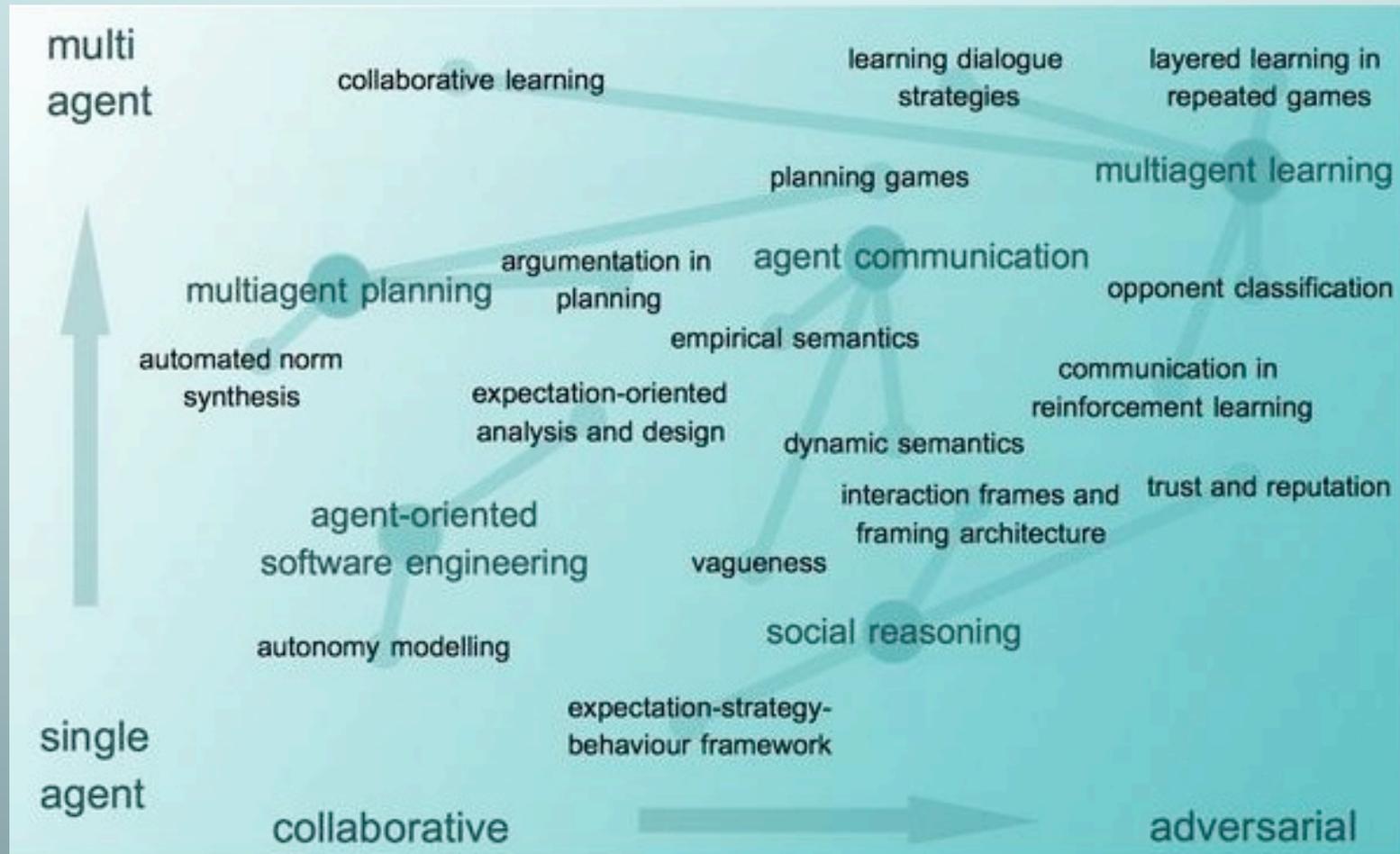


Strategic Knowledge-Based Technologies for the Web

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Background



Visit www.cisa.inf.ed.ac.uk/agents for details

Background

- What is special about agents? **Interaction** in a common environment
- To make agents intelligent and autonomous, we need to automate such interaction
- Interested in **knowledge-based reasoning about interaction**
- Reasoning about **interaction** is by definition practical reasoning
- **Vision:** given a specification of the interaction problem, automatically synthesise behaviour

