
Computational Interaction Frames

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Outline

- ▶ Background
- ▶ Interaction Frames and Framing
- ▶ The InFFrA Architecture
- ▶ Frames vs. Communication Semantics
- ▶ Reasoning and Learning in InFFrA
- ▶ Applications and Future Research
- ▶ Conclusions

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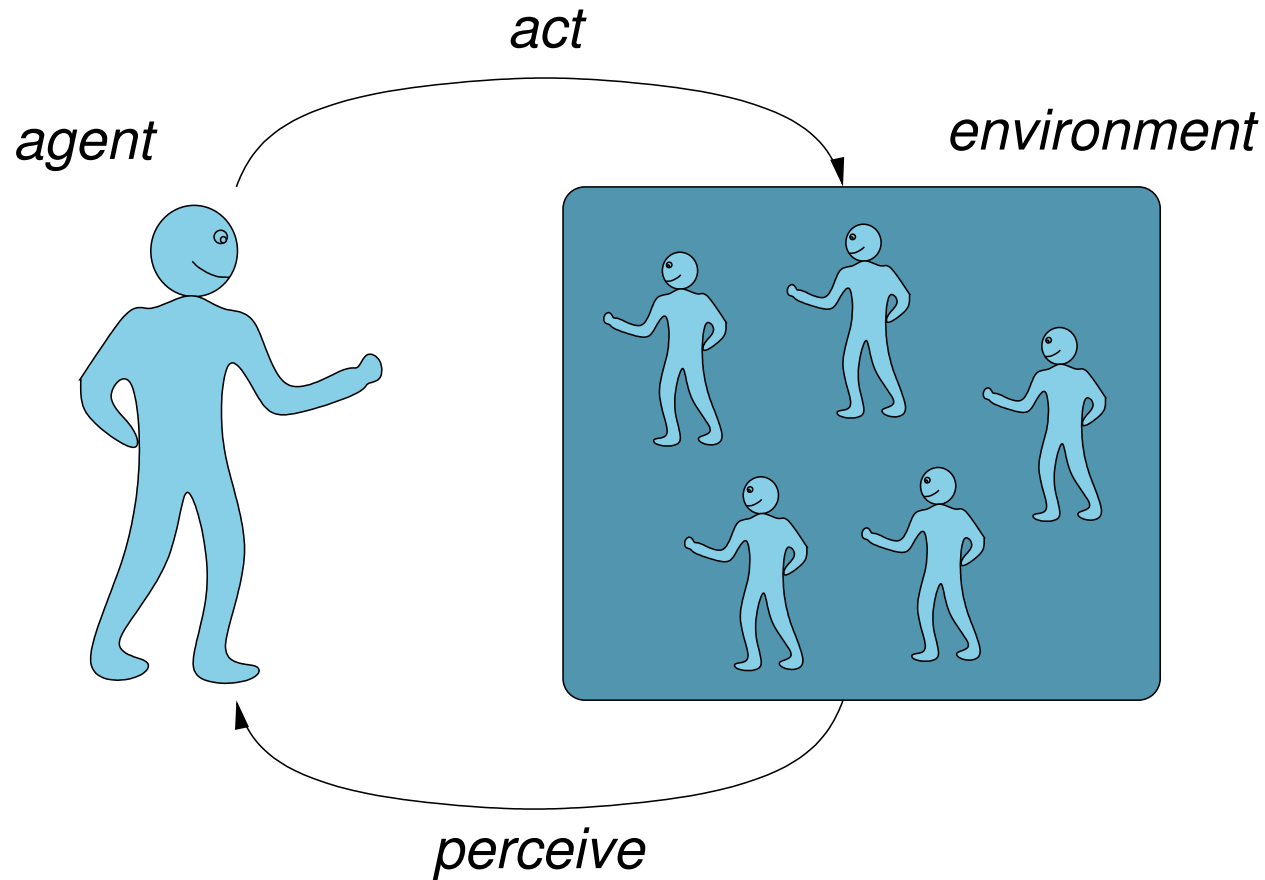
Background

- ▶ our group: “good old-fashioned **DAI**”
- ▶ “Socionics” project → new perspectives
- ▶ why sociology?
 - open systems
 - communication-oriented
 - interpretative focus
- ▶ Socionics = empirical communication analysis
+ rational action
 - deliberative black-box agents
 - observation of interaction structures
 - strategic application of interaction knowledge

Communication Systems

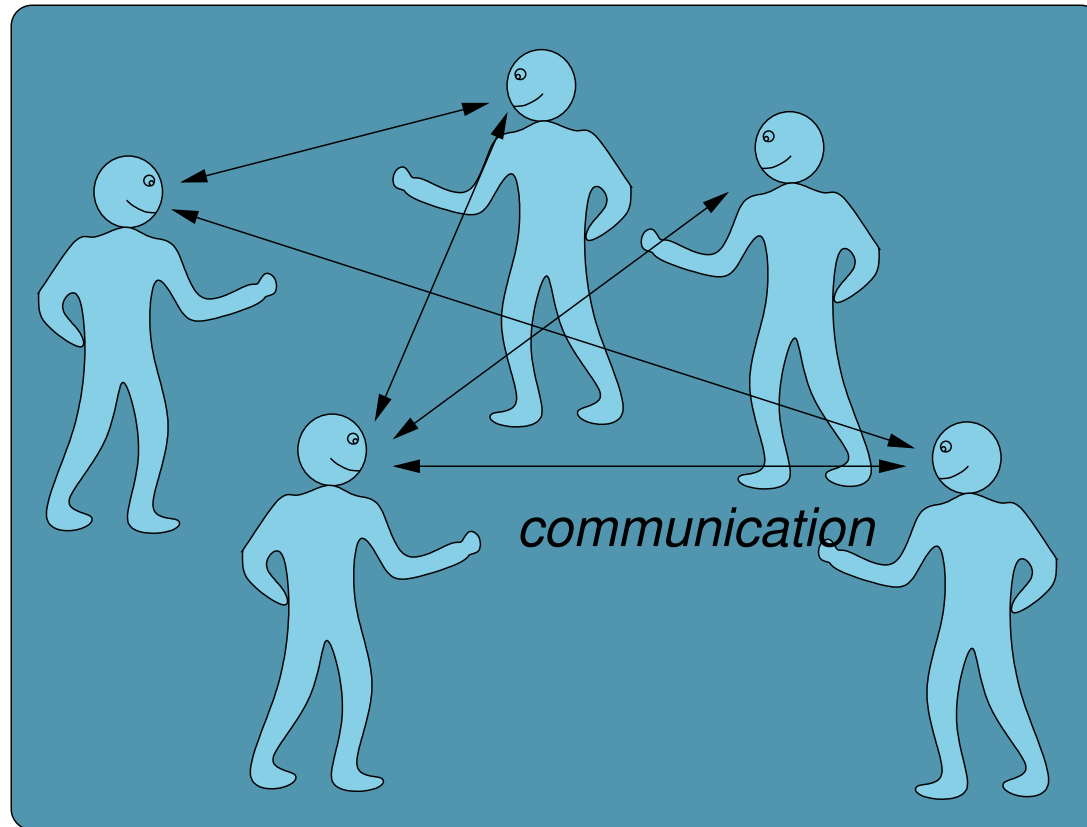
- ▶ systems of evolving communication structures
- ▶ communication
 - publicly performed → jointly observed
 - may include physical action
 - creates expectations that are rationally processed
- ▶ expectations
 - constructed from observation
 - generalised over different actors
 - exploited in a goal-directed fashion

Single-agent view

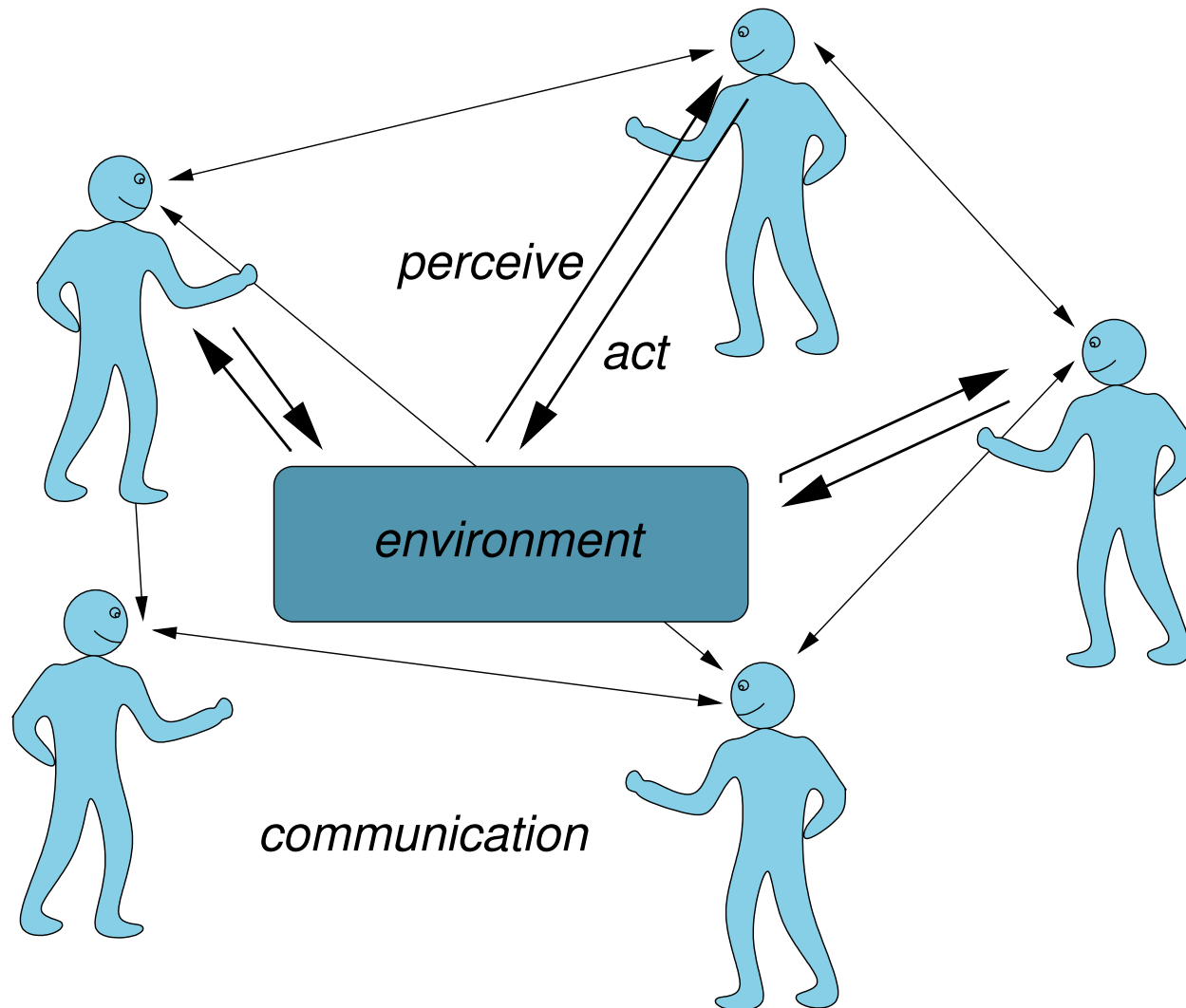


Multiagent view (1)

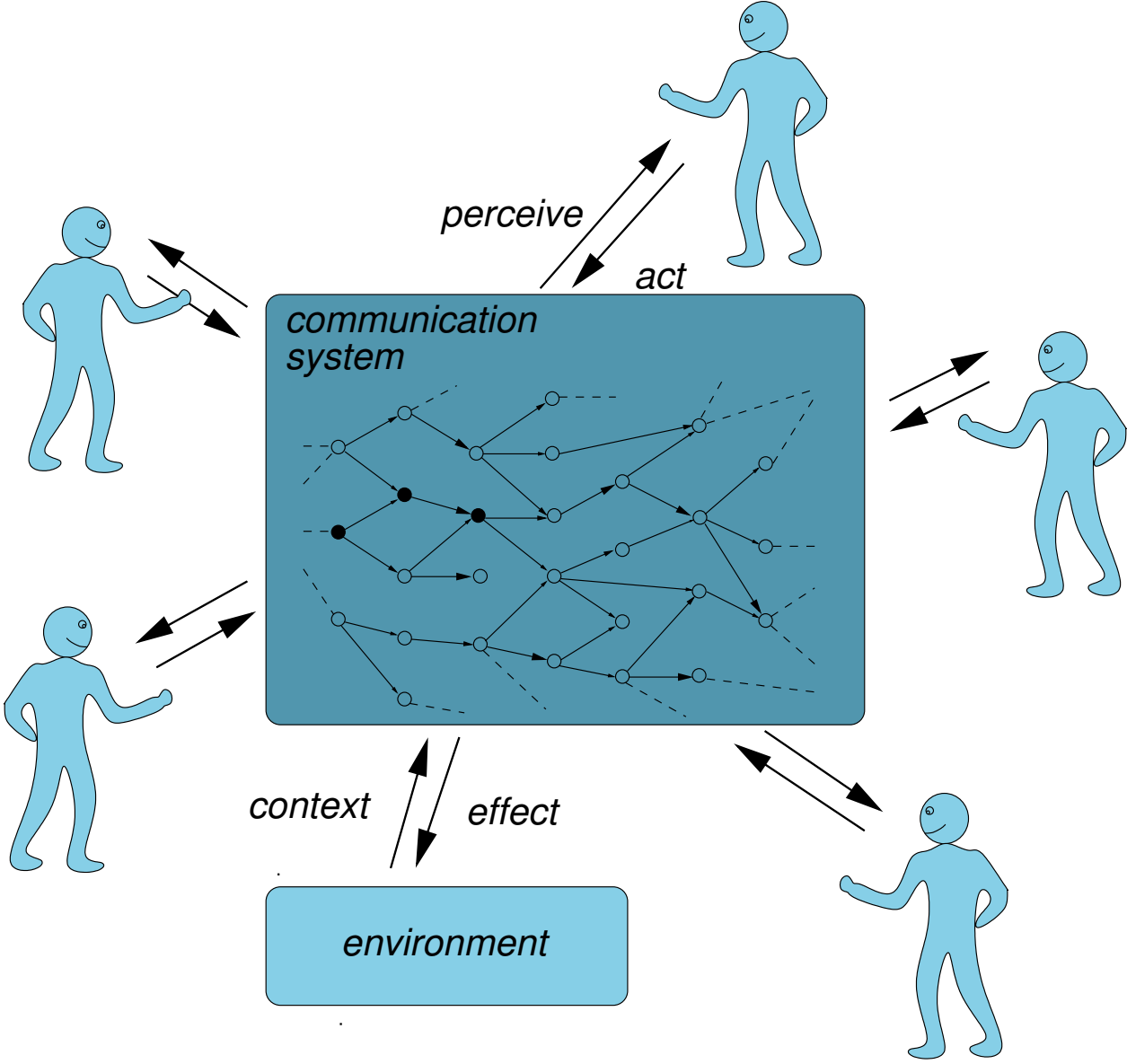
environment



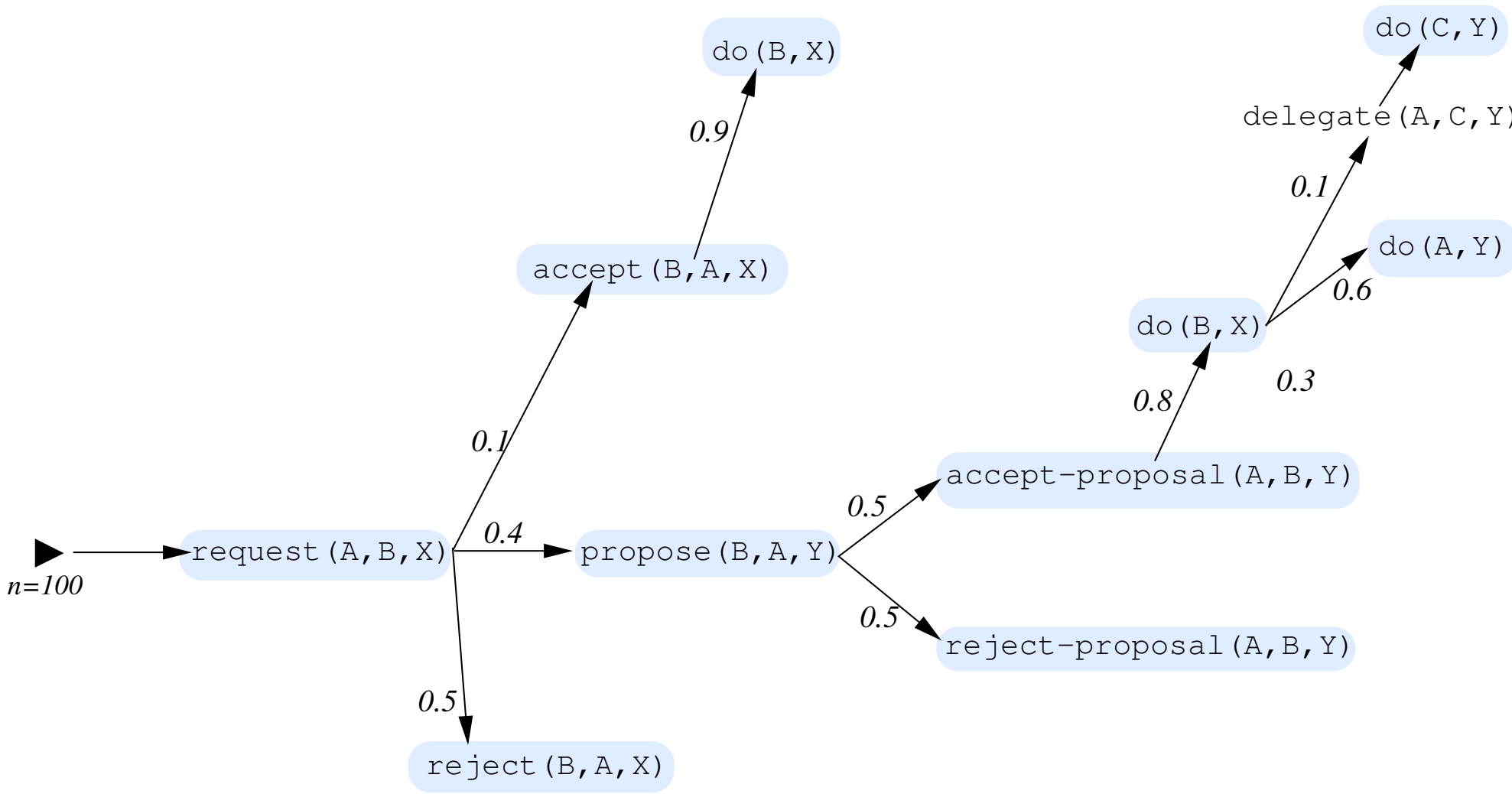
Multiagent view (2)



