

# Searching for middle ground with PEPA

Jane Hillston

Laboratory for Foundations of Computer Science  
The University of Edinburgh, Scotland

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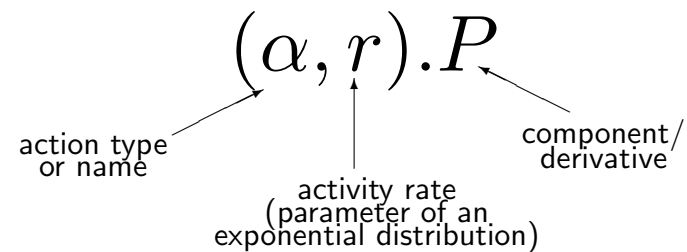
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# Introduction

- The PEPA formalism
- Integration via tools
  - Solvers
  - Specification
- Integration at the formalism level
- Outlook and on-going work

# Performance Evaluation Process Algebra (PEPA)

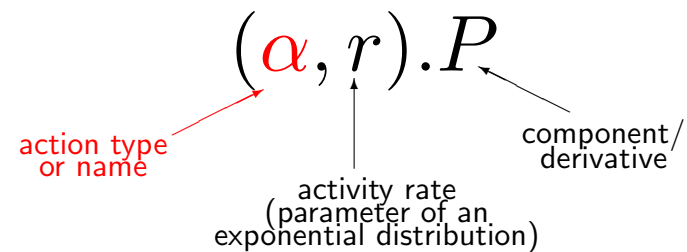
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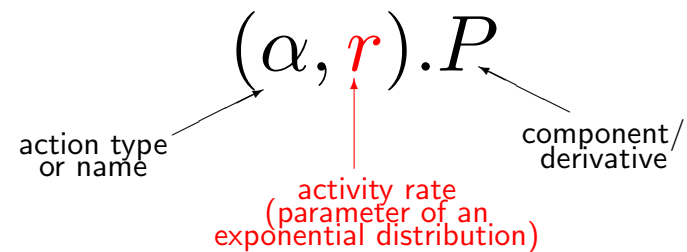
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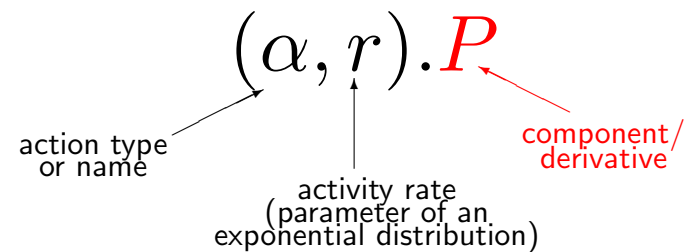
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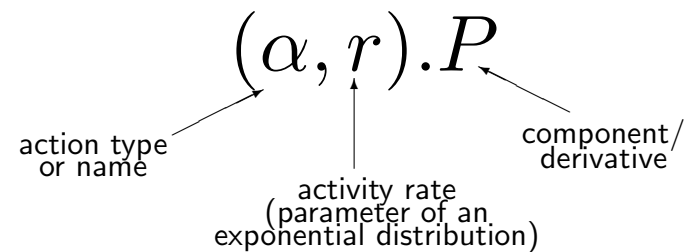
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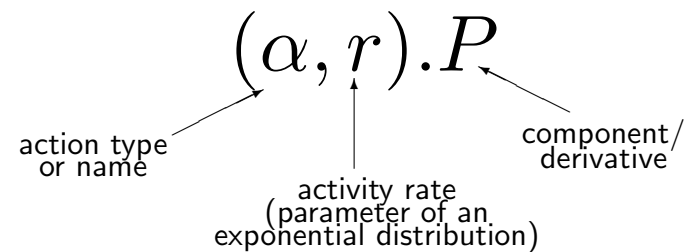
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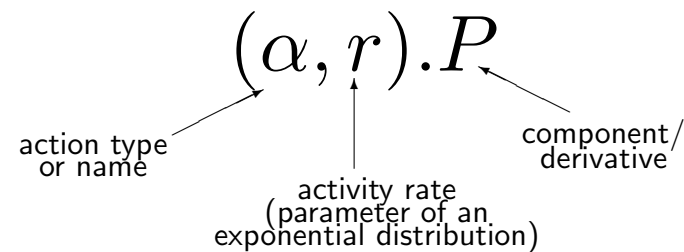
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## PEPA MODEL



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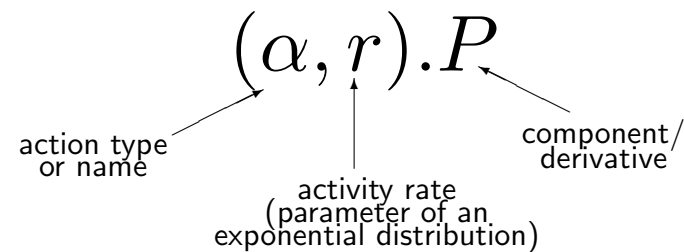


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PEPA MODEL  $\xrightarrow{\text{SOS rules}}$

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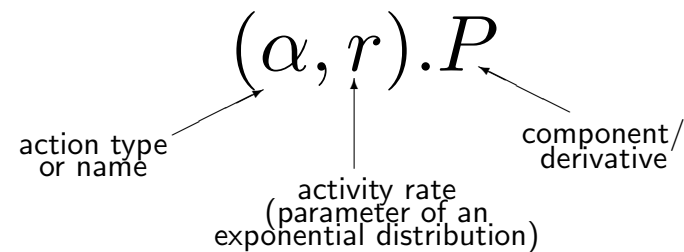


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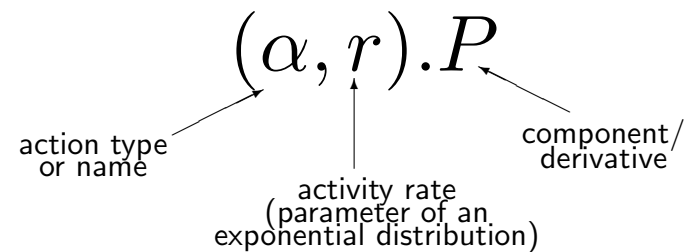


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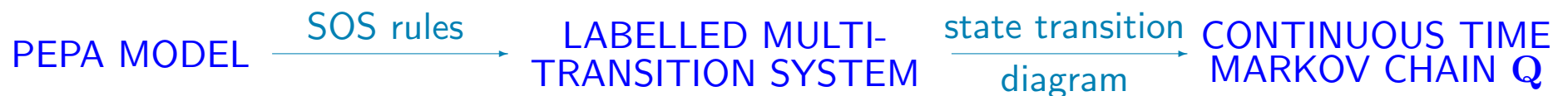


# Performance Evaluation Process Algebra (PEPA)

- Models are constructed from **components** which engage in **activities**.



- The language is used to generate a CTMC for performance modelling.



## The syntax of PEPA

$S ::=$  *(sequential components)*  
 $(\alpha, r).S$  *(prefix)*  
 $| S + S$  *(choice)*  
 $| I$  *(identifier)*

$P ::=$  *(model components)*  
 $P \bowtie_L P$  *(cooperation)*  
 $| P/L$  *(hiding)*  
 $| I$  *(identifier)*

---

# Tools and Integration



**PEPA**

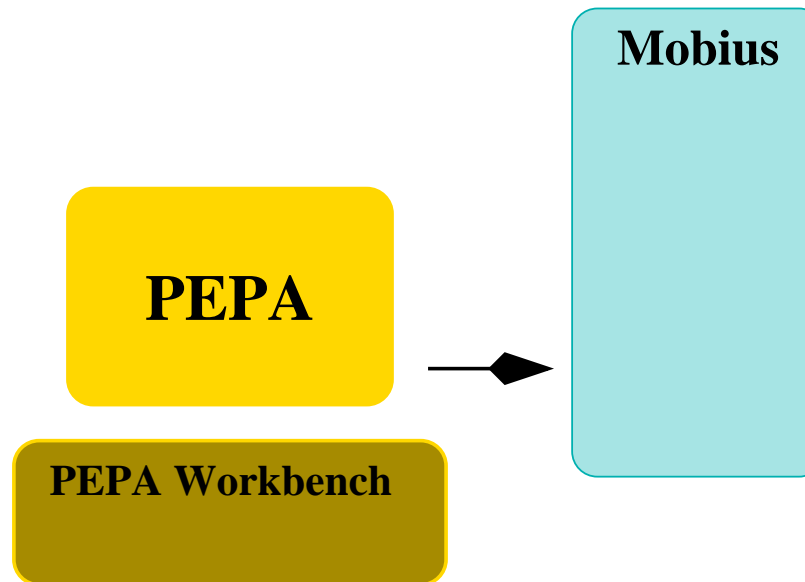
# Tools and Integration

The diagram consists of two vertically stacked rounded rectangular boxes. The top box is yellow and contains the text 'PEPA'. The bottom box is olive green and contains the text 'PEPA Workbench'.

