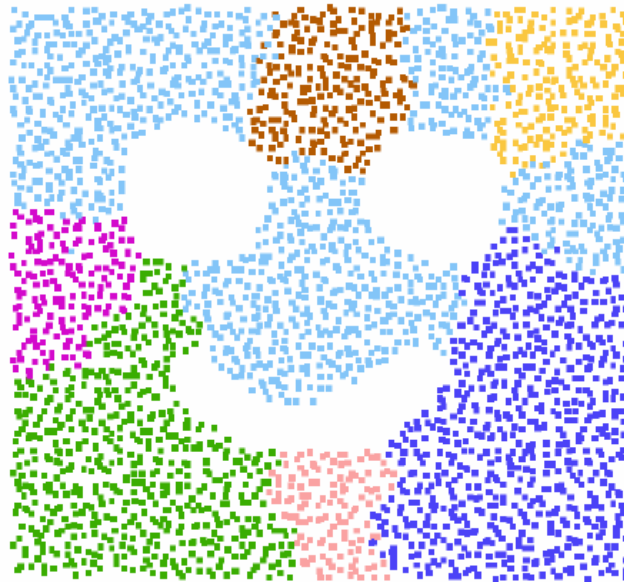
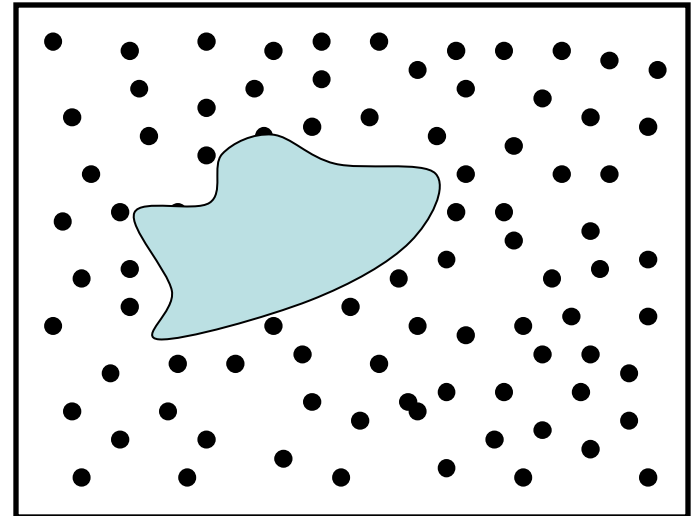

Shape Segmentation and Applications in Sensor Networks

Xianjin Zhu Rik Sarkar Jie Gao



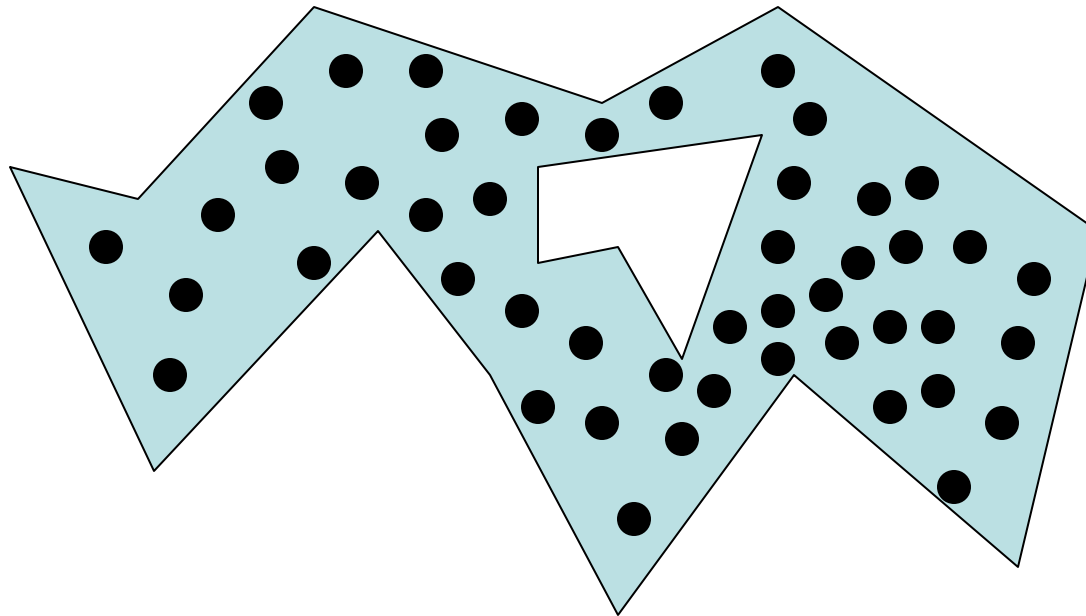
Motivation

- Common assumption: sensors are deployed uniformly randomly inside a simple region (e.g., square).
- In practice, **can be complex**.
 - Obstacles (lakes, buildings)
 - Terrain variation
 - Degradation over time



Sensor Distribution in Practice

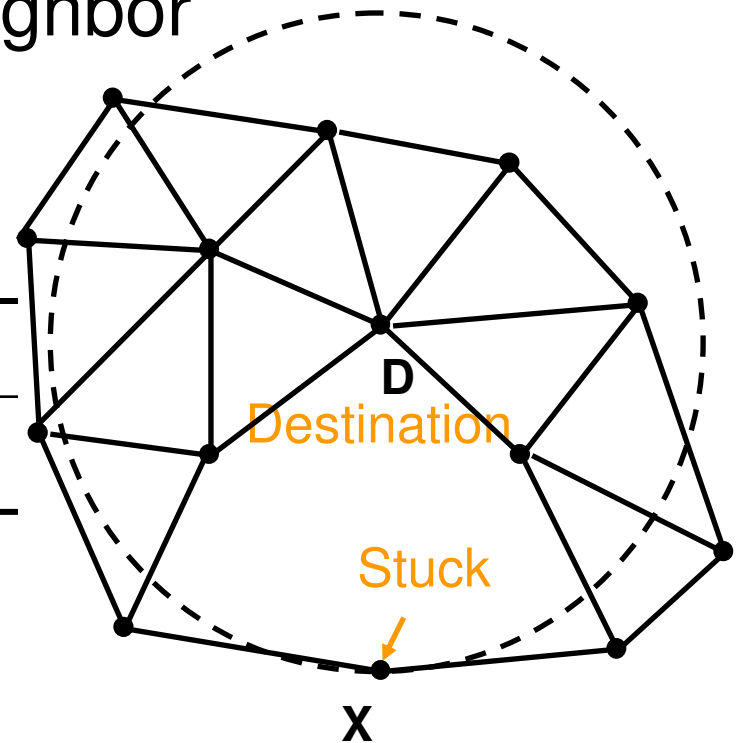
- Nodes are distributed in a geometric region with possible complex shape, with holes.



With holes or a complex shape...

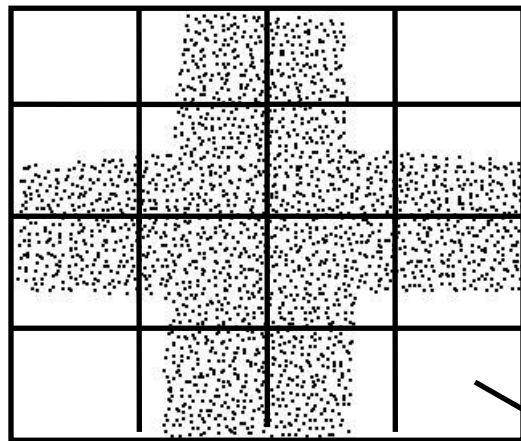
- Some protocols may fail:
 - **Greedy forwarding**: packets are greedily forward to the neighbor closest to the destination

Dense uniform	Sparse, non-uniform
Works well	May get stuck



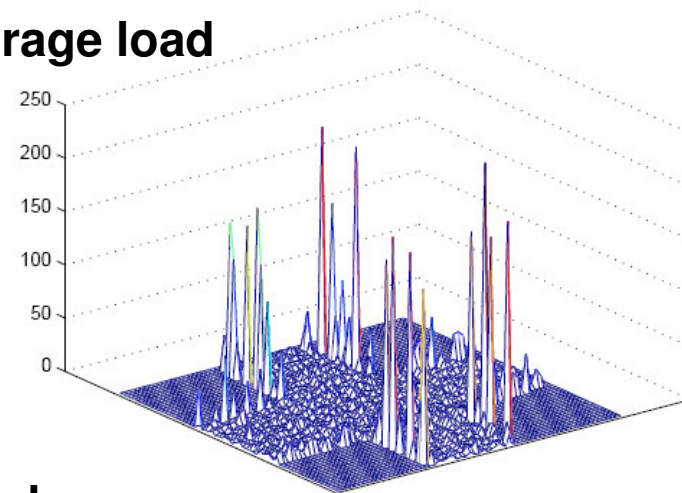
With holes or a complex shape...