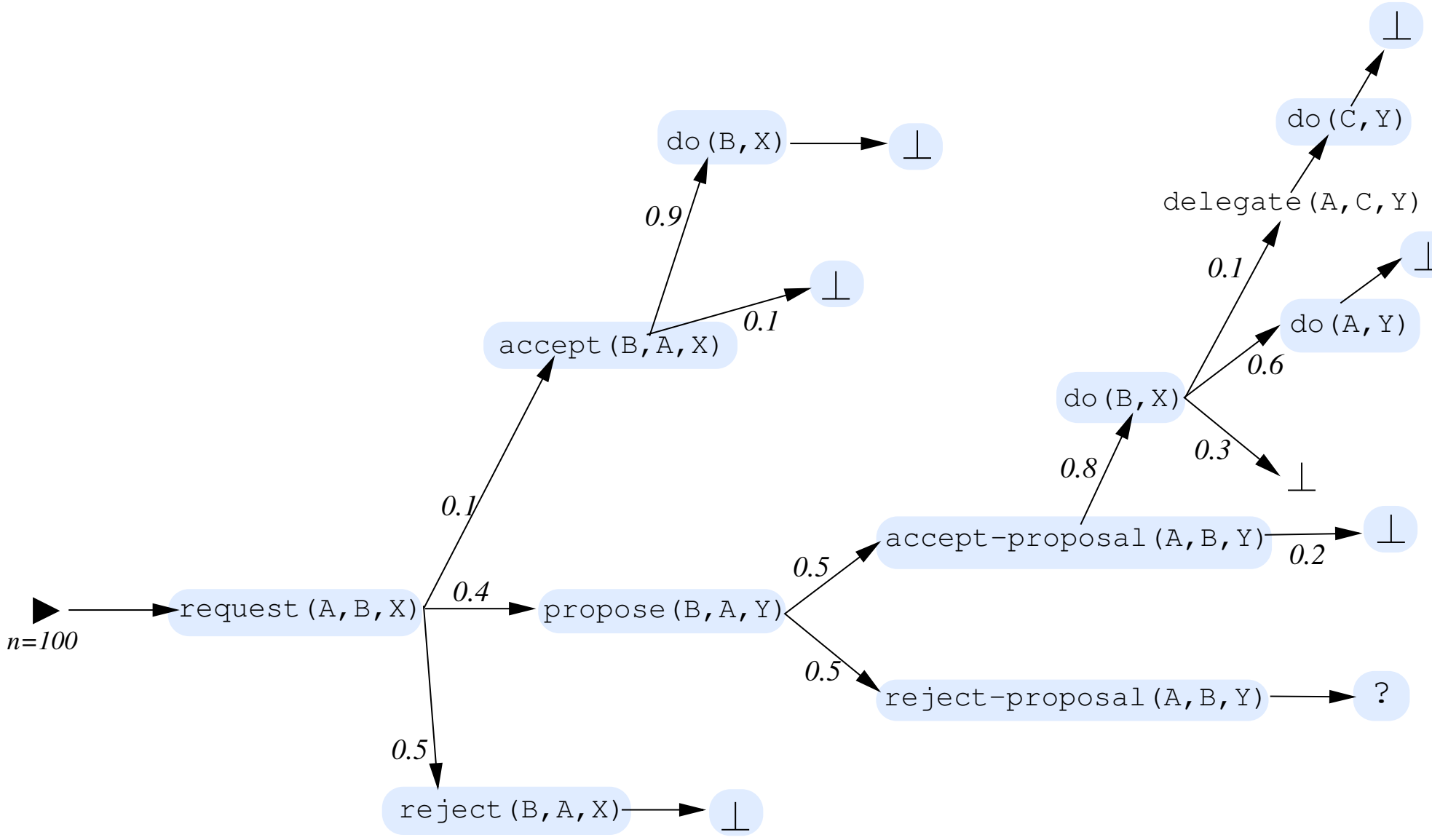
Communication systems view



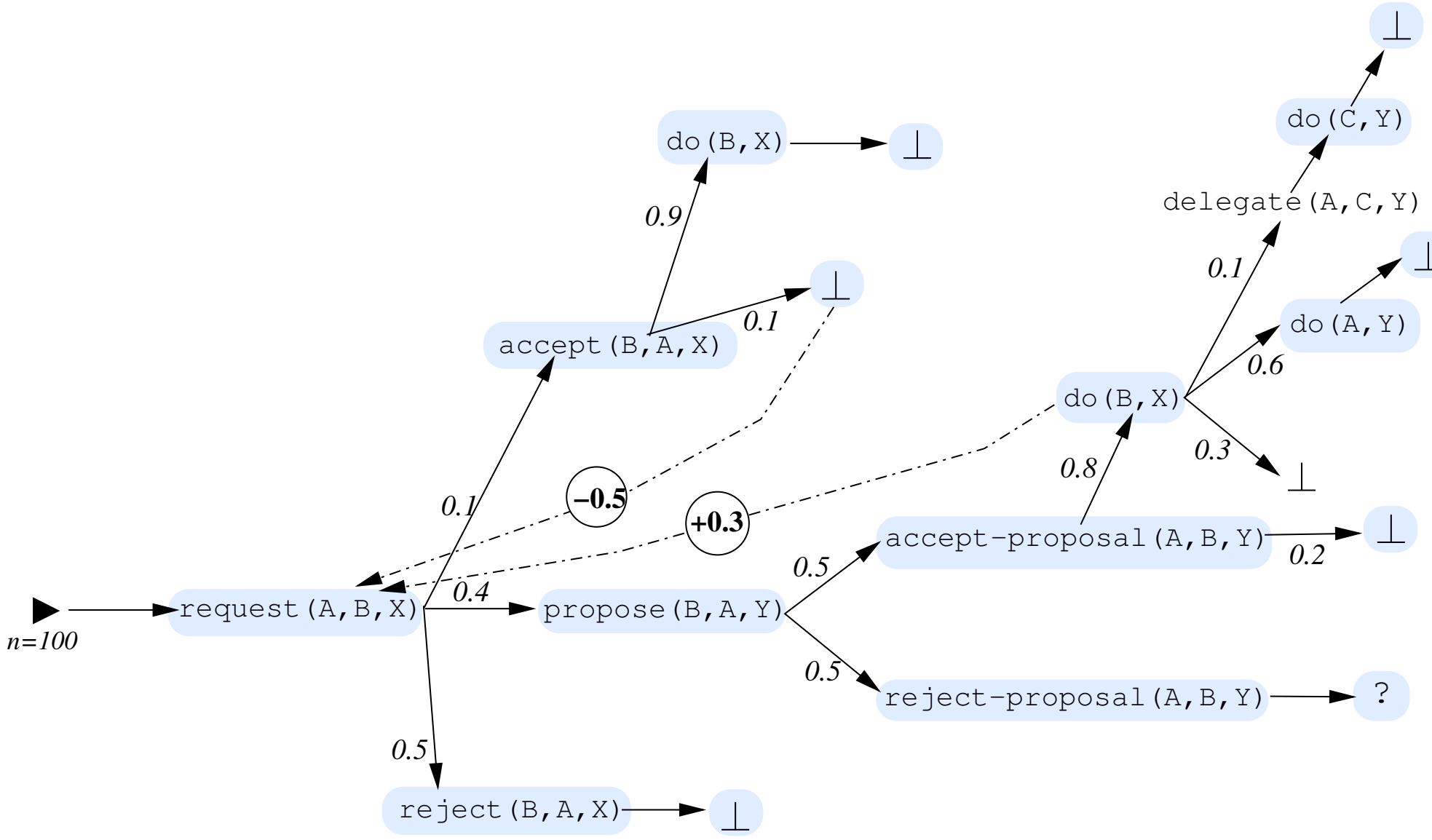
Expectation networks



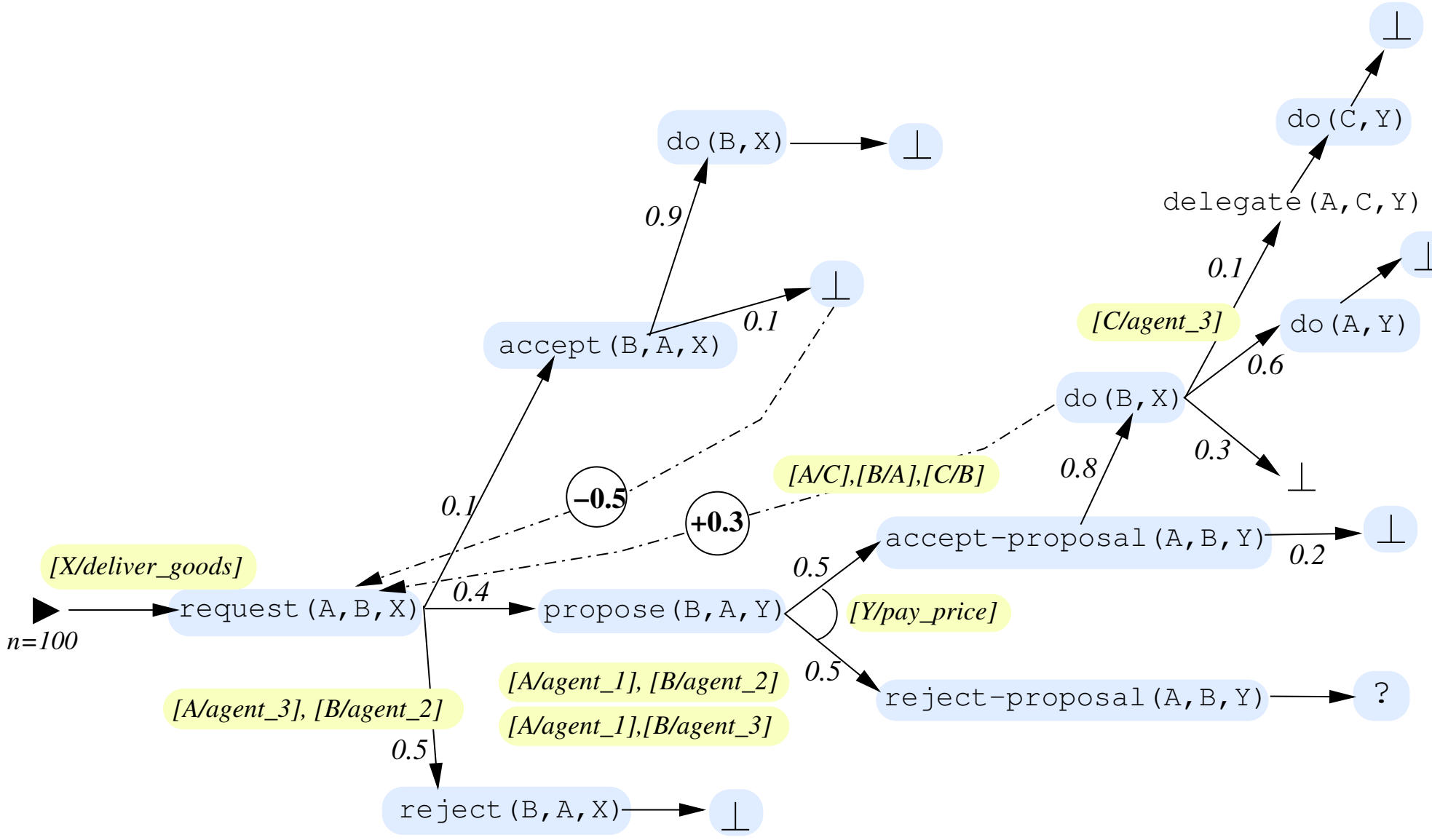
Expectation networks



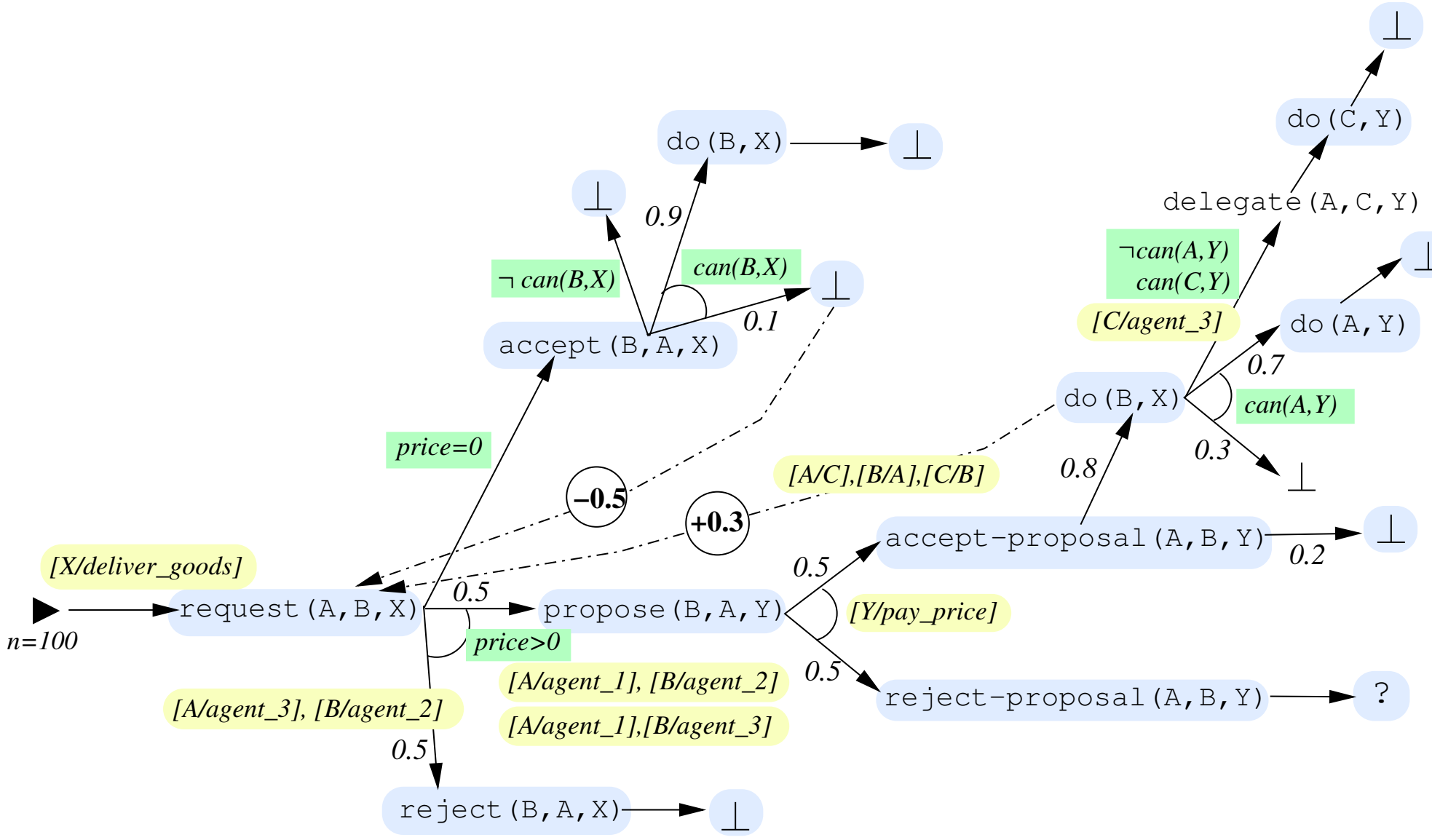
Expectation networks



Expectation networks



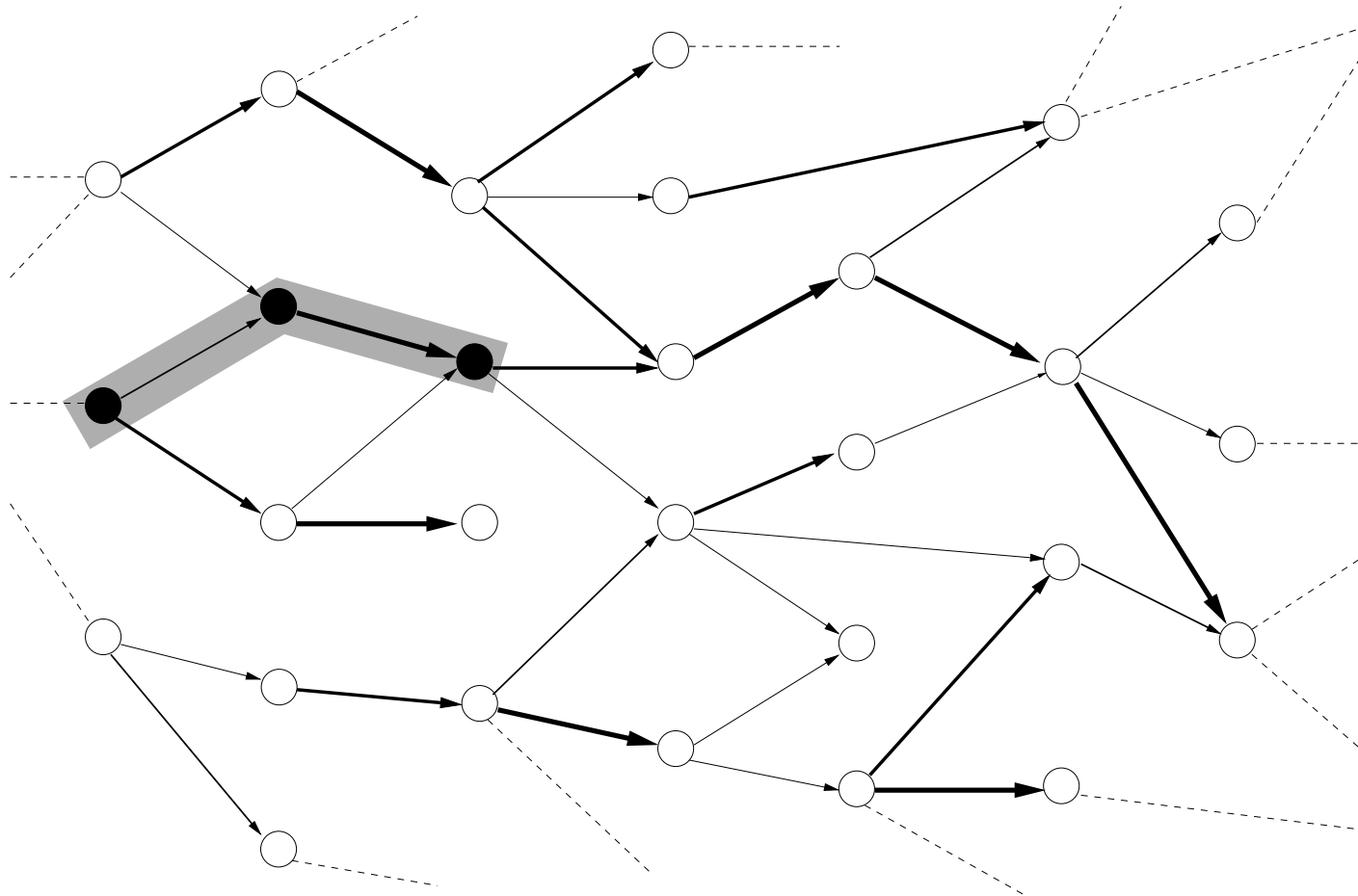
Expectation networks



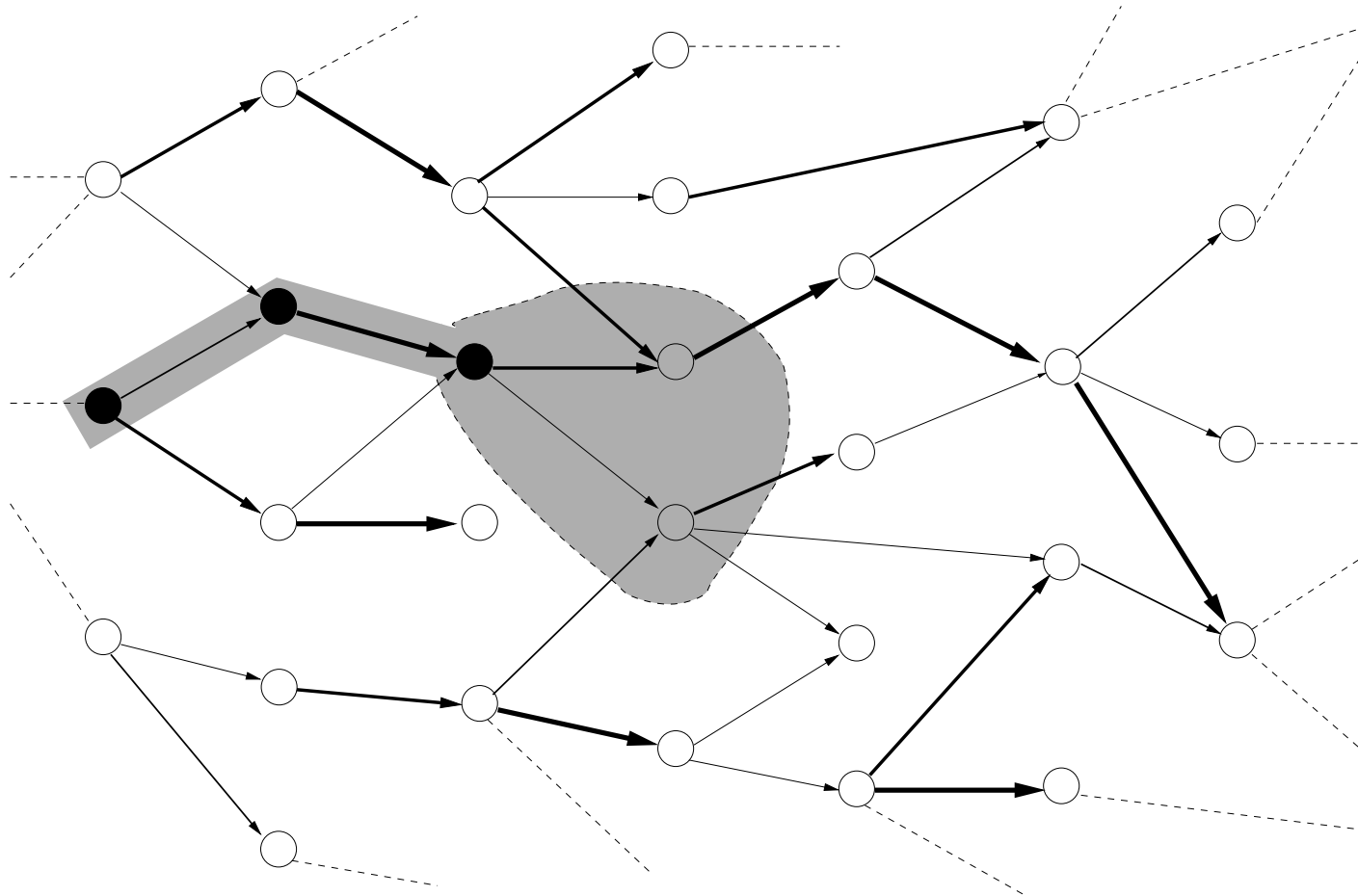
Communication Systems

- ▶ generic model for socially intelligent systems
- ▶ advantages over other models of communication semantics:
 - no mentalistic assumptions
 - can be used by agents/system observers
 - allows for context-sensitivity and uncertainty
 - captures the dynamics of evolving meaning
- ▶ expectation networks not the only possible formalism