**PEPA**

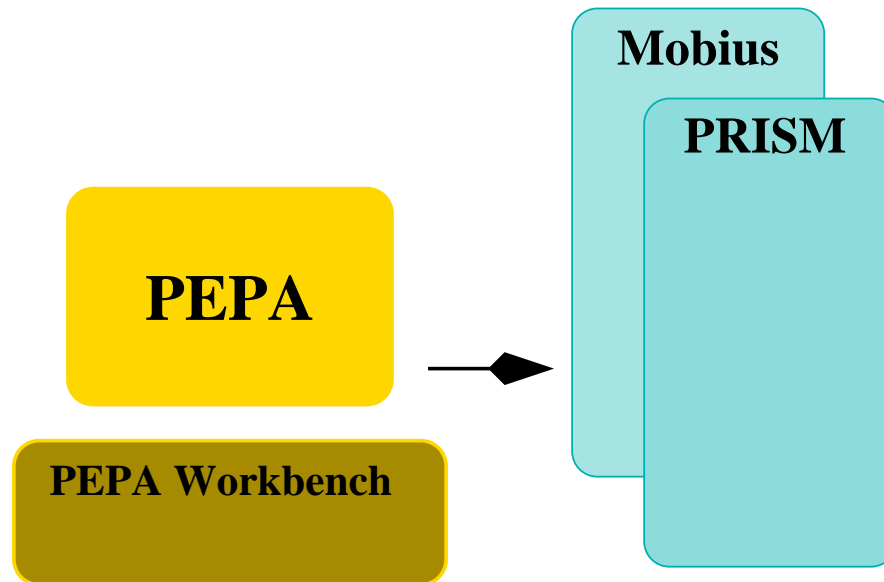
**PEPA Workbench**

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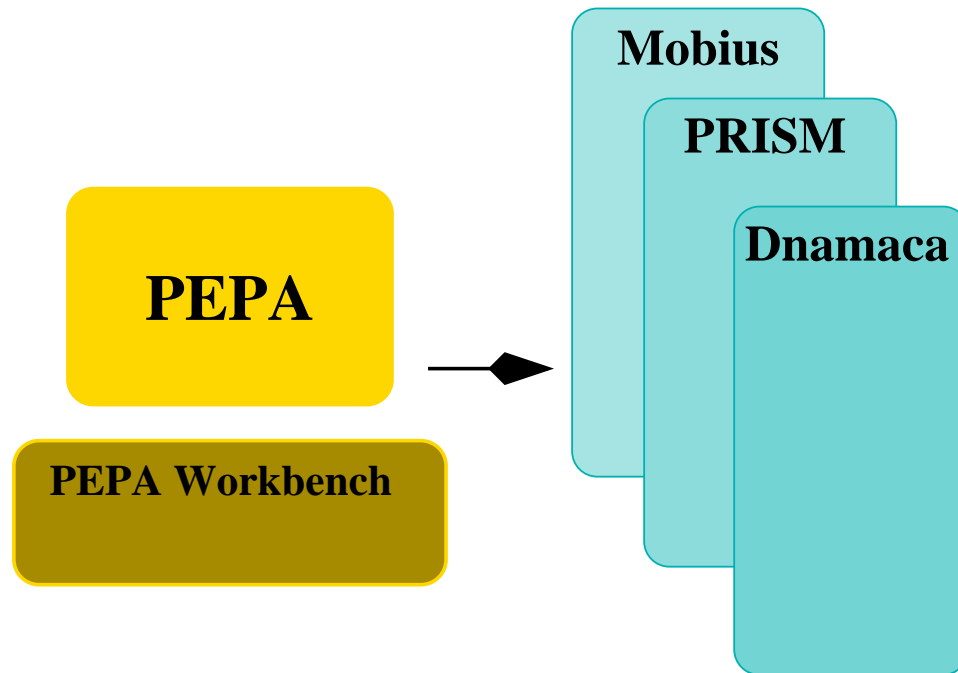




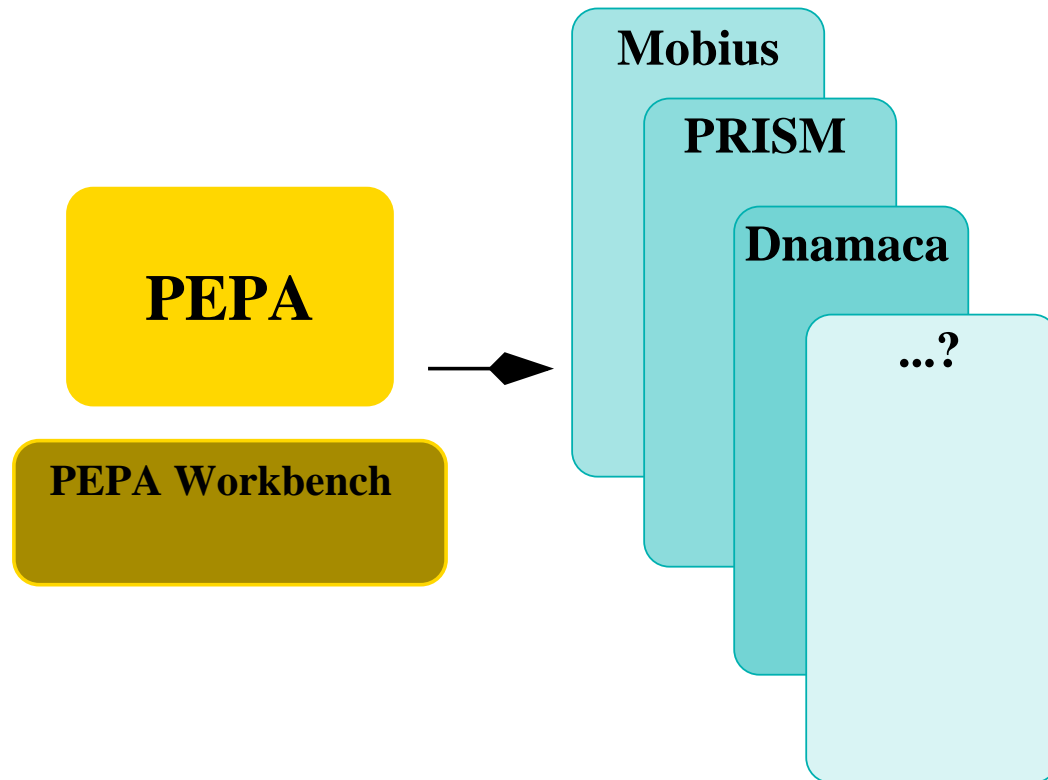
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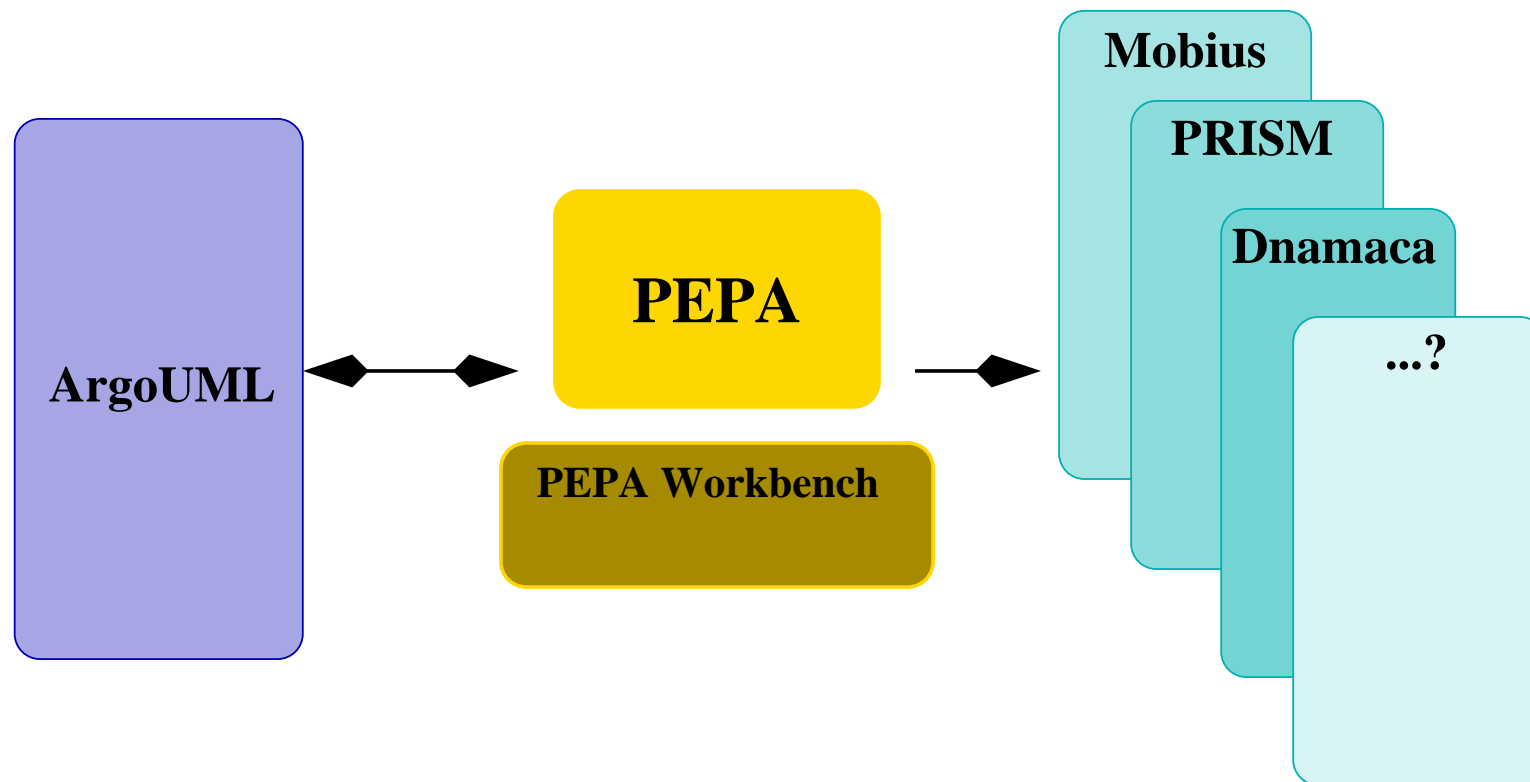
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## A first PEPA tool: The PEPA Workbench