Background

- We are interested in **building systems**, not only specifying them formally
- We want to tell them **what** to achieve, not **how**, abstraction desirable
- This suggests using **knowledge representation** techniques
- **Planning** is the interface between KR methods and practical reasoning
- But multiagent planning underdeveloped, no simple common framework

The “Strategic” Web

- Many interactions on the Web are **strategic**, i.e. involve potentially divergent views and objectives of users
- Currently, very little support for this on the Web (with exception of some eCommerce applications)
- Applications rely on hardcoded policies, large-scale data mining, or manual user intervention
- Vision: represent knowledge about **interests** of users to be able to **reason** about them
- *Warning: Same dangers as Semantic Web (standards, burden of annotation, scalability etc)*

Examples

BUYER-SELLER

B: I would like an art history book.

S: Good art history books range from \$35-\$55.

B: I would like something cheaper.

S: There's "Art for Kids" at \$15.

B: I want a book for adults.

S: There's "Art History for Dummies" at \$25.

B: Great, I'll take that.

(execution follows, including payment, delivery, etc)

PEER-TO-PEER

P: I'd like to stream a music concert in high quality tomorrow night.

Q: Who will be performing?

P: It's a "best-of" transmission from a festival.

Q: I don't like watching concerts unless I know what bands are playing.

P: Could I still borrow your bandwidth?

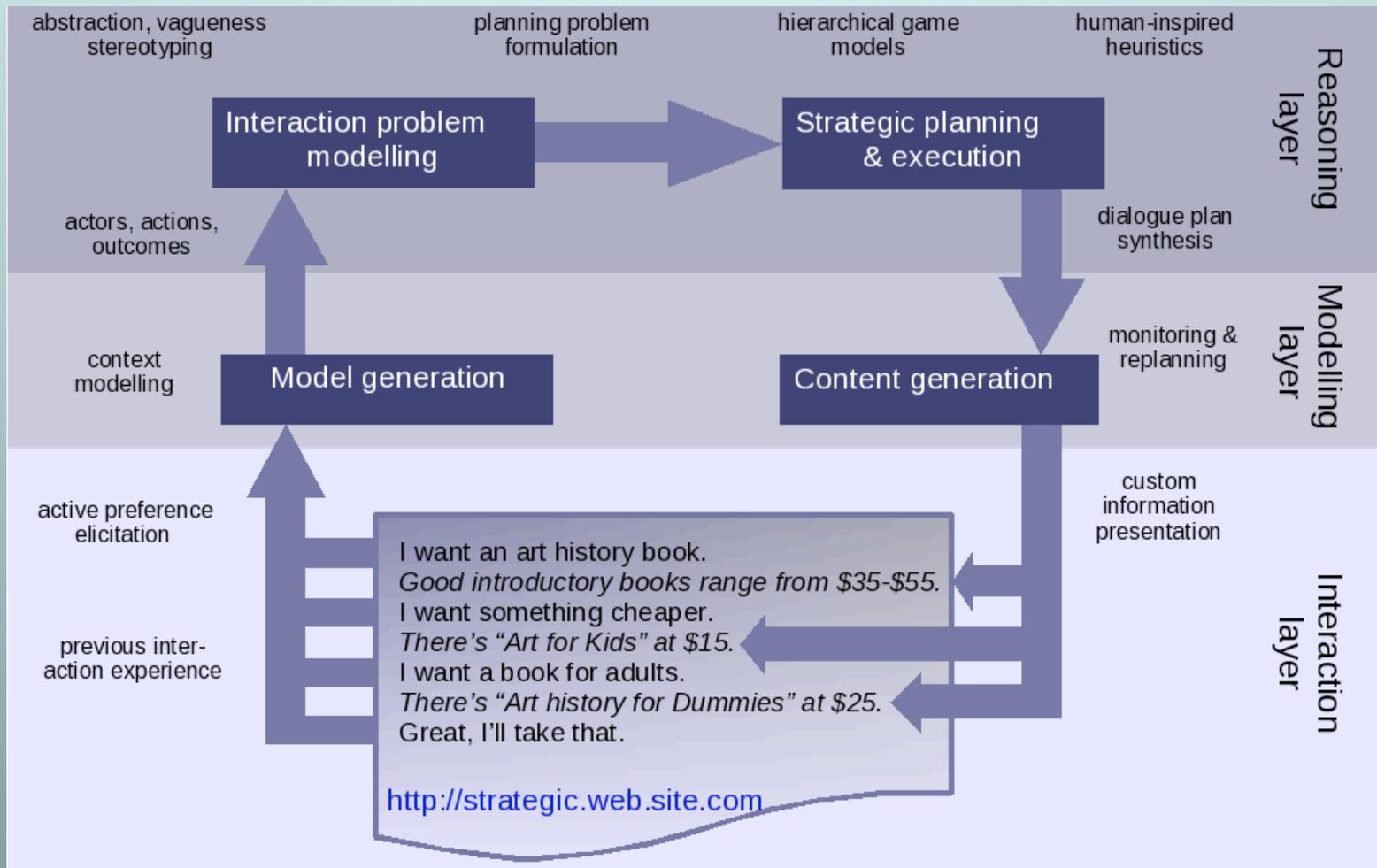
Q: OK, if you grant me prioritised access to yours for seven days after that.