- Some protocols have degraded performance
 - Quad-tree type data storage hierarchy
 - Data is hashed uniformly to the quads

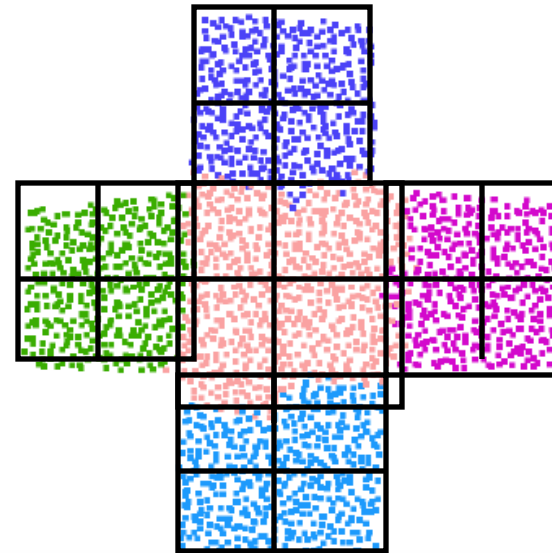
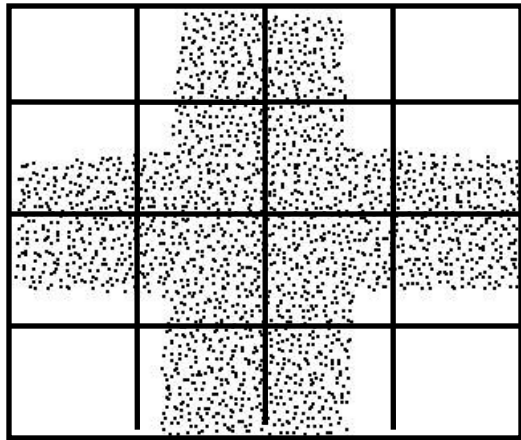


Empty Blocks

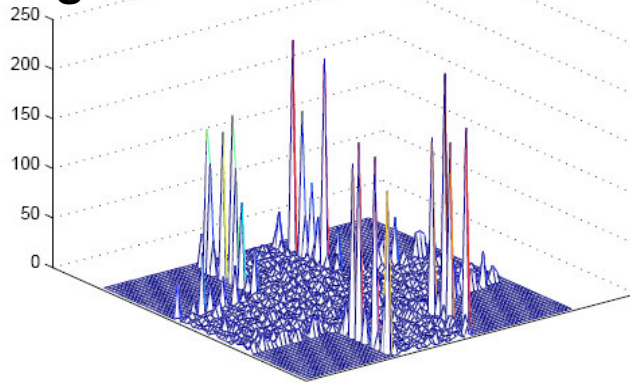
Storage load



Quad-Tree Type Hierarchy

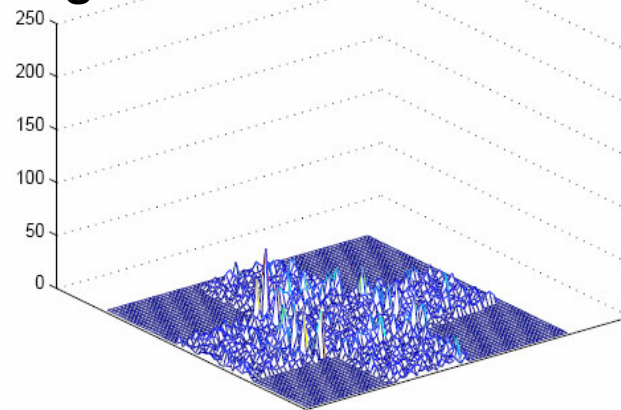


Storage load



w/o segmentation

Storage load

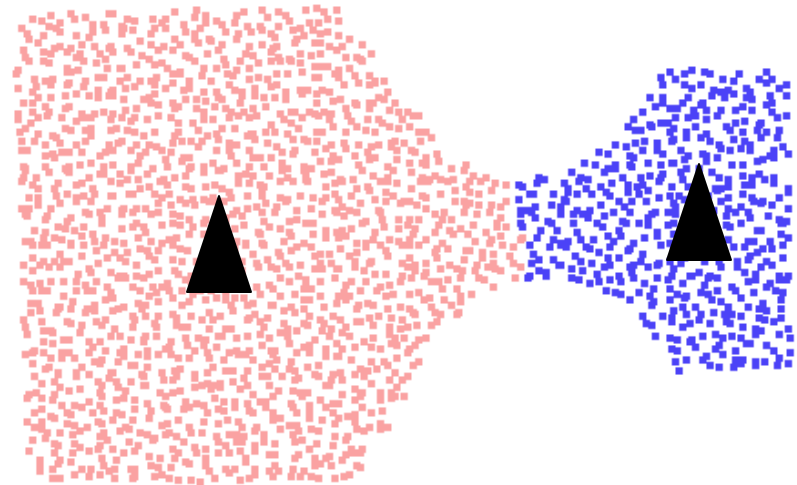


w/ segmentation

Lesson Learned

- Global geometric features affect many aspects of sensor networks.
 - Affect system performance.
 - Affect network design.

Place base stations and
avoid traffic bottleneck

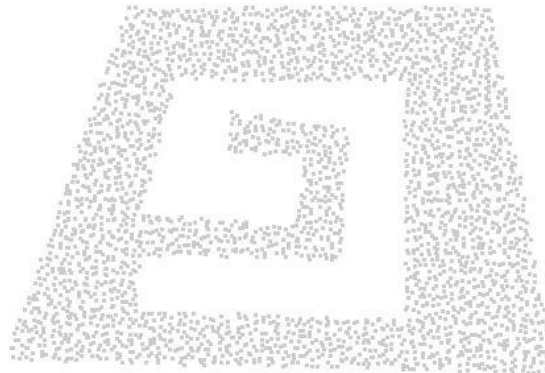
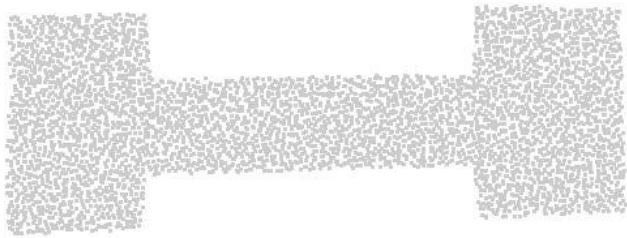


How to Handle Complex Shape?

- Previous work
 - Build problem specific virtual coordinate system (e.g., for routing)
 - Redevelop every algorithm on virtual coordinate system
- Our approach: **shape segmentation**
 - A unified approach to handle complex geometry
 - Make existing protocols reusable

