Enhancing the effective utilisation of Grid clusters by exploiting on-line performability analysis

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Joint work with Anne Benoit, Murray Cole and Jane Hillston

Outline

- Challenges of Grid performability
 - Addressing the challenges
 - Modelling and analysis
- Performance modelling with process algebras
 - Performance Evaluation Process Algebra
 - PEPA model of jobs and servers
 - Analysis of the model
- 3 A failure/repair model
 - Analysis of the failure/repair model
- 4 Commentary and comparison

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Addressing the challenges Modelling and analysis

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Addressing the challenges Modelling and analysis

Challenges of Grid performability

Grid computing is characterised by

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Addressing the challenges Modelling and analysis

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Addressing the challenges Modelling and analysis

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 - provide a parametric analysis which scales to large job sizes
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- scale
 - provide a parametric analysis which scales to large job sizes
- failures
 - allow custom recovery procedures to be specified

Addressing the challenges Modelling and analysis

Addressing the challenges

• Use a high-level programming model to structure code.

• Use a high-level modelling language to analyse performance.

Addressing the challenges Modelling and analysis

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 - Cole's "algorithmic skeletons" (eSkel library)
- Use a high-level modelling language to analyse performance.
 - Hillston's Performance Evaluation Process Algebra (PEPA)

Addressing the challenges Modelling and analysis

Modelling and analysis

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- We map PEPA models into ordinary differential equations (ODEs) for solution.
- The analysis is supported by an automated tool which handles the transformation from the high-level process algebra model into ODEs and numerical integration.
- The results are returned to the user as a plot of the numbers of model components as a function of time.

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Performance Evaluation Process Algebra PEPA model of jobs and servers Analysis of the model

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Performance Evaluation Process Algebra

PEPA components perform activities either independently or in co-operation with other components.

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The rate at which an activity is performed is quantified by some component in each co-operation. The symbol \top indicates that the rate value is quantified elsewhere (not in this component).

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$$\begin{array}{ll} (\alpha,r).P & \operatorname{Prefix} \\ P_1+P_2 & \operatorname{Choice} \\ P_1 \Join P_2 & \operatorname{Co-operation} \\ P/L & \operatorname{Hiding} \\ X & \operatorname{Variable} \end{array}$$

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Derived forms and additional syntax

 $P_1 \parallel P_2$ is a derived form for $P_1 \bowtie P_2$.

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When working with large numbers of jobs and servers, we write P[n] to denote an array of *n* copies of *P* executing in parallel.

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$$P[5] \equiv (P \parallel P \parallel P \parallel P \parallel P)$$

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Modelling jobs and nodes

Consider jobs with a number of ordered stages. (Here three.)

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Jobs must be loaded onto a node before execution. Stage 1 must be completed before Stage 2 and Stage 2 before Stage 3. After Stage 3 the job is cleared by being unloaded from the node, and is then finished.

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Here the number of compute jobs is larger than the number of nodes available to execute them. Nodes specify the rate at which jobs are completed.

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PEPA model of jobs and nodes

Jobs

 $\begin{array}{rcl} Job & \stackrel{\text{def}}{=} & (load, \top). Job1 \\ Job1 & \stackrel{\text{def}}{=} & (stage1, \top). Job2 \\ Job2 & \stackrel{\text{def}}{=} & (stage2, \top). Job3 \\ Job3 & \stackrel{\text{def}}{=} & (stage3, \top). Clearing \\ Clearing & \stackrel{\text{def}}{=} & (unload, \top). Finished \\ Finished & \stackrel{\text{def}}{=} & Stop \end{array}$

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PEPA model of jobs and nodes

Nodes

Nodeldle	def =	$(load, r_0).Node1$
Node1	def =	$(stage1, r_1).Node2$
Node2	def =	$(stage 2, r_2)$.Node3
Node3	def 	$(stage3, r_3)$. Node4
Node4	def =	(unload, r ₀).Nodeldle

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PEPA model of jobs and nodes

System

Nodeldle[100] \bowtie Job[1000]

where *L* is { *load*, *stage1*, *stage2*, *stage3*, *unload* }.

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Analysis of the model

Analysis of the model proceeds by choosing particular values for the rates. The values below are chosen to make the analysis easy to follow.

Rate	Value	Interpretation
<i>r</i> ₀	1	(Un)loading takes one time unit
r_1	0.1	Stage 1 takes ten time units
r_2	0.05	Stage 2 takes twenty time units
r_3	0.025	Stage 3 takes forty time units

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Analysis of the model: Nodes



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Analysis of the model: Jobs



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Analysis of the failure/repair model

A failure/repair model

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We take the modelling decision to ignore the potential failures which could occur during the very brief stages of loading and unloading jobs.

A failure/repair model

Analysis of the failure/repair model

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We model a failure and repair cycle taking a job back to re-execute the present stage (rather than restart the execution of the job from the beginning).

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Nodes

Nodeldle	def =	(load, r ₀).Node1
Node1	def =	$(stage1, r_1)$. Node2 + $(fail1, r_4)$. NodeFailed1
Node2	def =	$(stage 2, r_2)$. Node $3 + (fail 2, r_4)$. Node Failed 2
Node3	def ==	$(stage3, r_3)$. Node4 + $(fail3, r_4)$. NodeFailed3
Node4	def =	(unload, r ₀).Nodeldle
NodeFailed1	def =	(repair1, r ₅).Node1
NodeFailed2	def =	(repair2, r ₅).Node2
NodeFailed3	def =	(repair3, r ₅).Node3

Failure rates

Analysis of the failure/repair model

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With regard to the rates of failure of jobs, we estimate that one in ten jobs may fail during stage 3 (and so one in 20 during stage 2 and one in 40 during stage 1) and that the cost of repairs is relatively high, perhaps requiring a reboot of the failed node.

Rate	Value	Interpretation
r ₄	0.0025	On average 1 in 10 stage 3
		jobs will fail
r 5	0.0025	Repairing may require the reboot
		of a node

Analysis of the failure/repair model

Analysis of the failure/repair model: Nodes



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Analysis of the failure/repair model

Analysis of the failure/repair model: Jobs



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- Steady-state is cheaper but less informative. Transient is more informative but more expensive.

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- Major drawback: state-space explosion. Generating the state-space is slow. Solving the CTMC is slow.

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- Steady-state is cheaper but less informative. Transient is more informative but more expensive.
- Major drawback: state-space explosion. Generating the state-space is slow. Solving the CTMC is slow.
- In practice effective only to systems of size 10⁶ states, even when using clever storage representations.

Commentary and comparison

• Mapping PEPA to ODEs admits *course-of-values* analysis by solving the ODE (akin to transient analysis).

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Commentary and comparison

- Mapping PEPA to ODEs admits *course-of-values* analysis by solving the ODE (akin to transient analysis).
- Major benefit: avoids state-space generation entirely.
- Major benefit: ODE solving is effective in practice. (Suitable for on-line scheduling?)
- Effective for systems of size 2^{10^6} states and beyond.