

Coalgebraic bisimulation

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Motivation

- **Robin Milner**: bisimulation and coinduction.
- Coalgebra, the mathematics of *bisimulation*.
- Behavioural theory of systems.
- **CMCS, CALCO**; also presence in main conferences.
- Joint work with **many persons**.

Overview

1. Bisimulation everywhere
2. The power of coinduction
3. More bisimulations, still

1. Bisimulation everywhere

Coalgebraic bisimulation: Aczel & Mendler '89

An F -bisimulation, for a functor $F : \mathcal{C} \rightarrow \mathcal{C}$:

$$\begin{array}{ccccc}
 X & \xleftarrow{\pi_1} & R & \xrightarrow{\pi_2} & Y \\
 \alpha \downarrow & & \exists \downarrow \gamma & & \downarrow \beta \\
 F(X) & \xleftarrow{F(\pi_1)} & F(R) & \xrightarrow{F(\pi_2)} & F(Y)
 \end{array}$$

- As many types of bisimulation as there are functors . . .
- Well-behaved functors: universal coalgebra.
- Bisimulation/Coalgebra = Congruence/Algebra

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Example: universes of sets



write $y \in x$ for $y \in \alpha(x)$

- $R \subseteq X \times X$ is a \mathcal{P} -bisimulation if for all $(x, y) \in R$:
 - (1) $\forall x' \in x \Rightarrow \exists y' \in y \text{ s.t. } (x', y') \in R$
 - and
 - (2) $\forall y' \in y \Rightarrow \exists x' \in x \text{ s.t. } (x', y') \in R$
- C.f. strong bisimulation on transition systems.

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Sets: examples of bisimulations



write $y \in x$ for $y \in \alpha(x)$

- E.g., for $x = \{x\}$ and $y = \{y\}$,

$R = \{(x, y)\}$ is a bisimulation relation

- E.g., for $x = \{x\}$ and $y = \{x, y\}$,

$R = \{(x, y), (x, x)\}$ is a bisimulation relation

- Strong-extensionality

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Example: deterministic automata

$$\begin{array}{c} X \\ \langle o, t \rangle \downarrow \\ 2 \times X^A \end{array}$$

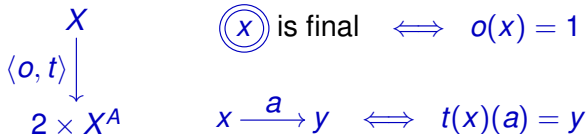
$$\textcircled{x} \text{ is final} \iff o(x) = 1$$

$$x \xrightarrow{a} y \iff t(x)(a) = y$$

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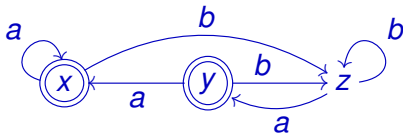
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Det. automata: bisimulation is language equivalence



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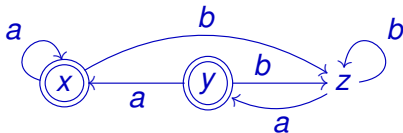
- Note that here bisimilarity is language (trace) equivalence:

$$L(x) = L(y)$$

. . . which confused the people from CONCUR for a while.

- Cf. ready, failure etc. equivalence [MFPS 2012].

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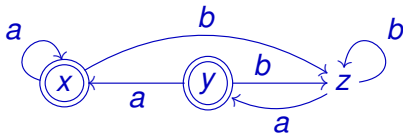
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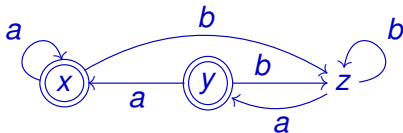
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Example: Streams

For a stream $\sigma = (\sigma(0), \sigma(1), \sigma(2), \dots) \in \mathbb{N}^\omega$,

- initial value: $\sigma(0)$
- derivative: $\sigma' = (\sigma(1), \sigma(2), \sigma(3), \dots)$



We call $R \subseteq \mathbb{N}^\omega \times \mathbb{N}^\omega$ a stream bisimulation if

$$\forall (\sigma, \tau) \in R : \sigma(0) = \tau(0) \text{ and } (\sigma', \tau') \in R$$

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$$\sigma \sim \tau \equiv \exists \text{ bisimulation } R \text{ s.t. } \langle \sigma, \tau \rangle \in R$$

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- We will illustrate the strength of the coinduction *proof* principle:

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- But first: *defining* streams with

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Stream differential equations

- Recall, for a stream $\sigma = (\sigma(0), \sigma(1), \sigma(2), \dots) \in \mathbb{N}^\omega$,
 - initial value (= head): $\sigma(0)$
 - derivative (= tail): $\sigma' = (\sigma(1), \sigma(2), \sigma(3), \dots)$
- Examples of stream differential equations:

initial value	derivative	solution
$\sigma(0) = 1$	$\sigma' = \sigma$	$(1, 1, 1, \dots)$
$\sigma(0) = 1$	$\sigma' = \sigma + \sigma$	$(2^0, 2^1, 2^2, \dots)$
$\sigma(0) = 1$	$\sigma' = \sigma \times \sigma$	$(1, 1, 2, 5, 14, 42, \dots)$

- Existence of unique solutions: by finality!