- Our first PEPA tool was the PEPA Workbench, implemented in Standard ML.
- The PEPA syntax can be represented simply as an ML datatype.

```
datatype Component =
  PREFIX of (Activity * Rate) * Component      (* . *)
| CHOICE of Component * Component             (* + *)
| COOP of Component * Component * Activity list (* ⊗ *)
| HIDING of Component * Activity list         (* / *)
| VAR of Identifier                           (* X *)
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## Beyond ML

- With the ML edition of the PEPA Workbench it was possible to solve small models using exterior solvers such as Maple and Matlab.
- However, users of the workbench wanted to make more detailed models (with larger state spaces).
- The ML edition of the PEPA Workbench could not solve Robert Holton's robotic workcell model efficiently enough so we interfaced it with an external solver written in C.
- Other users wanted to run the workbench on Solaris, Windows and Linux machines so we ported the Workbench and the solver to Java.

The PEPA Workbench [Java edition, 21-1-2003]

File Options Run Show **Solver** Experiment Simulate

Status Complete

Solve for steady state solution

Set steady state solver parameters

Solve for transient solution

Set transient solver parameters

Solve via successive over-relaxation

Set SOR solver parameters

Stop

```

54 P14 <{reg14}> S14' <{reg1
55 P15 <{reg14}> S14' <{reg1
56 P16 <{reg14}> S14' <{reg1
57 P14 <{reg14}> S14' <{reg1
58 P15 <{reg14}> S14' <{reg1
59 P15 <{reg14}> S14 <{reg1
60 P14 <{reg14}> S14 <{reg16, rep14}> DB15 <{rep16}> S16' <{reg15, rep15}> S15
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72 P14 <{reg14}> S14' <{reg16, rep14}> DB16 <{rep16}> S16' <{reg15, rep15}> S15'

```

States found	72	Transitions found	240
Number of iterations		Error value	

## PEPA in Möbius

- Graham Clark implemented an editor for PEPA in the Möbius multi-paradigm modelling framework, extending PEPA to  $PEPA_k$  with guards and parameters.

```
Consume[a,b] = [a > 0] => (outa, ar).Consume[a-1,b]
+ [(b > 0) && (a == 0)] => (outb, br).Consume[a,b-1];
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Breakdown = (outa, T).Breakdown
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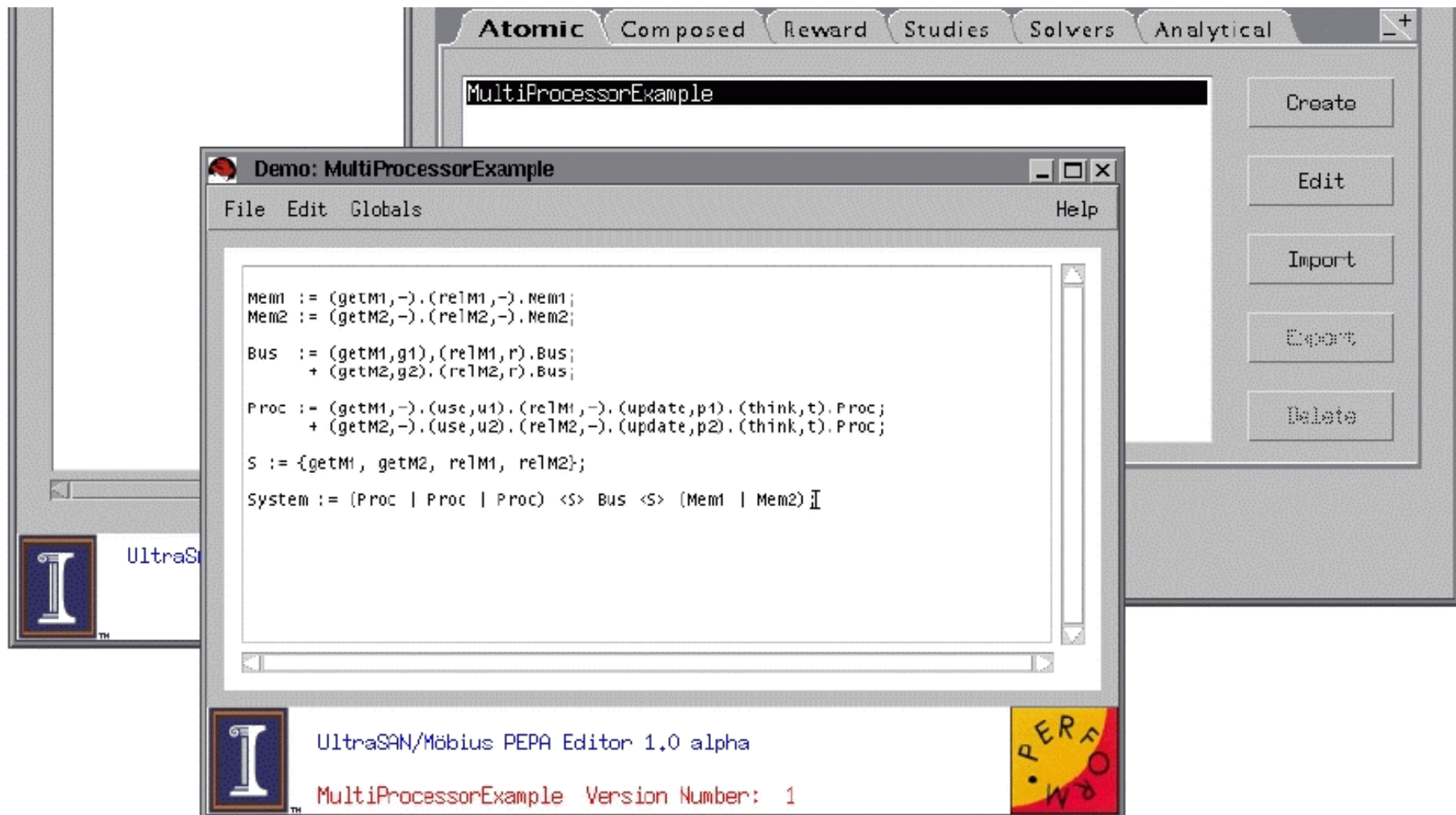
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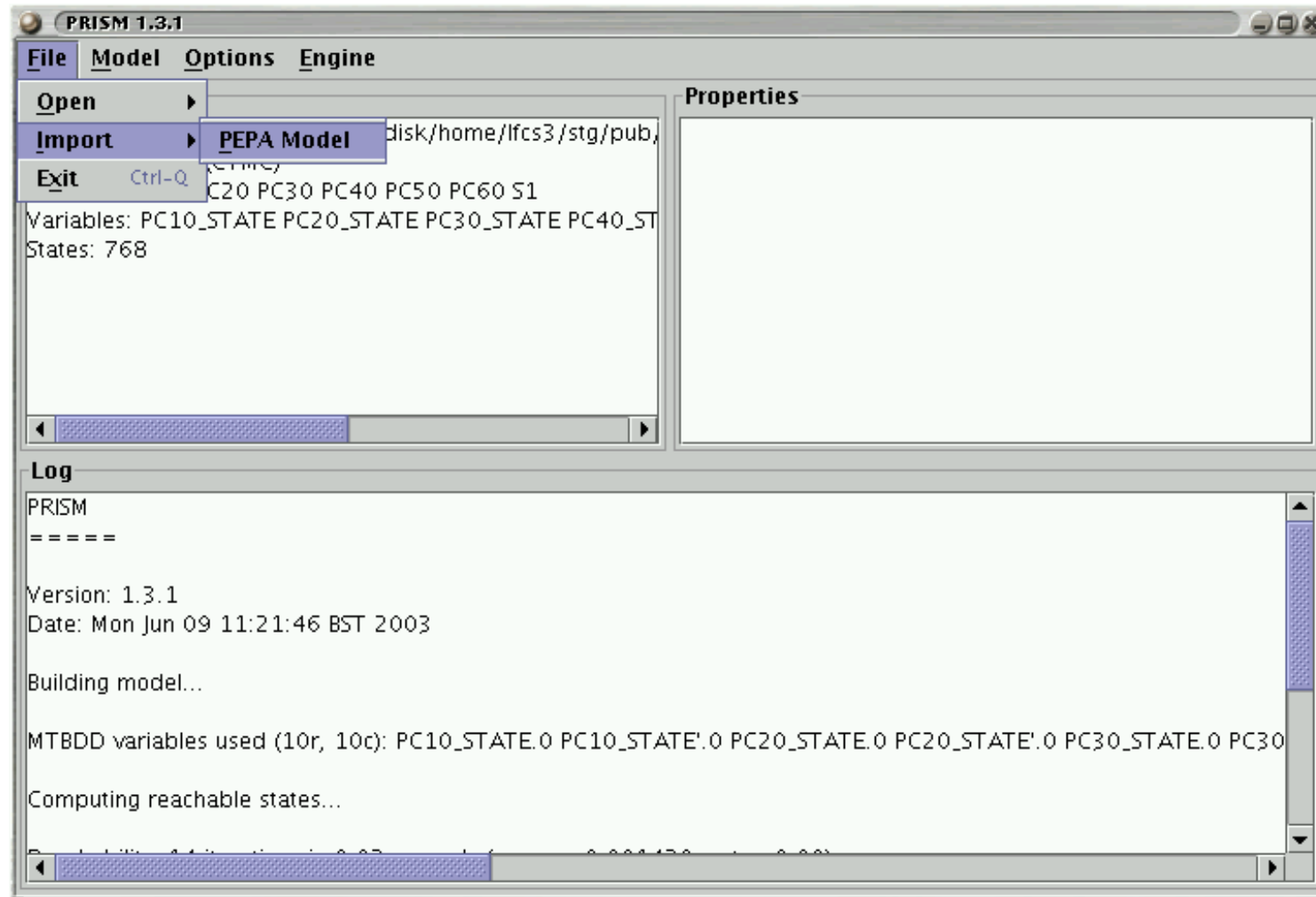
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## PEPA and PRISM

