

# Fourier Matching

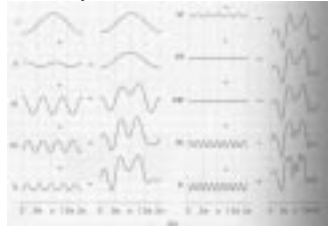
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- ## Image Matching
- To match registered images
    - one-to-one: correlation
    - one-to-many: eigenspaces
  - To match unregistered images:
    - cross-correlation
      - including rotation-free cross-correlation
    - *fourier methods -- how, why and when?*
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*Review (Lecture #8):*

## 2D Fourier Spectrum

- Any signal that is non-zero over a finite range can be represented by an (infinite number of) sine waves:



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*Review:*

## 2D Fourier (cont.)

- Mathematically, this is expressed as:

$$F(u) = \int_{-\infty}^{\infty} f(x) [\cos 2\pi ux - i \sin 2\pi ux] dx$$

where  $i$  is the square root of -1

- Sometimes, this is written as magnitude & phase shift:

$$|F(u)| = \sqrt{R^2(u) + I^2(u)}$$

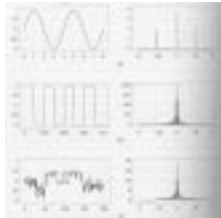
$$\phi(u) = \tan^{-1} \left( \frac{I(u)}{R(u)} \right)$$

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*Review:*

## 2D Inverse Fourier

- The inverse mapping from frequencies (sines) to the spatial domain is:

$$f(x) = \int_{-\infty}^{\infty} F(u) [\cos 2\pi ux + i \sin 2\pi ux] du$$


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- ## Matching
- The Fourier Transform converts spatial image into *frequencies* and *phases*. Can we use these to match images?
  - The Fourier transform is deterministic, so if two images are identical, so are their frequencies and phases.
  - Can we tell if two images are similar?
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## Scaling Functions

- For simplicity, let us focus on 1D functions (the same principles will apply in 2D)
- If we scale a function  $f(x)$ , we get  $f(ax)$ , where  $a$  is a constant

$$\text{Fourier}(f(ax)) = \int_{-\infty}^{\infty} f(ax)e^{i2\pi ux} dx = \frac{1}{|a|} F\left(\frac{u}{a}\right)$$

- What does this say?

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## Shifting functions

- Similarly, if we shift a function:

$$\text{Fourier}(f(x-x_0)) = \int_{-\infty}^{\infty} f(x-x_0)e^{i2\pi ux} dx = F(u)e^{i2\pi ux_0}$$

- The last term ( $e^{i2\pi ux_0}$ ) is imaginary, so:
  - it represents a phase shift (no frequency shift)
  - the amount of the phase shift is  $2\pi ux_0$
- The inverse is also true

$$F(s-s_0) = \text{Fourier}(f(x)e^{i2\pi sx_0})$$

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## Correlation in Frequency Space

- The frequency space version of correlation can be written as:

$$h(x) = f(x) \otimes g(x) = \int_{-\infty}^{\infty} f(u)g(x+u)du$$

- The mask  $g(x)$  is assumed infinite but zero outside of a finite range.

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## Correlation Theorem

- The Fourier transform of the cross-correlation is:

$$\text{Fourier}(h(x)) = F(s)G^*(s)$$

- $F(s)$  is the fourier transform of  $f(x)$
- $G(s)$  is the fourier transform of  $g(x)$ 
  - $G^*(s)$  is the complex conjugate of  $G(s)$ , defined as the real part of  $G(s)$  minus the imaginary part

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## So?

- Fascinating, but how do we use it?
- Go back to the shifting relation. The phase difference between two identical images shifted by  $(x_0, y_0)$  is:

$$e^{i2\pi(u x_0 + v y_0)}$$

- Why is this interesting? Because:

$$\frac{F_1(u, v)F_2^*(u, v)}{F_1(u, v)F_2(u, v)} = e^{i2\pi(u x_0 + v y_0)}$$

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## Mosaicing

- So how can we use this?
  - Image two pictures, taken by shifting the camera perpendicular to the optical axis
  - Each picture contains a piece of the scene not included in the other
  - “Mosaicing” is the process of stitching these together into one larger image
  - It requires finding the shift factor between the two images.

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## Example



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## Mosaicing (II)

- How do we Mosaic images?
  - We could do cross-correlation, but both images are large, so this is expensive.
  - Alternatively, we could take the Fourier transform of both (and the complex conjugate of one) and compute the phase shift using:

$$\frac{F_1(u,v)F_2^*(u,v)}{|F_1(u,v)F_2^*(u,v)|} = e^{i2\pi(ux_0+vy_0)}$$

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## Mosaicing ©

- What will be the result? If the images are identical (other than the shift) and you sum the power at each phase across frequencies  $u,v$ , you will find that all the energy lies at single phase corresponding to the shift  $x_0, y_0$
- What if they are similar but not identical? Then most of the power lies at a single phase, so perform the same calculation and then do peak detection.
- Is this cheaper than cross-correlation?

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## Fourier Methods

- Mosaicing involves matching a whole to a shifted whole
  - What if we want to find a small template in a larger image?
    - Will Fourier matching work?
    - Why or why not?
  - For what other types of problems does Fourier matching work?

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## Back to Correlation

- I said that if two images are similar, then phase correlation says that the maximum phase value corresponds to the best shift  $x_0, y_0$ .
- What is the relationship between the height of the peak and the correlation score of the images under that shift?
- Parseval's theorem says that:  $\int \vec{h}^2(x) dx = \int |H(f)|^2 df$
- So normalizing source image normalizes frequency space, and the height of the peak is the correlation score

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