”



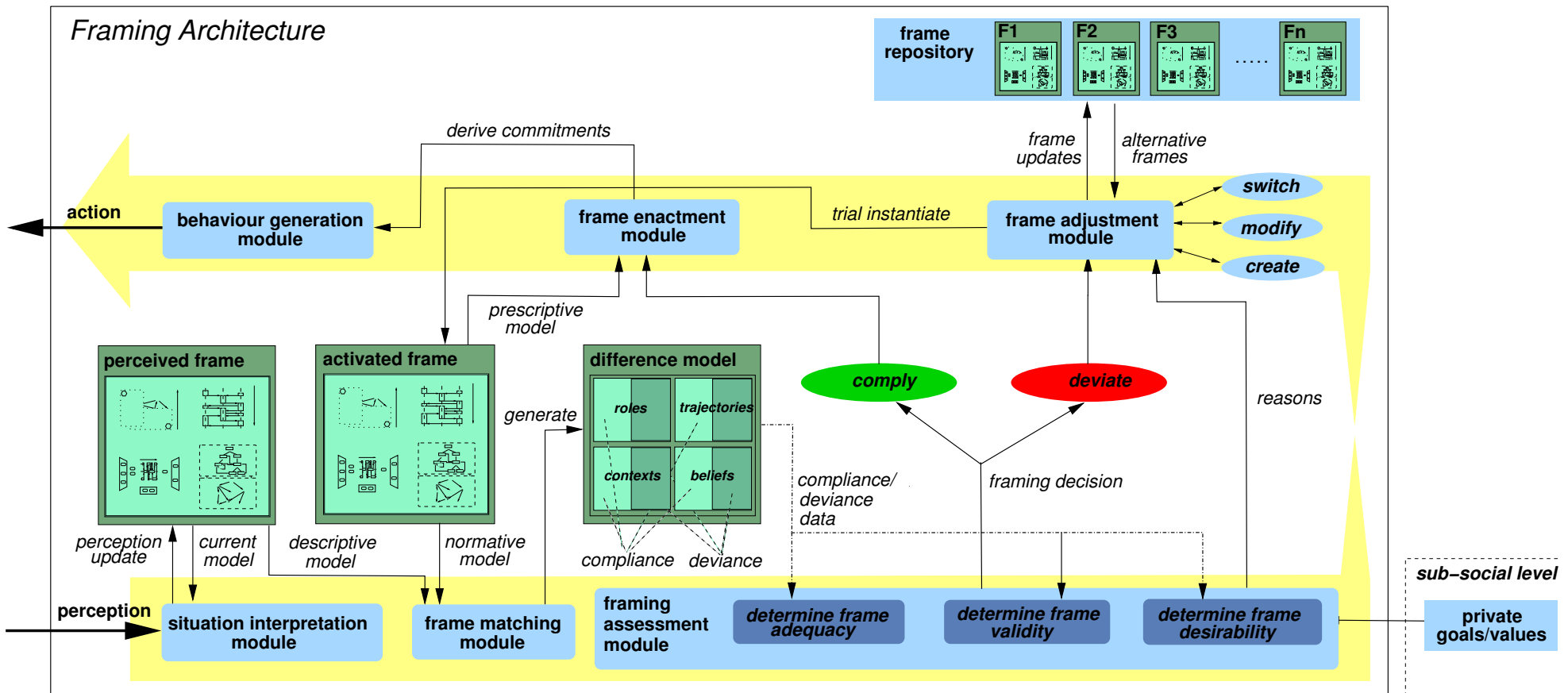
Assessment: “Deviate Case”



Enactment



Framing



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- ▶ AdHoc agents classify opponents dynamically in iterated multiagent games
- ▶ Scenario:
 - randomly moving agents on toroidal grid
 - fixed number of PD games upon encounter
 - goal: utility maximisation

Example – AdHoc

- ▶ Opponent class models c consist of:
 - Deterministic finite automaton describing behaviour of c [Carmel & Markovitch 96]
 - Q-table for optimal counter-strategy [Watkins & Dayan 92]
 - Similarity values $\sigma(a, c)$
 - Learning samples for c

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- ▶ Similarity = Ratio of encounters with opponent understood by class model