- PRISM is a probabilistic model checker which supports modelling in DTMCs, CTMCs and MDPs with PTCL and CSL model checking.
- The matrix storing the state space of the system is expressed as an MTBDD built using the CUDD package.
- Support for the PEPA language in PRISM was provided in two steps:
  1. extending the PRISM input language with a new **system** construct providing the PEPA composition operators for synchronisation over activity sets and hiding; and
  2. compiling the PEPA language into the extended PRISM language.



## PEPA modelling with PRISM

- PEPA modelling with PRISM has proved to be very effective in practice. The largest PEPA model so far solved has been solved with PRISM.
- However, there are a number of places where the user needs to understand the tool chain thoroughly:
  - The PEPA-to-PRISM compiler rejects (valid) PEPA models which use active/active synchronisation or anonymous components;
  - The compiler can fail during compilation with Java stack overflow;
  - PRISM can reject models which the PEPA-to-PRISM compiler outputs;
  - The CUDD package can fail with out-of-memory errors and need to be reconfigured.

## PEPA and IPC/Dnamaca

The Imperial PEPA compiler (IPC) compiles PEPA models into Petri nets which are solved with the Dnamaca solver. Dnamaca provides a number of numerical solvers and outperforms PRISM on small PEPA models.

```

P1 = (start, r1).P2; =
    \transition{P1_start} {
        %% PEPA action type { start }
        \condition{ P1 > 0 }
        \action {
            next -> P1 = P1 - 1;
            next -> P2 = P2 + 1;
        }
        \priority{1}
        \rate{ PEPA_r1 }
    }

```

## Synchronisation in Dnamaca

Suppose that two copies of P synchronise on the **run** activity.

```

P2 = (run, r2).P3; =
    \transition{P2_run__P2_1_run} {
        %% PEPA action type { run }
        \condition{ P2 > 0 && P2_1 > 0 }
        \action {
            next -> P2_1 = P2_1 - 1;
            next -> P3_1 = P3_1 + 1;
            next -> P2 = P2 - 1;
            next -> P3 = P3 + 1;
        }
        \priority{1}
        \rate{ PEPA_r2 }
    }

```



## PEPA modelling with IPC and Dnamaca

- More of the PEPA language is supported by IPC/Dnamaca than by PRISM. Active/active synchronisation and anonymous components are supported.
- However, there are still a number of places where the user needs to understand the tool chain thoroughly:
  - The IPC compiler can fail during compilation with Haskell memory exhaustion;
  - Dnamaca can reject models which IPC outputs; and
  - Dnamaca's numerical procedures can fail to converge.

## Dnamaca features and PEPA extensions

- Because Dnamaca supports non-Markovian modelling, beyond the models which are expressible in PEPA, it would be possible to support PEPA extensions with Dnamaca:
  - PEPA<sub>k</sub> guards and parameters; *[Clark, Sanders, '01]*
  - Weighted (WSCCS-style) PEPA; *[Bradley, '02]*
  - PEPA nets with priorities; *[Gilmore, Hillston, Ribaud, Kloul, '03]*
  - Semi-Markov PEPA; *[Bradley, '03]*
  - . . . .

## PEPA and Stochastic Petri nets

Since the initial development, the relationship between PEPA and stochastic Petri nets has been studied and investigated.

- Marina Ribaudó developed an SPN semantics for PEPA in her thesis [1994].
- She also investigated the relationship between the aggregation offered within PEPA and that offered by Stochastic Well-formed Nets [1995].
- Donatelli, Hermanns, Hillston and Ribaudó informally investigated the expressiveness of the two formalisms via case study [1995].
- Hillston, Recalde, Ribaudó and Silva developed a compositional mapping from bounded SPNs to PEPA models [2001].

## Petri nets and process algebras

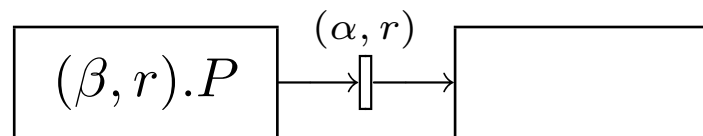
- Petri nets provide a **graphical presentation** of a model which has an easily accessible interpretation and they also have the advantage of being supported by an unambiguous formal interpretation.
- Stochastic process algebras lack the attractive graphical presentation of Petri nets. In contrast though, an **explicit compositional structure** is imposed on the model. This structure can be exploited for both qualitative and quantitative analysis.
- The present work considers using both Petri nets and process algebras together as a single, **structured** performance modelling formalism.