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A proof by coinduction: Moessner's theorem

- A. Moessner (1951), proof by O. Perron (1951) and I. Paasche (1952).
- Cf. Ralf Hinze: Scans and convolutions - a calculational proof of Moessner's theorem (Oxford University, 2010).
- Our proof: by coinduction (Niqui & R., 2011) . . .
- . . . is a student's exercise.
- Cf. the original proof: advanced binomial coefficient manipulation!!

Moessner's theorem ($k = 3$)

nat 1 2 3 4 5 6 7 8 9 10 11 12 ...

*Drop*₃ 1 2 4 5 7 8 10 11 ...

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Moessner's theorem (k=3)

$$\text{nat}^3 = \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat})$$

where $\text{nat} = (1, 2, 3, \dots)$ satisfies

$$\text{nat}(0) = 1 \quad \text{nat}' = \text{nat} + \text{ones}$$

with $\text{ones} = (1, 1, 1, \dots)$; and

$$\text{nat}^3 = (1^3, 2^3, 3^3, \dots) = \text{nat} \odot \text{nat} \odot \text{nat}$$

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$$(\sigma \odot \tau)(0) = \sigma(0) \cdot \tau(0) \quad (\sigma \odot \tau)' = \sigma' \odot \tau'$$

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$$\Sigma(\sigma) = (\sigma(0), \sigma(0) + \sigma(1), \sigma(0) + \sigma(1) + \sigma(2), \dots)$$

$$\text{Drop}_2(\sigma) = (\sigma(0), \sigma(2), \sigma(4), \dots)$$

$$\text{Drop}_3(\sigma) = (\sigma(0), \sigma(1), \sigma(3), \sigma(4), \sigma(6), \sigma(7), \dots)$$

can all be specified by elementary stream diff. equations.

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Proving Moessner's theorem

$$\text{nat}^3 = \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat})$$

- We use the *coinduction proof principle*: for all $\sigma, \tau \in \mathbb{N}^\omega$,

$$\sigma \sim \tau \Rightarrow \sigma = \tau$$

- So it suffices to construct a bisimulation R with

$$\langle \text{nat}^3, \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat}) \rangle \in R$$

- Easy, using the previous stream differential equations . . .

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Proof: We define R as the smallest set such that

- (i) $\langle \text{nat}^3, \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat}) \rangle \in R$
- (ii) $\langle \text{nat} \odot (\text{nat} + \text{ones})^2, \Sigma \circ \text{Drop}_2^0 \circ \Sigma \circ \text{Drop}_3^1(\text{nat}) \rangle \in R$
- (iii) if $\langle \sigma_1, \sigma_2 \rangle \in R$ and $\langle \tau_1, \tau_2 \rangle \in R$ then $\langle \sigma_1 + \tau_1, \sigma_2 + \tau_2 \rangle \in R$
- (iv) $\langle \sigma, \sigma \rangle \in R$ (all σ)

Then: R is a bisimulation relation.

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$$\text{nat}^3 = \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat})$$

Proof. We define R as the smallest set such that

- (i) $\langle \text{nat}^3, \Sigma \circ \text{Drop}_2 \circ \Sigma \circ \text{Drop}_3(\text{nat}) \rangle \in R$
- (ii) $\langle \text{nat} \odot (\text{nat} + \text{ones})^2, \Sigma \circ \text{Drop}_2^0 \circ \Sigma \circ \text{Drop}_3^1(\text{nat}) \rangle \in R$
- (iii) if $\langle \sigma_1, \sigma_2 \rangle \in R$ and $\langle \tau_1, \tau_2 \rangle \in R$ then $\langle \sigma_1 + \tau_1, \sigma_2 + \tau_2 \rangle \in R$
- (iv) $\langle \sigma, \sigma \rangle \in R$ (all σ)

Then: R is a bisimulation relation.

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- Every functor F has a notion of F -bisimulation . . .
- . . . and F -coinduction definition and proof principles.
- Next: *different* notions of bisimulation for *single* F .
- Again, we use *streams* as an example.
- Cf. Conway, R., Escardo & Pavlovic, Rosu, Kupke & R.