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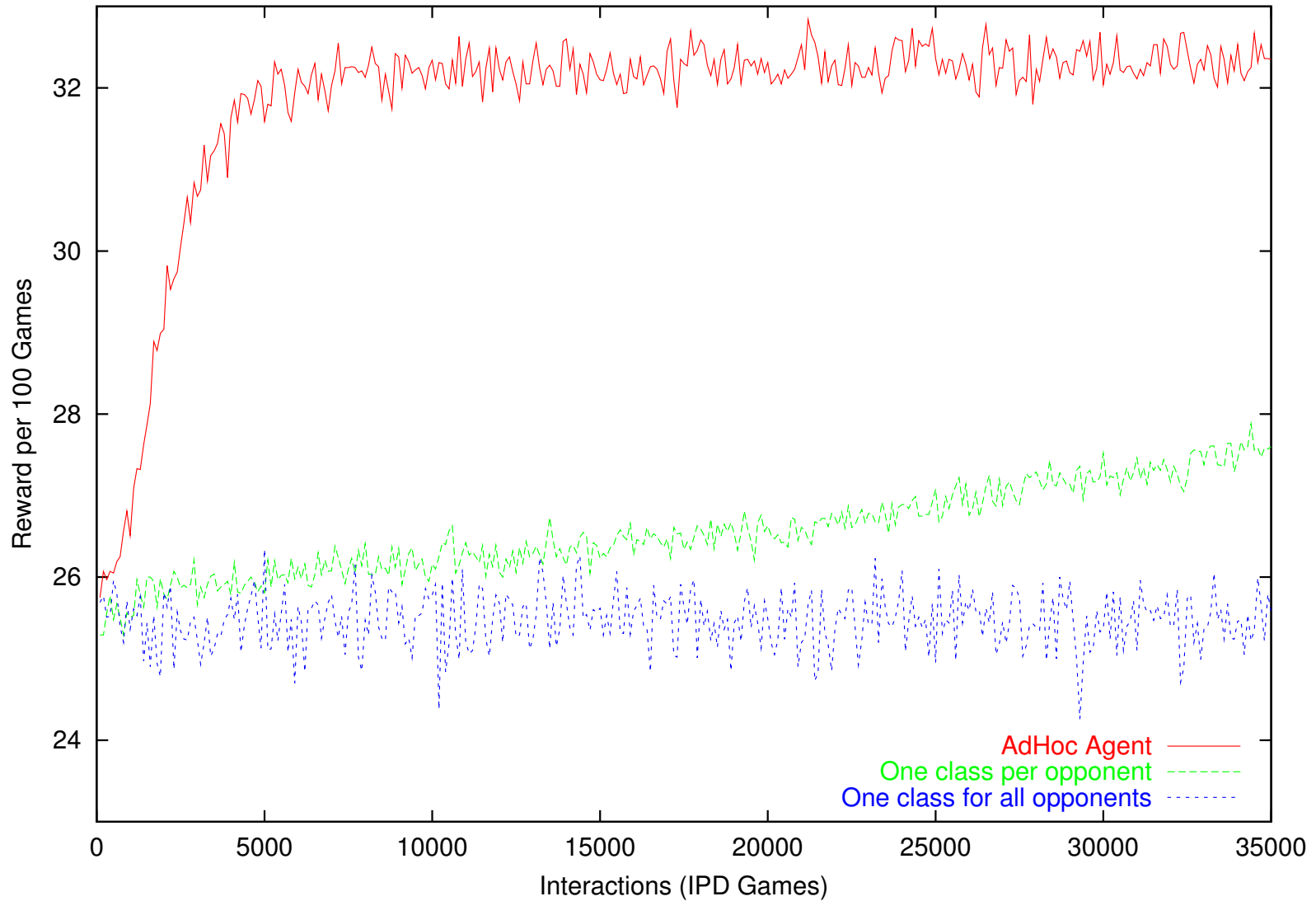
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