## PEPA nets

- **Coloured Petri nets** are a high-level form of classical Petri nets. The plain (indistinguishable) tokens of a classical Petri net are replaced by arbitrary terms which are distinguishable.
- In **stochastic Petri nets** the transitions from one marking to another are associated with a random variable drawn from an exponential distribution. Here we consider **coloured stochastic Petri nets** where the colours used as the tokens of the net are PEPA components. We refer to these as **PEPA nets**.
- Petri nets have previously been combined with other performance modelling formalisms e.g. Bause's **Queueing Petri nets** and Haverkort's **Dynamic Queueing Networks**. Other extensions of (non-stochastic) Petri nets have programmable tokens, e.g. Valk's **Elementary Object systems**.

## Transitions in a PEPA net

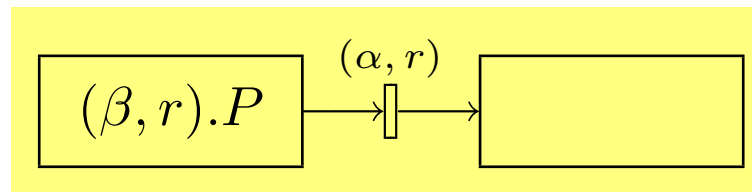
- A **transition** in a PEPA net takes place whenever a transition of a PEPA component can occur (either individually, or in co-operation with another component at the same place).



- Transitions of PEPA components are used to model small-scale changes of state as components undertake activities. The PEPA net formalism does not allow components at different places in the net to co-operate on a shared activity so transitions have only **local** effect.

## Transitions in a PEPA net

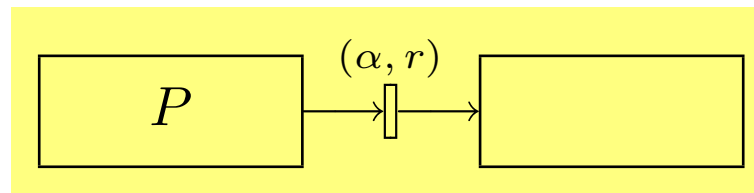
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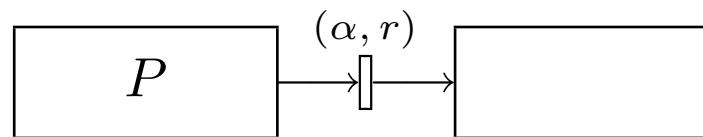


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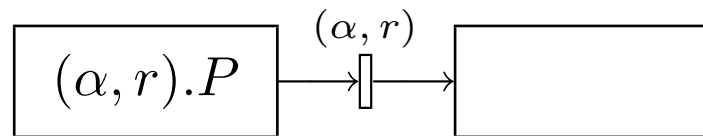
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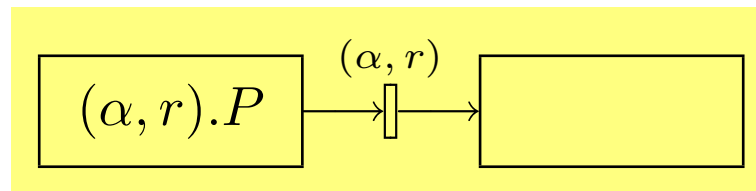
- **Firings** in a PEPA net are used to model macro-step changes of state such as breakdowns and repairs, one thread yielding to another, or a mobile software agent moving from one network host to another.



- A firing causes the transfer of one token from one place to another. The token which is moved is a PEPA component, which causes a change in both the **input place** (where existing co-operations now can no longer take place) and the **output place** (where previously disabled co-operations are now enabled).

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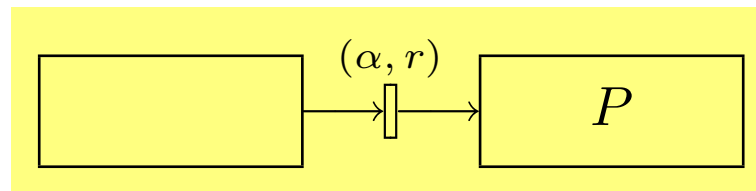
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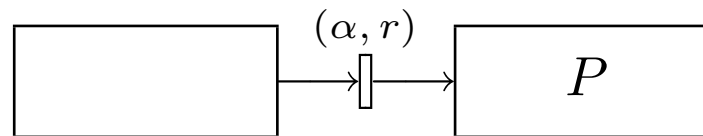
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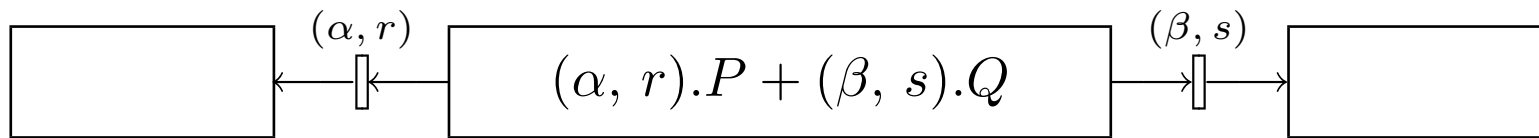
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- A firing causes the transfer of one token from one place to another. The token which is moved is a PEPA component, which causes a change in both the **input place** (where existing co-operations now can no longer take place) and the **output place** (where previously disabled co-operations are now enabled).

## Choice in a PEPA net

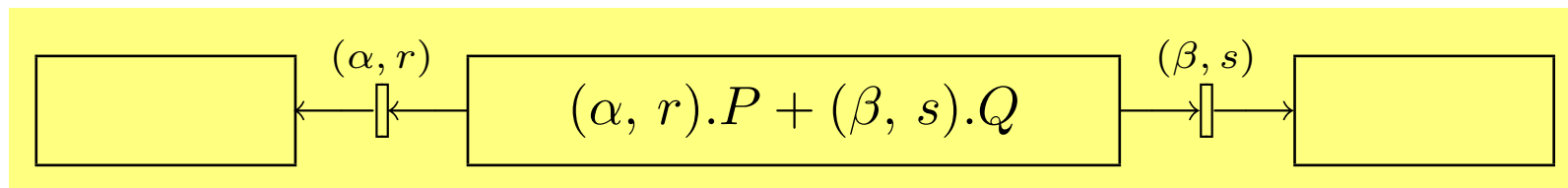
- Choices in a PEPA net occur when the token has a choice of possible behaviours and a choice of possible output places. Choices are used to model decisions in a system.



- The outcome of a choice is governed by a **race condition**.

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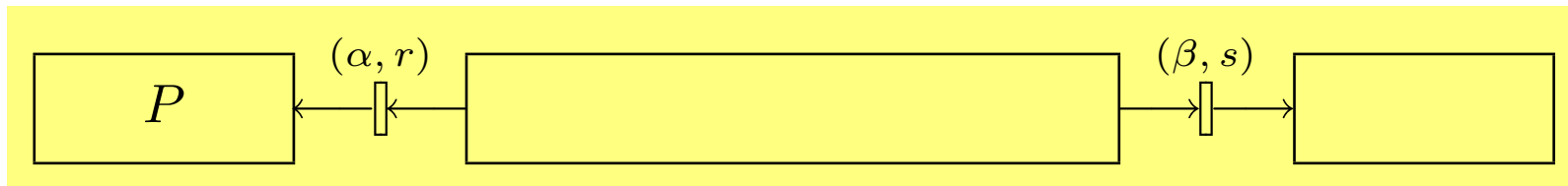
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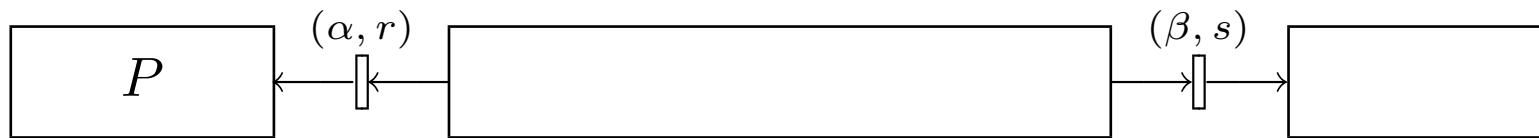