(execution follows, including settings to preference in P2P system, actual streaming actions, etc)

The dialogue metaphor

- Examples deliberately looked like conversations, a simple, intuitive way of thinking about Strategic Web
- **Dialogue planning metaphor** covers synthesis, negotiation, and execution aspect
 - If communication actions are interpreted in a planning-based way, we should be able to plan them just like physical actions
 - But hard to decide about communication strategy before having synthesised collaborative plans
 - Actions planned for deception detection ahead of execution may affect suggested deals

The technology



Challenges

- **Languages for describing strategic interaction situations on the Web**
- **Tractable (approximate?) inference and plan synthesis algorithms**
- **Preference elicitation and content presentation techniques**
- **Human-centric & interdisciplinary approach required**

Game theory? Yes, *but...*

- Game-theoretic methods very popular currently and address the problem of reasoning about interaction
- Information in real-world domains available in **relational** terms (e.g. on the Web), not enumerated state actions as assumed in game theory
- **Non-incremental**: unable to express how a game changes when we incrementally change background knowledge
- Knowledge-based methods might be useful in lifting overly restrictive assumptions (full rationality, perfect knowledge, etc)
- Intuition: many large-scale games might be actually “easier” than we think (*this is speculative*)

Previous work

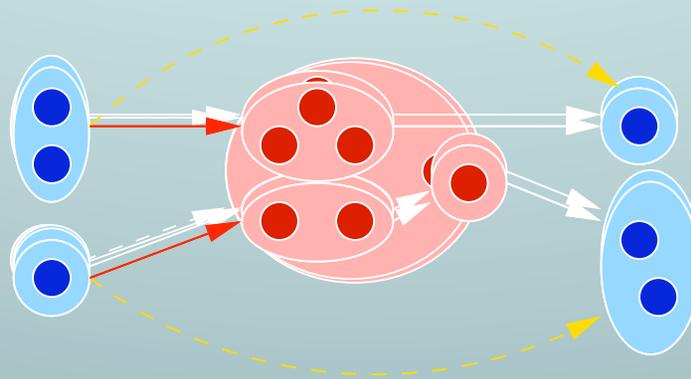
- Two examples of our current work on knowledge-based reasoning about interaction:
 - **Automated norm synthesis**
 - **Argumentation-based conflict resolution**
- Address general multiagent systems problems :
 - Setting up social laws to avoid undesirable states
 - Exchanging information to align divergent views
- From a general computer science point of view:
 - Designer-level specification of system constraints
 - Integration of distributed sources of data

Automated norm synthesis in a planning environment

- **Norms** ensure global **conflict states** are never entered by prohibiting actions in certain states
- At the same time agents' private goals should remain achievable
- Automated synthesis of such norms is NP-hard in enumerated state systems
- Existing methods don't exploit abstractions of propositional/first-order domain theories
- Our method: find “detours” around conflict states by local search in generalised state spaces

