# Describing 2D Shapes for Geometric Matching

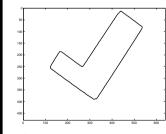
Robert B. Fisher School of Informatics University of Edinburgh

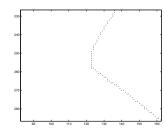
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# **Boundary Finding**

1) Get points that lie on boundary:





2) Remove any spurs on boundary, track and segment

[sr,sc] = removespurs(r,c,H,W);

[tr,tc] = boundarytrack(sr,sc);

[cr,cc] = findcorners(tr,tc);

# **Data Description**

Goal: describe parts in same vocabulary of boundary shapes as model

Assume a binary image of the part

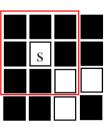
Need to find pixels that lie on the boundary

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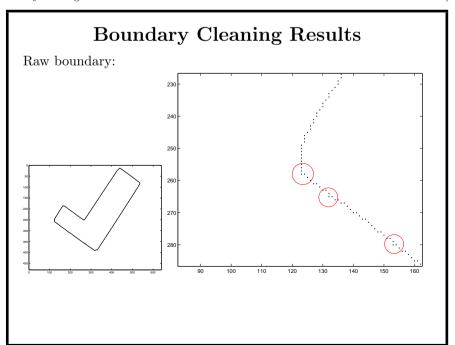
# Removing Dangling Spurs

Spur: any boundary pixel with only 1 neighbor inside a 3x3 neighborhood



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# Removing Unnecessary Boundary Pixels

Find unnecessary corners:

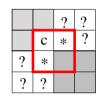
- \* boundary point to keep
- c boundary point to remove
- ? boundary point thru here somehow

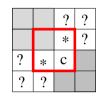
shaded box - interior or exterior pixel

thick red box - pixel neighbourhood inspected

?	?		
?	*		
	С	*	?
		?	?

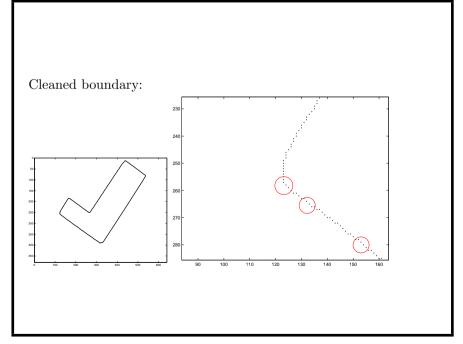
?	?		
?	*	c	
		*	?
		?	?





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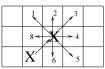
# Getting a Consecutive Boundary Track

TRACK TO FIRST UNTRACKED BOUNDARY PIXEL ENCOUNTERED AS i GOES 1...7

### **NEXT DIRECTIONS**



## **EXAMPLE TRACKING**



LAST MOVE = 3NEXT MOVE = 8,1,2,3,4,5,6

NEXT = (LAST + 3 + i) MOD 8 + 1

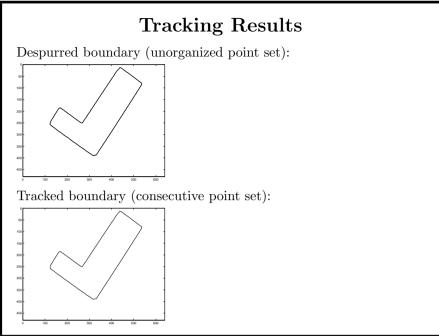
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# What Have We Learned?

Introduction to

- Getting a boundary from a binary image
- Cleaning that boundary up using morpholgical operations
- Making a consecutive list of points



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