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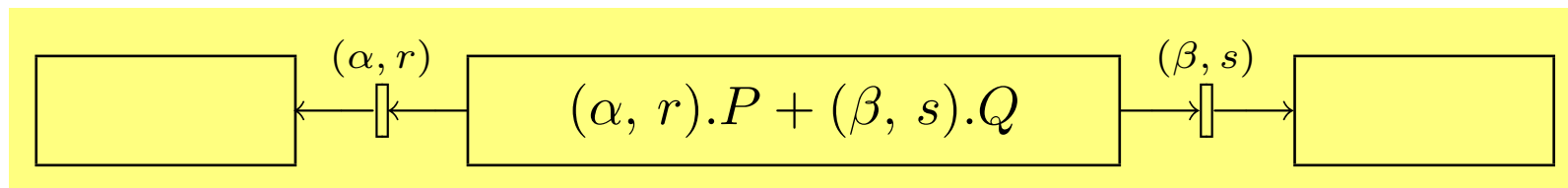
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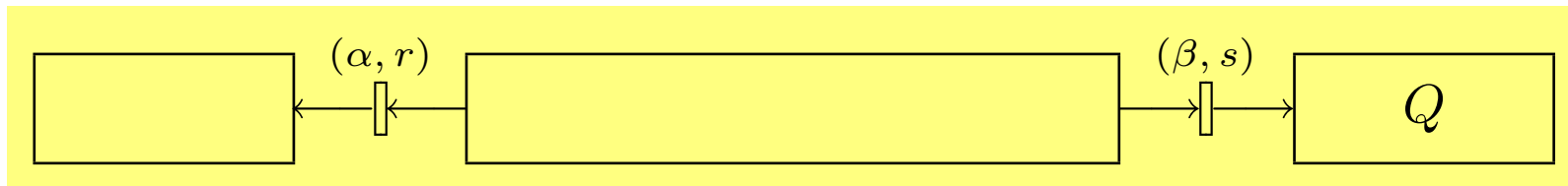
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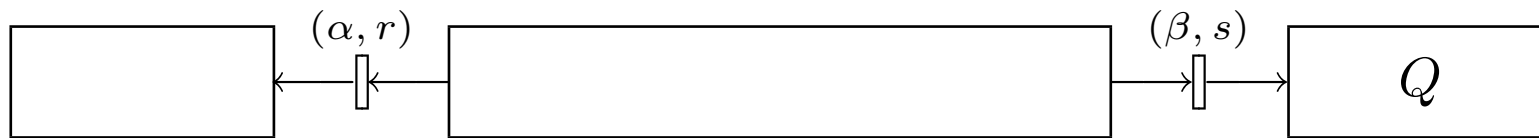
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## Markings in a PEPA net

- The marking of a PEPA net is made up of a list of PEPA **contexts**, one at each place in the net, where the system descriptions can also contain component **cells**.
- A cell is a slot to be filled by a component of a particular type.
  - Components which fill these cells can circulate as the tokens of the net.
  - Components which are not in a cell are static and cannot move.
- We use the notation  $P[-]$  to denote a context or a place which could be filled by the PEPA component  $P$  or one with the same alphabet.

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## The syntax of PEPA with cells

$S ::=$  *(sequential components)*  
 $(\alpha, r).S$  *(prefix)*  
 $| S + S$  *(choice)*  
 $| I$  *(identifier)*

$P ::=$  *(model components)*  
 $P \underset{L}{\bowtie} P$  *(cooperation)*  
 $| P/L$  *(hiding)*  
 $| I$  *(identifier)*  
 $| P[C]$  *(cell)*

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		$S + S$	( <i>choice</i> )		
		$I$	( <i>identifier</i> )		
				$C$	$::=$
					( <i>cell terms</i> )
$P$	$::=$		( <i>model components</i> )		'-'
		$P \boxtimes_L P$	( <i>cooperation</i> )		$P$
		$P/L$	( <i>hiding</i> )		( <i>component</i> )
		$I$	( <i>identifier</i> )		
		$P[C]$	( <i>cell</i> )		

## Example: a mobile agent system

- In this example *a roving agent* visits three sites. It interacts with static software components at these sites and has two kinds of interactions.
- When visiting a site where *a network probe* is present it interrogates the probe for the data which it has gathered on recent patterns of network traffic.
- When it returns to the central co-ordinating site it dumps the data which it has harvested to *the master probe*. The master probe performs a computationally expensive statistical analysis of the data.
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## PEPA components

$$Agent \stackrel{def}{=} (\mathbf{go}, \lambda).Agent'$$

$$Agent' \stackrel{def}{=} (interrogate, r_i).Agent''$$

$$Agent'' \stackrel{def}{=} (\mathbf{return}, \mu).Agent'''$$

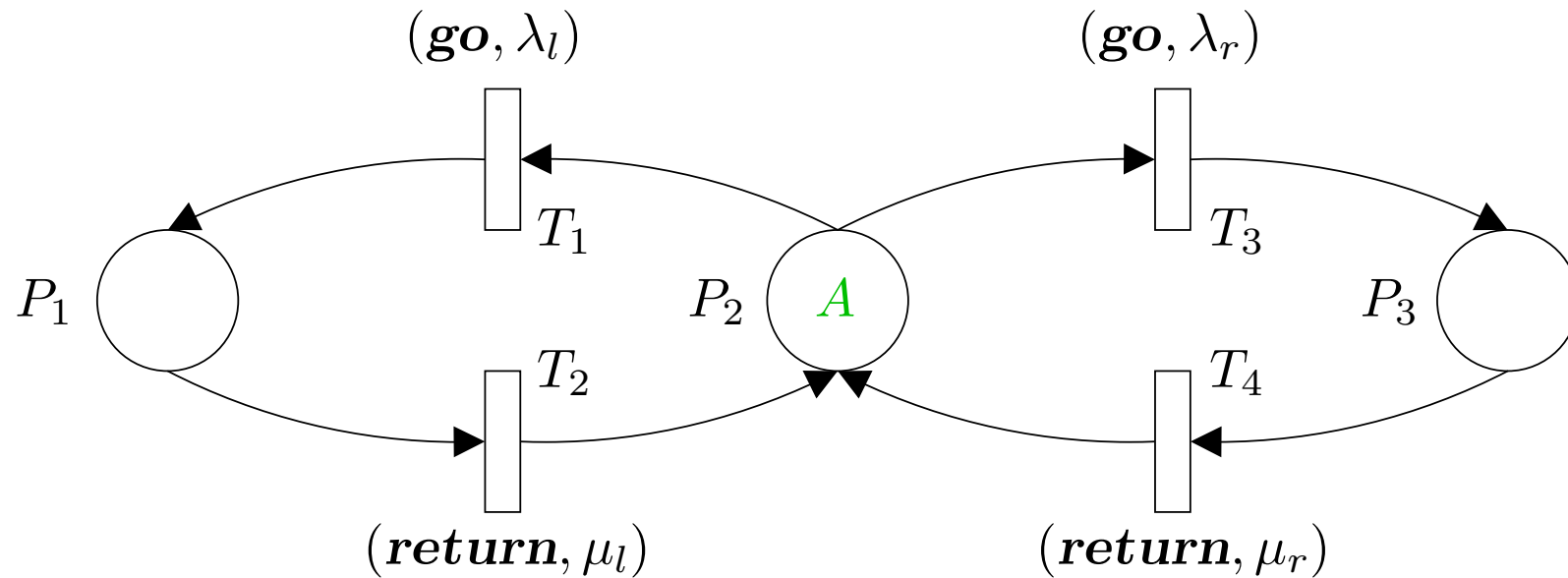
$$Agent''' \stackrel{def}{=} (dump, r_d).Agent$$