Automated norm synthesis

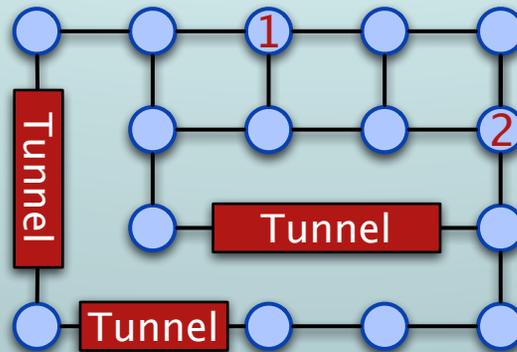
Iterated process of forward-backward search around conflict state specification:



- Not better than full state-space search in the worst case but often get lucky
- With simple additional pruning techniques search can often be cut down drastically
- Currently working on synthesising sanctions

Example

- Tunnel world example:



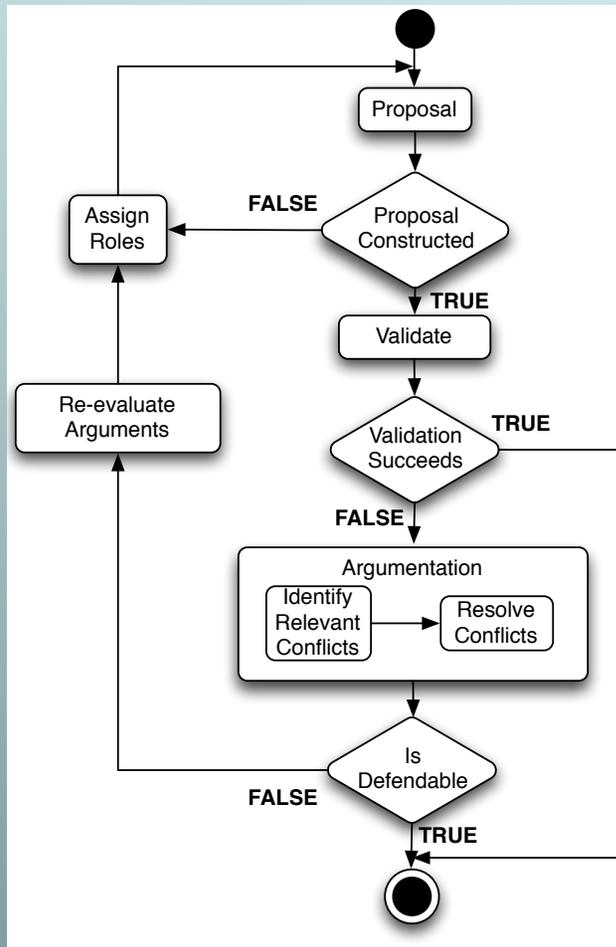
- Agents entering tunnels have to leave them out the opposite end immediately (on entering tunnel, future crash not avoidable)
- Our algorithm solves this by computing a general norm

$(\{at_1(N), at_2(N'), tunnel(T), conn(N,T), conn(T,N')\},$
 $move_1(N,T))$

Argumentation-based conflict resolution in planning

- **Argumentation** is a method for determining the status of propositions in the presence of conflicting information
- Different acceptability-based semantics and protocols that implement these
- Rarely used for reasoning about action, our intuition is that this can be done more efficiently due to domain structure
- Suggest framework for **acceptable** planning:
A plan P is acceptable wrt (potentially conflicting) knowledge bases KB_1 and KB_2
iff $KB_1 \models P$ and $KB_2 \models P$