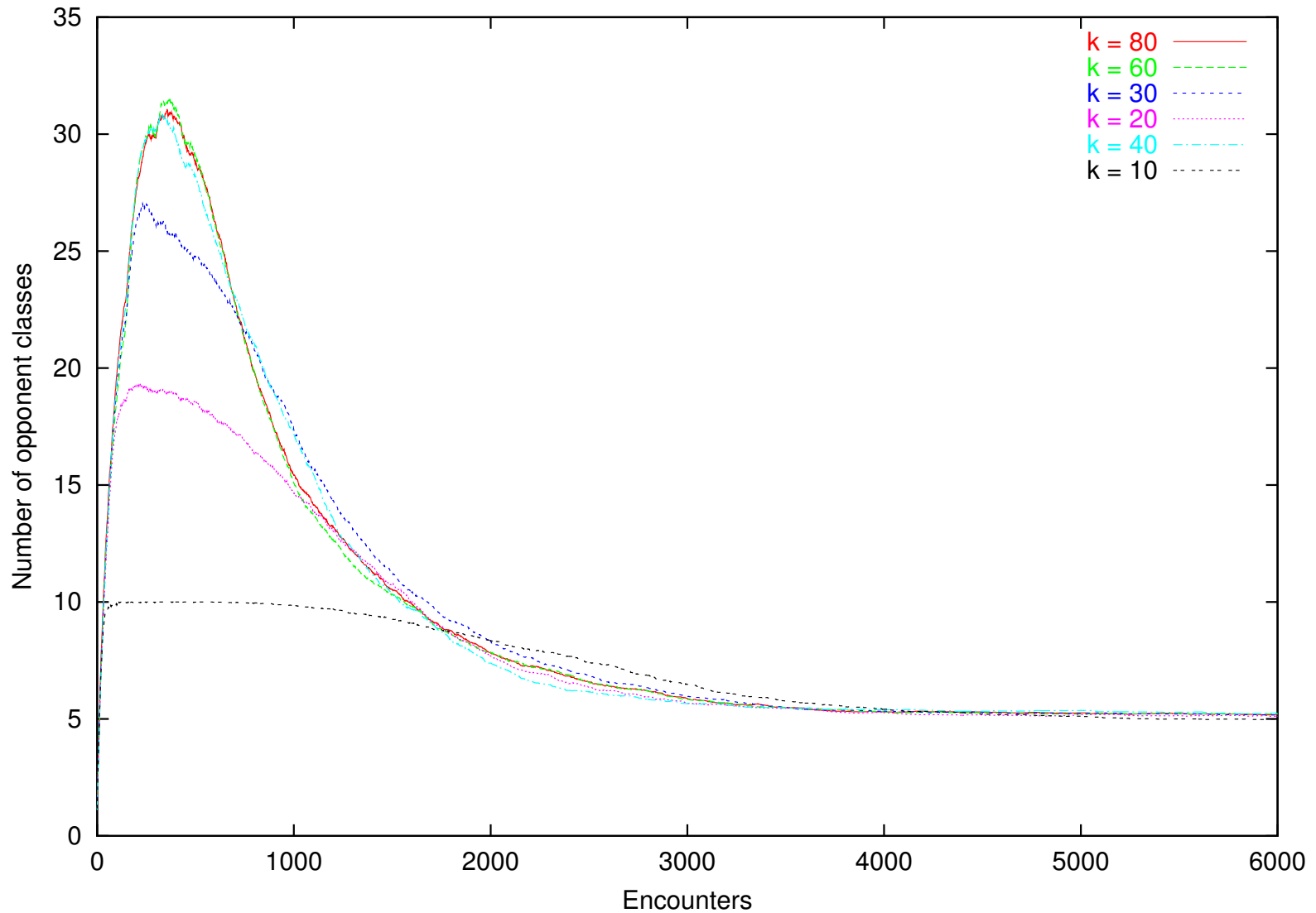
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- ▶ Problem: AdHoc vs. AdHoc agents
- ▶ Can be solved “heuristically”