Sensor Field with Arbitrary Shape

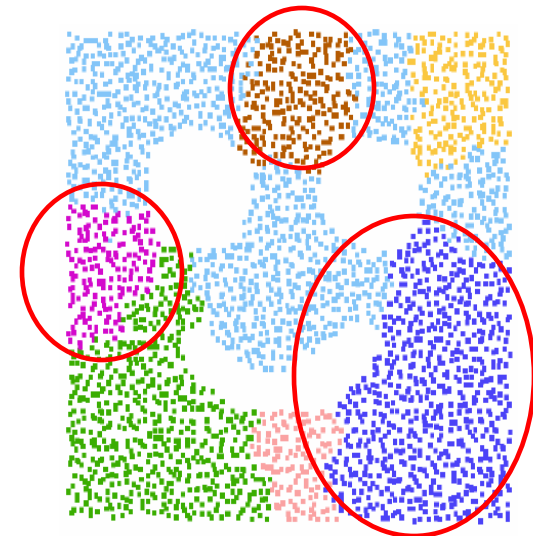
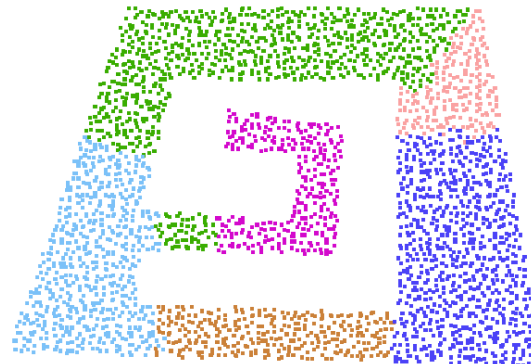
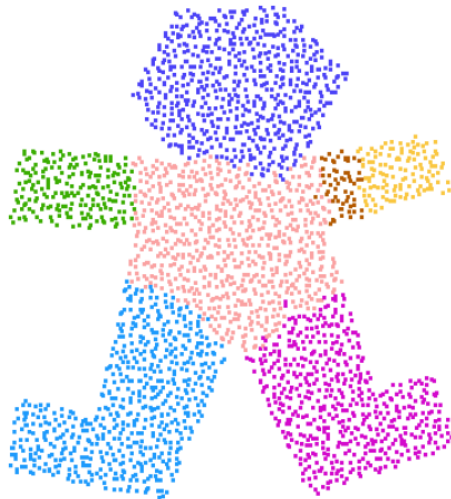
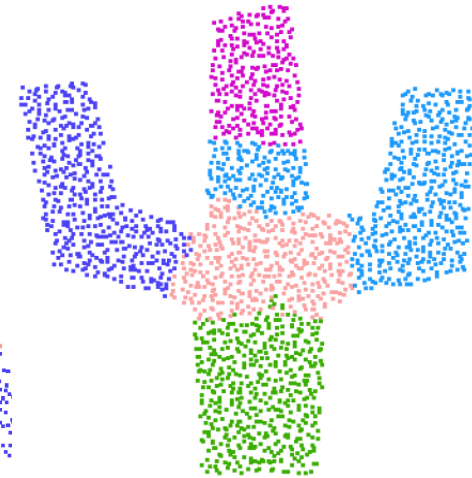
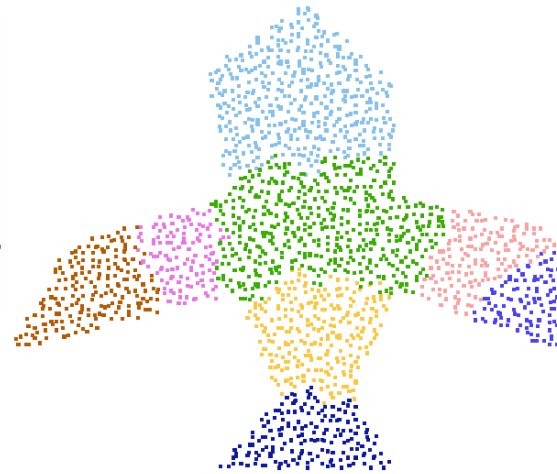
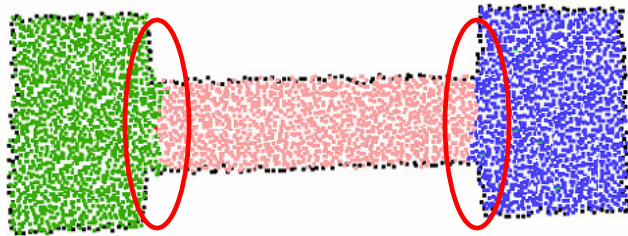
- Density ranges from 7-12 neighbors/node



Simulation Results on Segmentation

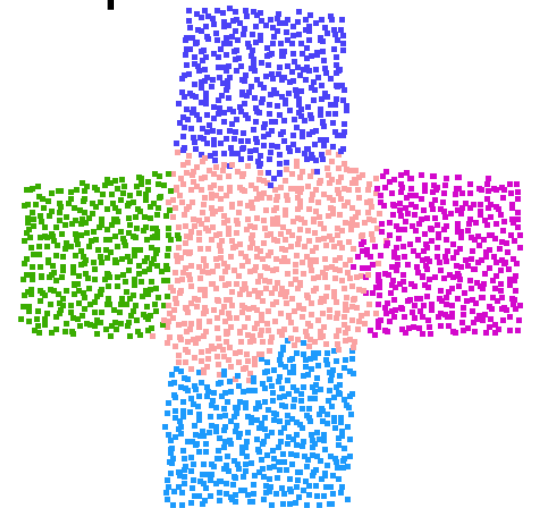
- Density ranges from 7-12 neighbors/node

Narrow necks



Our Approach: Shape Segmentation

- Segment the irregular field into “nice” pieces.
 - Each piece has no holes, and has a relatively nice shape
- Apply existing algorithms inside each piece.
 - Existing protocols are reusable
- Integrate the pieces together with a problem-dependent structure.

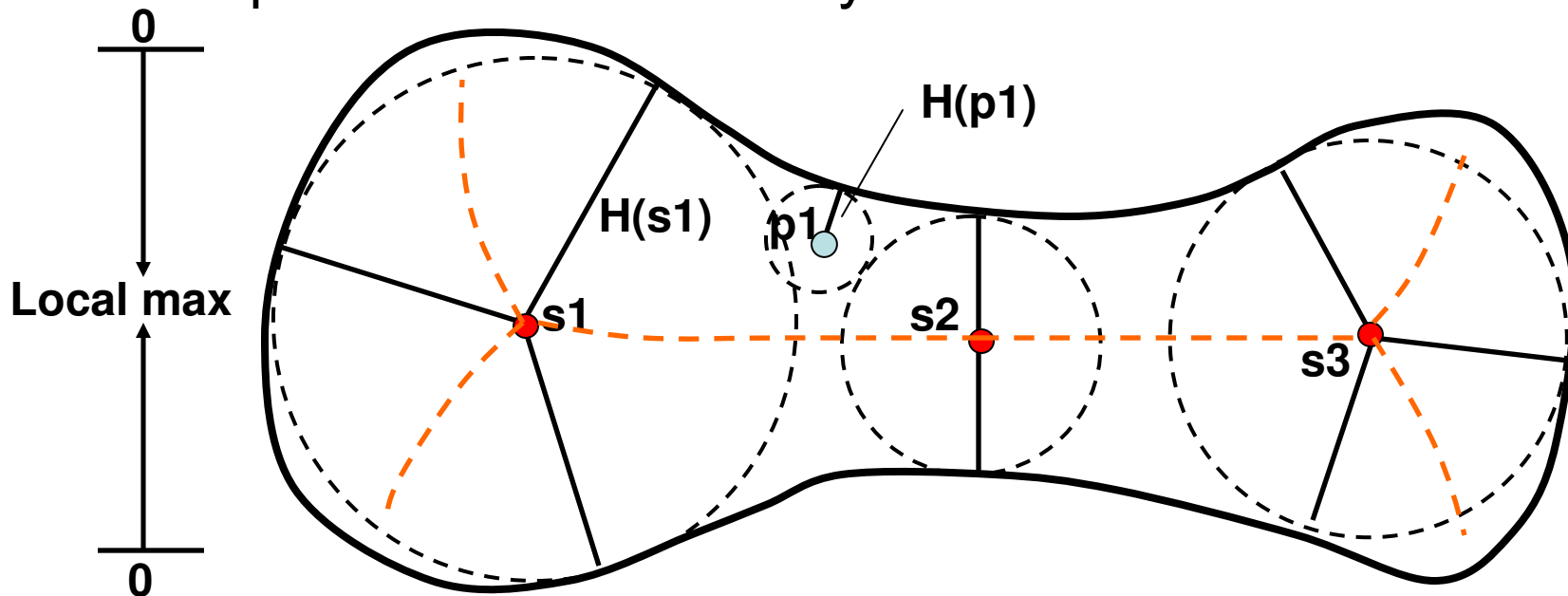


The rest of the talk ...