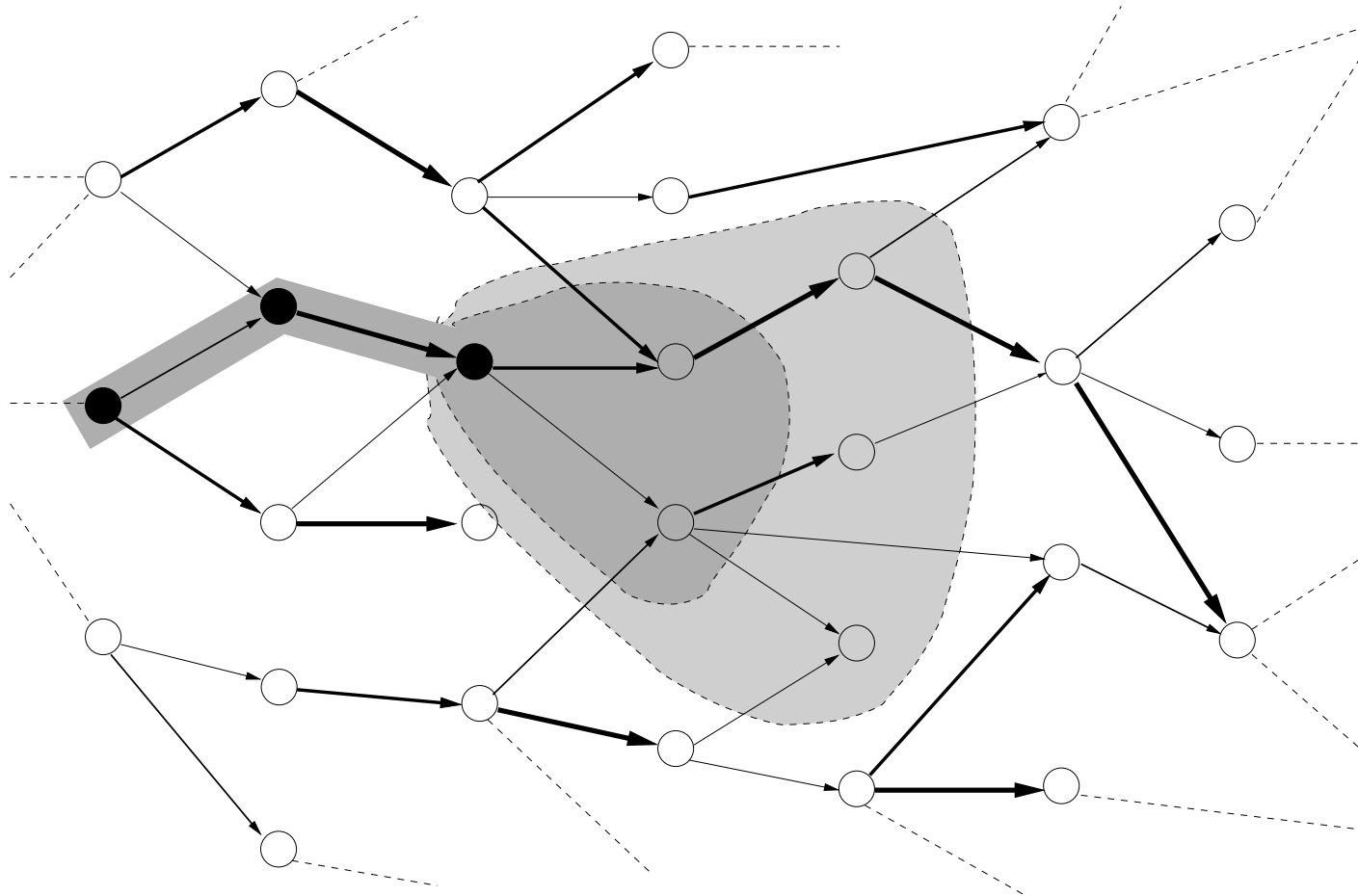
Empirical semantics



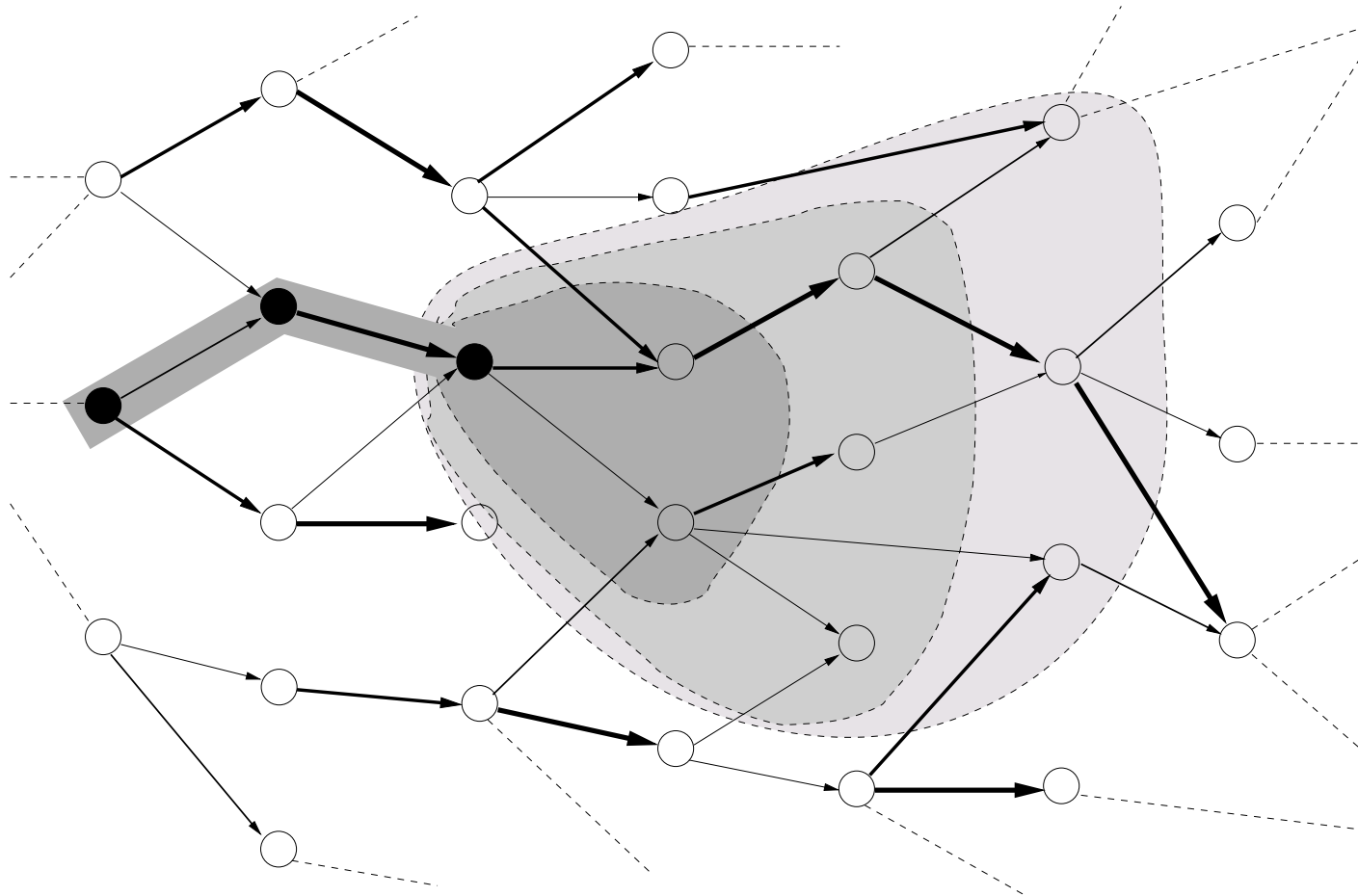
Empirical semantics



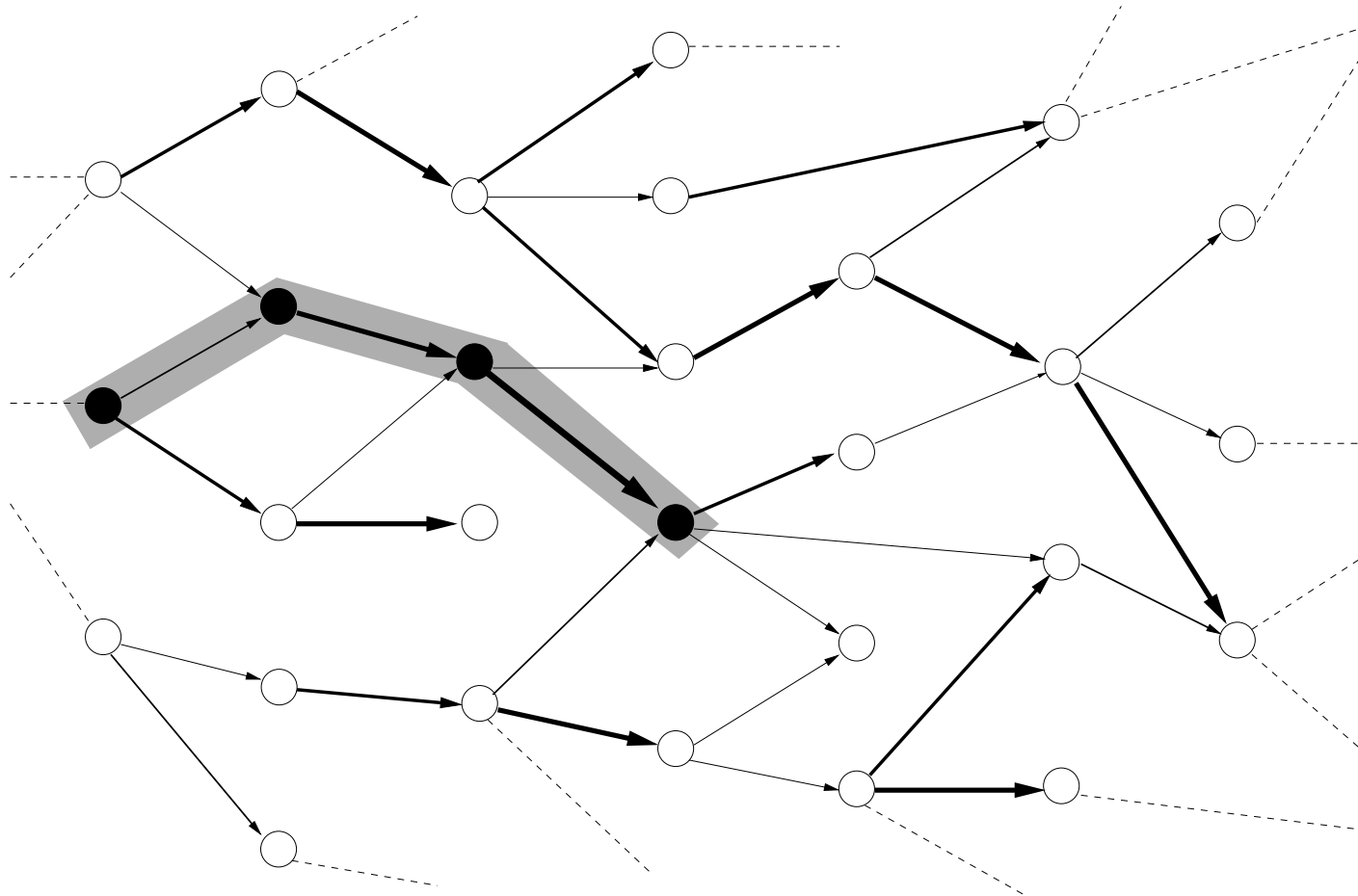
Empirical semantics



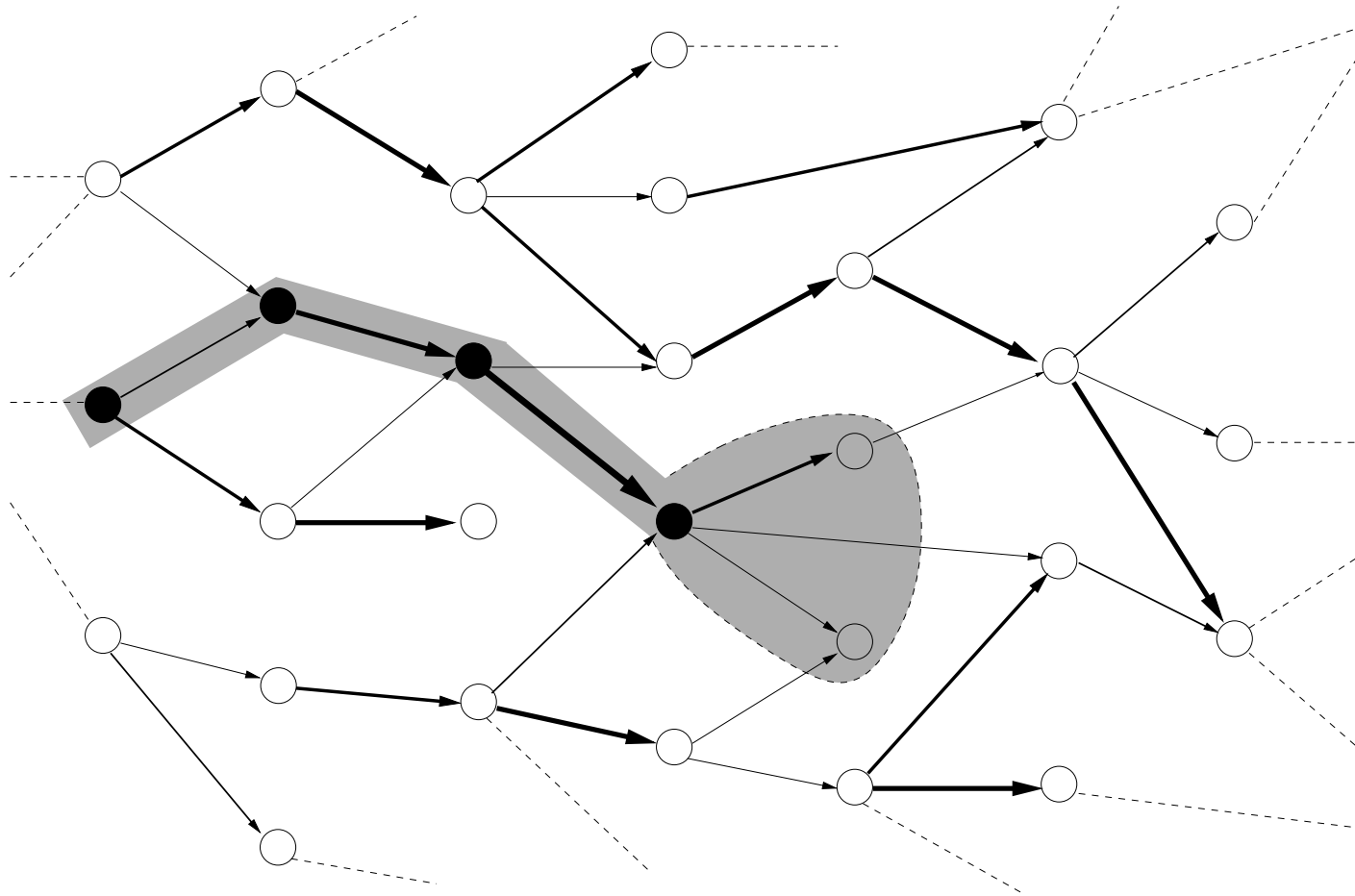
Empirical semantics



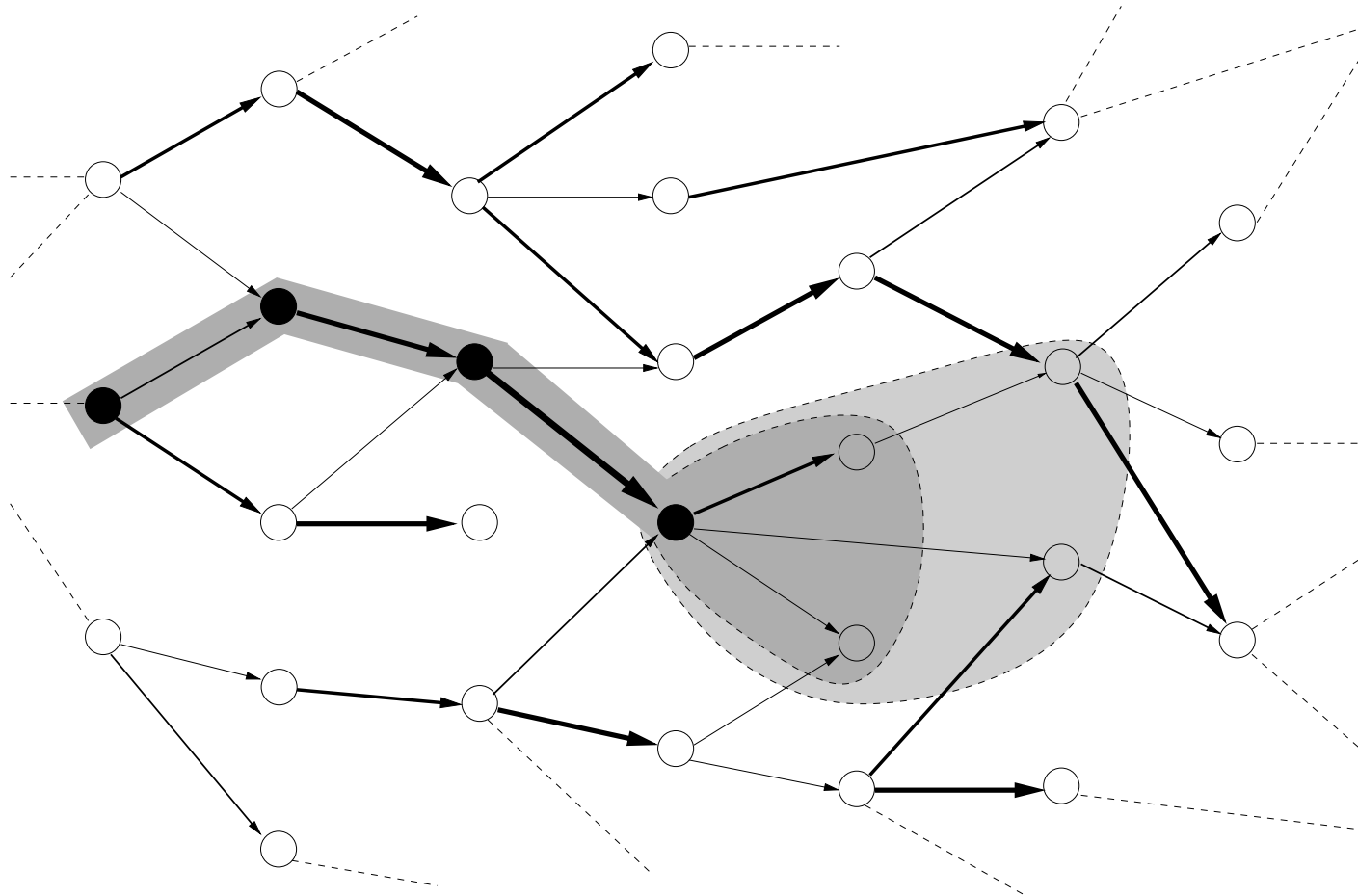
Empirical semantics



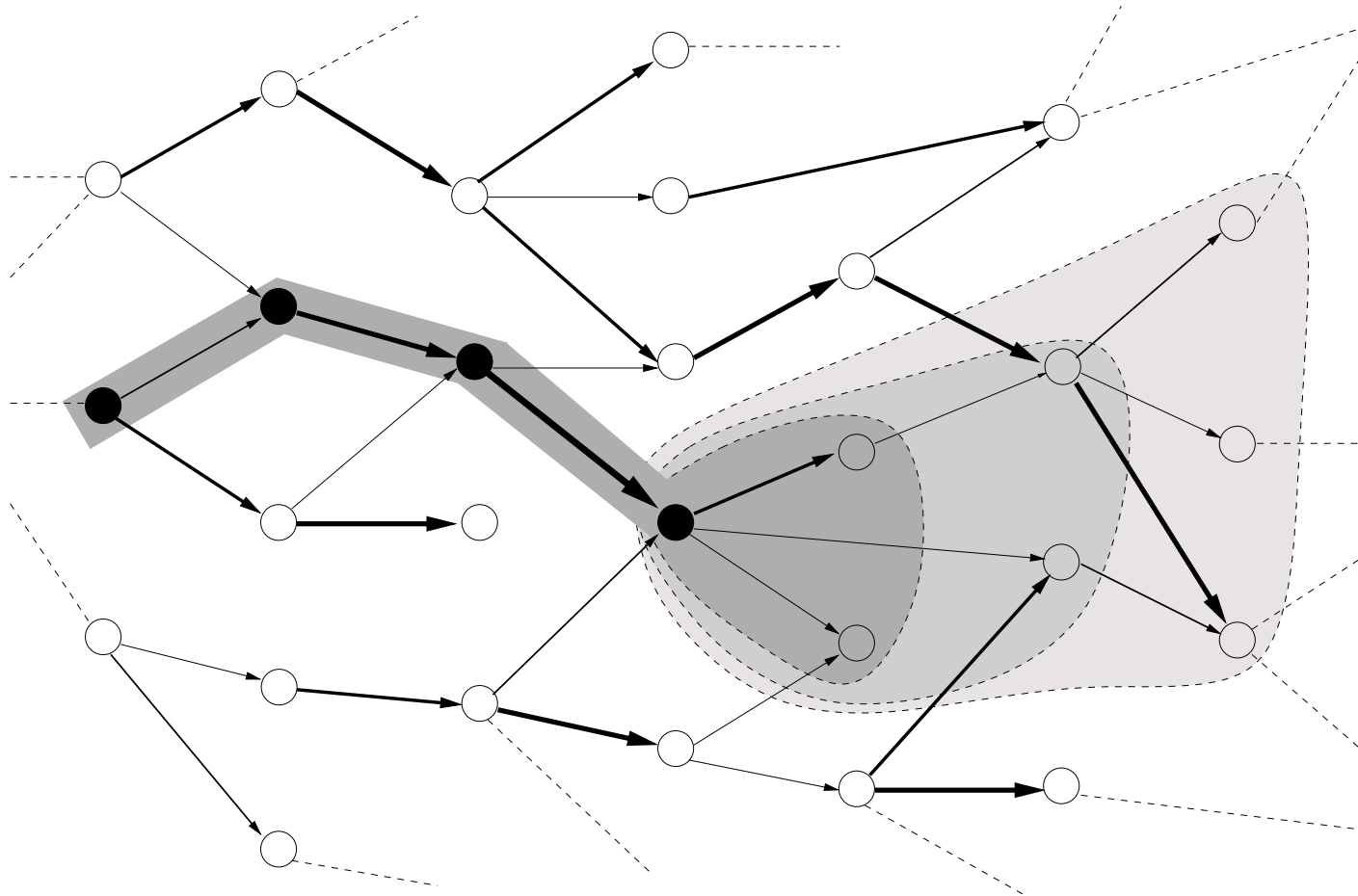
Empirical semantics



Empirical semantics



Empirical semantics



Applications

- ▶ EXPAND – EXPection-Oriented Analysis aNd Design (Brauer et al., AOSE'01)
- ▶ RNS/cRNS – Roles, Norms and Sanctions (Weiss et al., AAMAS'03)
- ▶ Mirrors and Mirror-Holons (Nickles et al.)
- ▶ Open Ontologies (Nickles & Weiss, P2P'03)
- ▶ Social Performance Measurement (Rovatsos, Schillo, Fischer, Weiss, MATES'03)
- ▶ ... and, of course, **Interaction Frames**

▶ Example: basic activity

ACT deliver (*material, quantity*)

{ STATUS RANGE

<IND> : NORM <**P**> <NO> + SANC <NO> <NO>

<DEP EACH> : NORM <**O**> <*quantity* ≤ 100> + SANC <**PU**> <withdraw_role>

<DEP AssemblyMg> : NORM <**I**> <*material = steel*> + SANC <**PU**> <pay_fine>

}

▶ Example: request activity

ACT REQUEST (EACH ; USsupplier, EUROsupplier ; NOT deliver (*material, quantity*))

{ STATUS RANGE

<IND> : NORM <**P**> < (*material = steel*) AND (rating(*material*) = poor)> +

SANC <NO> <NO>

NORMATIVE IMPACT

NORM <**I**> <*material = steel*>

}

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Interaction Frames & Framing

- ▶ “frame” & “framing” concepts grounded in the sociological theory of Erving Goffman (1922-1982)

- ▶ a frame is

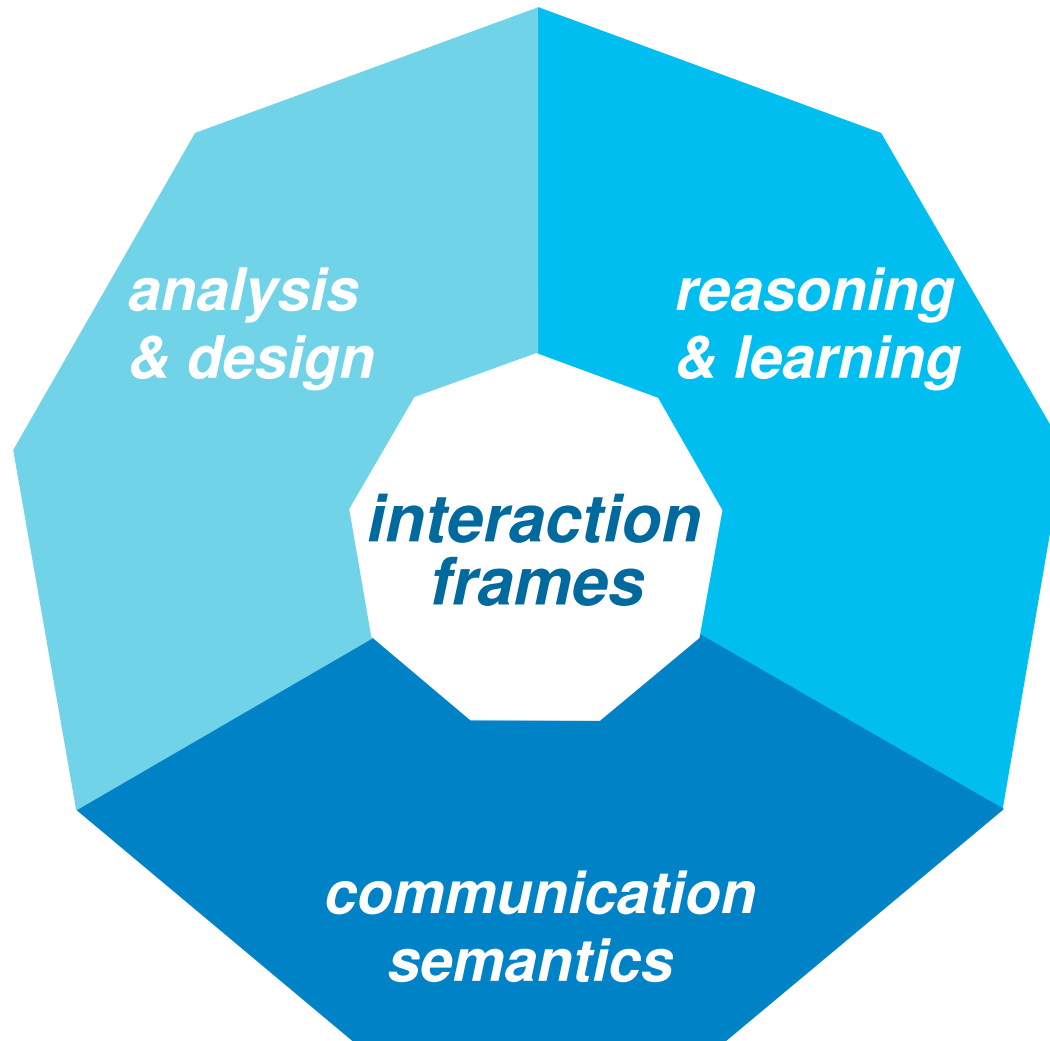
 - “the participants’ own conceptualisation of the structure within which they are interacting, which may change very quickly as the situation develops”

or

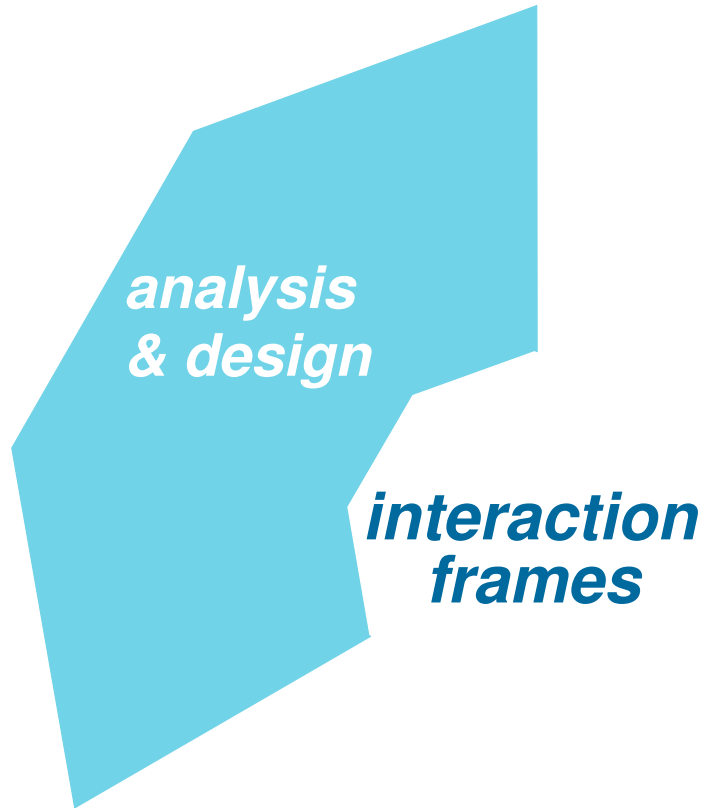
 - “the answer to the question ‘what is going on here?’ that everyone poses to oneself in an interaction situation”

- ▶ framing = strategic application of frames

Interaction Frames

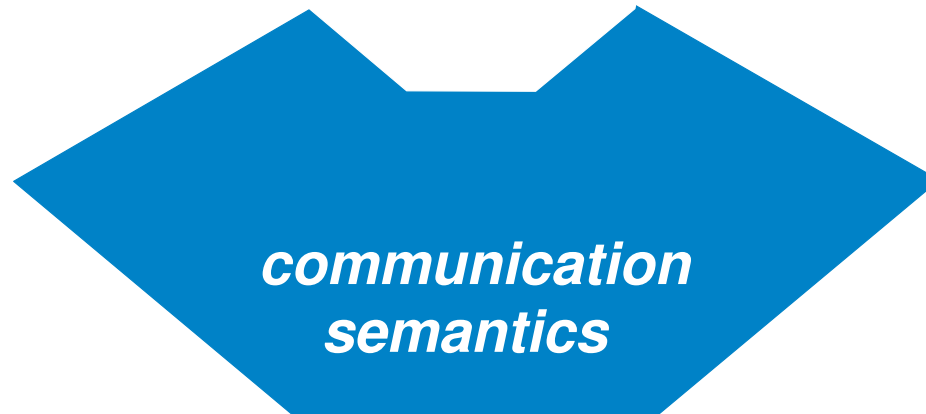


Interaction Frames

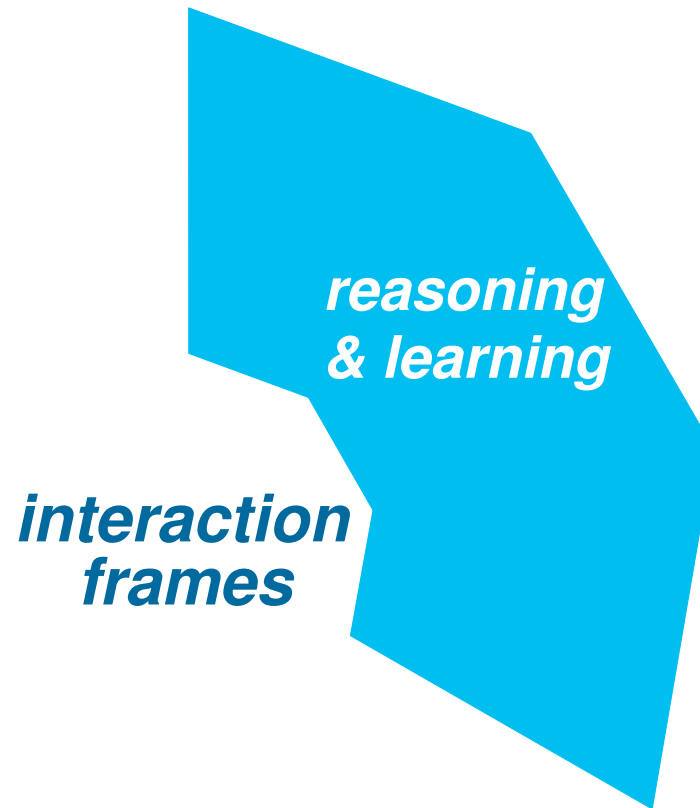


Interaction Frames

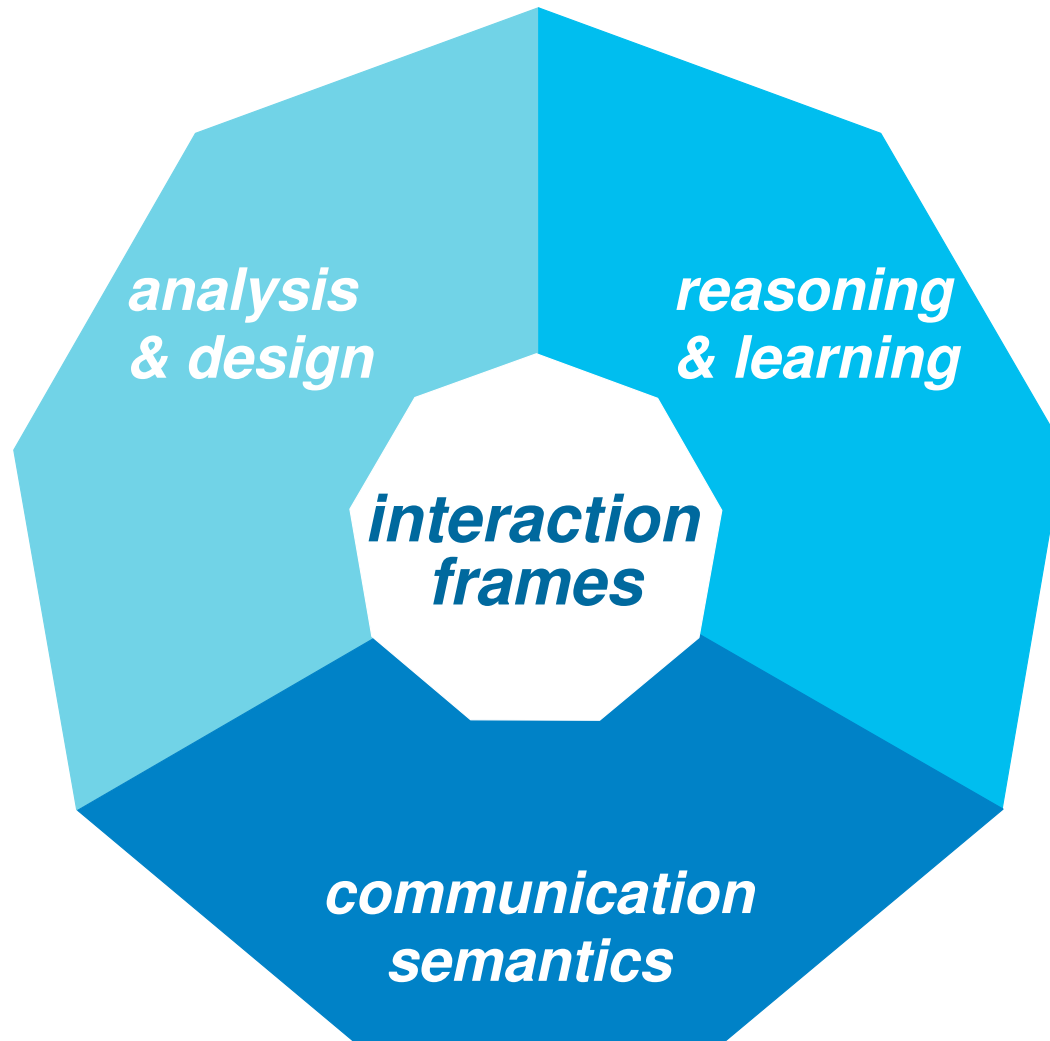
*interaction
frames*



Interaction Frames



Interaction Frames

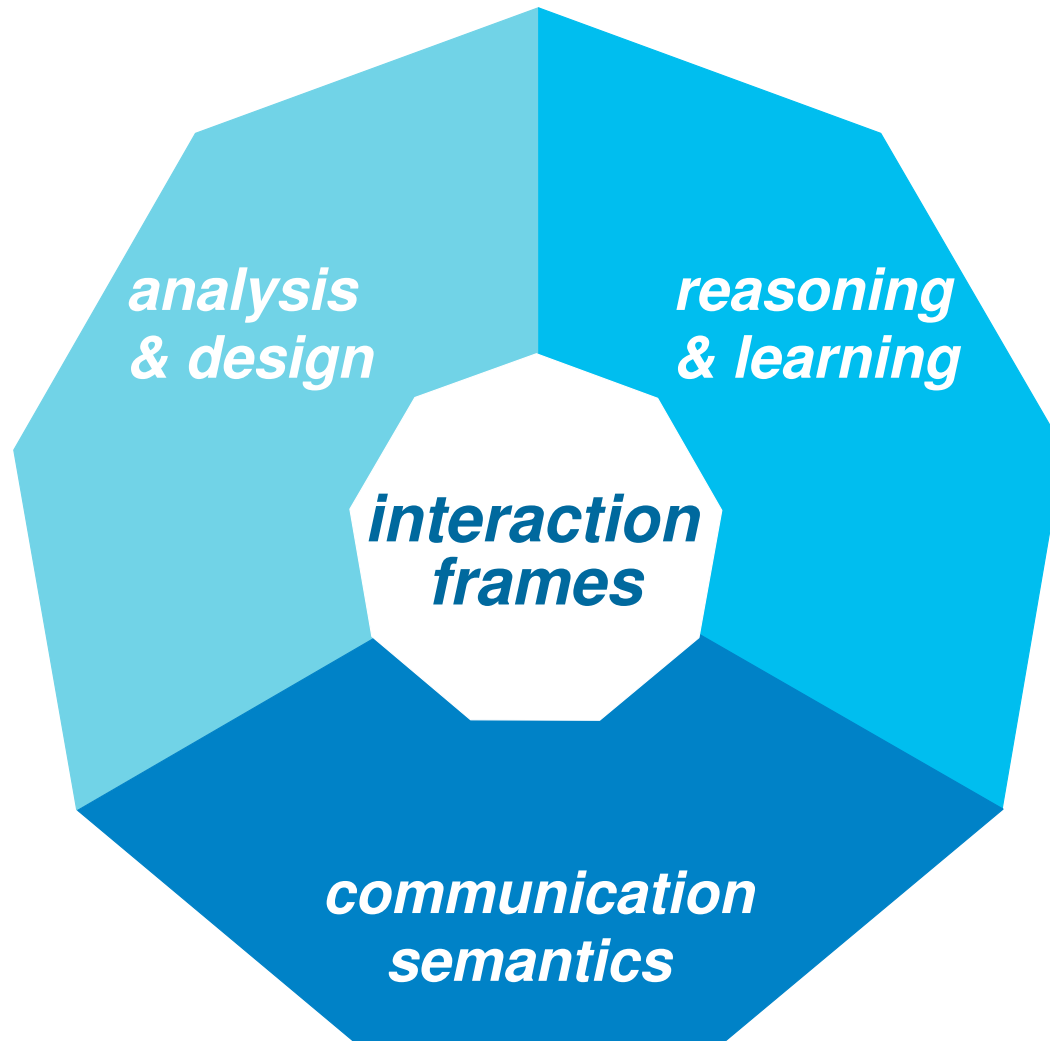


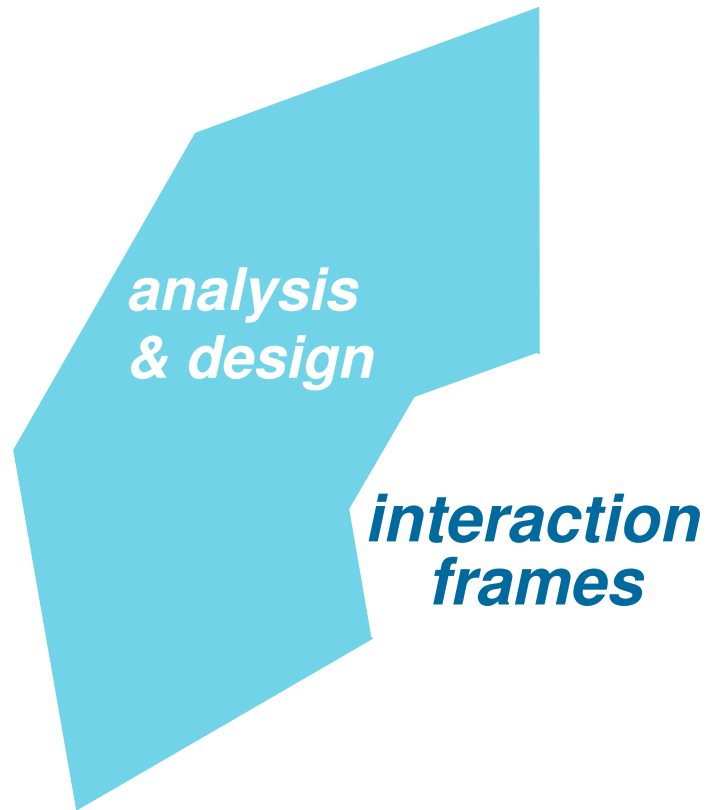
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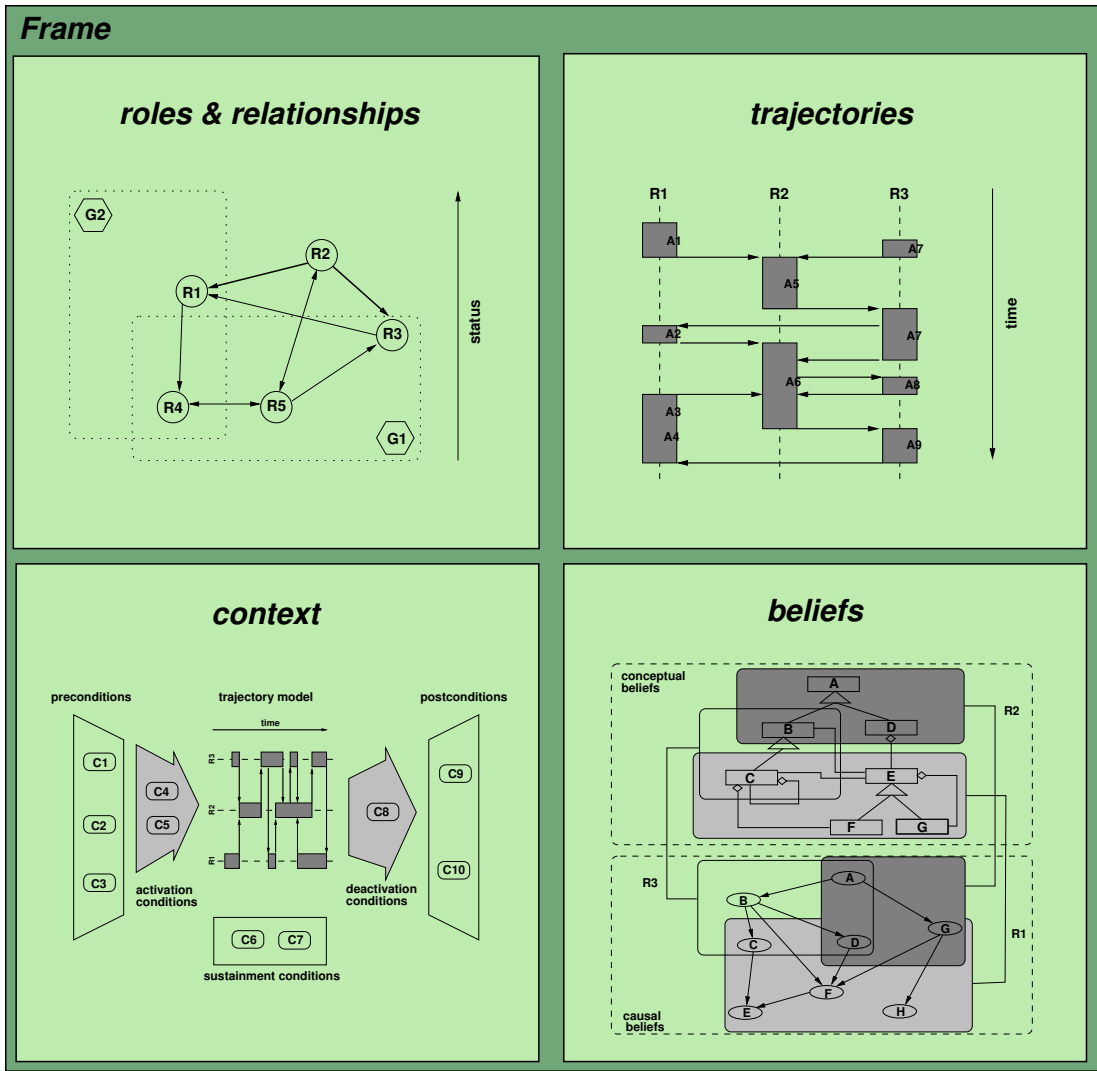