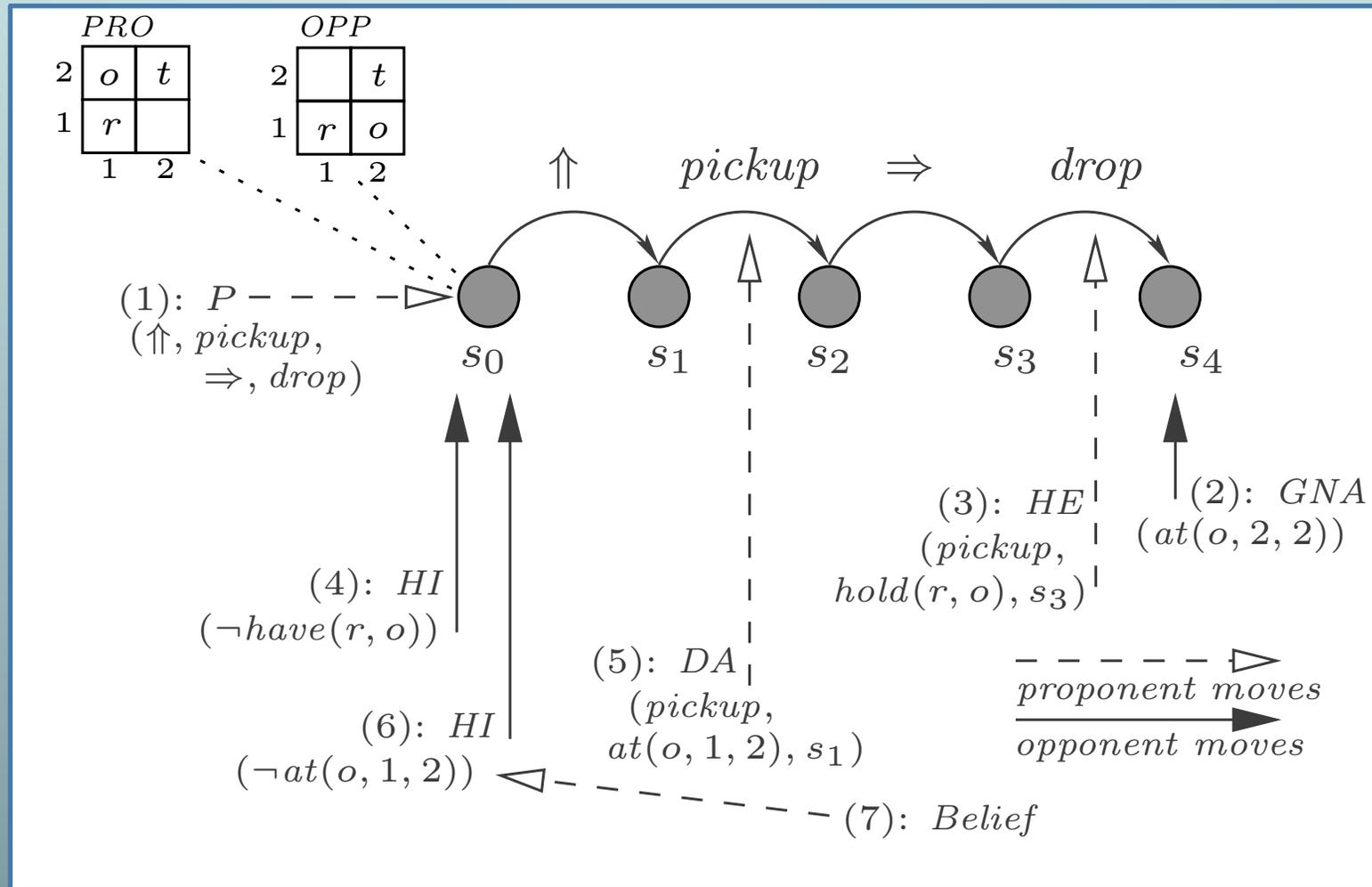
Argumentation-based conflict resolution



- Plan proposal generated by single agent (with any planner)
- Validation based on simple plan projection
- Dispute in case of disagreement, argumentation follows
- Ends in successful defence of initial proposal or rejection
- An alternative to generating one *P* that works under both *KBs*