- Segmentation algorithm
- Implementation issues

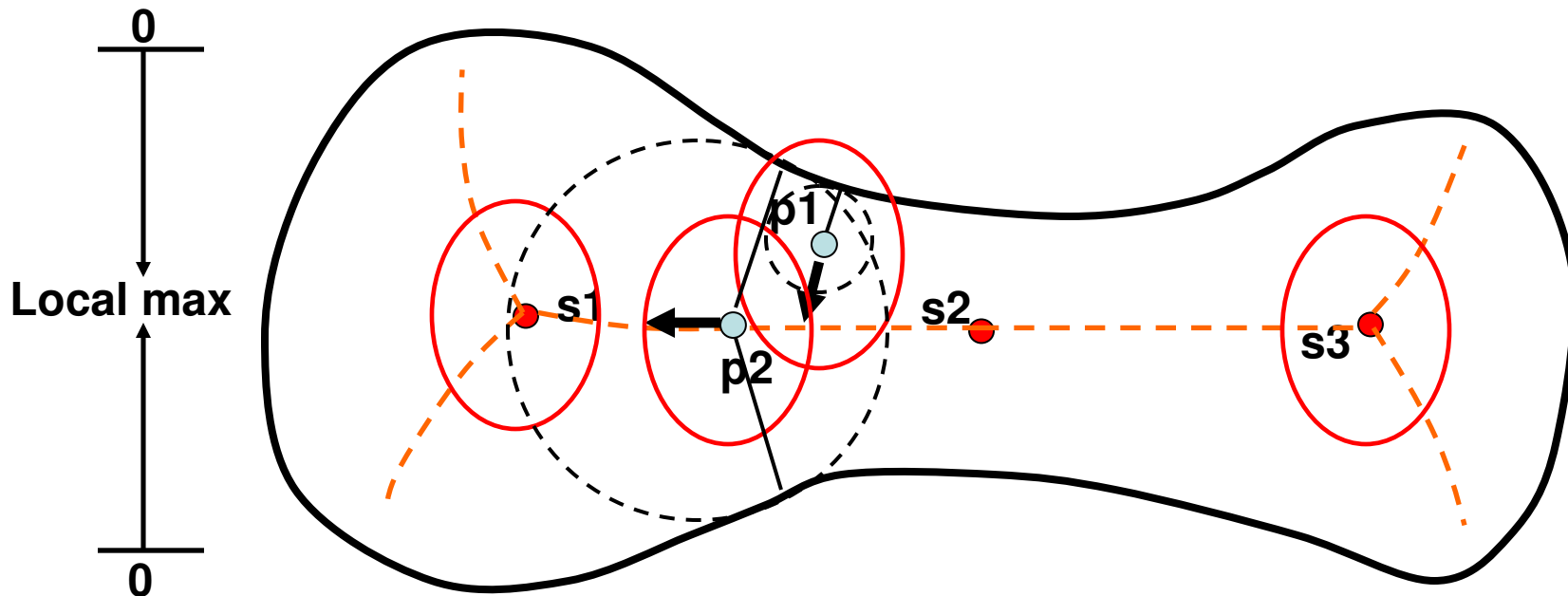
Segmentation with Flow Complex

- Flow Complex in continuous domain
 - Distance function $h(x) = \min\{\|x-p\|^2 : p \text{ on boundary}\}$
 - Medial axis: a set of points with at least two closest points on the boundary



Segmentation with Flow Complex

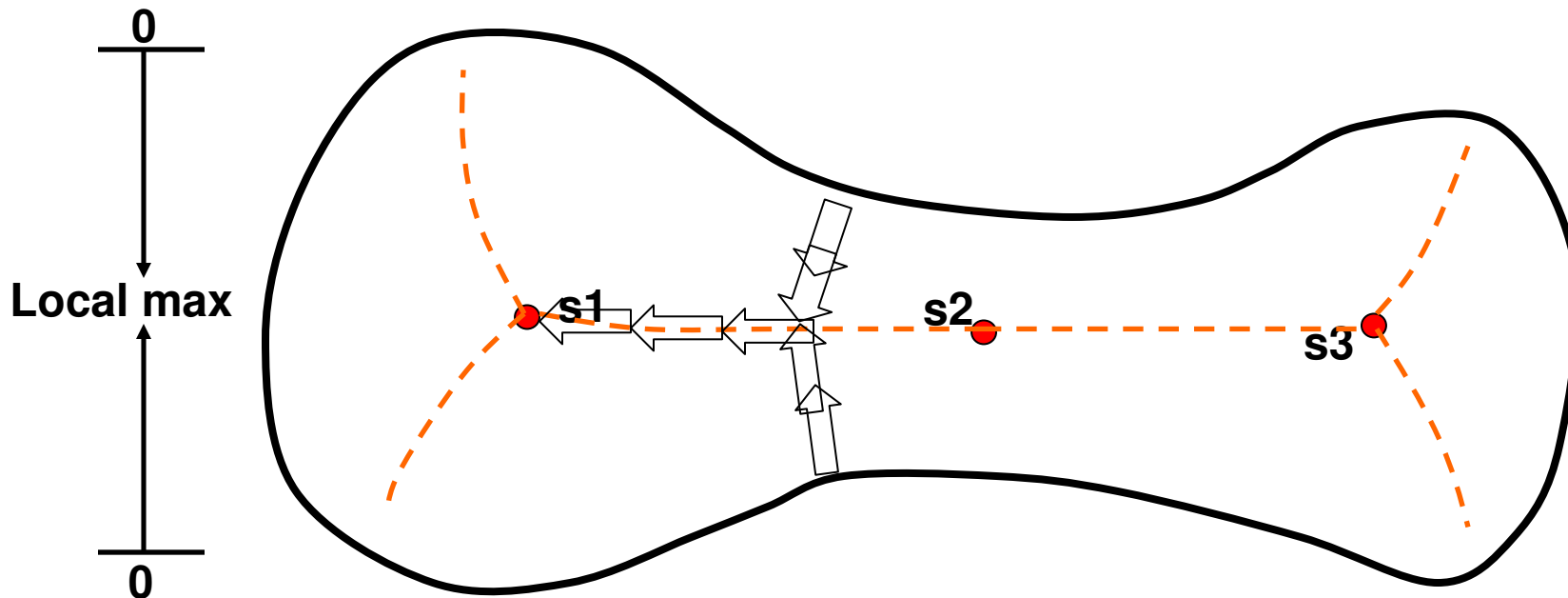
- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
 - **Sinks**: local maximum, no flow direction (s1 & s3 here)



Reference: flow complex [Dey, Giesen, Goswami, WADS'03]

Segmentation with Flow Complex

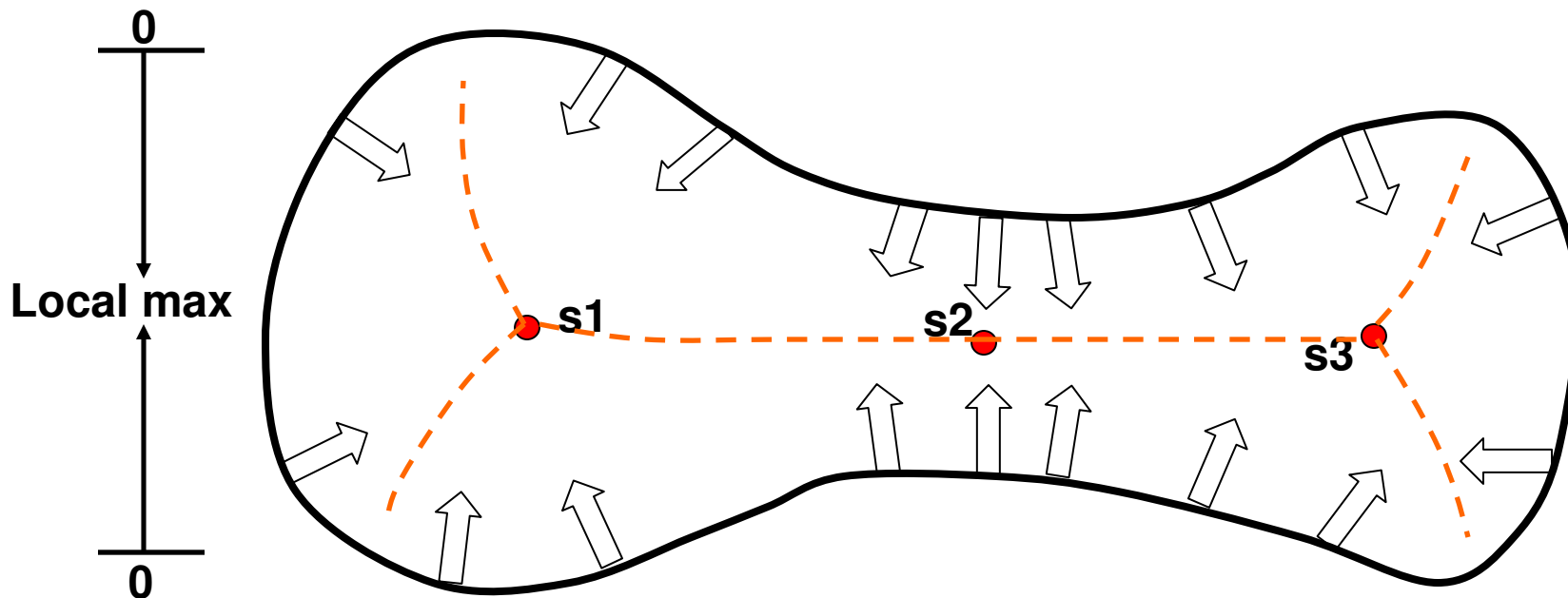
- Flow Complex in Continuous domain
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Segmentation with Flow Complex