(Rovatsos et al., AAMAS'02)

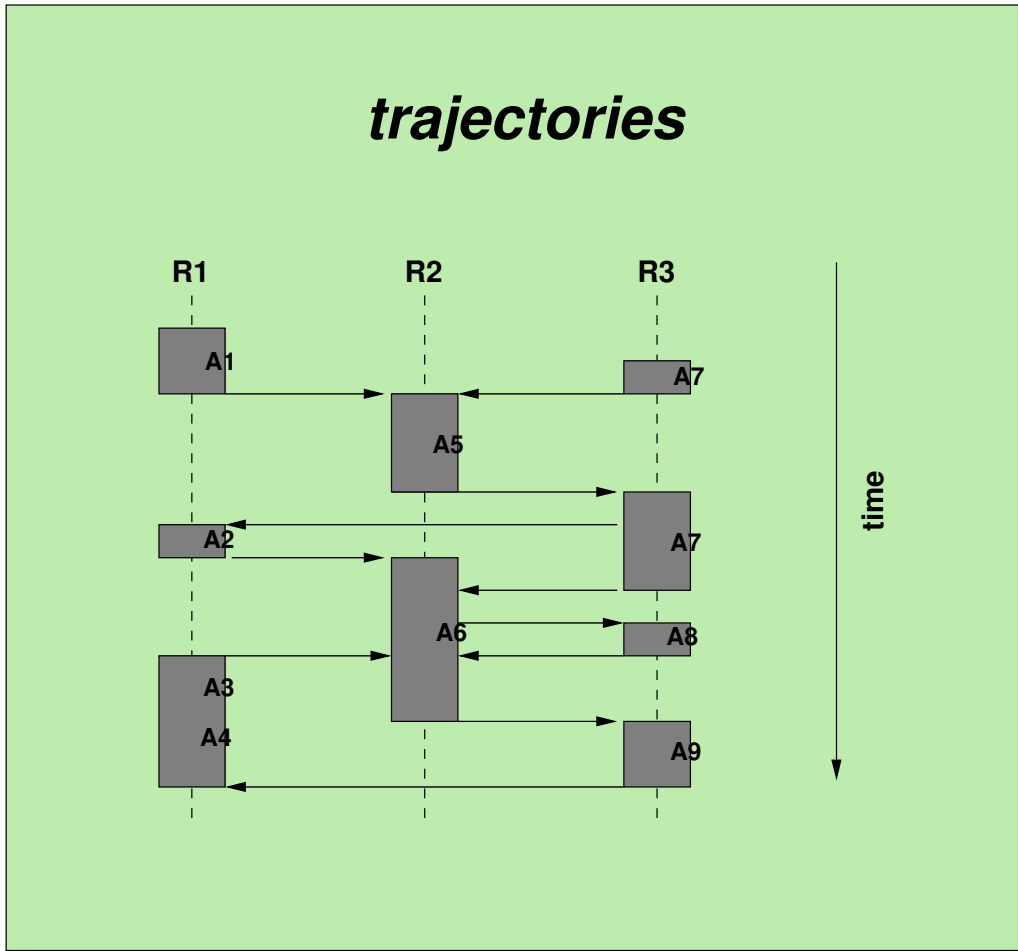
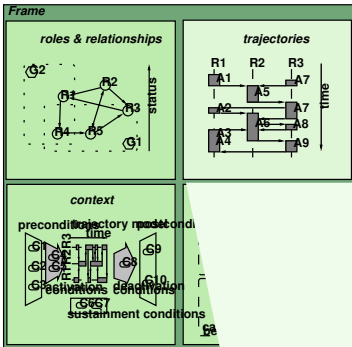
- ▶ InFFrA = Interaction Frames and Framing Architecture
- ▶ architecture for social reasoning and learning
- ▶ individualist perspective on communication systems
- ▶ socio-centric view with individualist “touch”
- ▶ interactions are not subject to agent control, but the application of frames is!
- ▶ InFFrA is an abstract architecture
 - ▶ conceptual level description
- ▶ no modelling of human social behaviour

- ▶ capture the regularities of interaction processes
- ▶ descriptive attributes
 - roles & relationships,
 - trajectories (courses of interaction),
 - contexts & conditions,
 - beliefs.
- ▶ meta-level attributes
 - status (current state of frame attributes)
 - links (“alternative”, “variant”, etc.)
 - history (of frame evolution)
 - extension (distribution of frame knowledge)

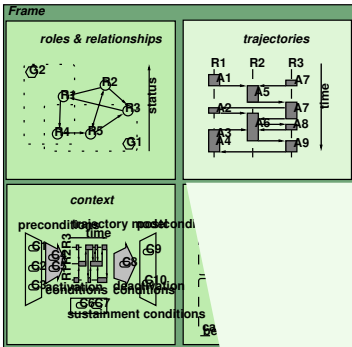
InFFrA – Frames



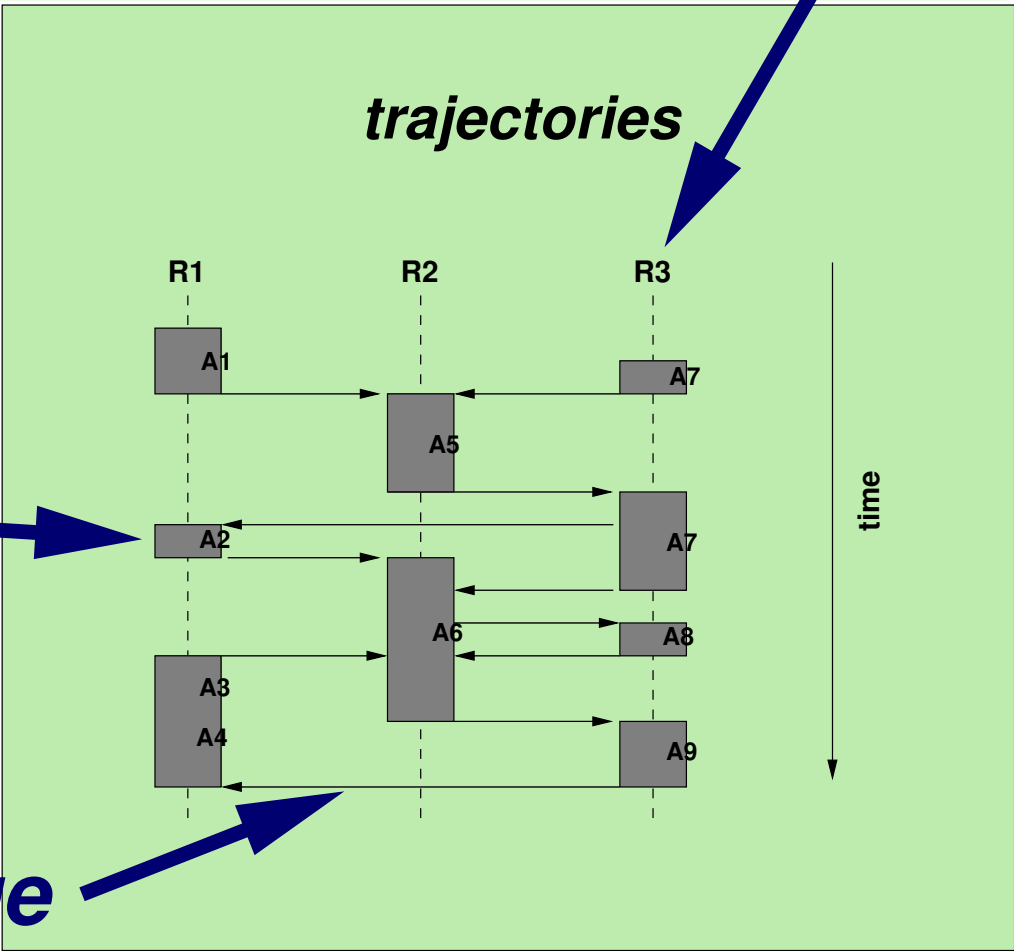
InFFrA – Frames



InFFrA – Frames



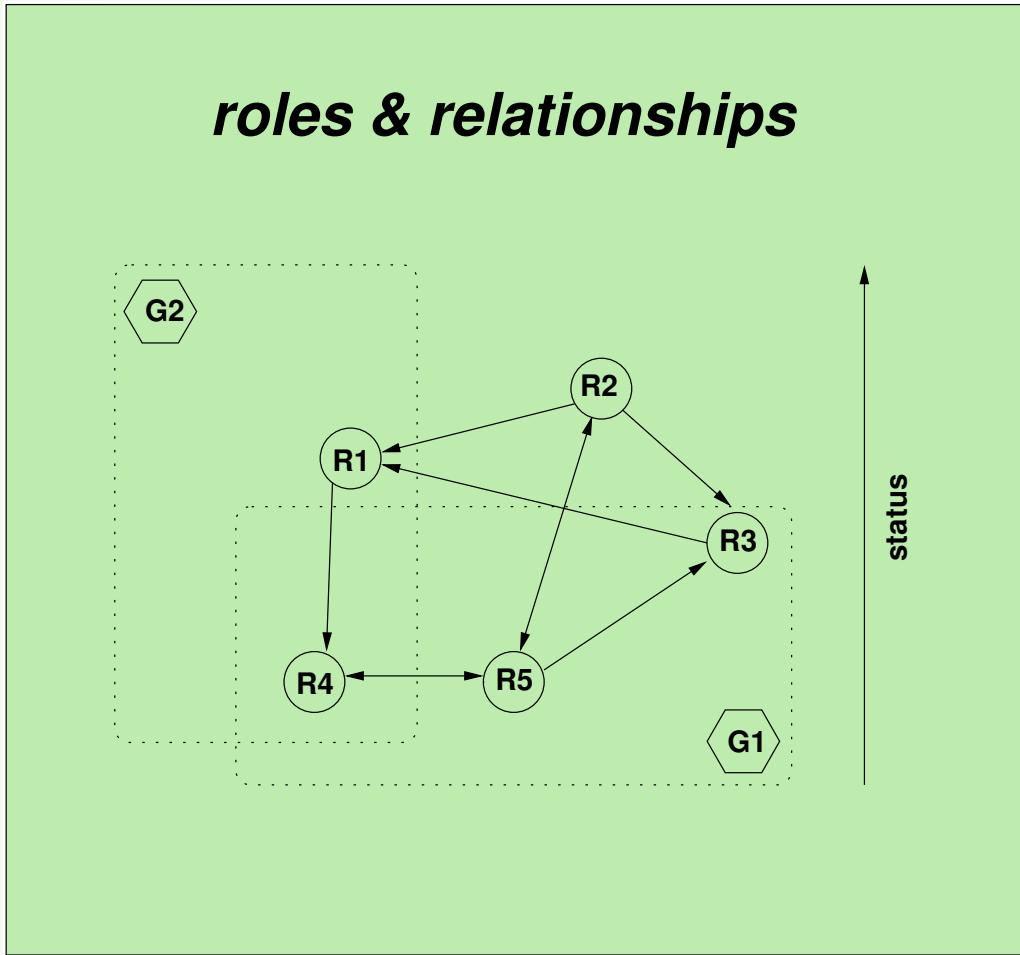
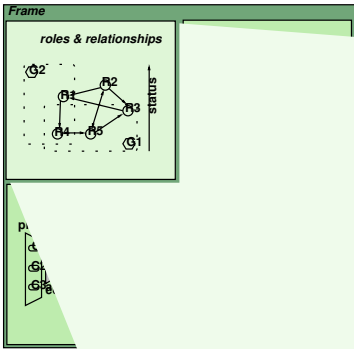
actor role



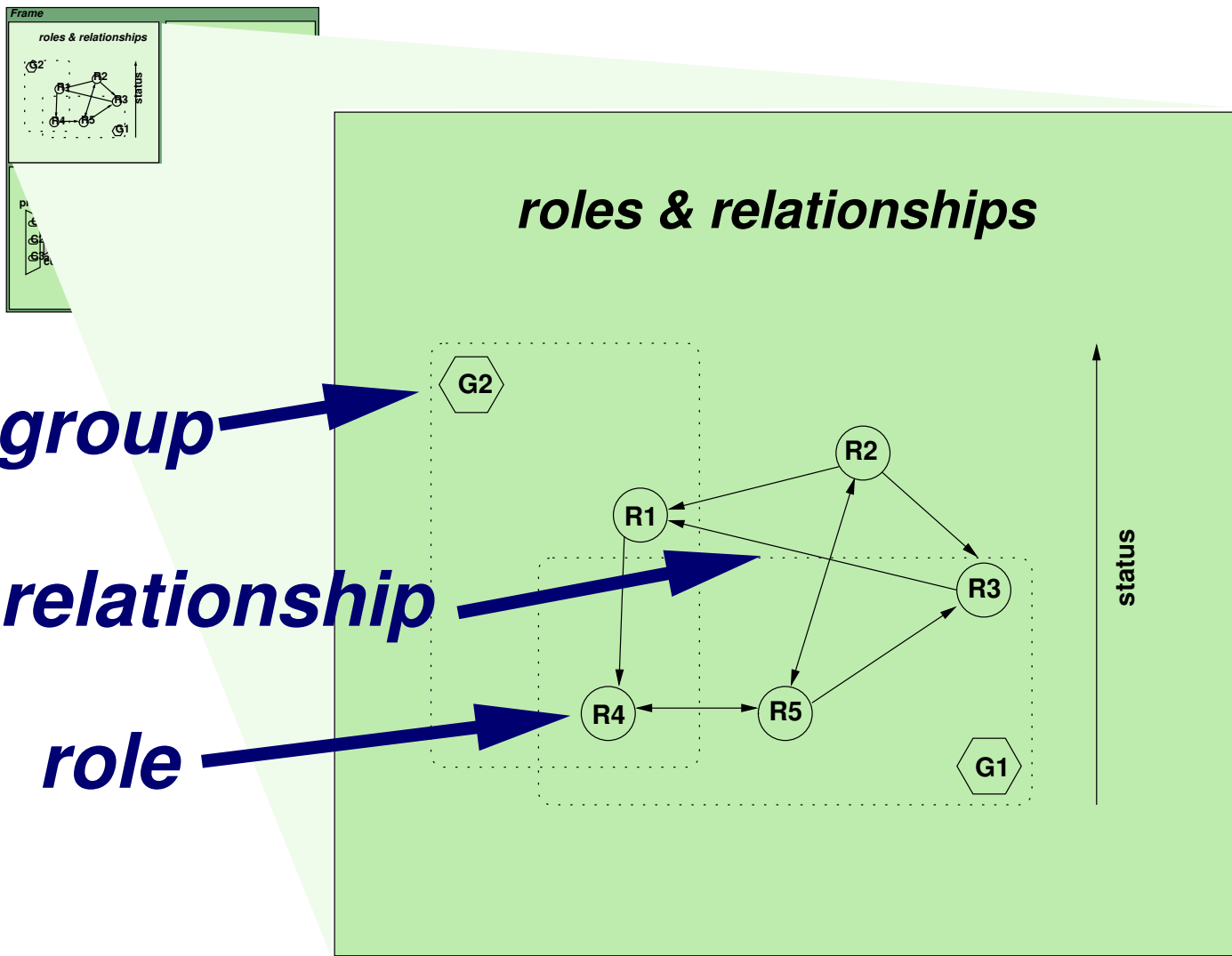
action

message

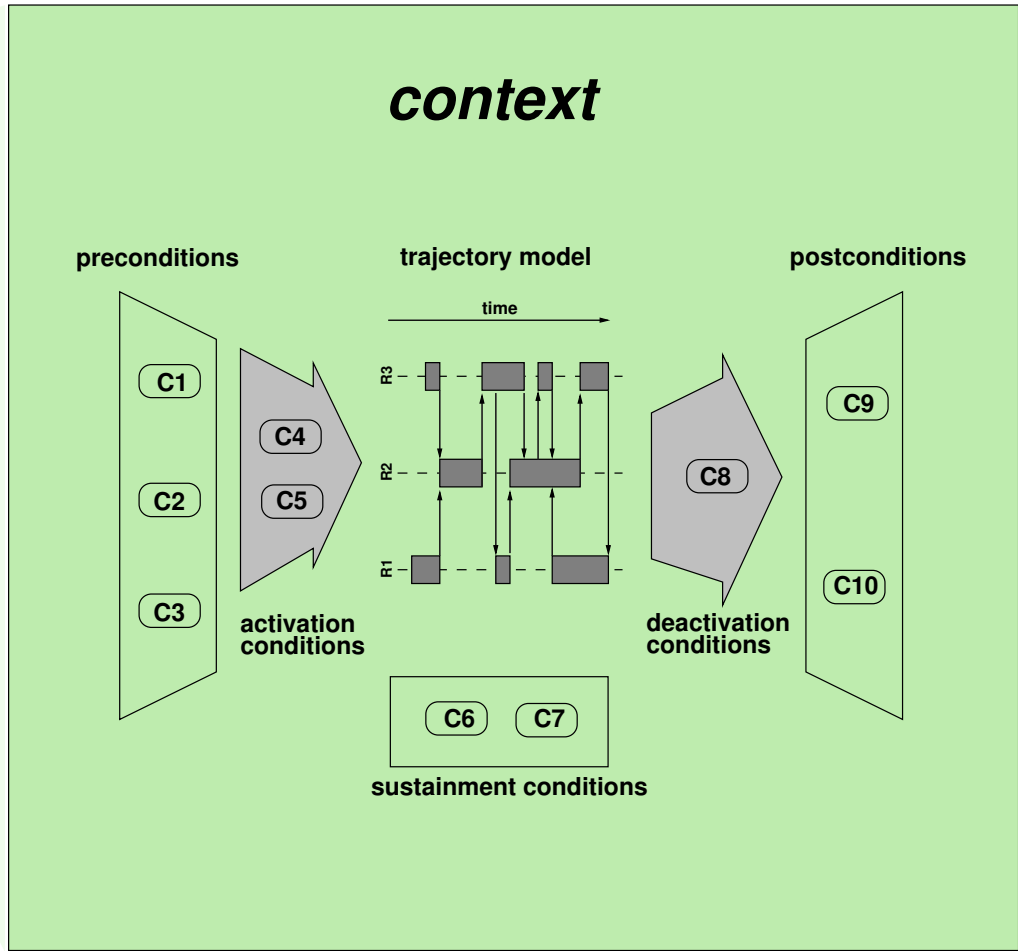
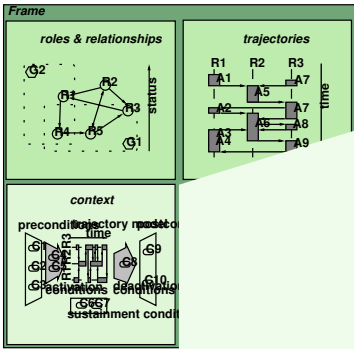
InFFrA – Frames



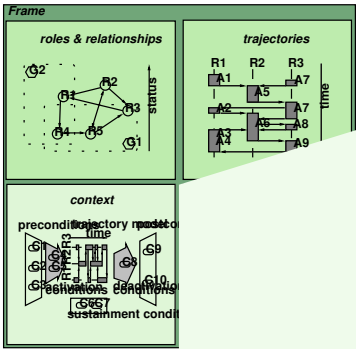
InFFrA – Frames



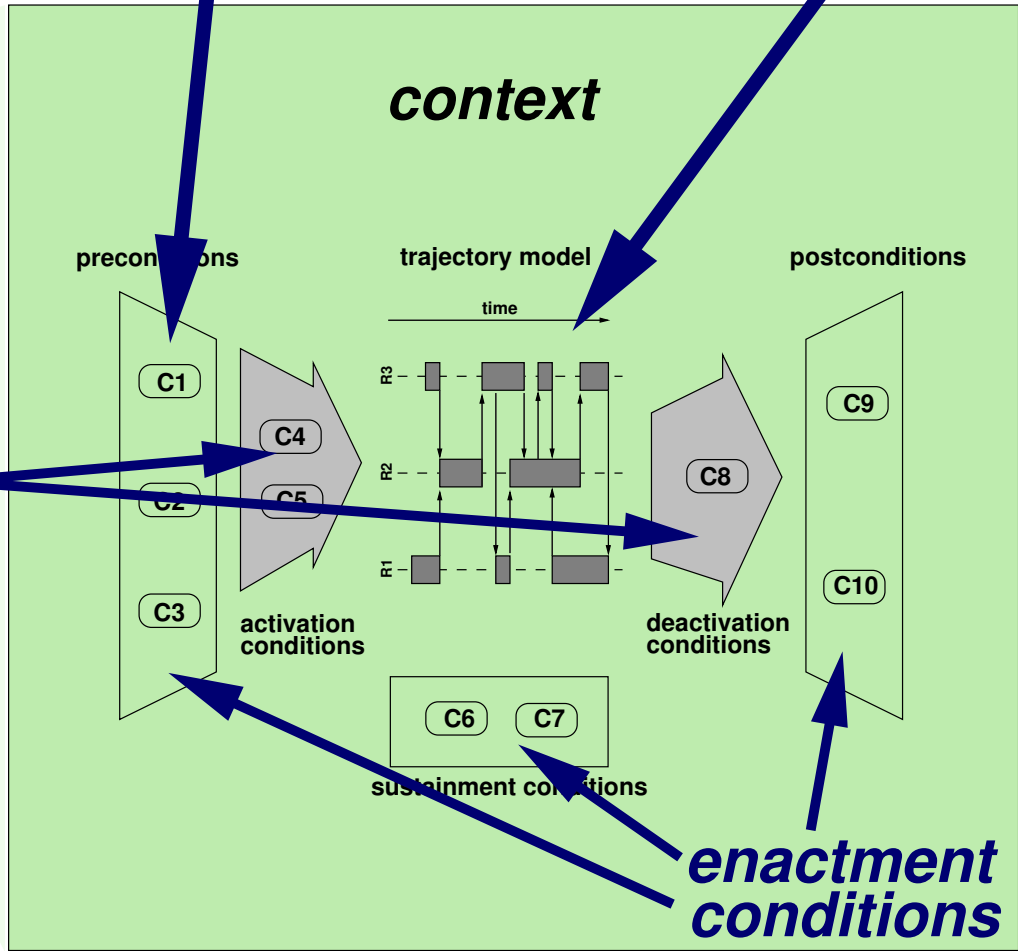
InFFrA – Frames



InFFrA – Frames



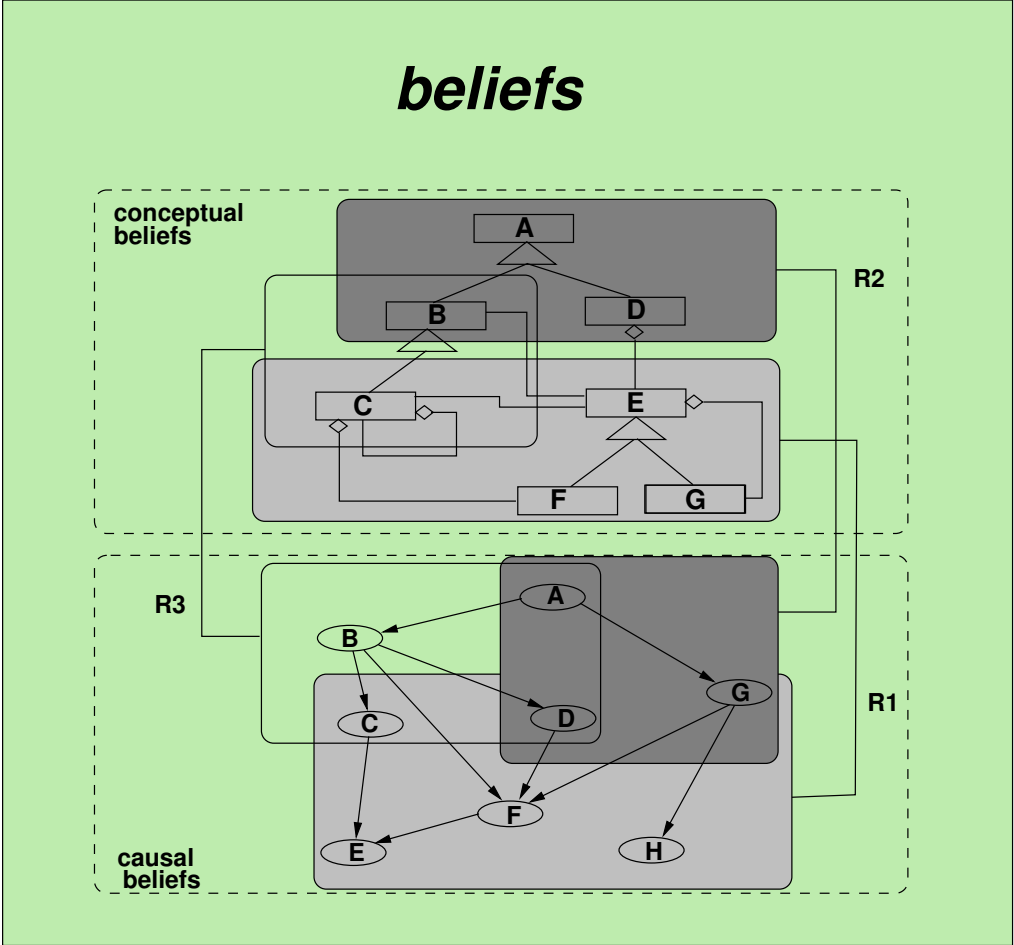
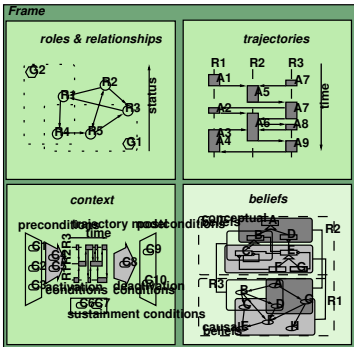
condition *trajectory*