$$Master \stackrel{def}{=} (dump, \top).Master'$$

$$Master' \stackrel{def}{=} (analyse, r_a).Master$$

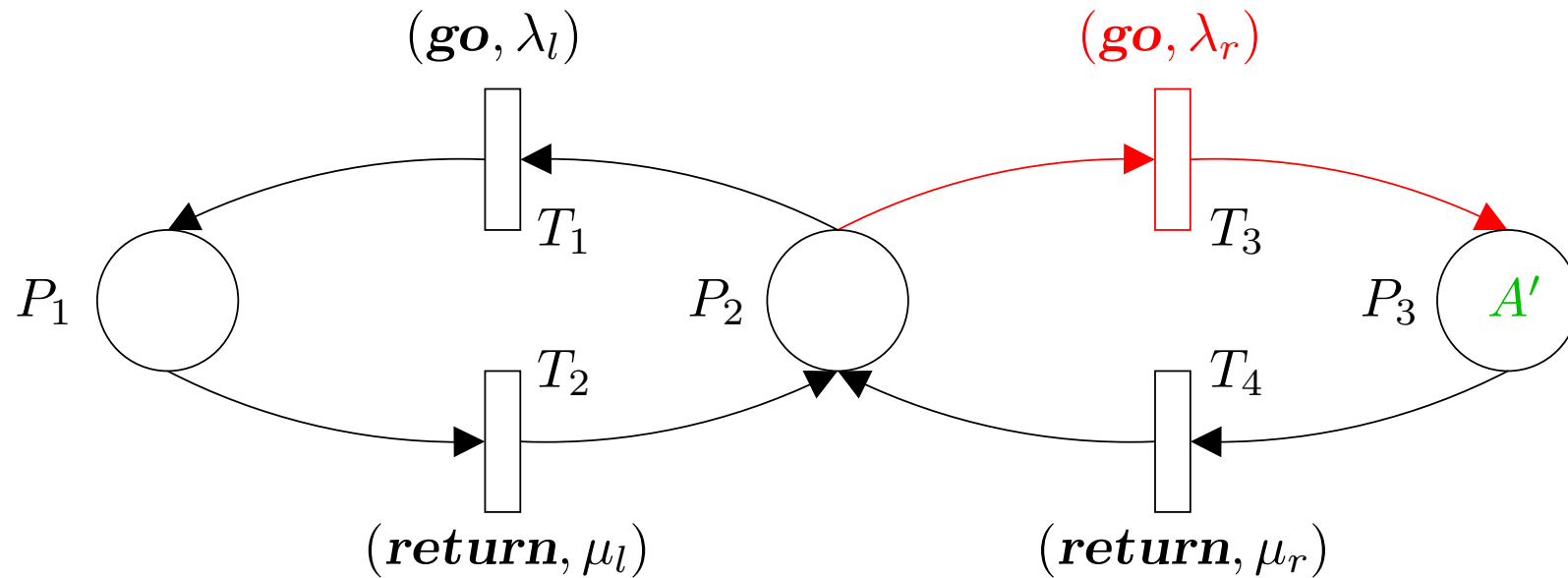
$$Probe \stackrel{def}{=} (monitor, r_m).Probe + (interrogate, \top).Probe$$

## A mobile agent system (1)



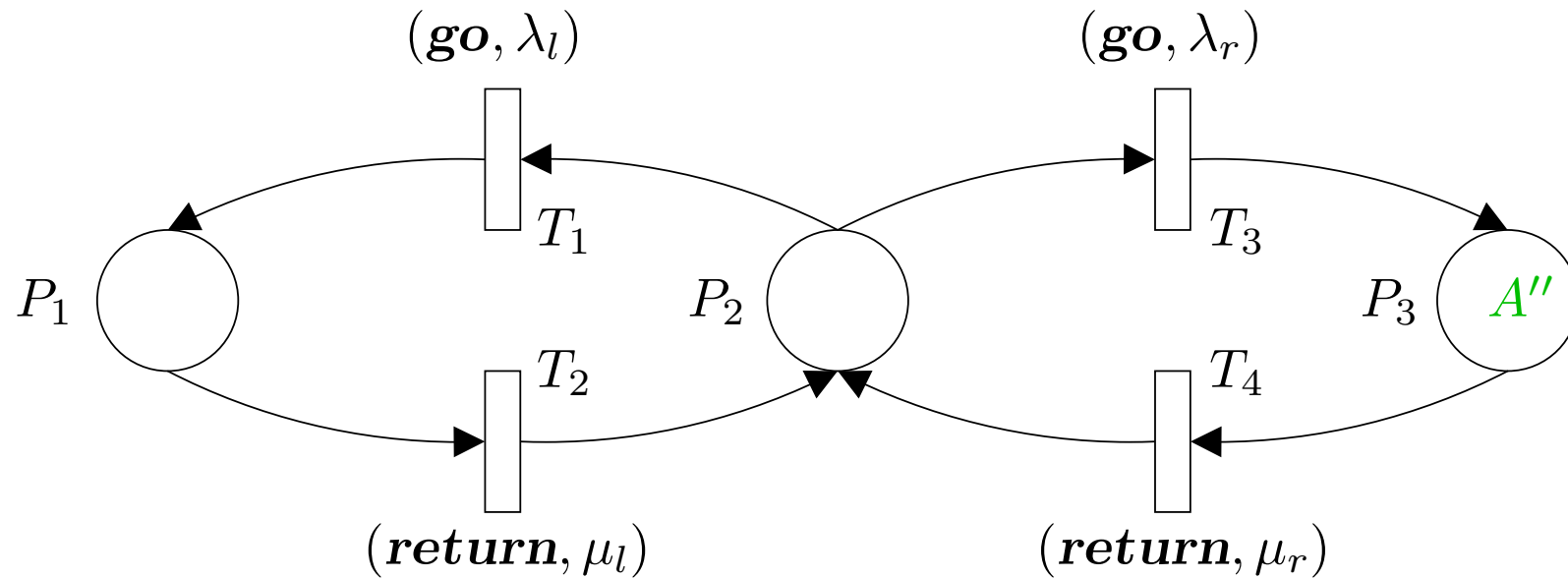
$$Agent \stackrel{def}{=} (go, \lambda).Agent'$$

## A mobile agent system (2)



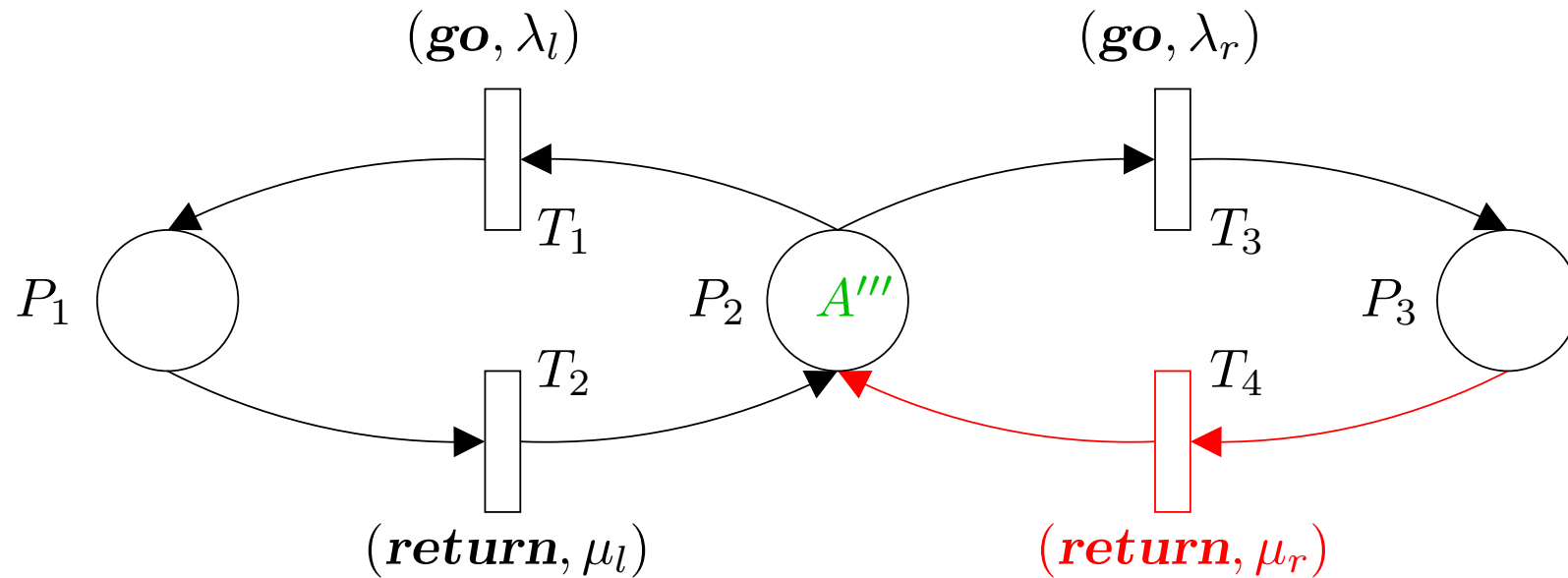
$$Agent' \stackrel{def}{=} (interrogate, r_i).Agent''$$