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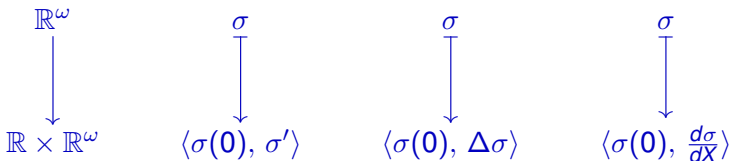
Different final coalgebra structures on \mathbb{R}^ω

$$\begin{array}{cccc} \mathbb{R}^\omega & & \sigma & & \sigma & & \sigma \\ \downarrow & & \downarrow & & \downarrow & & \downarrow \\ \mathbb{R} \times \mathbb{R}^\omega & & \langle \sigma(0), \sigma' \rangle & & \langle \sigma(0), \Delta\sigma \rangle & & \langle \sigma(0), \frac{d\sigma}{dX} \rangle \end{array}$$

where

- $\sigma' = (\sigma(1), \sigma(2), \sigma(3), \dots)$
- $\Delta\sigma = (\sigma(1) - \sigma(0), \sigma(2) - \sigma(1), \sigma(3) - \sigma(2), \dots)$
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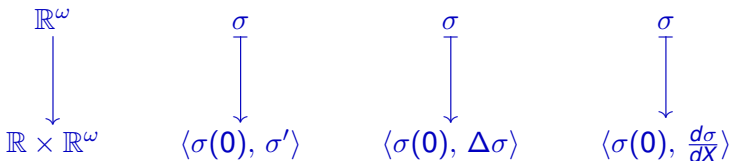
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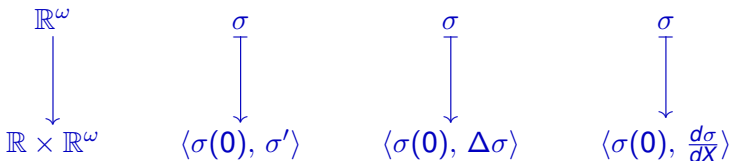
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Non-standard stream differential equations:

initial value derivative solution

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- $R \subseteq \mathbb{N}^\omega \times \mathbb{N}^\omega$ is a Δ -bisimulation if

$$\forall (\sigma, \tau) \in R : \sigma(0) = \tau(0) \text{ and } (\Delta\sigma, \Delta\tau) \in R$$

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$$\sigma \sim_{\Delta} \tau \equiv \exists \Delta\text{-bisimulation } R \text{ s.t. } \langle \sigma, \tau \rangle \in R$$

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An example of Δ -coinduction

- A generalised **Euler** formula (cf. **Taylor** series):

$$\sigma = \frac{(\Delta^0\sigma)(0) \times X^0}{(1-X)^1} + \frac{(\Delta^1\sigma)(0) \times X^1}{(1-X)^2} + \frac{(\Delta^2\sigma)(0) \times X^2}{(1-X)^3} + \dots$$

- *Proof:* Using

$$\Delta\left(\frac{X^{n+1}}{(1-X)^{n+2}}\right) = \frac{X^n}{(1-X)^{n+1}}$$

one easily shows that

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Yet another final coalgebra structure on streams

$$\begin{array}{ccc}
 \mathbb{N}^\omega & & \sigma \\
 \downarrow & & \downarrow \\
 \mathbb{N} \times \mathbb{N}^\omega \times \mathbb{N}^\omega & & \langle \text{head}(\sigma), \text{even}(\sigma), \text{odd}(\sigma) \rangle
 \end{array}$$

where

- $\text{head}(\sigma) = \sigma(0)$
- $\text{even}(\sigma) = (\sigma(0), \sigma(2), \sigma(4), \dots)$
- $\text{odd}(\sigma) = (\sigma(1), \sigma(3), \sigma(5), \dots)$

Final among *zero*-consistent systems

If S is *zero*-consistent:

$$\begin{array}{ccc}
 S & & \forall s \in S, \quad o(l(s)) = o(s) \\
 \langle o, l, r \rangle \downarrow & & \\
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{head, even, odd}-differential equations

Ex.

$$\text{head}(\tau) = 0 \quad \text{even}(\tau) = \tau \quad \text{odd}(\tau) = \rho$$

$$\text{head}(\rho) = 0 \quad \text{even}(\rho) = \tau \quad \text{odd}(\rho) = \tau$$

has as unique solution

$$\tau = 0110100110010110 \dots$$

Thue-Morse

(and its complement)

- {head, even, odd}-bisimulation
- {head, even, odd}-coinduction
- Cf. Kupke & R. [2010,2011].

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Future

1. For instance: classifying SDEs
2. For instance: bisimulation-up-to
3. For instance: . . .

Classifying SDEs

initial value	derivative	solution
$\sigma(0) = 1$	$\sigma' = \sigma$	$(1, 1, 1, \dots)$
$\sigma(0) = 1$	$\sigma' = \sigma + \sigma$	$(2^0, 2^1, 2^2, \dots)$
$\sigma(0) = 1$	$\sigma' = \sigma \times \sigma$	$(1, 1, 2, 5, 14, 42, \dots)$
$\sigma(0) = 1$	$\Delta\sigma = \sigma$	$(2^0, 2^1, 2^2, \dots)$
$\sigma(0) = 1$	$\frac{d\sigma}{dX} = \sigma$	$(\frac{1}{0!}, \frac{1}{1!}, \frac{1}{2!}, \frac{1}{3!}, \dots)$
$\sigma(0) = 0$	$\text{even}(\sigma) = \sigma$ $\text{odd}(\sigma) = \bar{\sigma}$	Thue-Morse