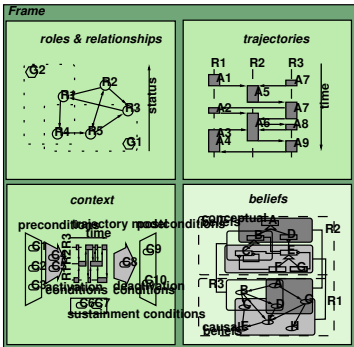
activation conditions

enactment conditions

InFFrA – Frames

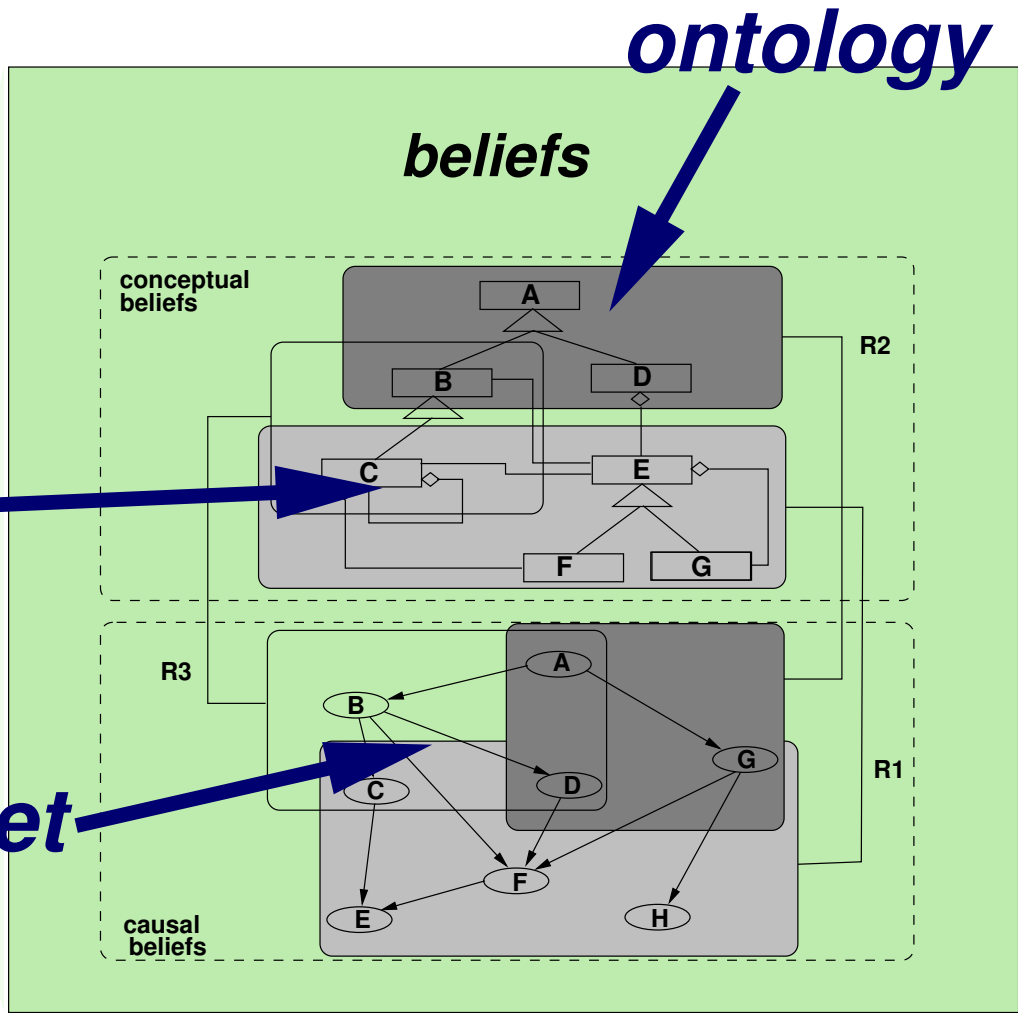


InFFrA – Frames

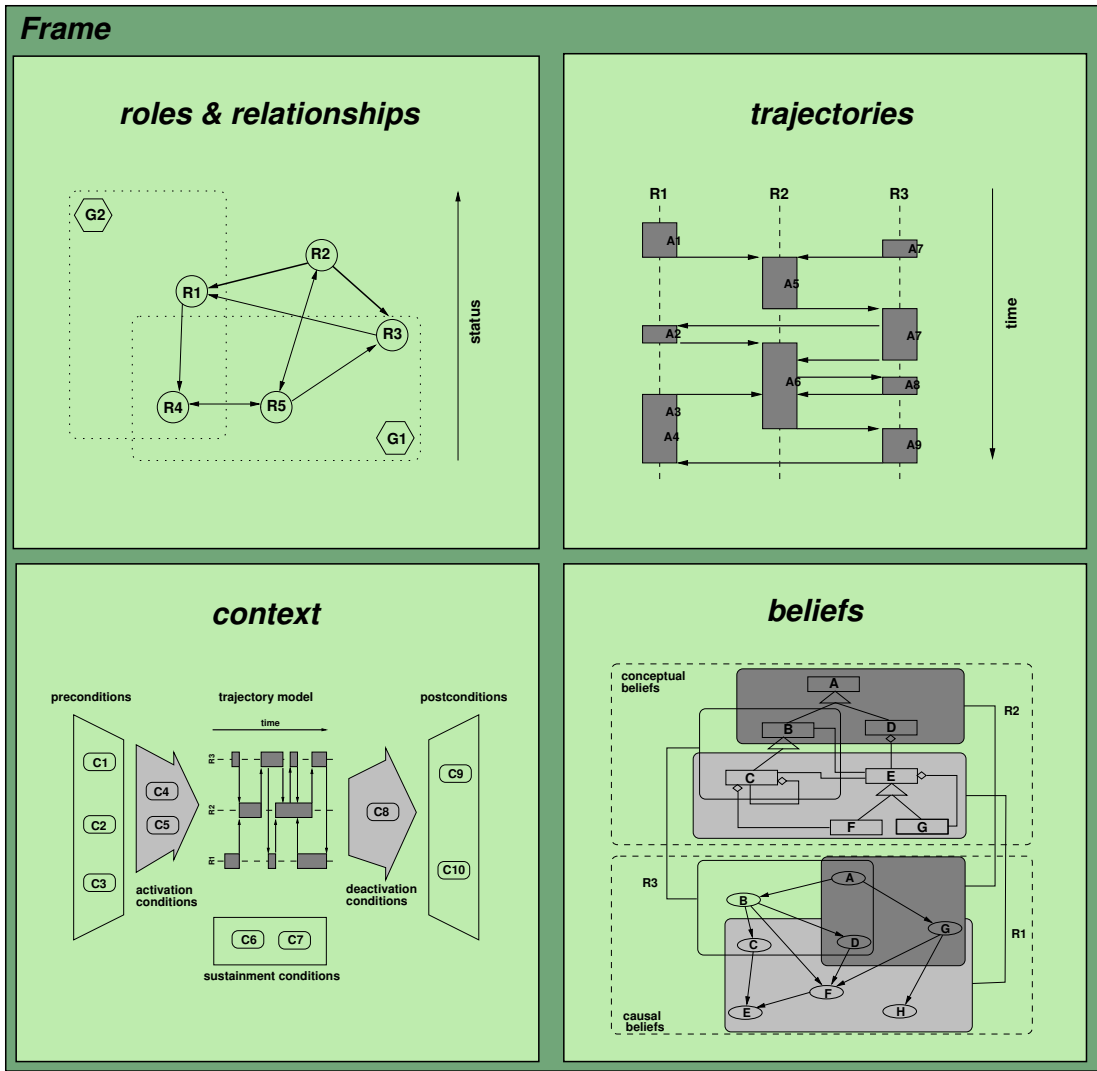


role

belief net



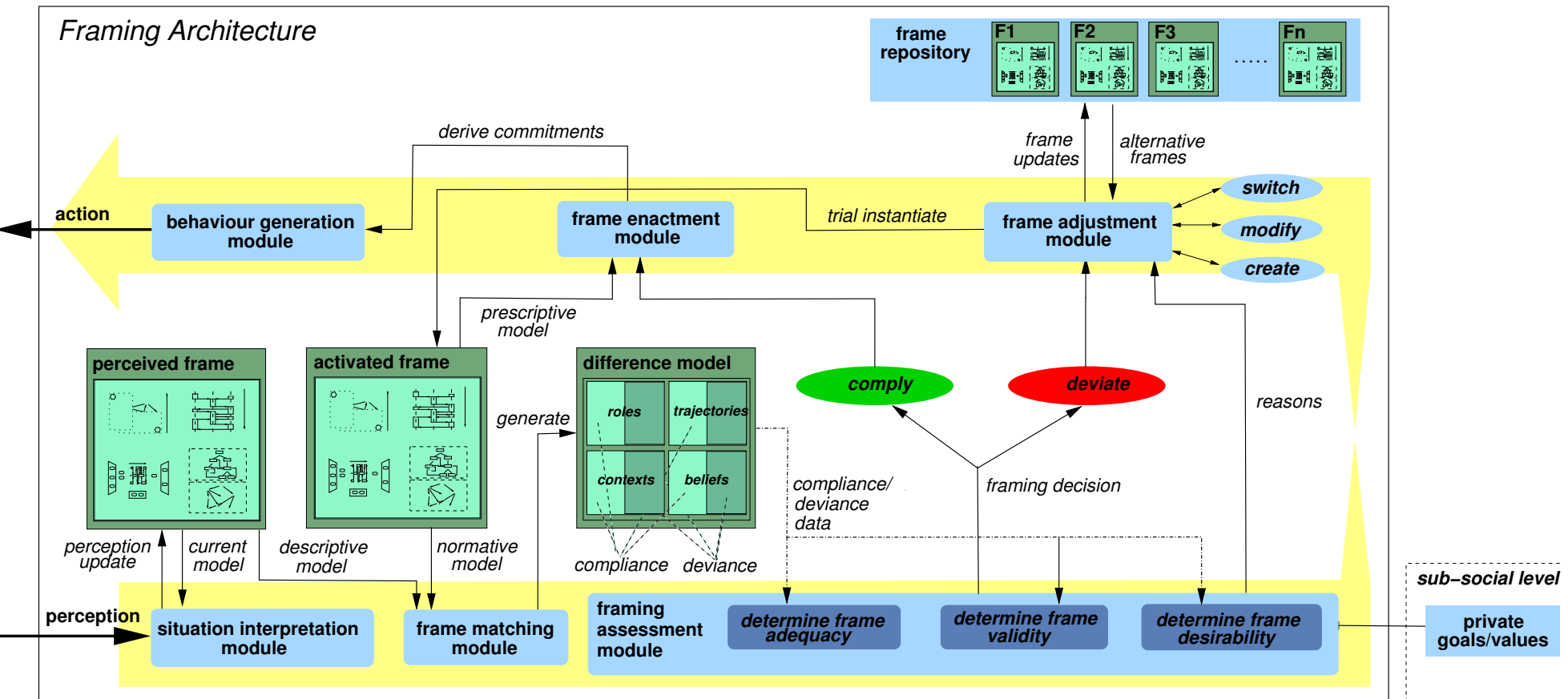
InFFrA – Frames



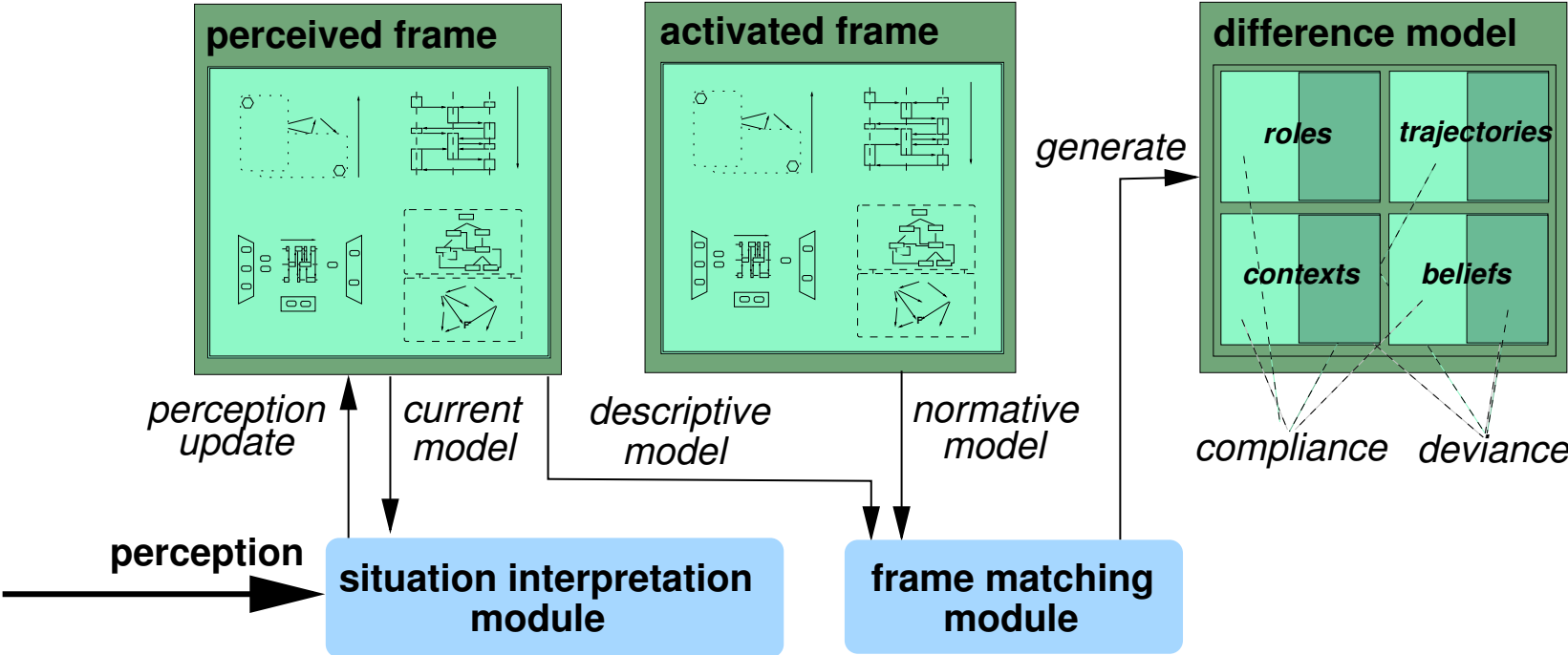
- ▶ framing is social reasoning that
 - interprets situations in terms of frames,
 - adapts frame conceptions,
 - strategically employs frames to guide interaction behaviour.
- ▶ data structures:
 - perceived frame
 - active frame
 - difference model
 - trial frame
 - frame repository

- ▶ inference steps:
 - situation interpretation
 - matching
 - assessment
 - framing decision
 - adjustment/re-framing
 - enactment
 - behaviour generation

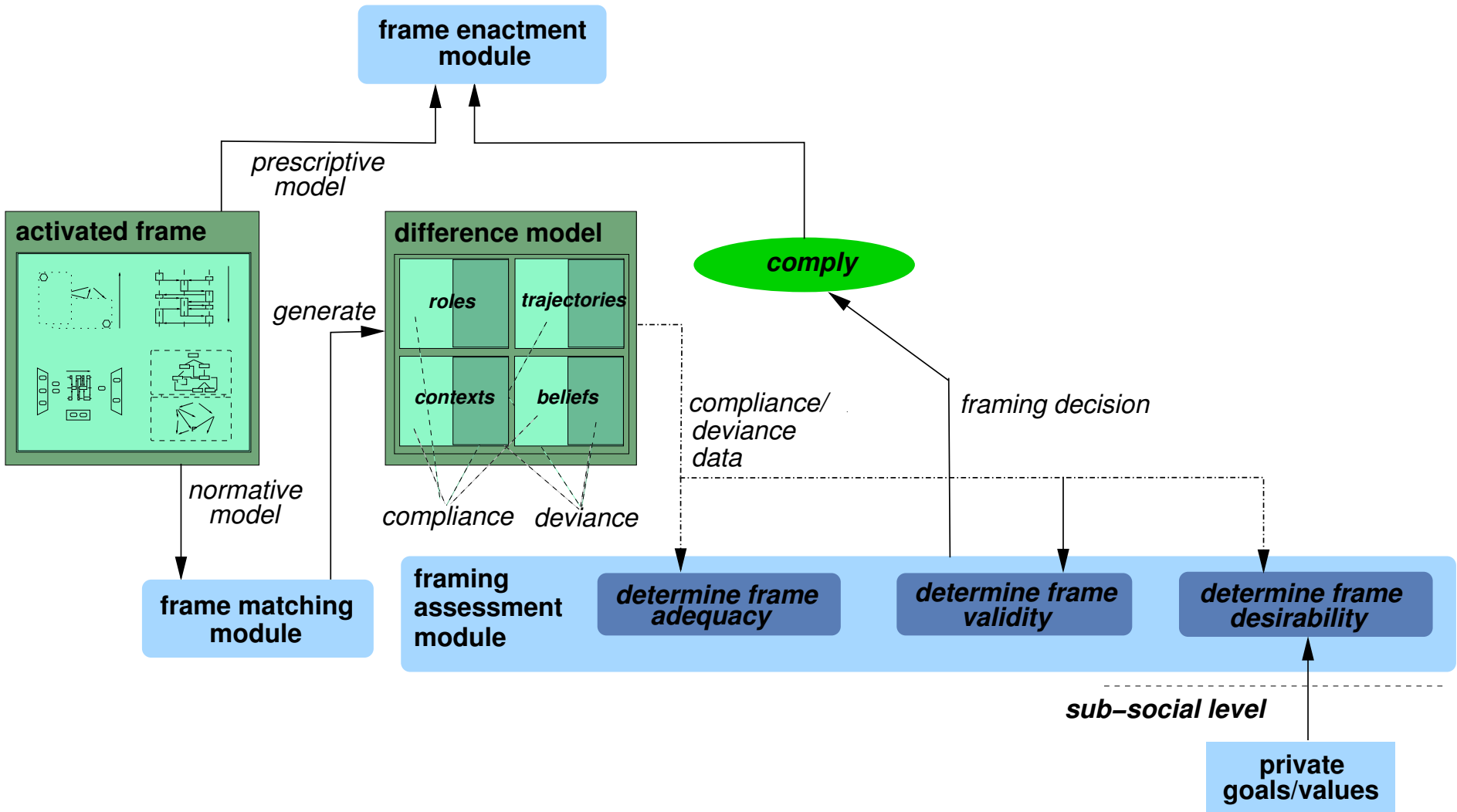
Framing



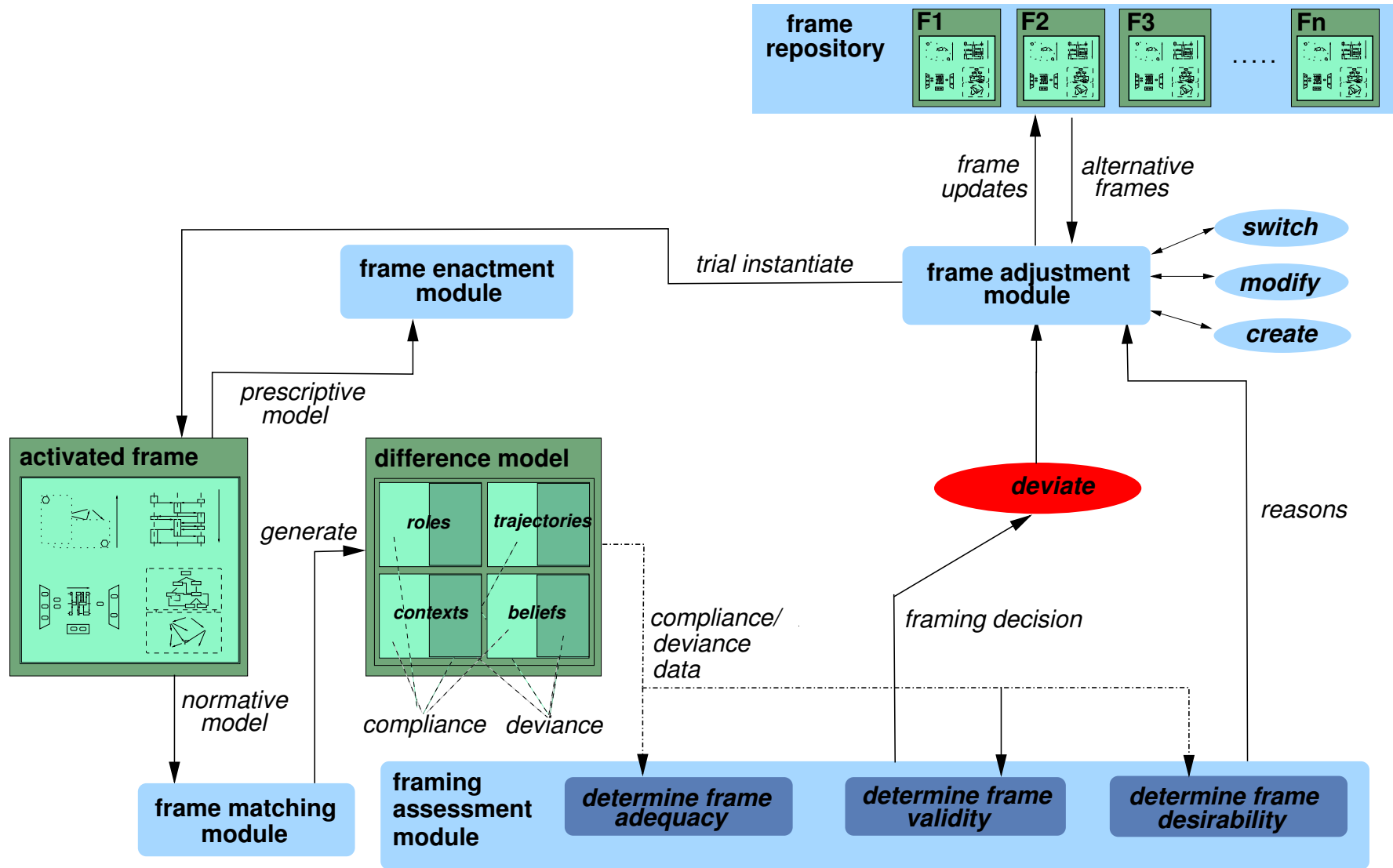
Interpretation & Matching



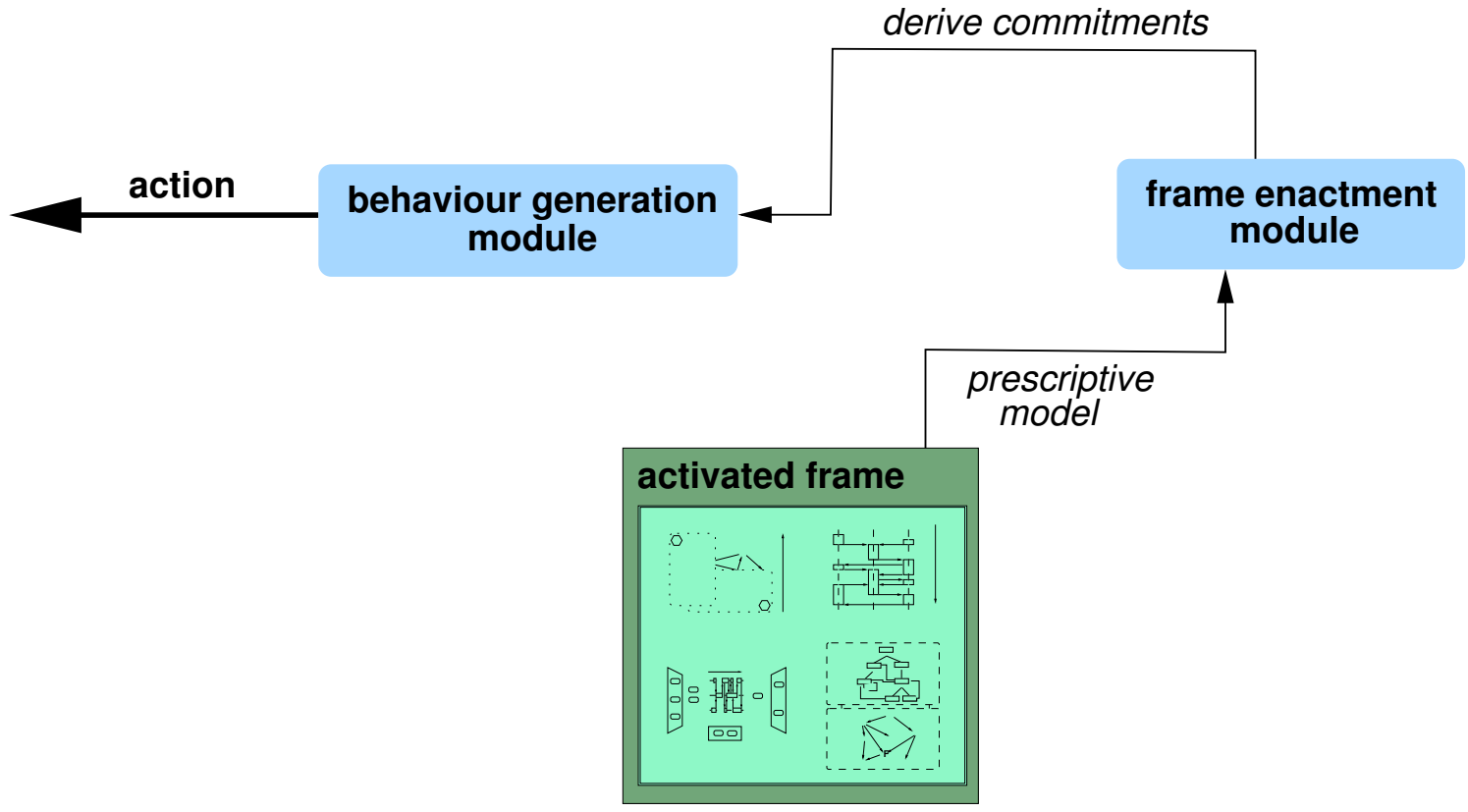
Assessment: "Comply Case"