Example

- Robot gridworld domain

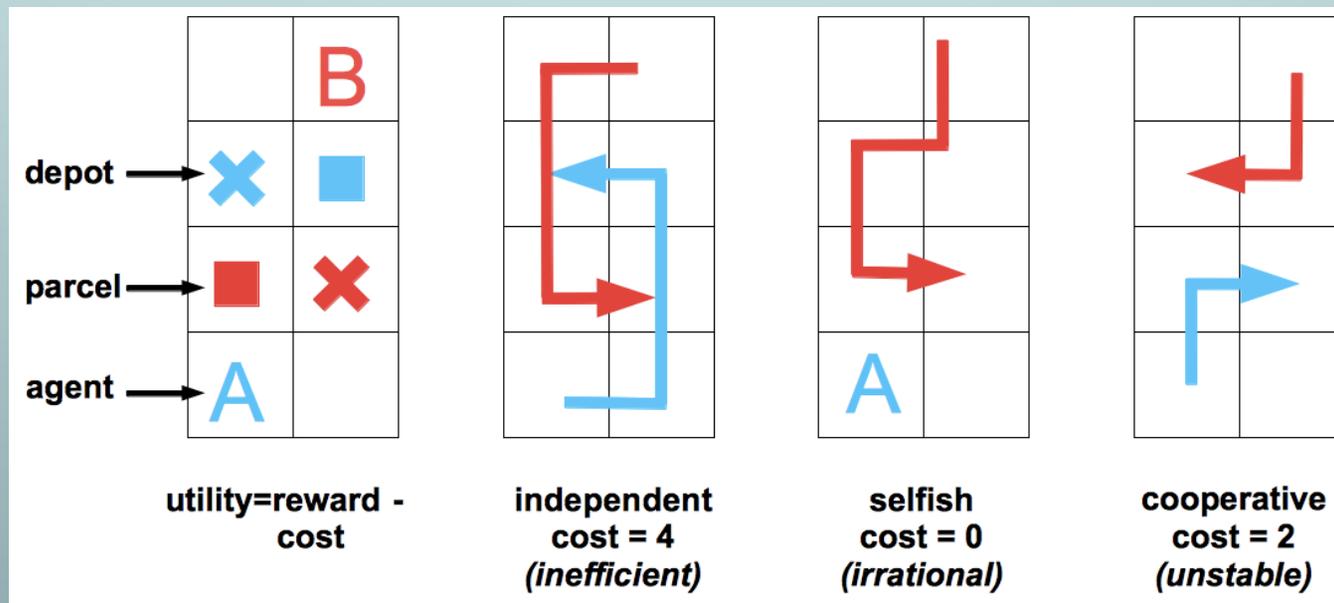


Planning Games

- Examples illustrate use of knowledge-based methods for reasoning about interaction
- But so far not concerned with **strategic** interaction
- Currently trying to look at more general framework of strategic multiagent planning
- Why planning? At the frontline of what is possible in terms of scalability while maintaining “knowledge-level” flavour

Examples

- Parcel delivery: the simplest (?) domain which raises interesting issues



- Fundamental question: how can domain structure help here?

Brafman/Domshlak/Engel/ Tennenholtz (IJCAI 2009)

- Introduce notion of **coalition-planning game** (reward for goal, cost for plan, no action = 0)
- Solution **stable** if no set of agents can increase utility by jointly adopting other plan
- Formally: plan π **stable** for iff no plan π' exists for any subset Φ' of agents Φ such that $u_{\phi}(\pi') > u_{\phi}(\pi)$ for all ϕ in Φ'
- Present an algorithm for computing stable plans, but complexity issues (enumeration of strategies necessary)

Interesting problems

Three general problems seem interesting:

- How to **compute acceptable plan** given a solution criterion (in particular adapting existing planning heuristics)
- How to **search plan space incrementally** for generating proposals during negotiation
- How to **use background knowledge** to guide plan recognition and optimal response generation

Computing acceptable plans

- *How do you find a plan that is a **reasonable compromise**?*
- Initial idea: look at actions that A performs “for” B and vice versa
- Adjust planning heuristics by “discounting” the cost of actions done for the other
- This is currently being implemented in state of the art planners

Incremental plan space search

- *Given a joint plan P , how do you find P' that is **slightly more/less acceptable**?*
- Important for negotiation: finding a selfish/selfless plan is trivial, search for proposal in between hard
- Hierarchical representations should help: if sub-tasks can be identified they can be re-assigned to different agents

Guiding plan recognition and response

- *How can knowledge about other's preferences **help filter possible plans** given action sequence observation?*
- Plan recognition can already be done in a scalable way
- When jointly executing an agreed plan, likely alternative execution paths are contingent on (joint) preferences
- Important for detecting deception or risk of deception, and responding to it

Conclusions

- Argued for “Strategic” Web as an interesting field for agent applications
- Personal view: automated reasoning about strategic interaction is key contribution of agent technology
- Examples of previous work indicate practical reasoning algorithms are possible
- Current goal is to develop similar methods for settings of strategic interaction
- A lot of scope for doing things in a multiagent planning setting, very little previous work

Thank you. Questions?

Material based on
Christelis, MR & Petrick @ AAMAS 2009/2010
Belesiotis, MR & Rahwan @ AAMAS 2010

Find out more/get involved at
<http://www.cisa.inf.ed.ac.uk/agents>