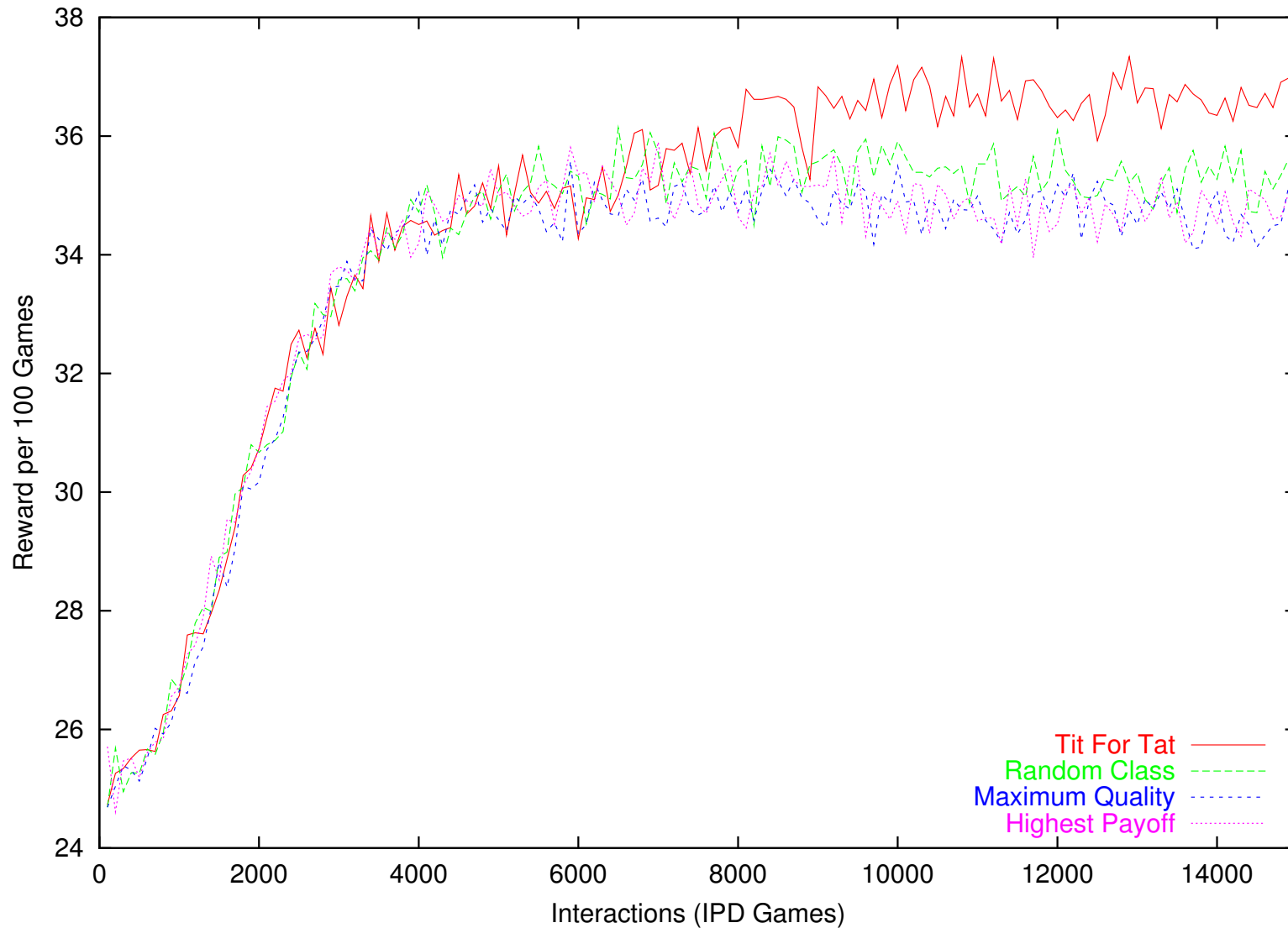
Example – Performance



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 - Similarity values → Difference model
 - Learning samples for class → History
- ▶ Roles, links and beliefs: trivial
- ▶ Perceived frame = current encounter game sequence

InFFrA Analysis – Observations

- ▶ if opponent is known, no re-framing during encounter
- ▶ else, matching after each round
- ▶ frame matching updates *all* similarity values
- ▶ assessment and re-framing only after encounter
- ▶ no adequacy and desirability test

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- ▶ frame adjustment very complex
- ▶ heart of AdHoc system
- ▶ trial instantiation trivial
- ▶ enactment: use Q-table
- ▶ trajectory does *not* restrict ego's actions!

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 - ➔ reason for AdHoc vs. AdHoc problem

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Depends on frame construction & combination.

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*Certainly **not!***
 - too few InFFrA-compliant systems
 - heavy cognitive assumptions

Outlook

- ▶ Richer communicative scenarios

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- ▶ Organisational interaction frames
- ▶ Develop adaptive InFFrA agents

Things to remember!

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- ▶ Socio-empirically rational agents
- ▶ Sociological grounding: frames and framing
- ▶ InFFrA meta-architecture
- ▶ Multi-perspective applicability

Thank you for your attention!