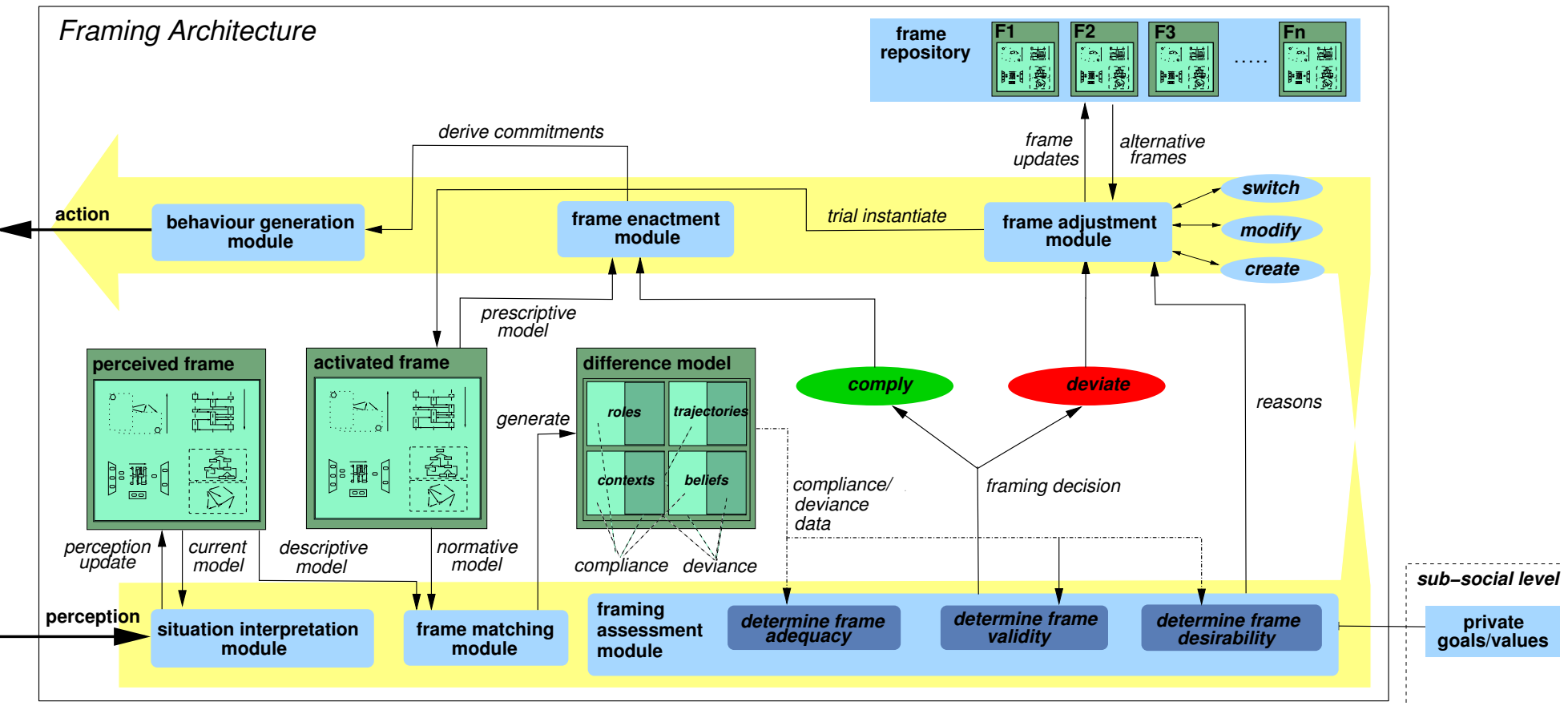
Assessment: "Deviate Case"



Enactment



Framing



InFFrA – Summary

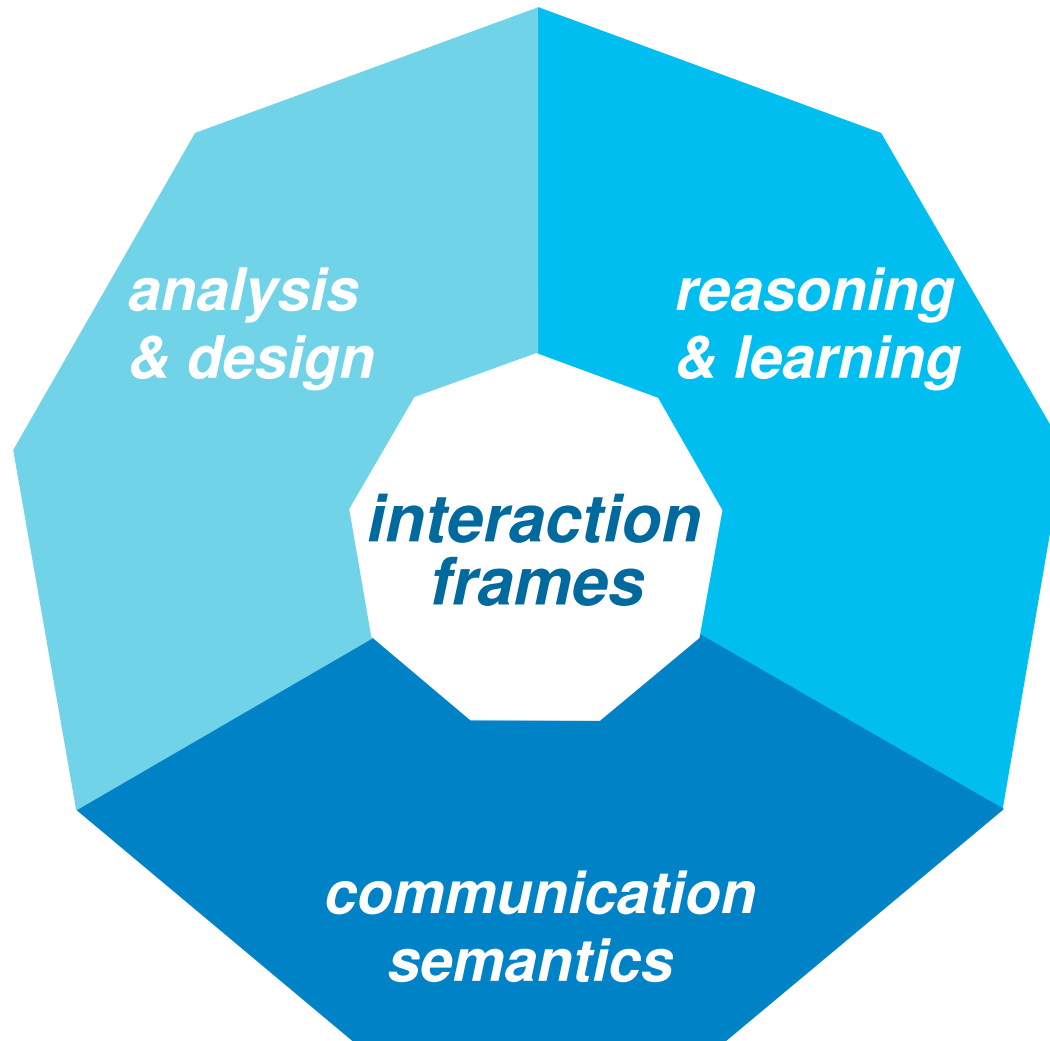
- ▶ abstract architecture, many possible designs
- ▶ generic model for agent-level reasoning about interaction
- ▶ difference between frames and interaction protocols/conversation policies:
 - not fixed *a priori*, evolving
 - include information about context and experience
 - are vulnerable to manipulation (e.g. deception)
 - actors move fluidly rapidly between frames

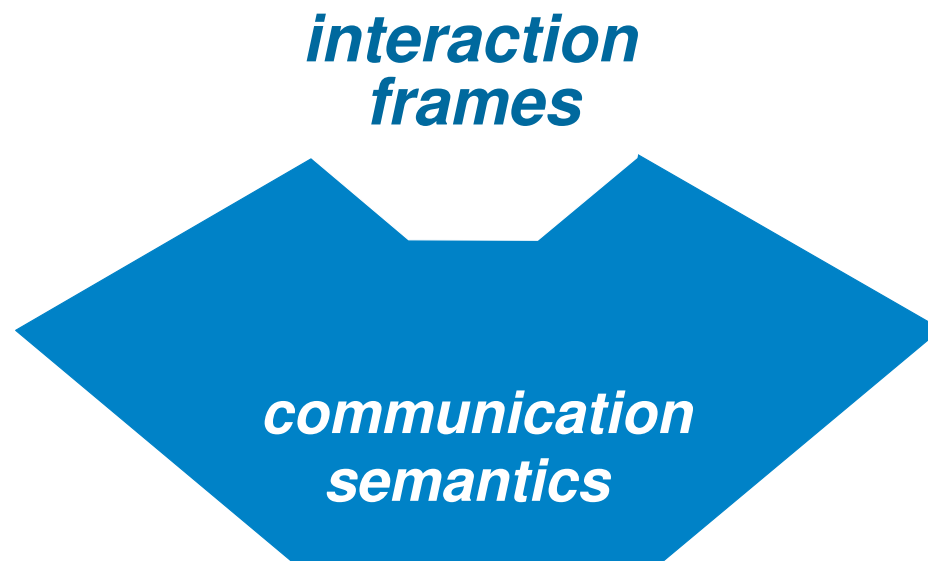
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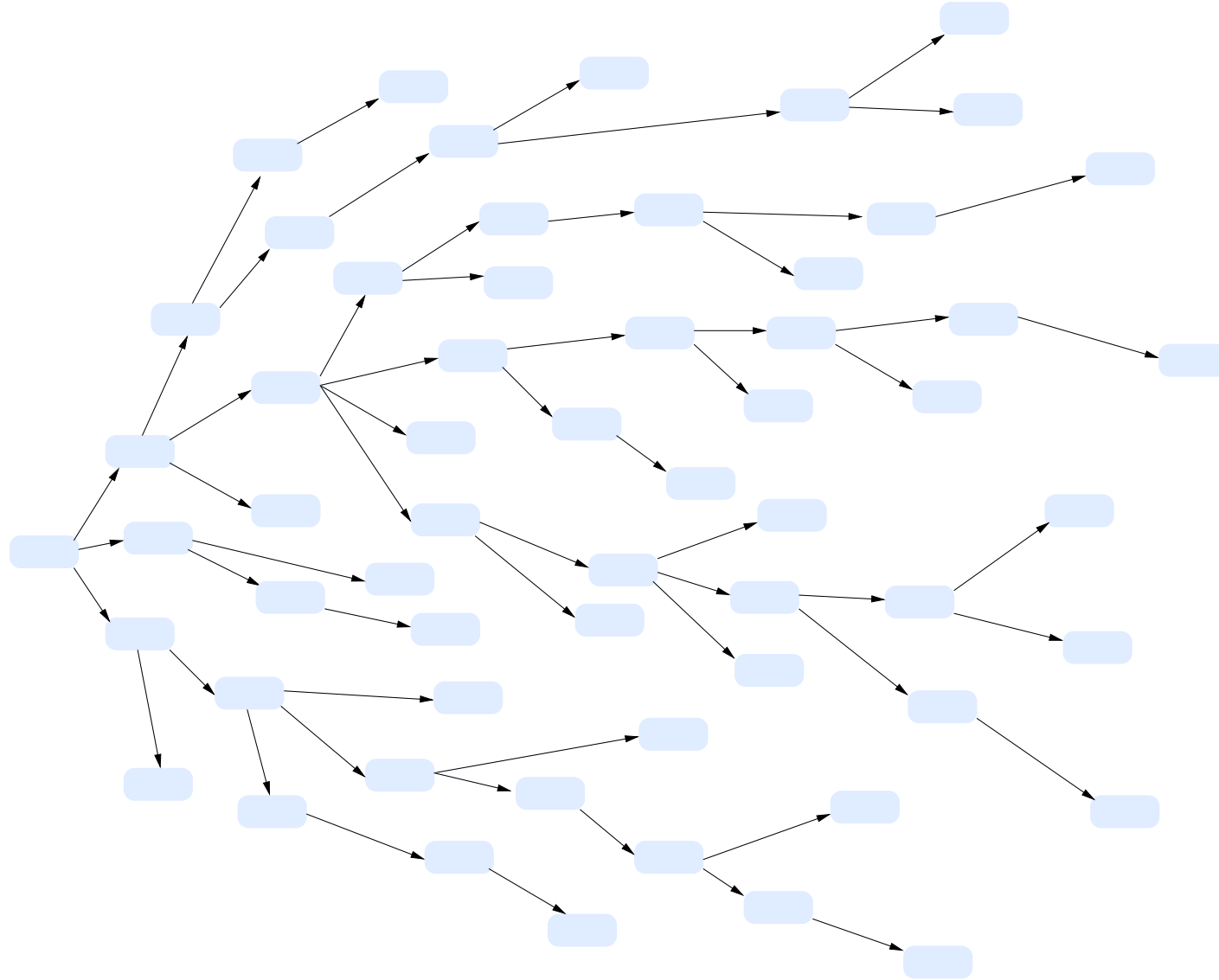


(Rovatsos et al., AAMAS'03)

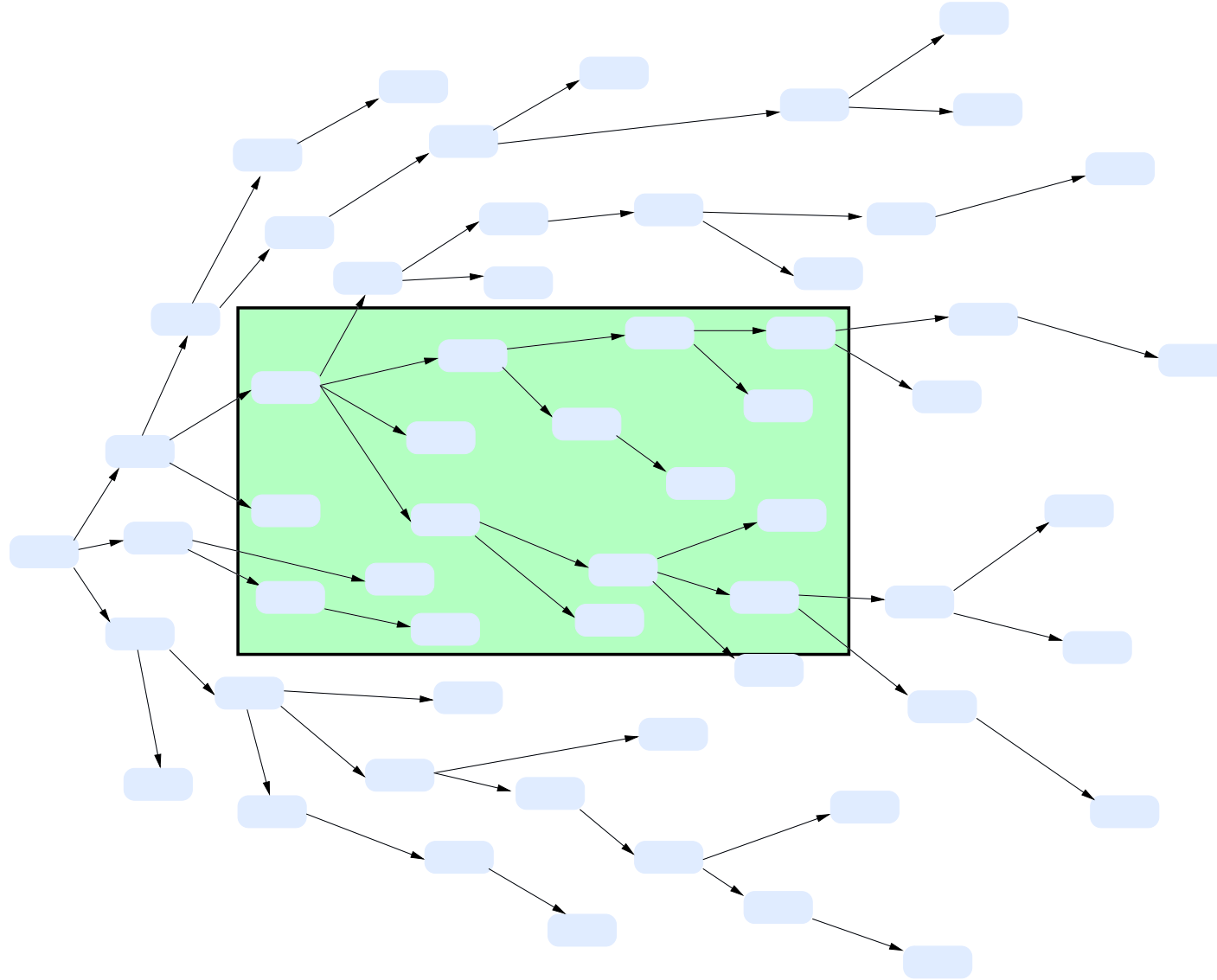
Communication Semantics

- ▶ frame repositories can be interpreted as communication system
 - ➔ agent-level modelling of meaning
- ▶ linking expectation structures to agent interests
- ▶ view essential for developing decision-making procedures
- ▶ enables entropy-based analysis methods
 - ➔ meta-heuristics for intelligent communicative behaviour

InFFrA vs. Com. Systems



InFFrA vs. Com. Systems

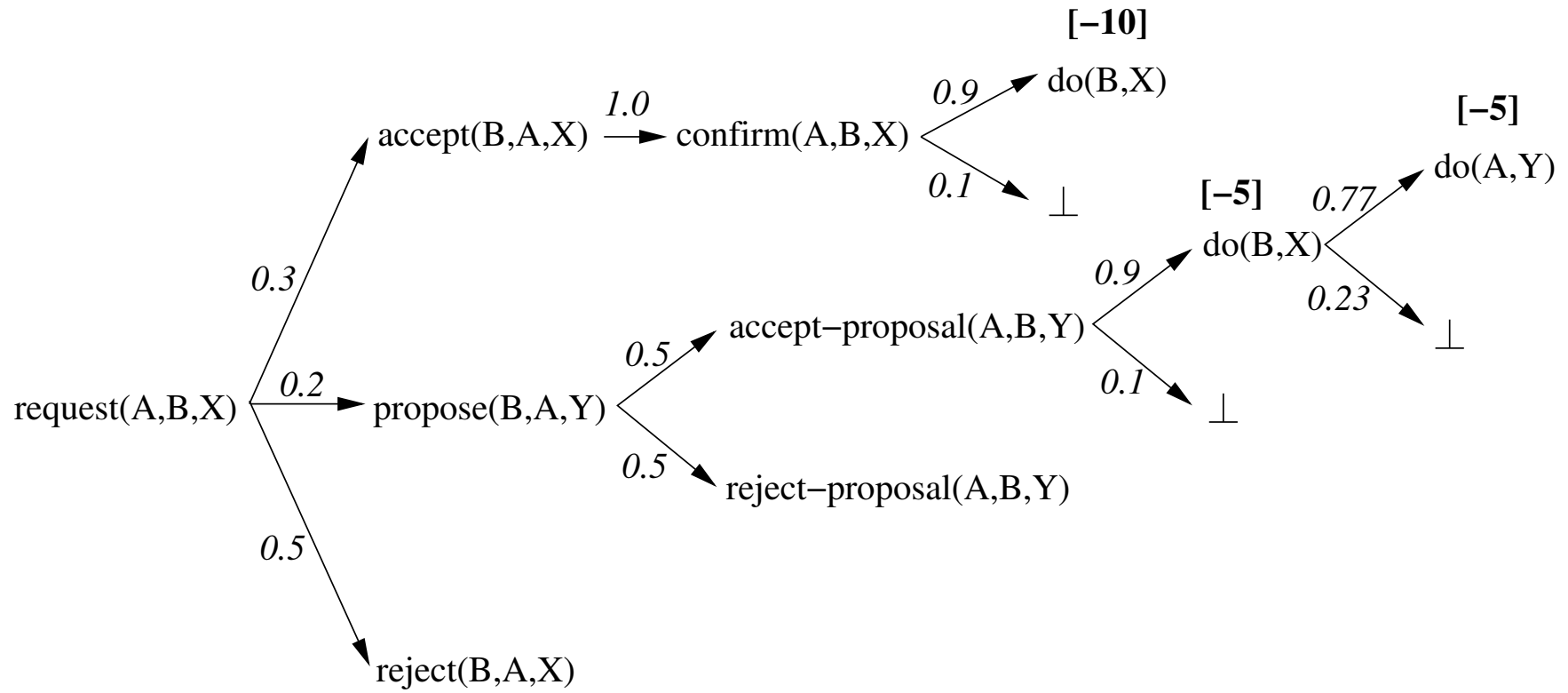


Minimal InFFrA Agents

- ▶ a simple variant of InFFrA
- ▶ agents that record (and count) two-party encounters
- ▶ frames = simple message sequences + counters + conditions
- ▶ roles/relationships, contexts and beliefs packed into conditions
- ▶ main goal: maximise expected utility
- ▶ entropy considerations useful?

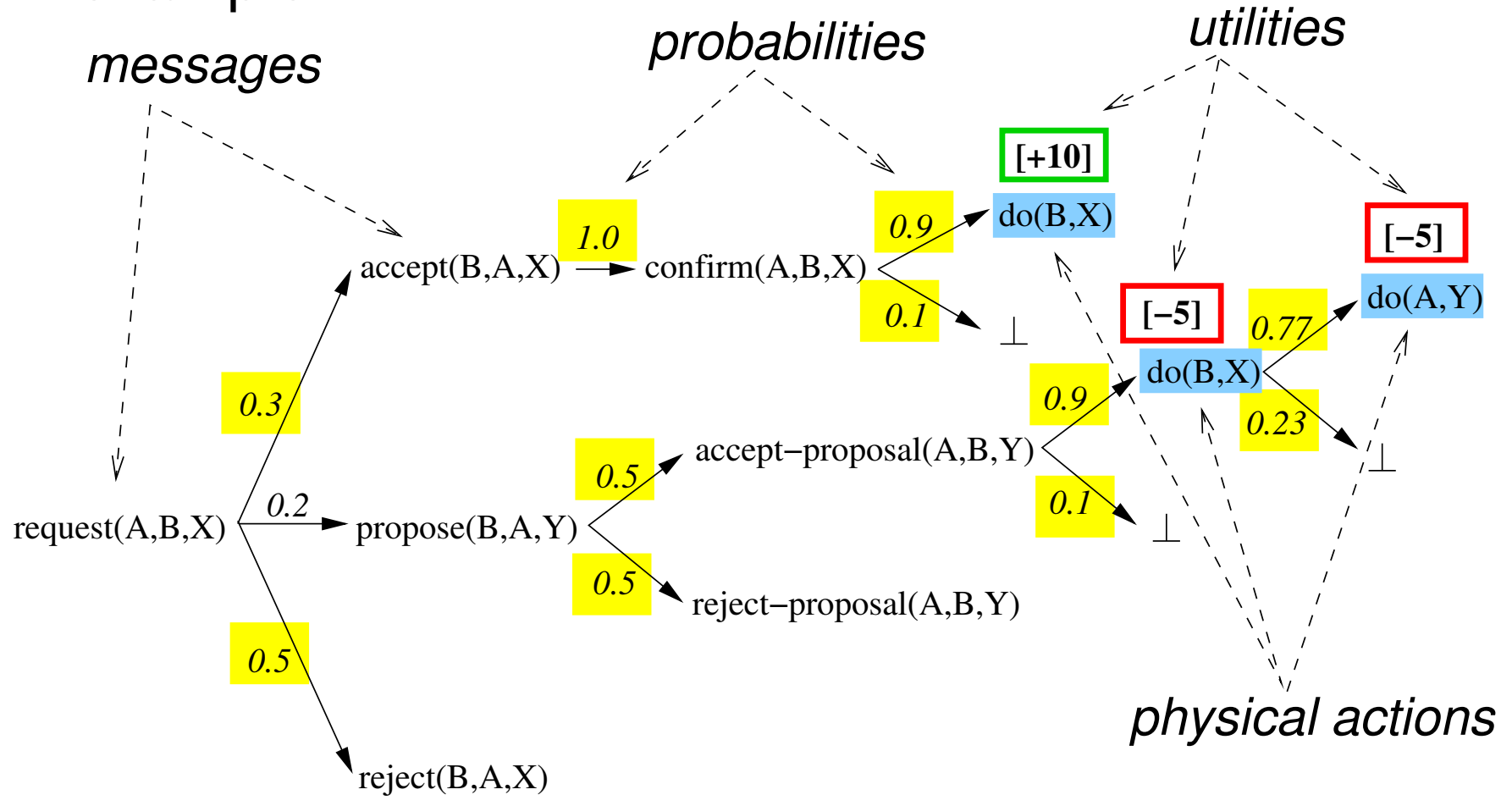
Probabilistic semantics

An example:



Probabilistic semantics

An example:



Probabilistic semantics

- ▶ assume agent maintains such a graph \mathcal{F} , and encounters (conversations) are sequences

$$w = w_1 w_2 \cdots w_n$$

- ▶ easy to compute distribution $I_{\mathcal{F}}(w)$ of “continuations” for any current prefix w :

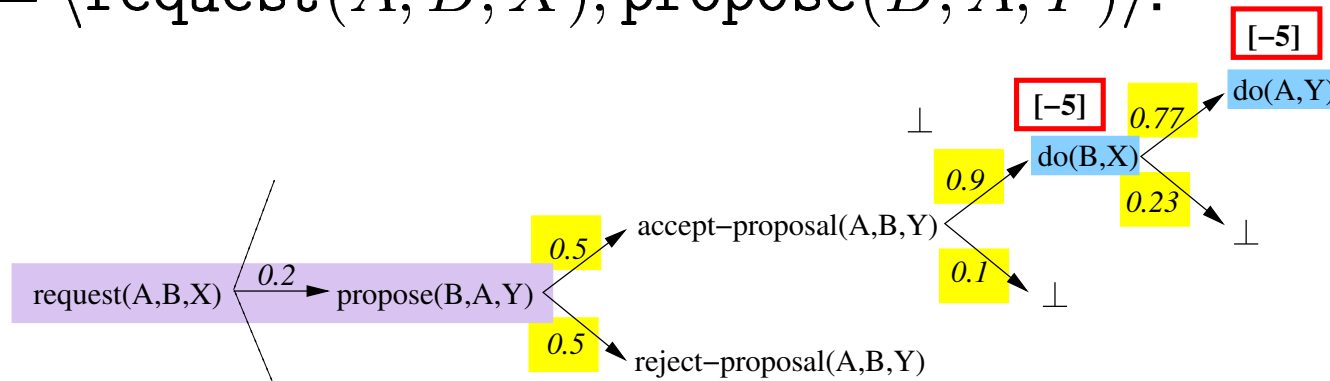
$$I_{\mathcal{F}}(w) = \lambda w'. P(w'|w)$$

- ▶ calculate expected utility after encounter prefix w :

$$\bar{u}(w) = \sum_{w'} I_{\mathcal{F}}(w)(w') \cdot u(w')$$

Example

Let $w = \langle \text{request}(A, B, X), \text{propose}(B, A, Y) \rangle$:



$$I_{\mathcal{F}}(w) = \left\{ \left(\langle \text{accept-proposal}(A, B, Y), \text{do}(B, X), \text{do}(A, Y) \rangle, 0.3456 \right), \right. \\ \left. \langle \text{accept-proposal}(A, B, Y), \text{do}(B, X) \rangle, 0.1035 \right), \\ \langle \text{accept-proposal}(A, B, Y) \rangle, 0.05 \rangle, \\ \left. \langle \text{reject-proposal}(A, B, Y) \rangle, 0.5 \rangle \right\}$$

$$\bar{u}(w) = -10 \cdot 0.3456 + (-5) \cdot 0.103 + (0 \cdot 0.05 + 0 \cdot 0.5) = -3.971$$