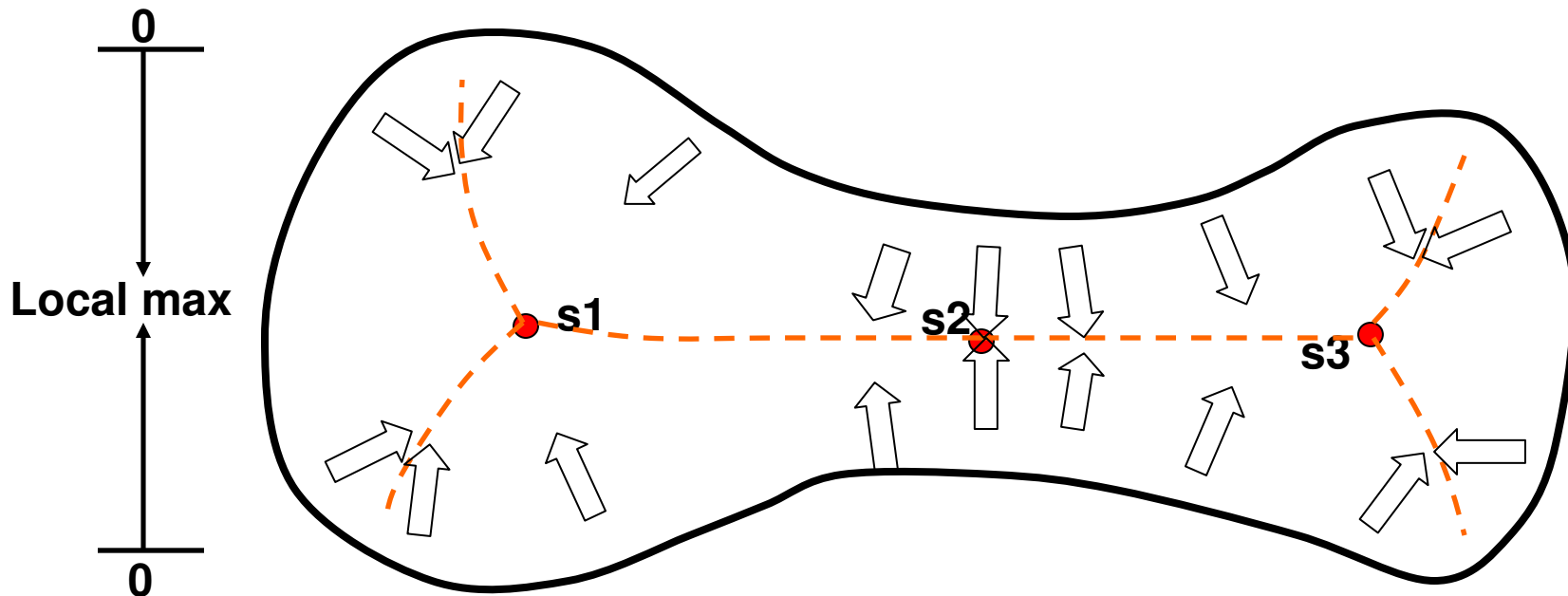
- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
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Reference: flow complex [Dey, Giesen, Goswami, WADS'03]

Segmentation with Flow Complex

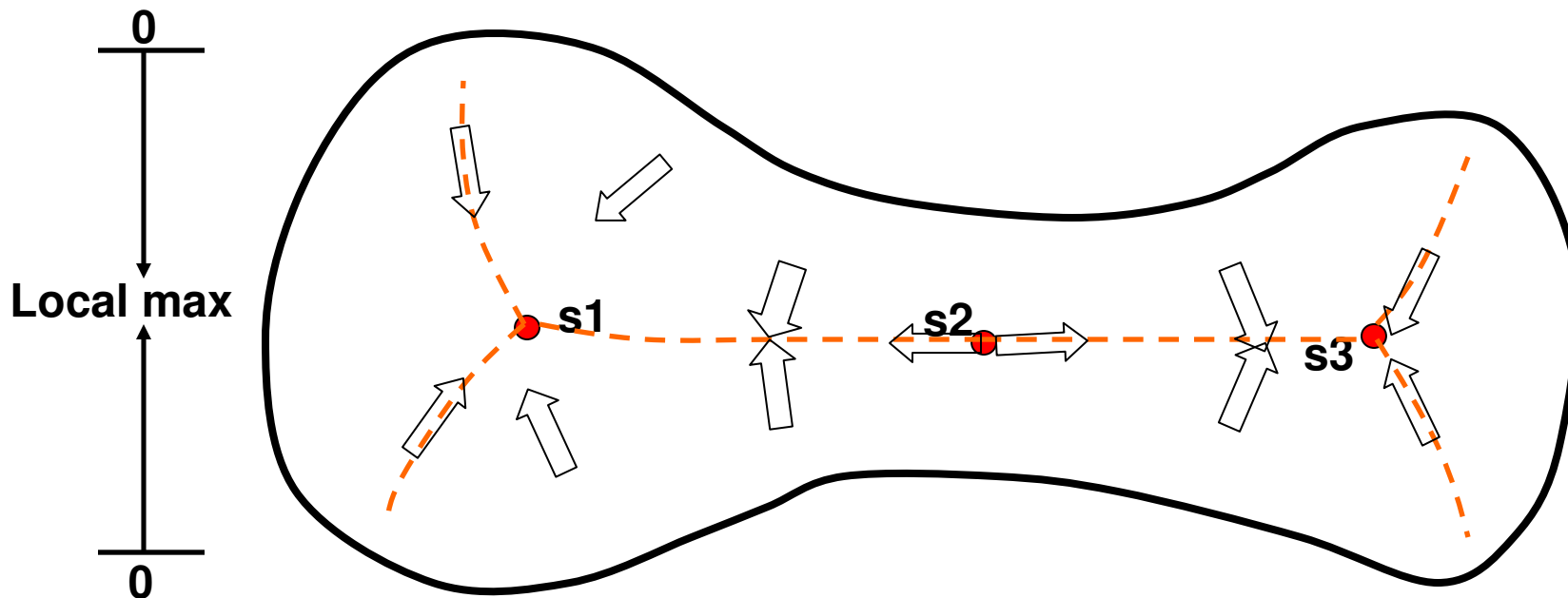
- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
 - **Sinks**: local maximum, no flow direction (s1 & s3 here)



Reference: flow complex [Dey, Giesen, Goswami, WADS'03]

Segmentation with Flow Complex

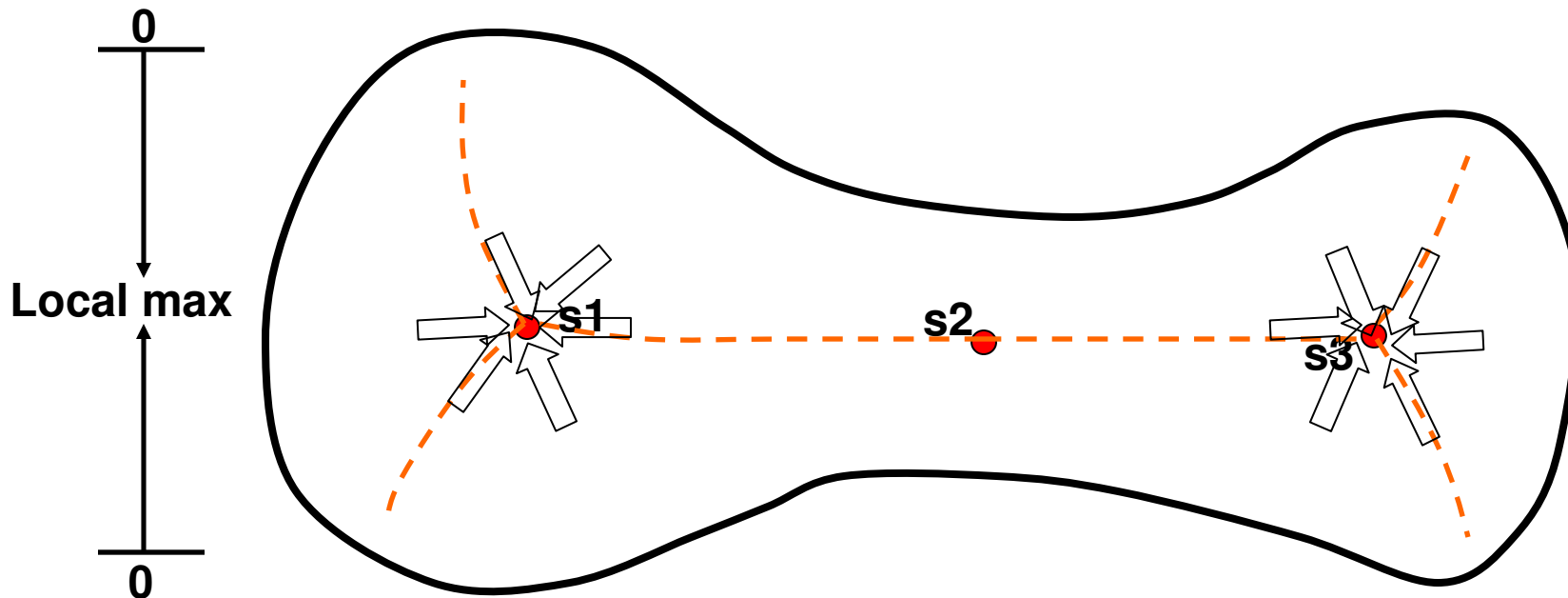
- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
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Reference: flow complex [Dey, Giesen, Goswami, WADS'03]