Entropy Heuristics

- ▶ define measures to determine degree of **uncertainty** and own **autonomy**

$$EE_{\mathcal{F}}(w) = \sum_{w'} -P(w') \log_2 P(w')$$

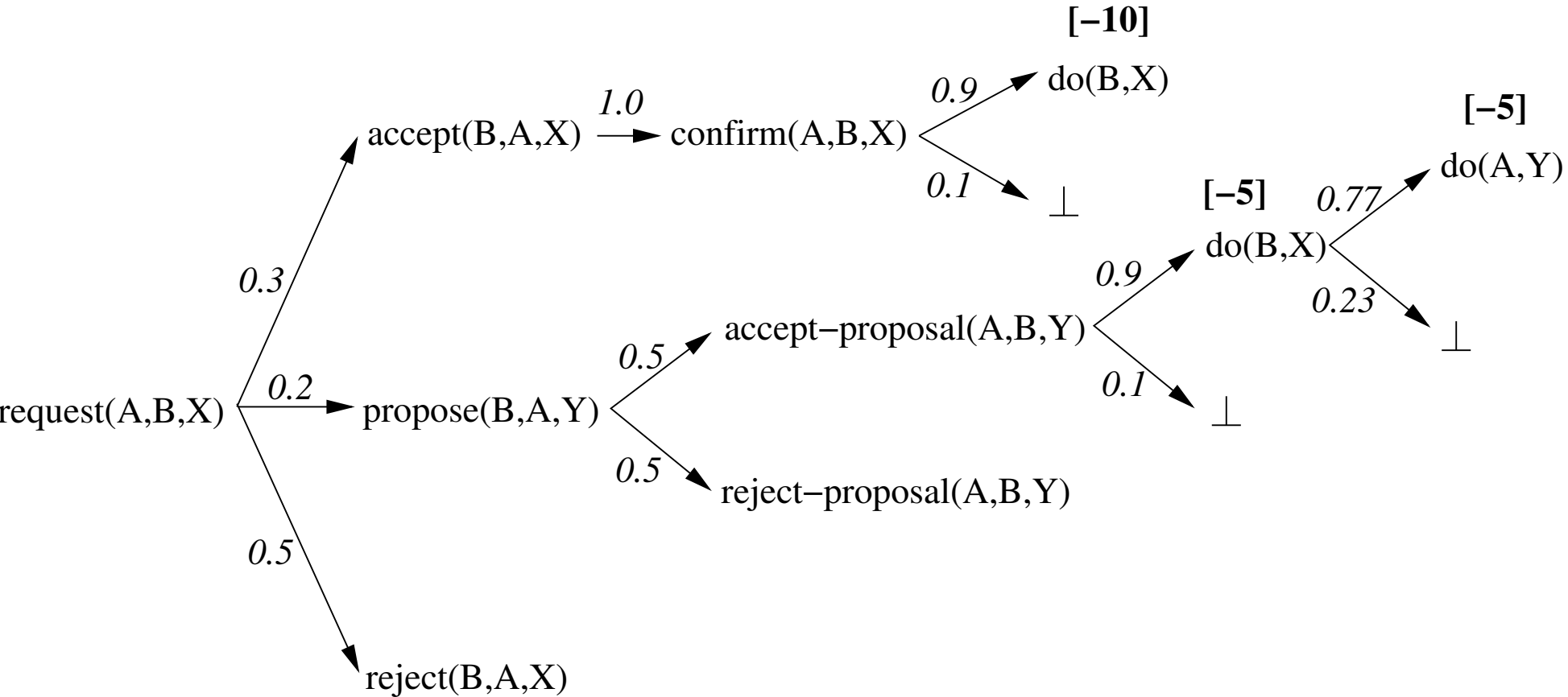
$$UD_{\mathcal{F}}(w) = \sqrt{\sum_{w'} (u(w') - \bar{u}(w'))^2}$$

- ▶ total **entropy** as combined measure:

$$\mathcal{E}_{\mathcal{F}}(w) = EE_{\mathcal{F}}(w) \cdot UD_{\mathcal{F}}(w)$$

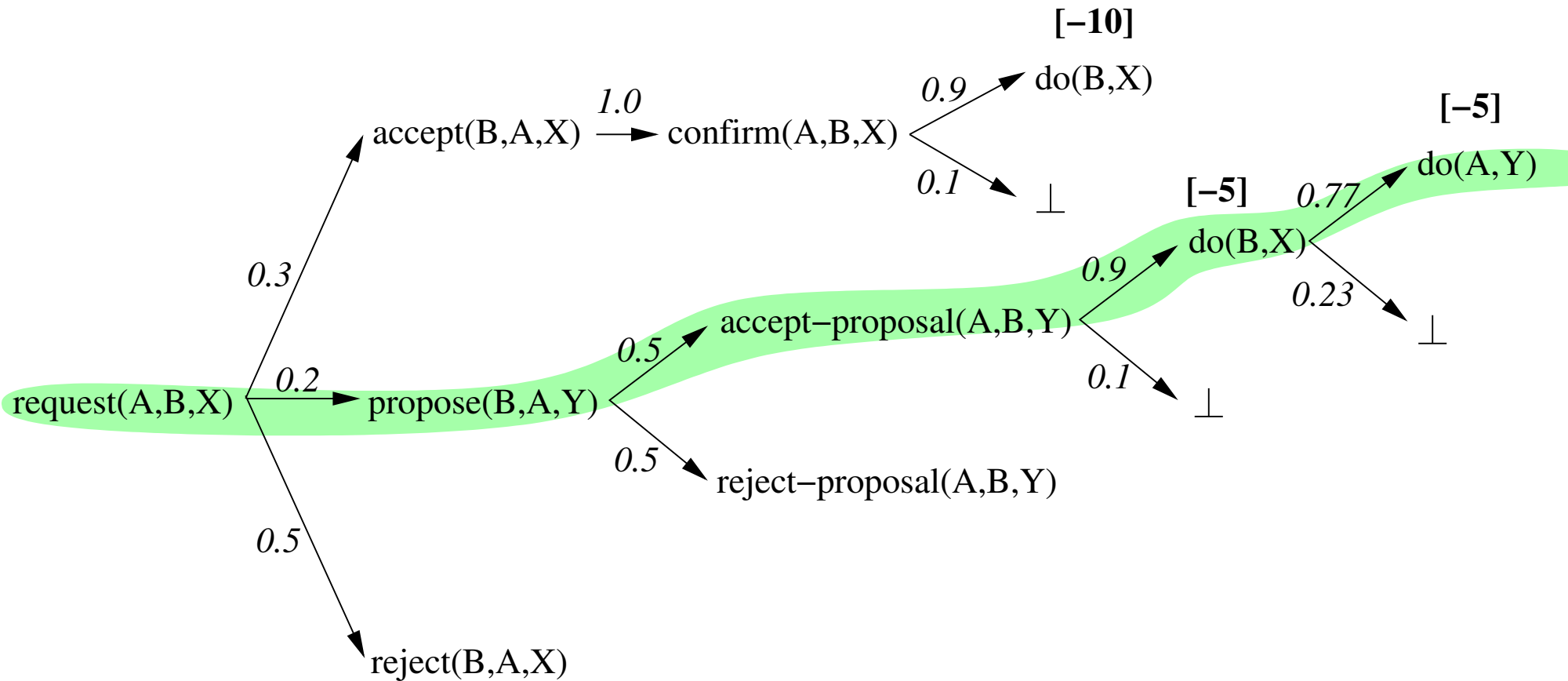
Example

Back to complex protocol:



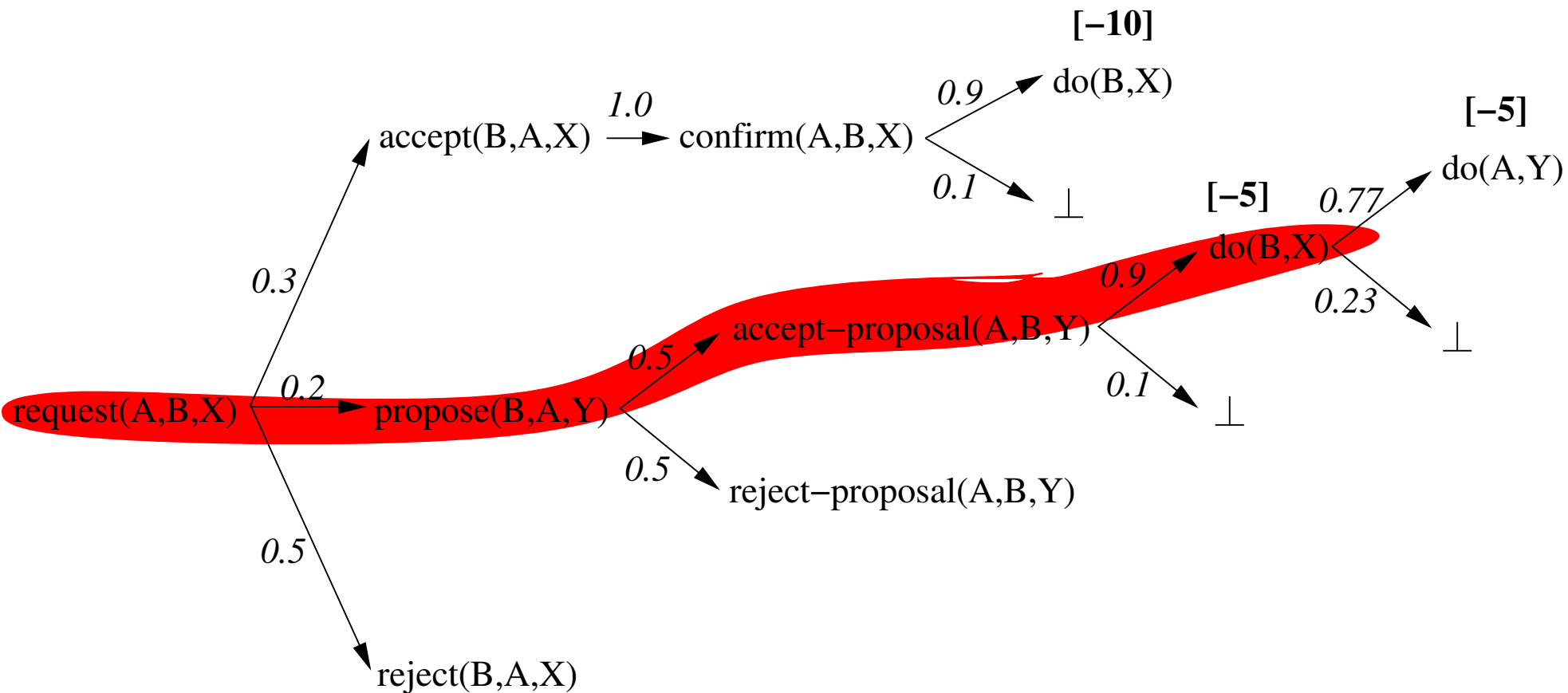
Example

Successful completion:



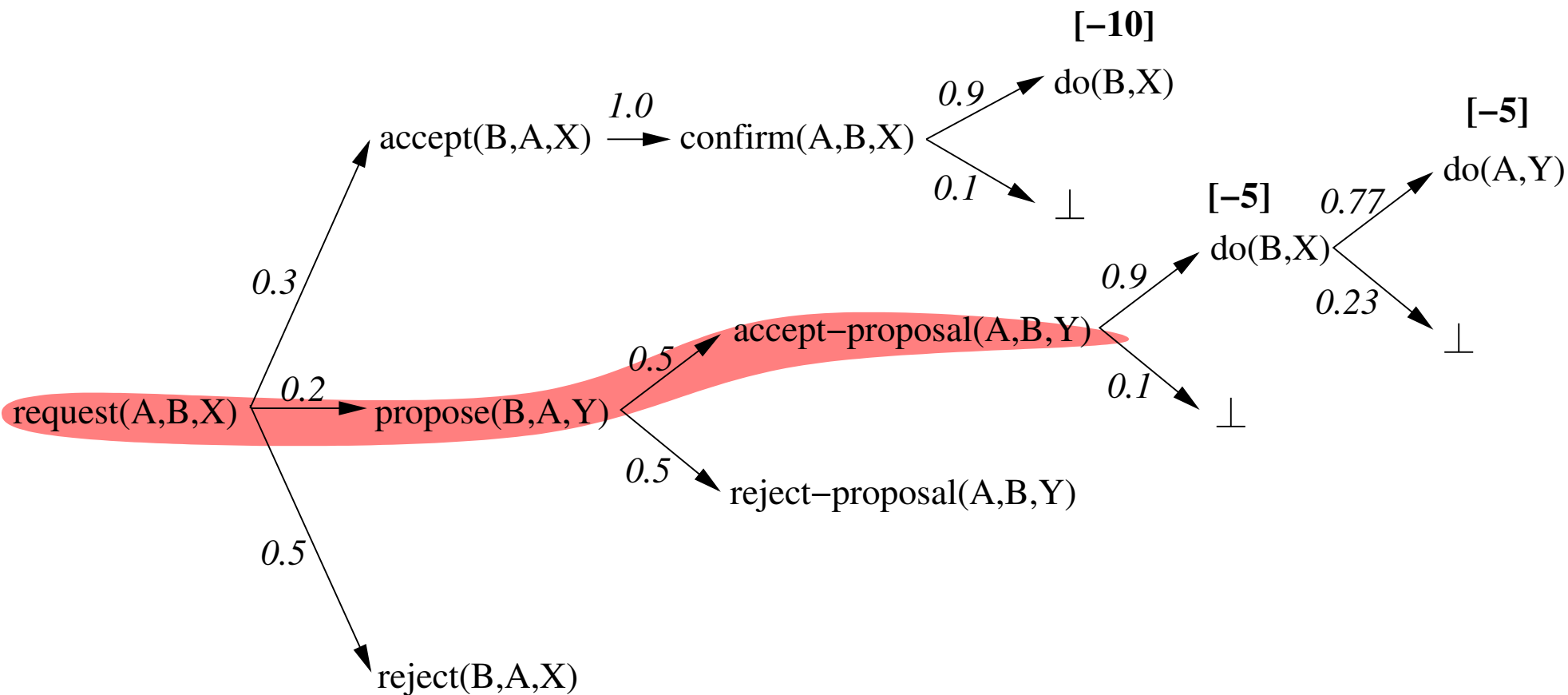
Example

A cheats:



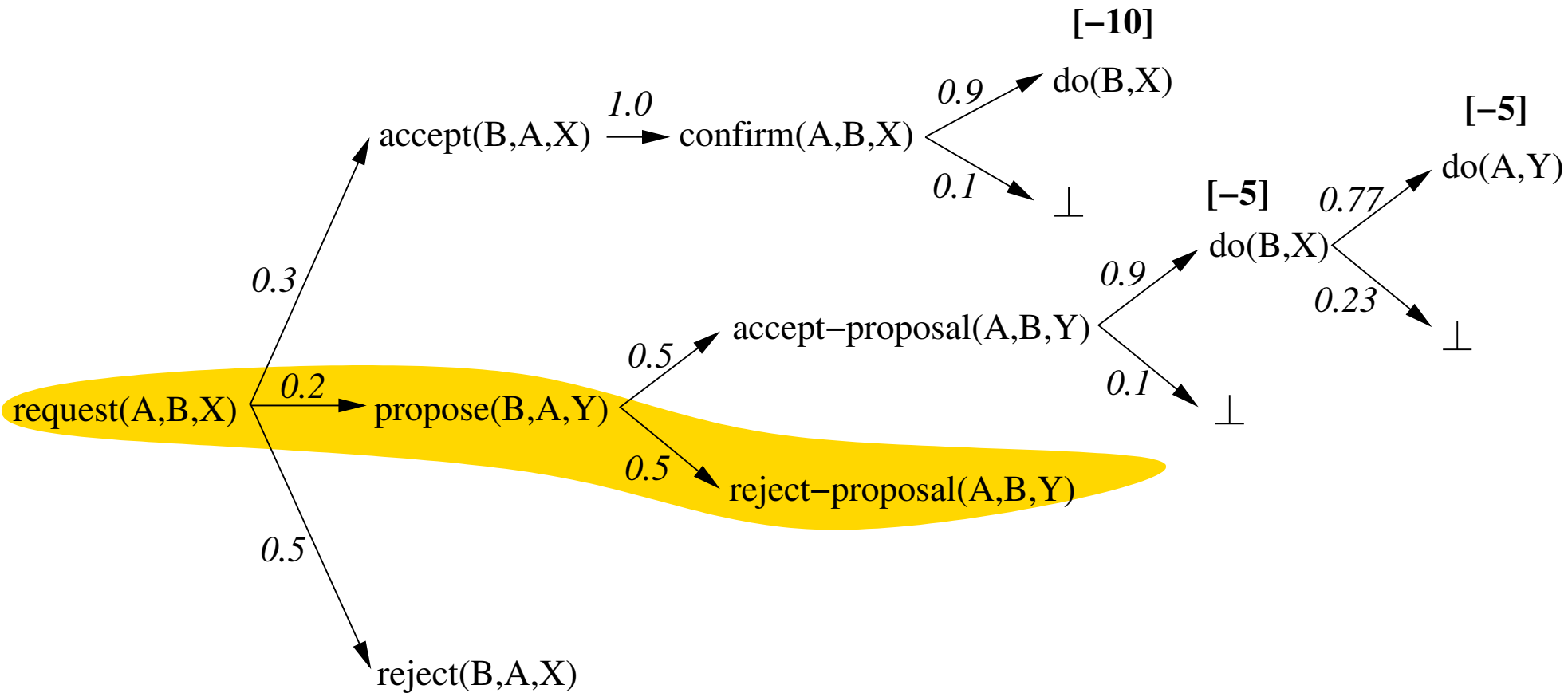
Example

B cheats:



Example

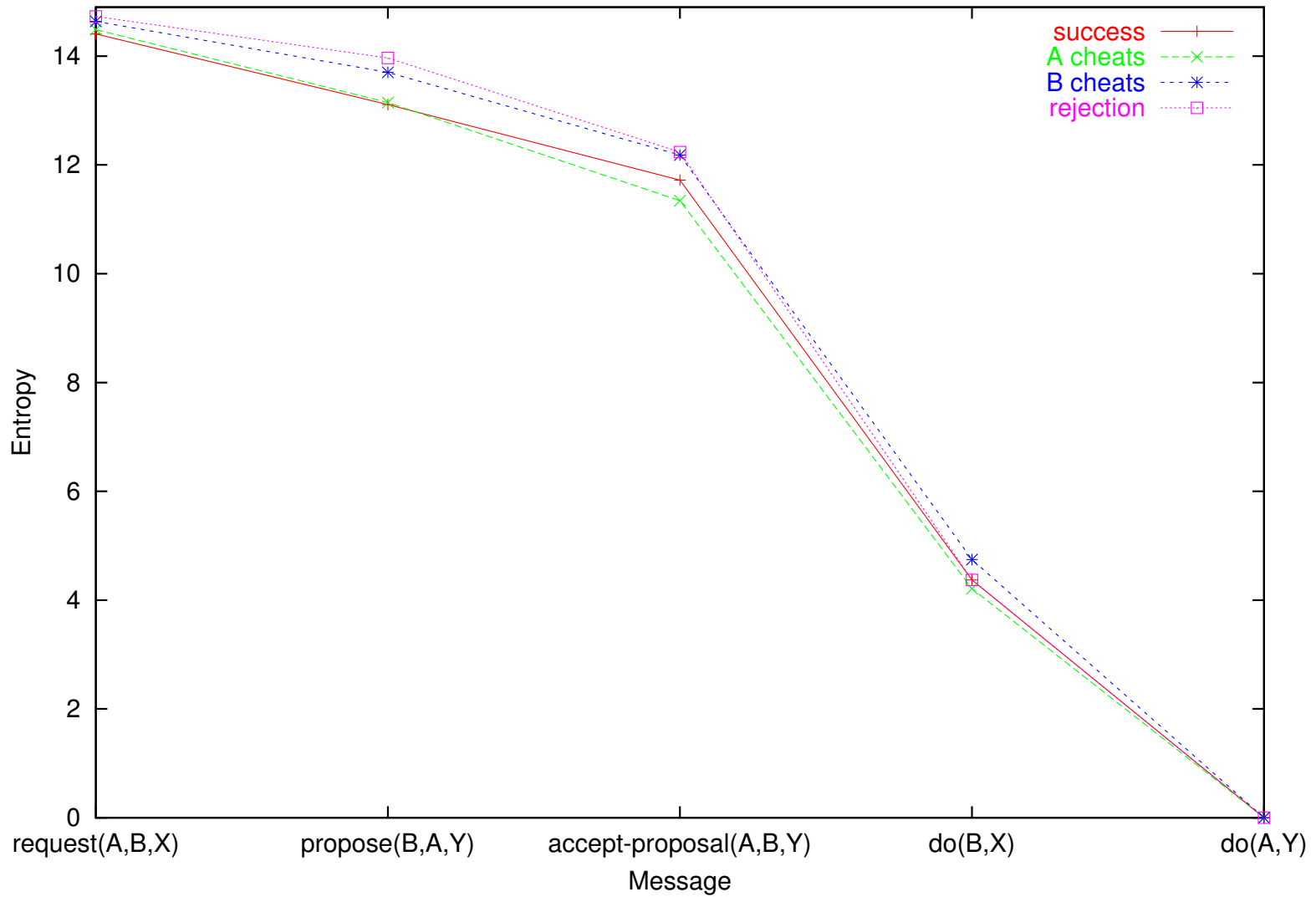
Rejection:



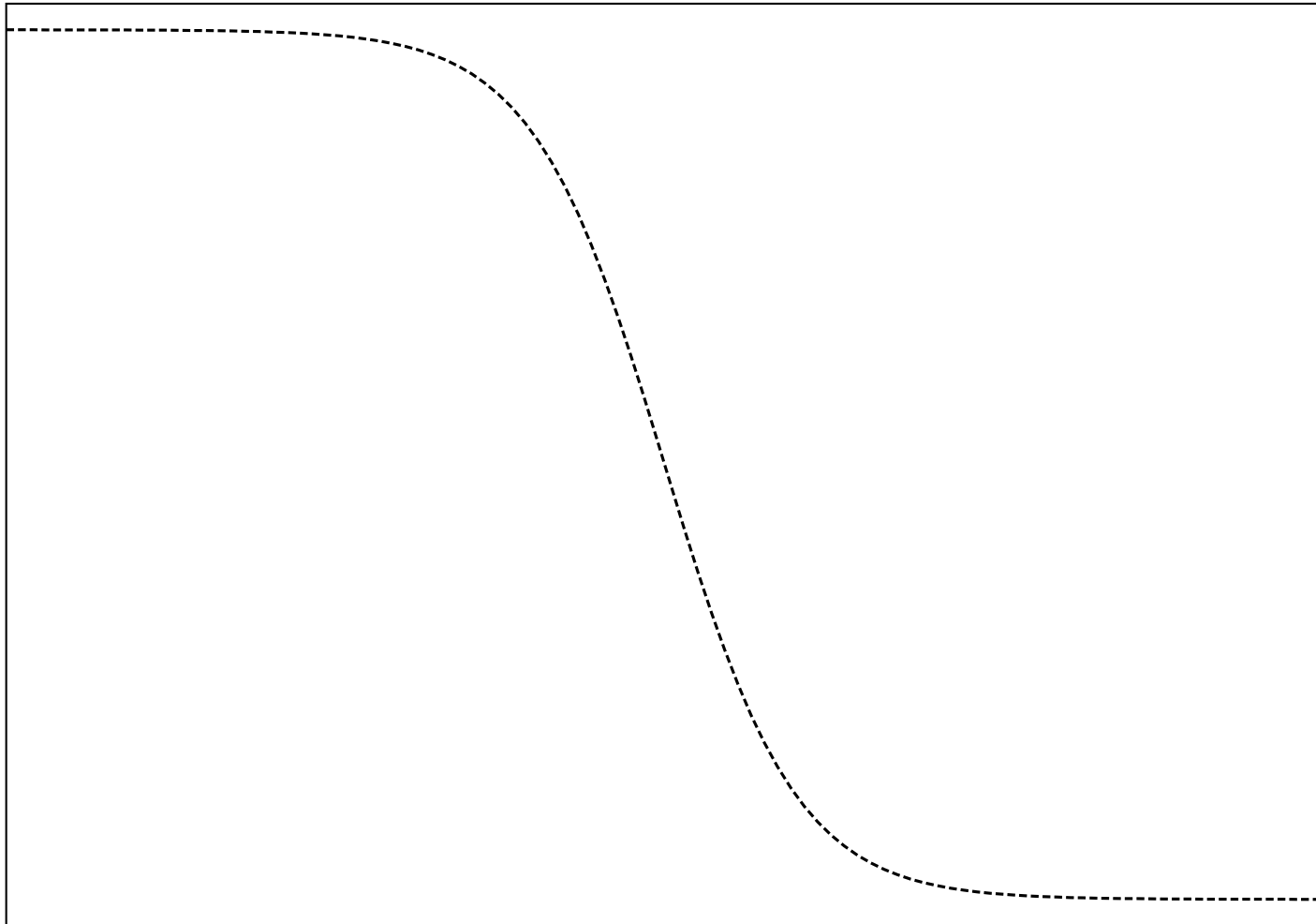
Trajectory Shapes

- ▶ analyse effects of each of the trajectories on $\text{propose}(A, B, X) \rightarrow \dots \rightarrow \text{do}(A, Y)$
- ▶ Observations:
 - “perfect” entropy curves consist of **autonomy** and **commitment** part
 - effects of “*A* cheats” much worse than “*B* cheats”

Trajectory shapes



Trajectory shapes



Conflict Potential

- ▶ If \mathcal{F}' is the product of v in \mathcal{F} , define:

$$\Delta\mathcal{E}_{\mathcal{F}}(w, v) = \mathcal{E}_{\mathcal{F}'}(w) - \mathcal{E}_{\mathcal{F}}(w)$$

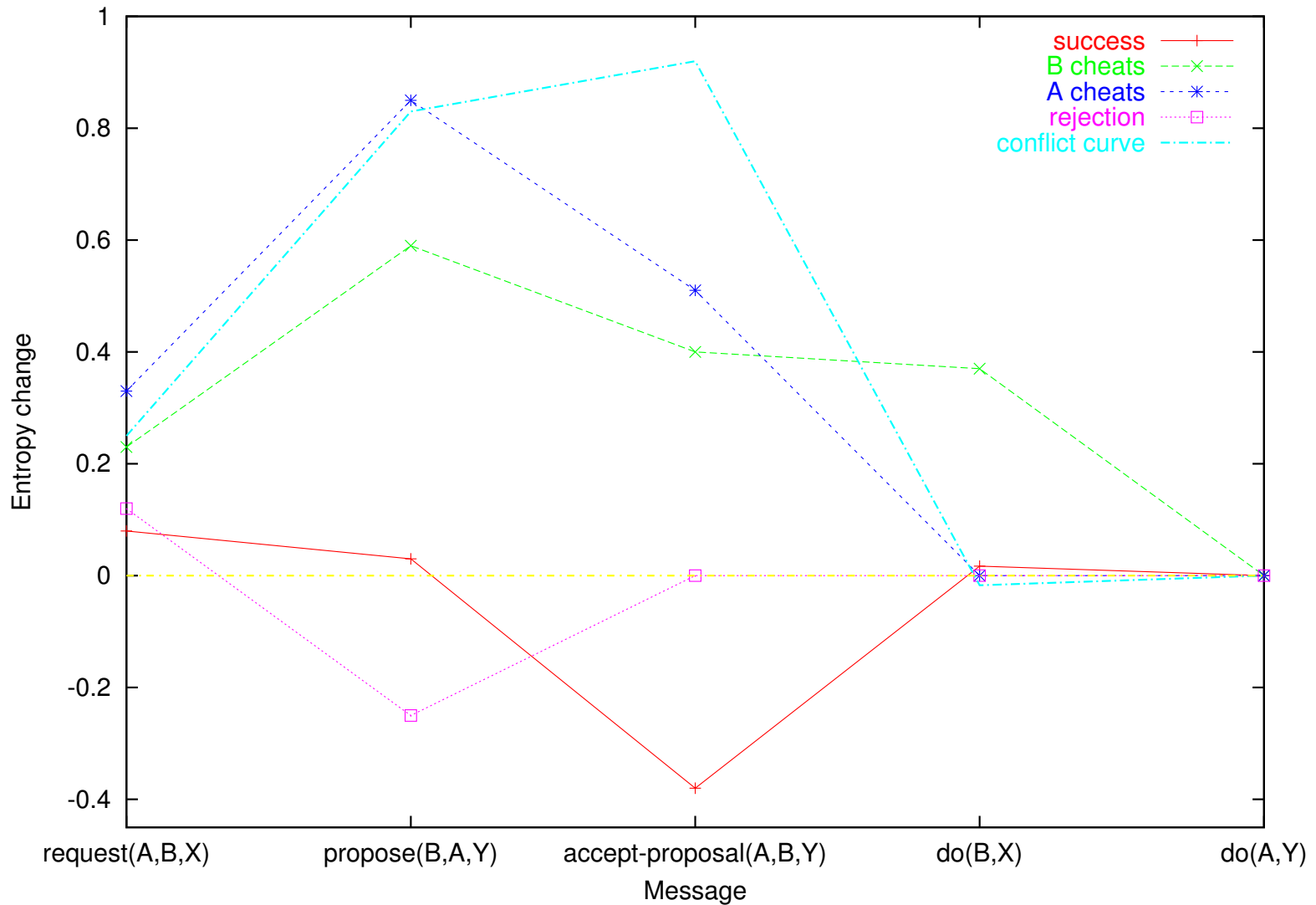
- ▶ If v was expected, and v' occurred, define:

$$\mathcal{CP}_{\mathcal{F}}(v', v, w) = \int_{w[1]}^{w[|w|]} \Delta\mathcal{E}_{\mathcal{F}}(w, v') - \Delta\mathcal{E}_{\mathcal{F}}(w, v) dw_i$$

- ▶ Example:

$$\Delta\mathcal{E}(\text{“success”, “A cheats”}) - \Delta\mathcal{E}(\text{“success”, “success”})$$

Conflict Potential



Significance?