Segmentation with Flow Complex

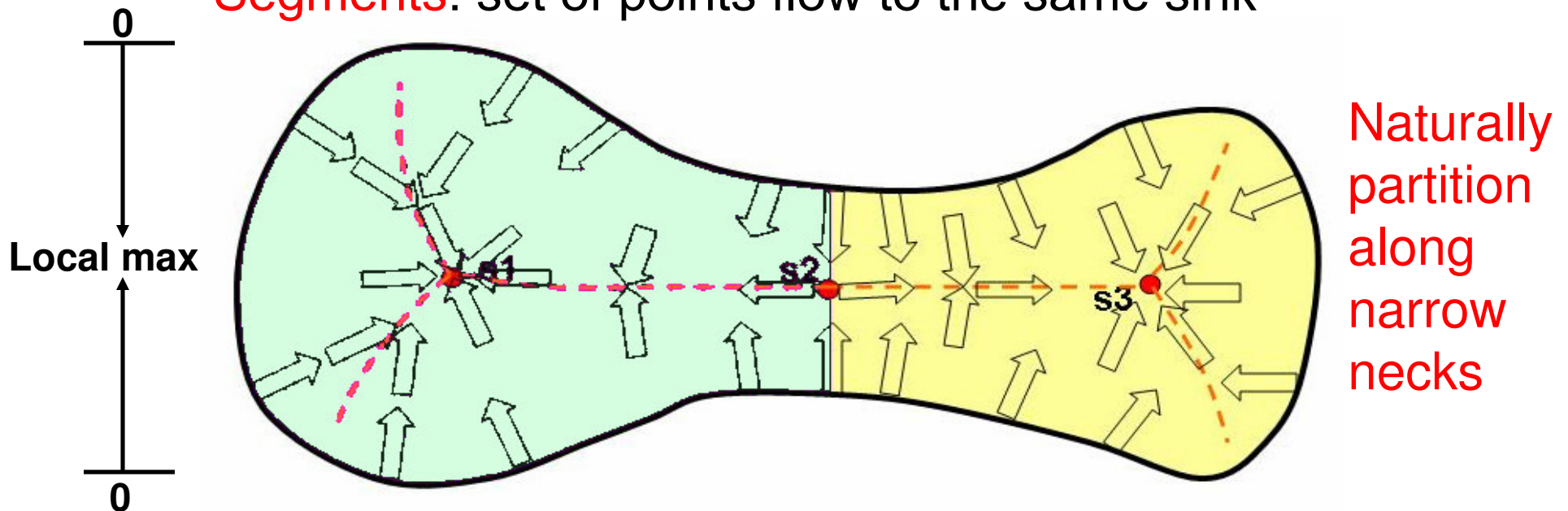
- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
 - **Sinks**: local maximum, no flow direction (s1 & s3 here)



Reference: flow complex [Dey, Giesen, Goswami, WADS'03]

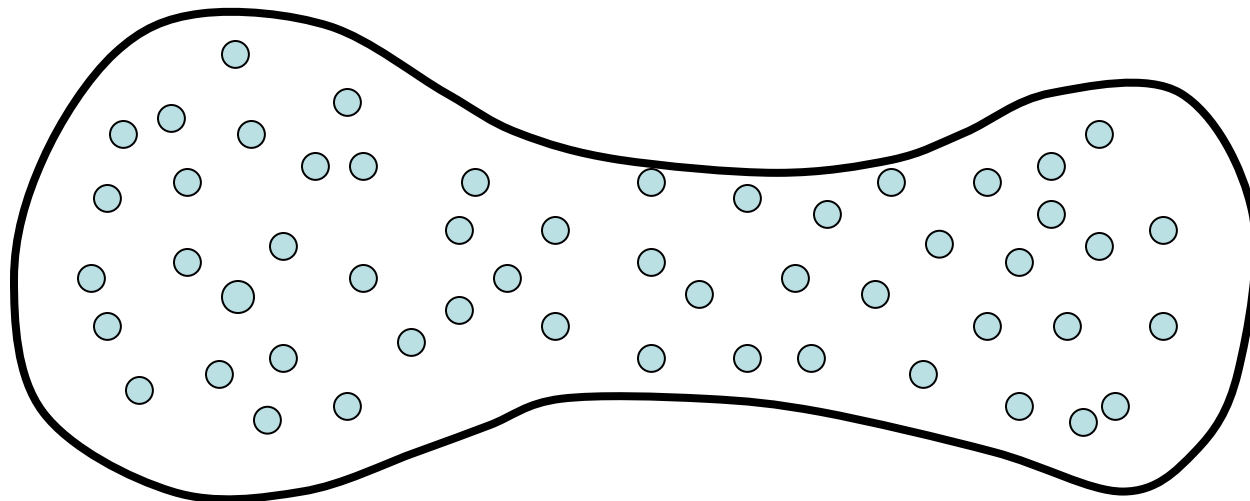
Segmentation with Flow Complex

- Flow Complex in Continuous domain
 - **Flow direction**: the direction that $h(x)$ increases fastest
 - **Sinks**: local maximum, no flow direction (s1 & s3 here)
 - **Segments**: set of points flow to the same sink



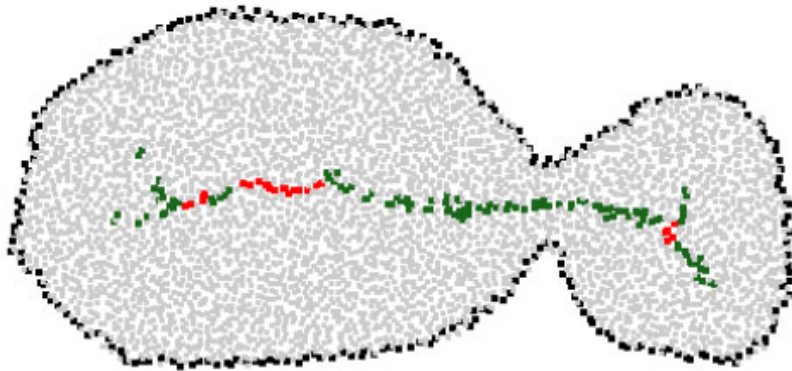
Implementation Challenges

- No global view, no centralized authority
- No location, only connectivity information
 - Distances are approximated by **hop count**
- Robust to inaccuracy, packet loss, etc.
- **Goal: a distributed and robust segmentation algorithm.**

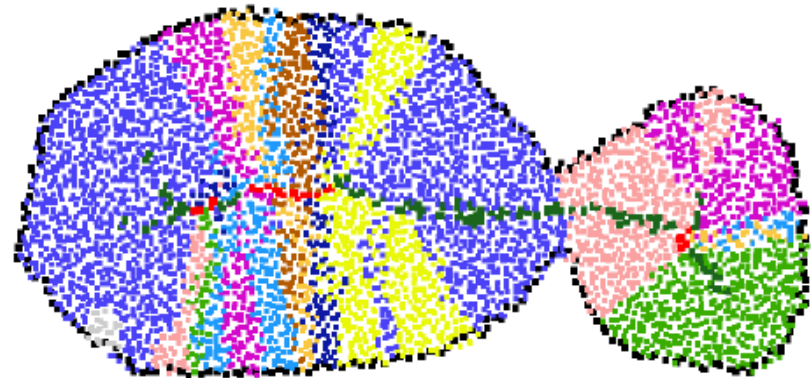


Algorithm Outline

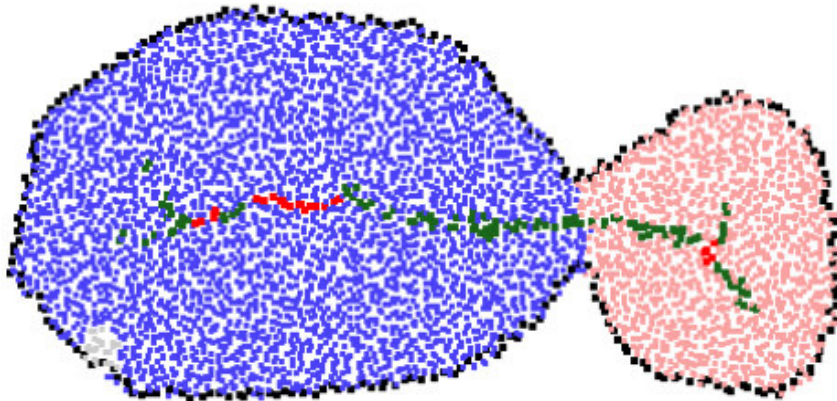
1. Compute the medial axis



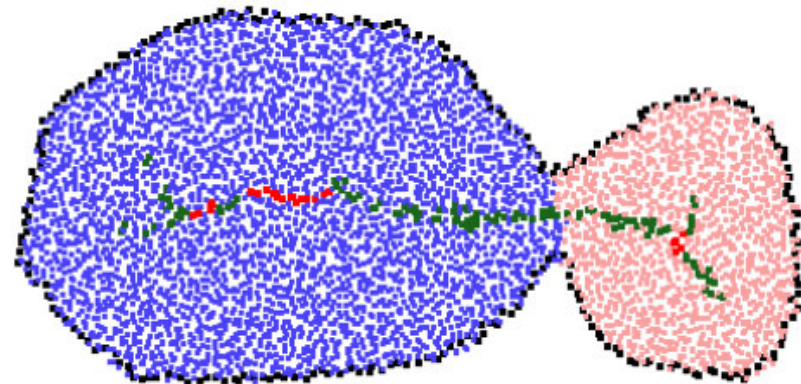
2. Compute the flow



3. Merge nearby sinks

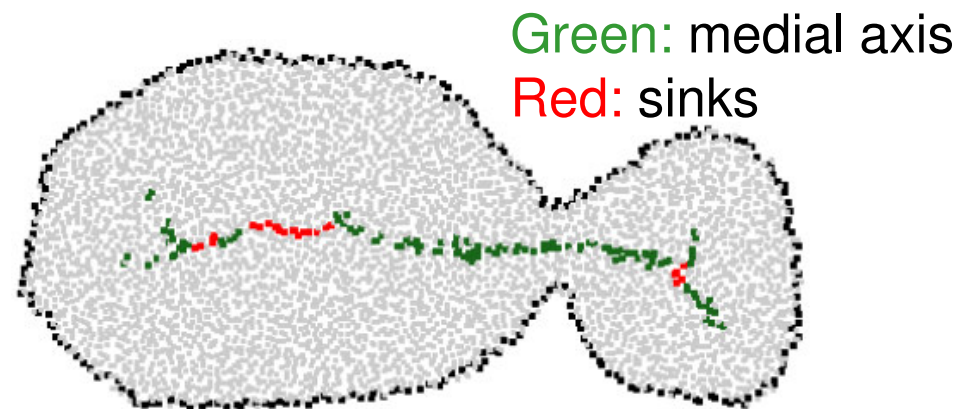
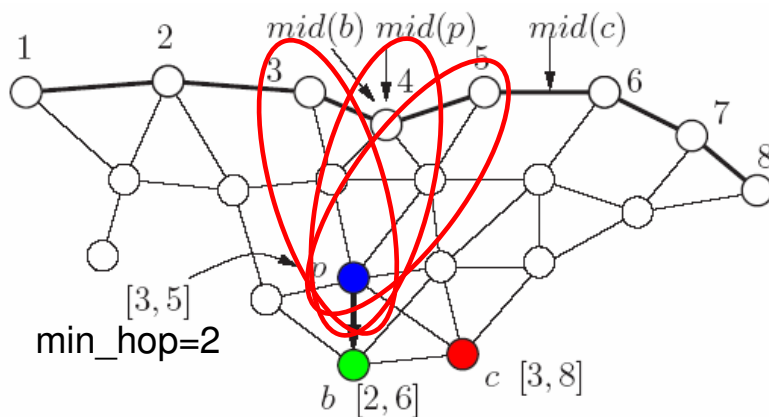


4. Final clean-up



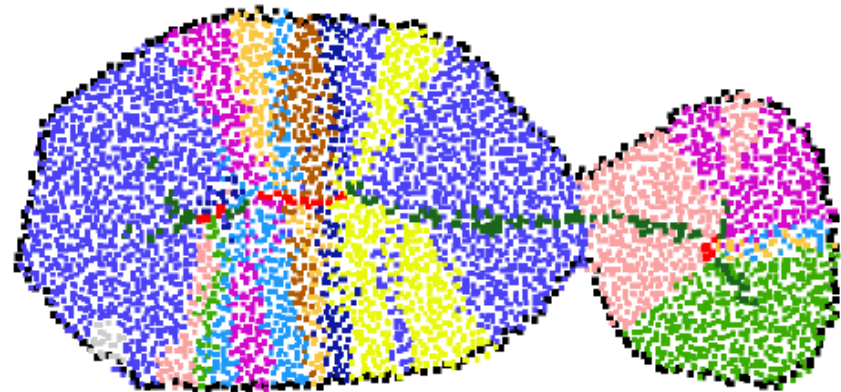
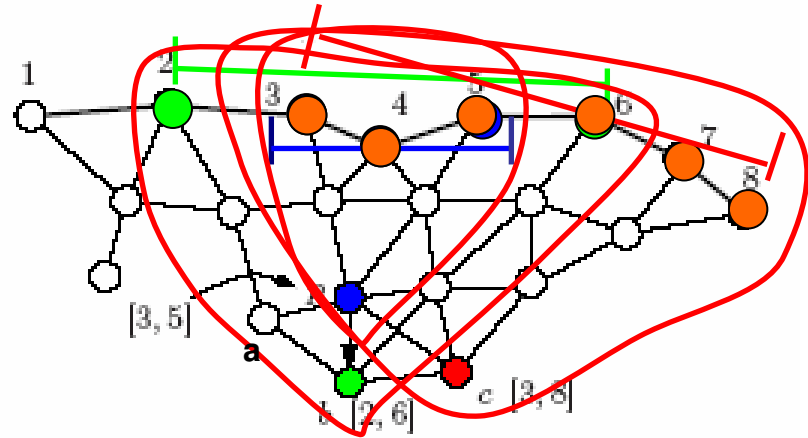
Step 1: Compute the medial axis

- Boundary nodes flood inward simultaneously.
- Nodes record: minimum hop count & closest intervals on the boundary
- **Medial axis:** more than two closest intervals



Step2: Compute the flow

- **Flow direction:** a pointer to a neighbor with a higher hop count from the same boundary
 - Prefer neighbor with the most symmetric interval
- Sinks must be on the medial axis.
- Network is organized into forests, **sinks are roots**
- Nodes are classified into segments by their sinks.



Too many segments!

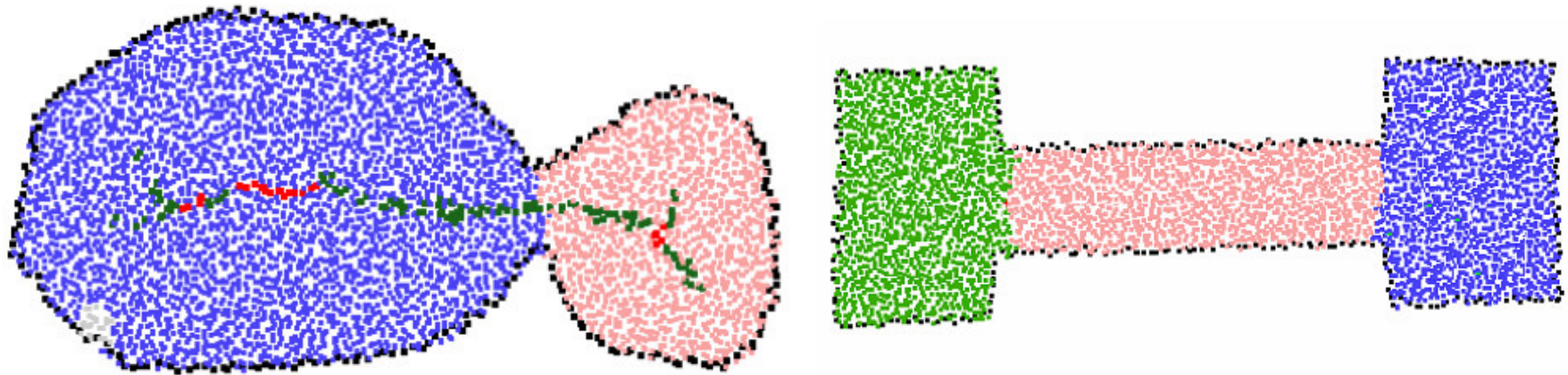
Example of Heavy Fragmentation

- Fragmentation problem becomes severe with parallel boundaries.



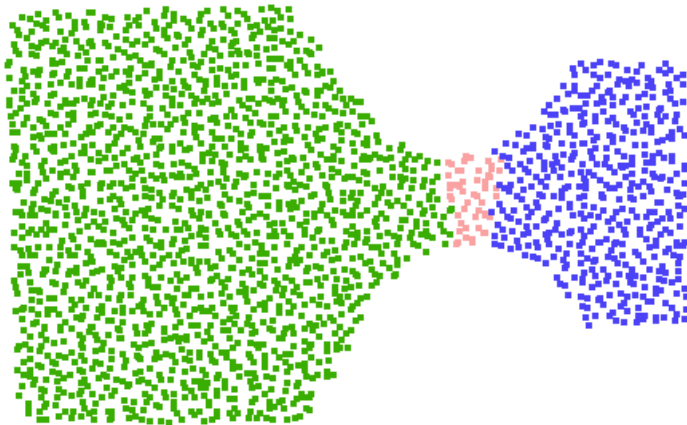
Step3: Merge nearby sinks

- Nearby sinks with similar hop count to the boundaries are merged (together with their segments).