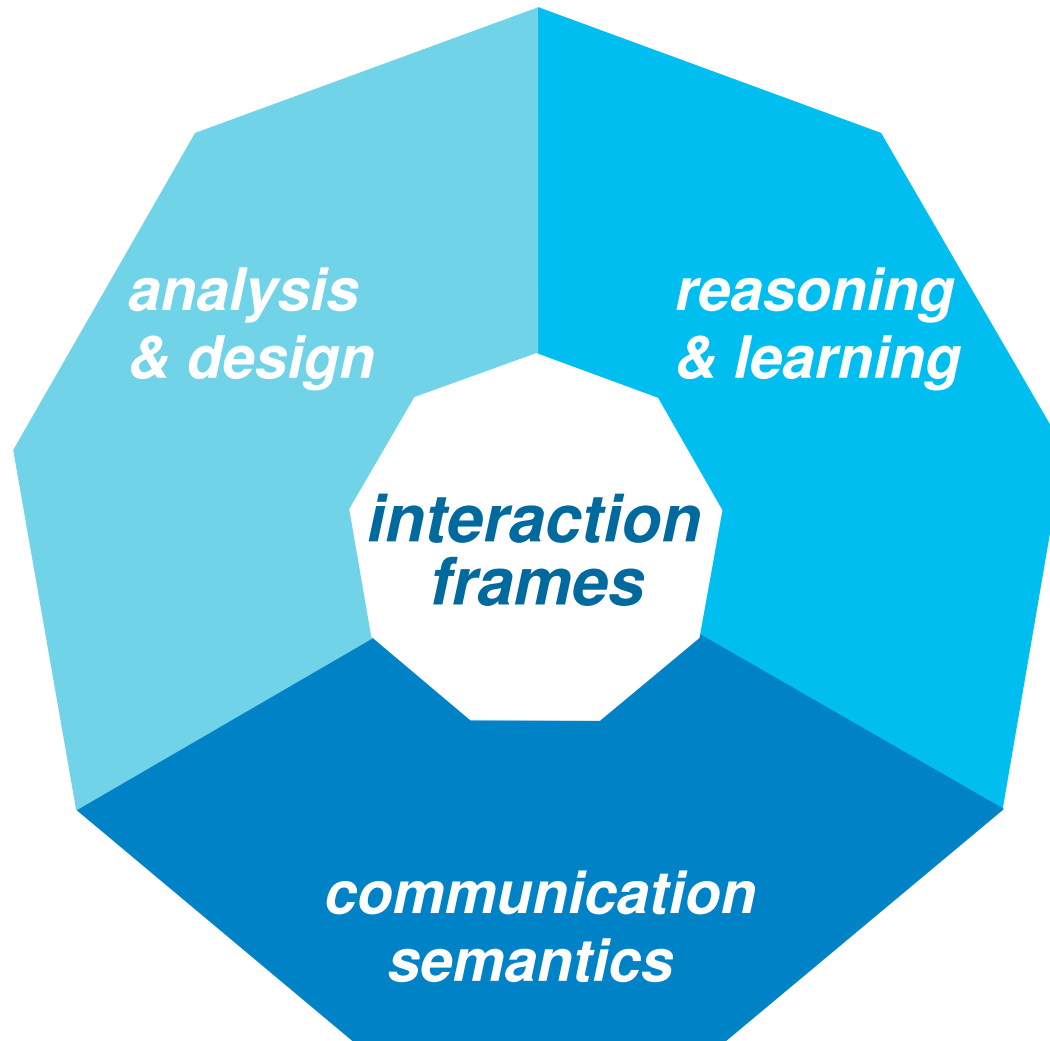
- ▶ application of communication systems approach to agent design
- ▶ “consequentialist” view enables decision-theoretic approach
- ▶ agents have to consider effects of utterances, i.e.
 - reactions of self and others to message (“first-order”)
 - impact on expectation structures (“second-order”)and reason about “utility” of semantics
- ▶ entropy measures can be useful with this respect (e.g. domain-independent notion of conflict)

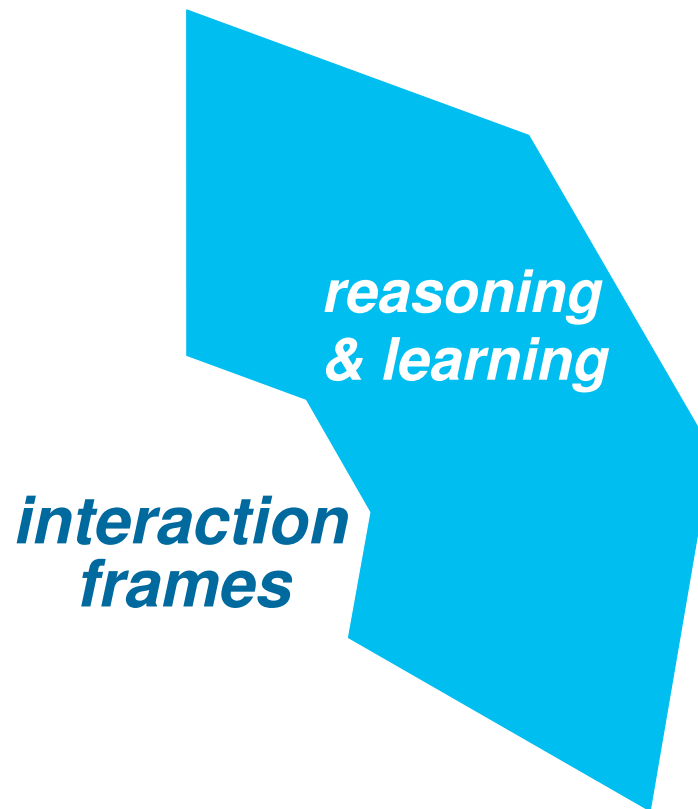
Outline

- ▶ Background
- ▶ Interaction Frames and Framing
- ▶ The InFFrA Architecture
- ▶ Frames vs. Communication Semantics
- ▶ Reasoning and Learning in InFFrA
- ▶ Applications and Future Research
- ▶ Conclusions

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(Rovatsos & Fischer, upcoming TechReport)

- ▶ concrete instance of InFFrA for “almost-minimal” agents
- ▶ two-layer model for learning and employing frames
- ▶ realises two principles:
 - **social abstraction**
 - **transient social optimality**
- ▶ use of reinforcement-learning methods

exploration + perceived payoffs = *utility estimate*

→	→	→	+1
↑		↑	-1
↑	←	←	←

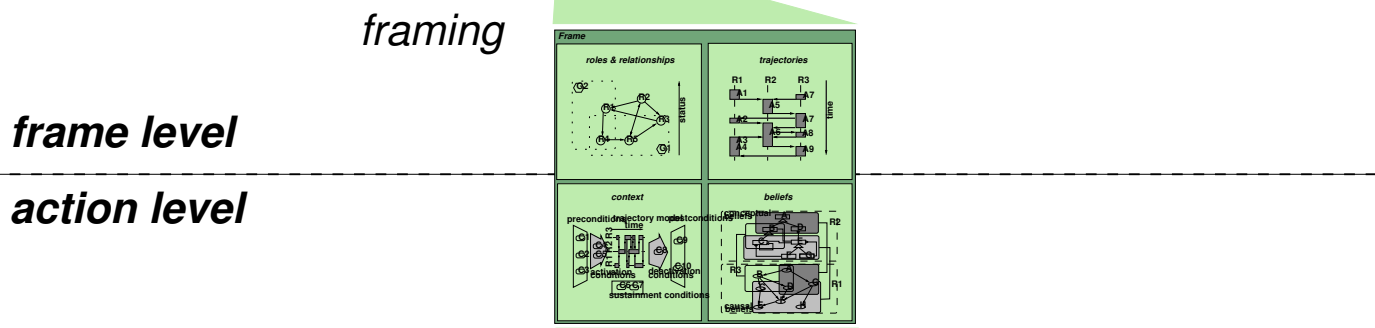
→

0.812	0.868	0.918	+1
0.762		0.611	-1
0.705	0.655	0.611	0.388

framing decisions + long-term payoffs = *framing utility*

→

0.812	0.868	0.918	
0.762		0.611	0.534
0.705	0.655	0.611	0.388



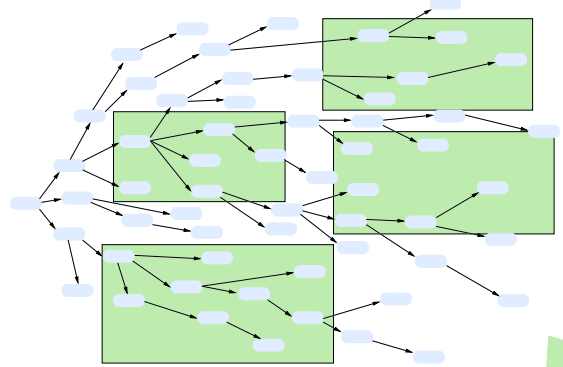
in-frame action decisions + immediate payoffs = *action utility*

→	→	→	+1
↓	↑		↑
→	-1	←	←

→

0.455	0.686	0.874	+1
0.512	0.112		0.766
0.377	-1	0.245	0.621

frame management + entropy considerations

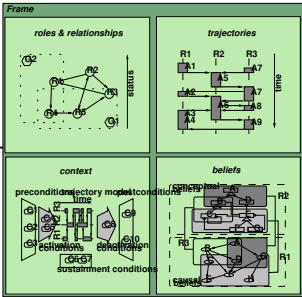


0.812	0.868	0.918	
0.762		0.611	0.534
0.705	0.655	0.611	0.388

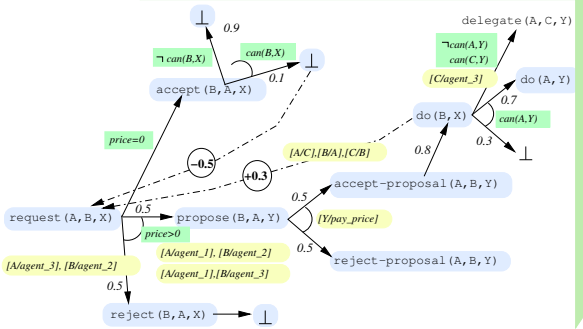
framing

frame level

action level



frame communication system



0.455	0.686	0.874	+1
0.512	0.112		0.766
0.377	-1	0.245	0.621

$$F = \left\langle \left\langle \begin{array}{l} \xrightarrow{5} \text{propose}(A_1, A_2, \text{do}(A_1, X_1)) \xrightarrow{3} \text{accept}(A_2, A_1, \text{do}(A_1, X_1)) \\ \xrightarrow{2} \text{do}(A_1, X_1) \end{array} \right\rangle, \right. \\ \left. \left\langle \{ \text{self}(A_1), \text{other}(A_2), \text{can}(A_1, \text{do}(A_1, X_1)) \}, \right. \right. \\ \left. \left. \{ \text{agent}(A_1), \text{agent}(A_2), \text{action}(X_1) \} \right\rangle, \right. \\ \left. \left\langle \xrightarrow{4} \langle [A_1/\text{agent}_1], [A_2/\text{agent}_2] \rangle, \right. \right. \\ \left. \left. \xrightarrow{1} \langle [A_1/\text{agent}_3], [A_2/\text{agent}_1], [X_1/\text{deliver_goods}] \rangle \right\rangle \right\rangle$$

- ▶ considers similarity between situations (similar to case-based reasoning)
- ▶ frame application connected to agent's knowledge base
- ▶ generalisation capabilities (frame merging)
- ▶ entropy considerations for frame repository management
- ▶ invention of new frames (underway)

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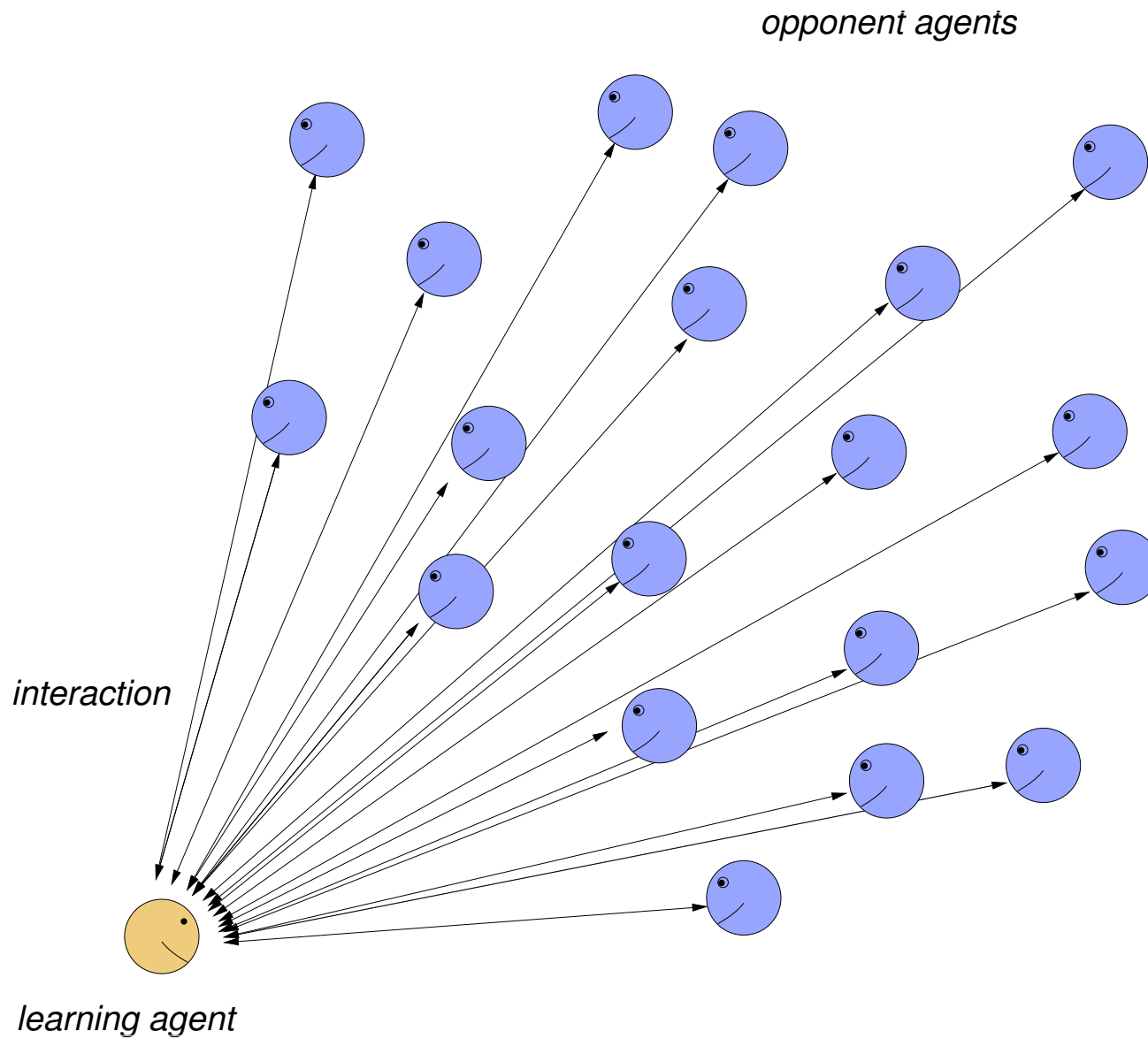
Outline

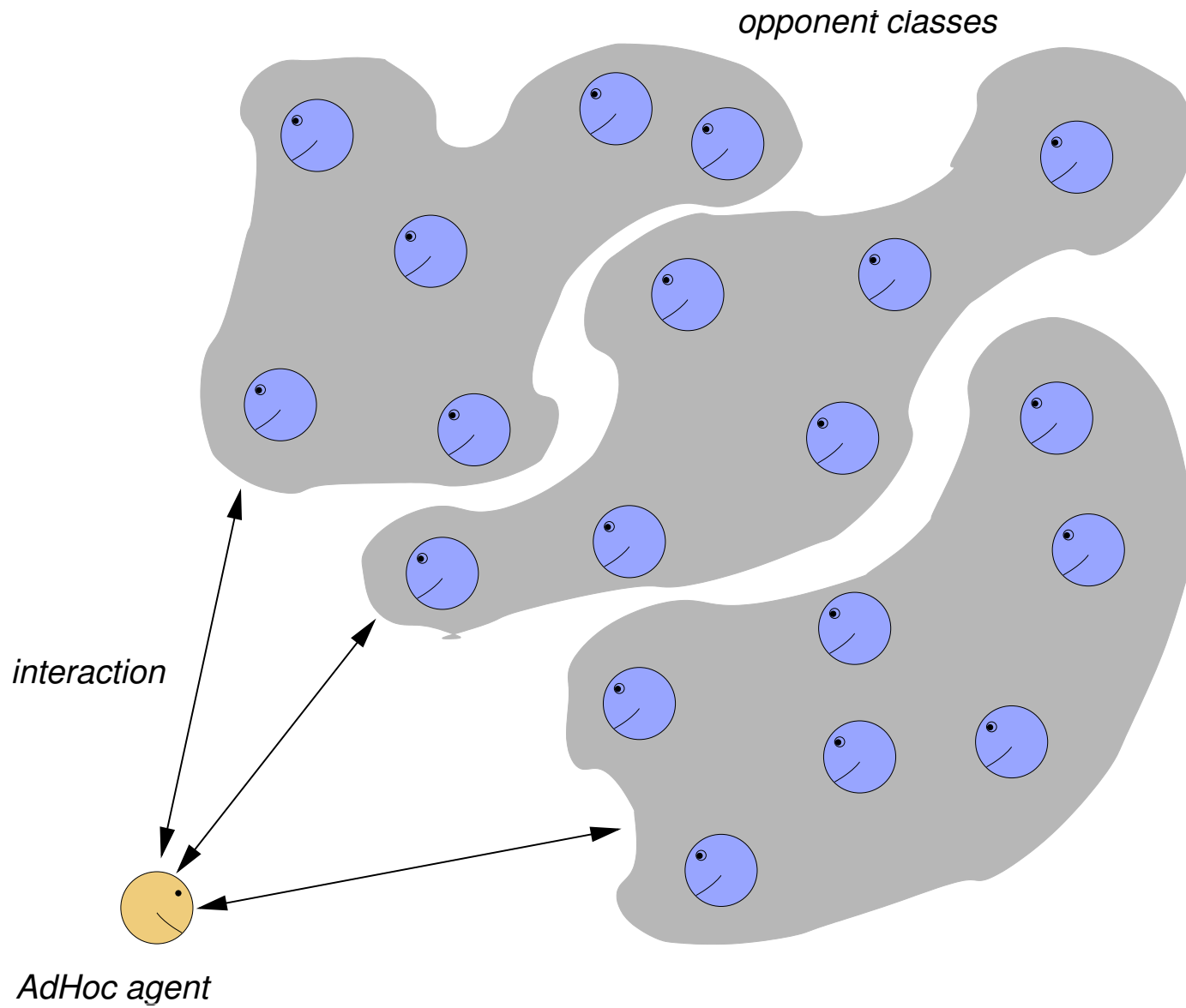
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Applications – AdHoc

- ▶ Adaptive Heuristic for Opponent Classification
- ▶ goal: complexity reduction through opponent classification
- ▶ evolves dynamically changing set of opponent models and learns optimal counter-strategies
- ▶ opponent models = deterministic finite automata (approach of Carmel & Markovitch)
- ▶ strategy optimisation uses Q-learning
- ▶ successful experiments wrt classification
- ▶ “AdHoc vs. AdHoc” problem!

Applications – AdHoc

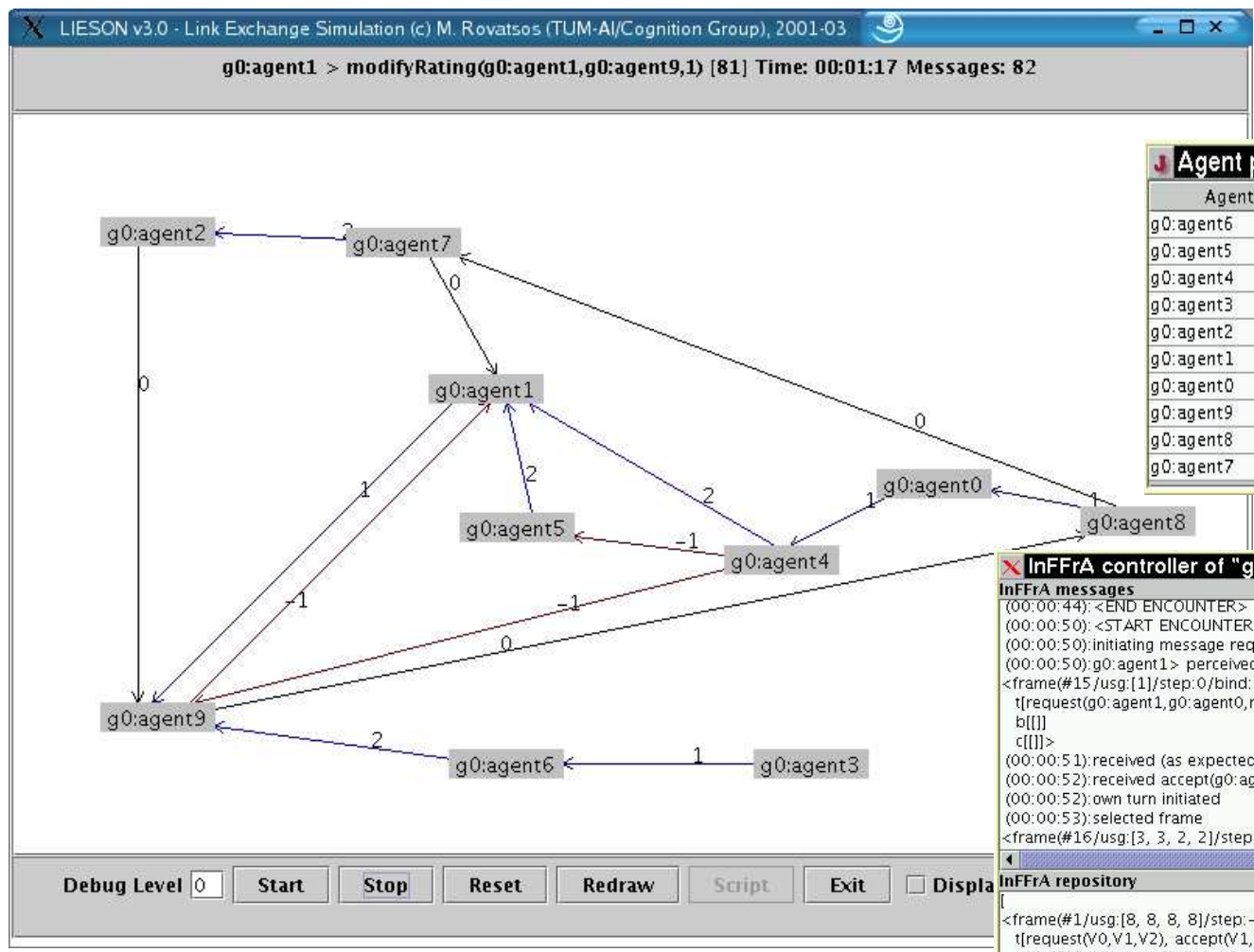




Applications – LIESON

- ▶ Link Exchange SimulatiON System
- ▶ objective: increase linkage transparency on the WWW using automated link exchange
- ▶ includes implementation of BDI-like agents with m²inffra engine
 - self-interested agents
 - maximise dissemination of own opinion
 - (highly) boundedly rational
- ▶ todo: agents that intelligently negotiate over linkage
- ▶ todo: study of macro-level effects

Applications – LIESON



Agent	Popularity	Simple Popularity
g0:agent6	0.6111	0.2777
g0:agent5	0.1	0.1
g0:agent4	0.5908	0.1777
g0:agent3	0.5407	0.2444
g0:agent2	0.3116	0.1222
g0:agent1	0.1	0.1
g0:agent0	0.5987	0.2333
g0:agent9	0.5765	0.3555
g0:agent8	0.5101	0.1777
g0:agent7	0.6024	0.2888

```

InFFrA controller of "g0:agent1"
InFFrA messages
(00:00:44): <END ENCOUNTER>
(00:00:50): <START ENCOUNTER>
(00:00:50): initiating message request(g0:agent1,g0:agent0,modifyRating(g0:agent0,g0:agent1,0))
(00:00:50): g0:agent1 > perceived frame updated to
<frame(#15/usg:[1]/step:0/bind:0)
t[request(g0:agent1,g0:agent0,modifyRating(g0:agent0,g0:agent1,0))
b[[]]
c[[]]>
(00:00:51): received (as expected) accept(g0:agent0,g0:agent1,modifyRating(g0:agent0,g0:agent1,0))
(00:00:52): received accept(g0:agent0,g0:agent1,modifyRating(g0:agent0,g0:agent1,0))
(00:00:52): own turn initiated
(00:00:53): selected frame
<frame(#16/usg:[3, 3, 2, 2]/step:1/bind:0)
InFFrA repository
[
<frame(#1/usg:[8, 8, 8, 8]/step:-1/bind:0)
t[request(V0,V1,V2), accept(V1,V0,V2), confirm(V0,V1,V2), do(V1,V2)]
b[[], [[V0, g0:agent1], [V1, g0:agent0], [V2, addLink(g0:agent0,g0:agent1,-2)]]], [[V0, g0:agent1], [V1, g0:age
c[[]], [other(V0)@3, number(-2)@3, other(V1)@3, can(V1,addLink(V1,V0,-2))@3, existsLink(V1,V0,-2)@4], [oth
<frame(#29/usg:[2]/step:-1/bind:0)
t[request(g0:agent0,g0:agent1,addLink(g0:agent1,g0:agent0,0))]
b[[]]
c[[]]>
<frame(#41/usg:[1]/step:-1/bind:0)
t[request(g0:agent0,g0:agent1,addLink(g0:agent1,g0:agent0,-2))]
b[[]]
c[[]]>
    
```



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Outlook

- ▶ global impact of local expectation structures
- ▶ emergence of globally valid frames?
- ▶ conflict resolution (reification of expectation structures and negotiation)
- ▶ decision-theoretic framework for second-order utility of semantics
- ▶ “related topics”
 - frames vs. ontologies
 - interaction frame calculi
 - organisational interaction frames
 - empirical approach “on top of” other semantics

Thank you for your attention!