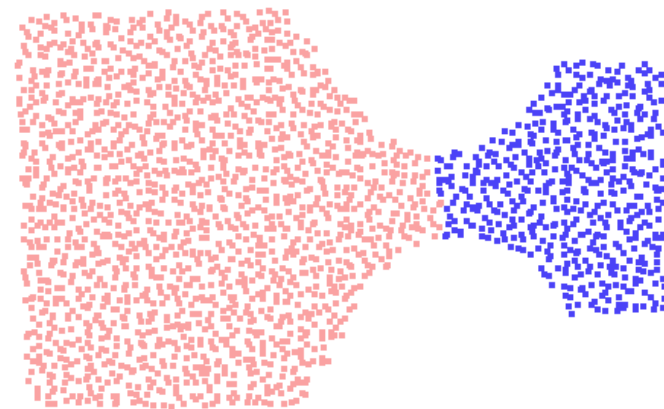


Step3: Merge nearby sinks

- Nearby sinks with **similar** hop count to the boundaries are merged (together with their segments).
 - **Segmentation granularity**: $|H_{\max} - H_{\min}| < t$



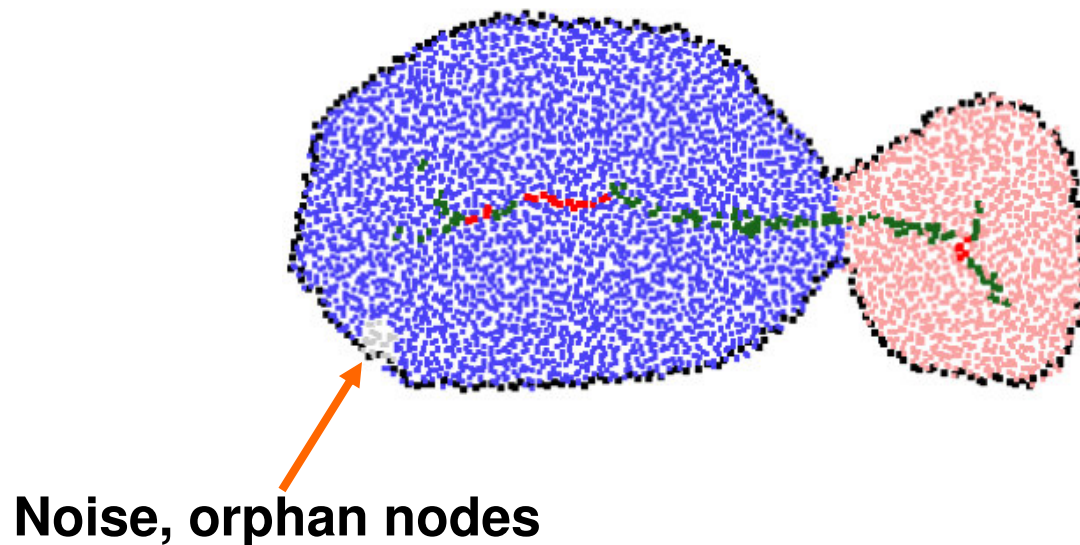
t=2



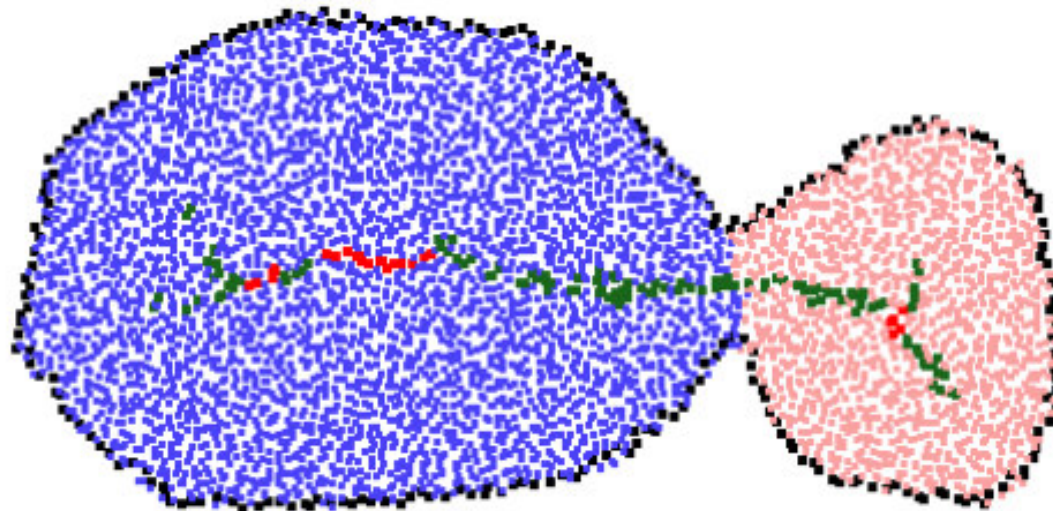
t=4

Step4: Final clean-up

- Merge orphan nodes with nearby segments
- **Orphan nodes:** local maximum and nodes that flow into them

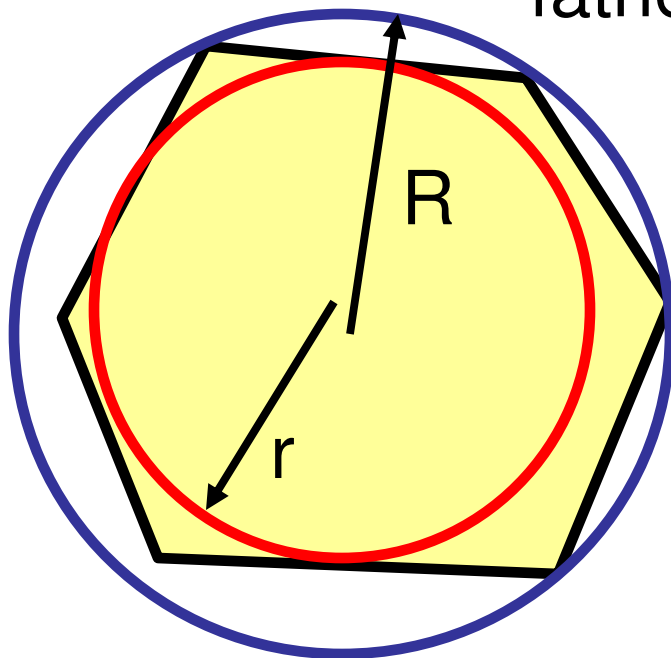


Final Result



Properties of Segmentation

- A few “fat” segments
- Further merging only hurts fatness



$$\text{fatness} = \frac{\text{max inscribing ball radius}}{\text{min enclosing ball radius}} \\ = \frac{r}{R}$$

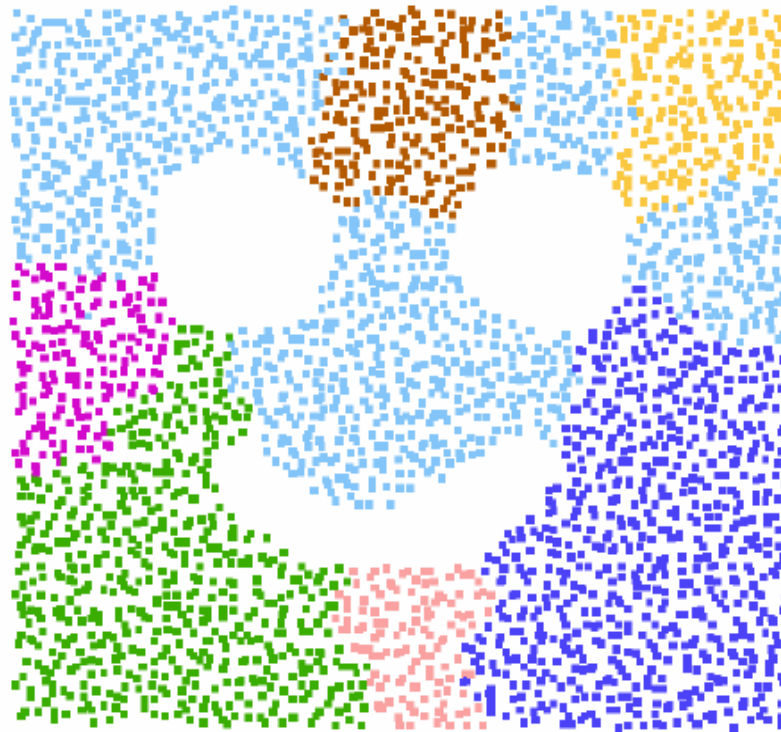
The bigger the fatter.

Conclusion

- A unified approach handling complex shape in sensor networks.
- A good example to extract high-level geometry from connectivity information.
- Network self-organizes by local operations.

Thank you!

- Questions ?



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