## A mobile agent system (3)



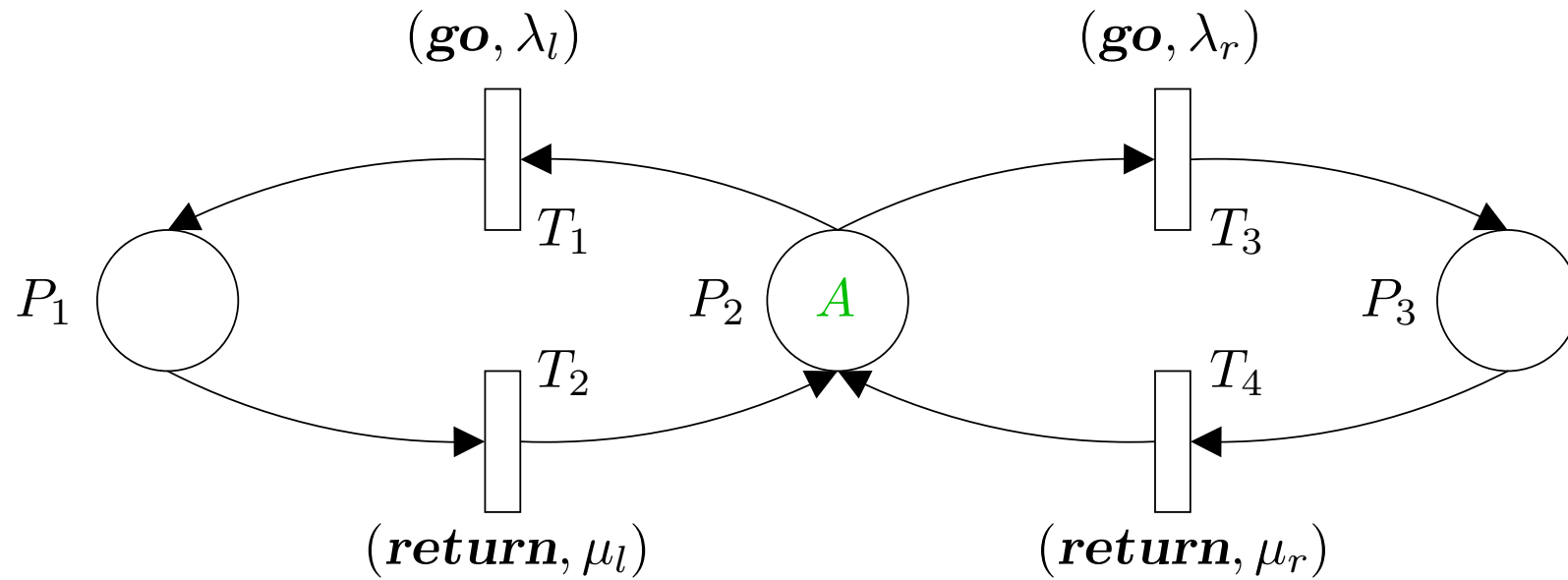
$$Agent'' \stackrel{def}{=} (return, \mu).Agent'''$$

## A mobile agent system (4)



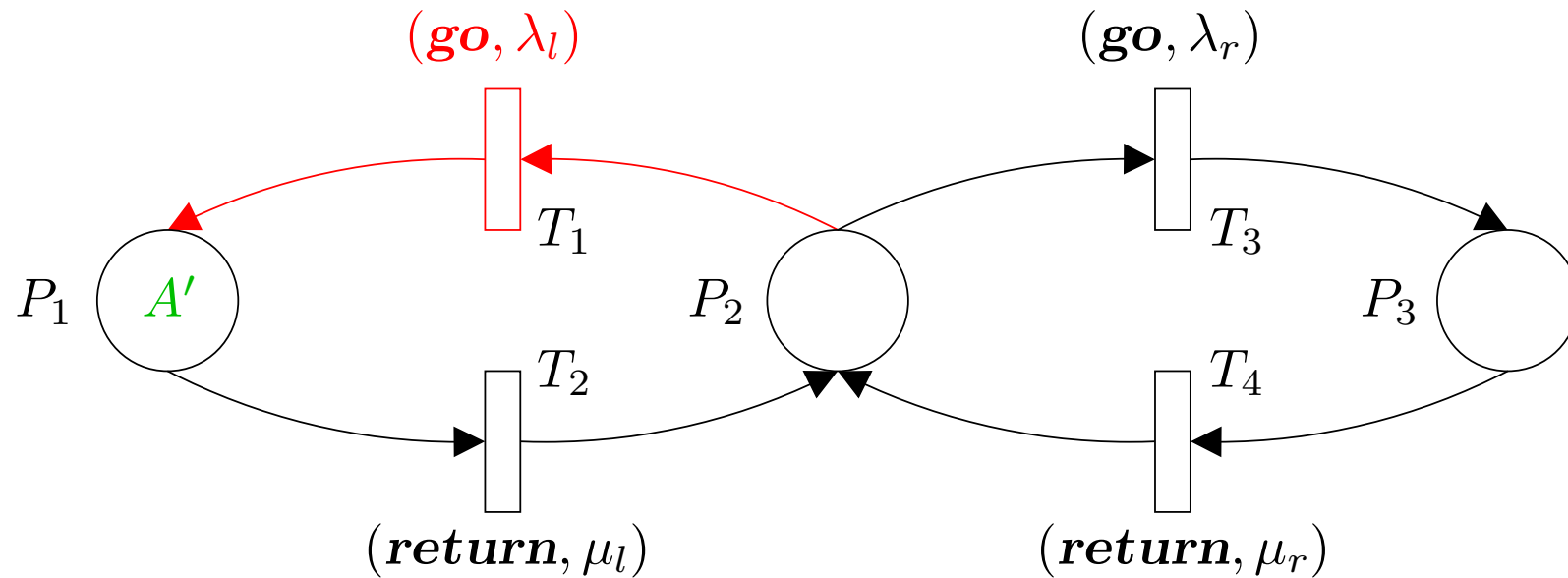
$$Agent''' \stackrel{def}{=} (dump, r_d).Agent$$

## A mobile agent system (5)



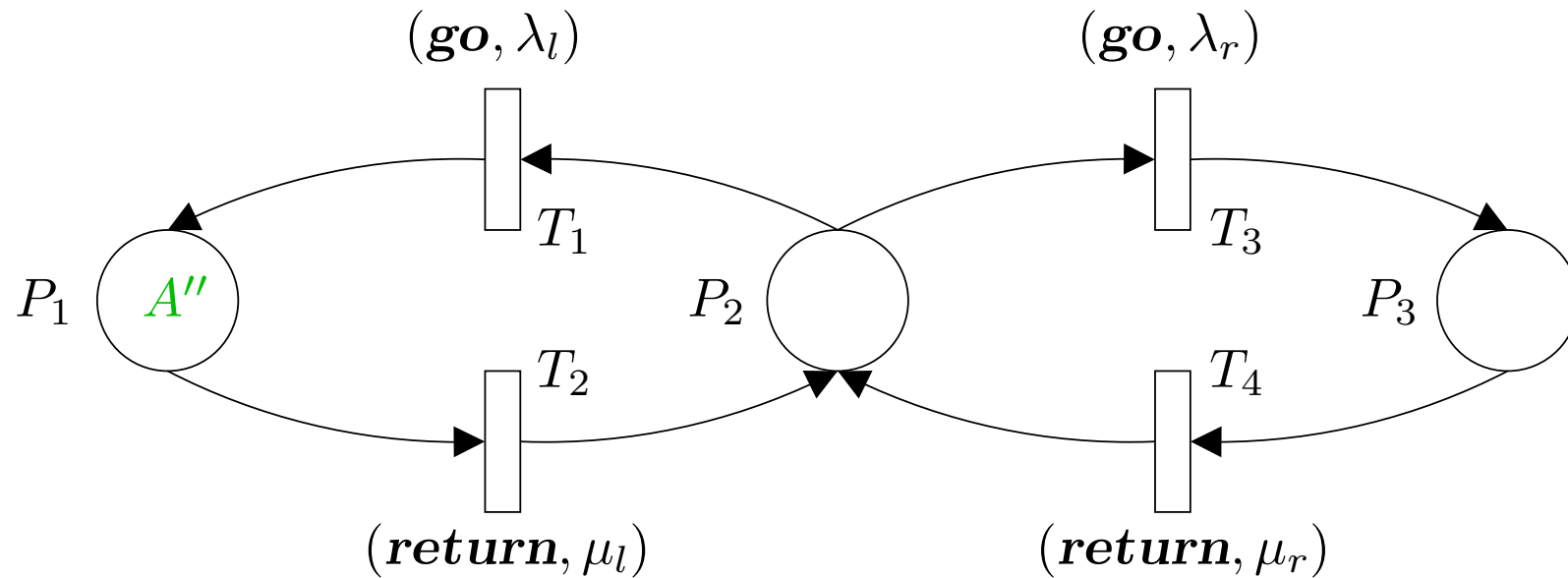
$$Agent \stackrel{def}{=} (go, \lambda).Agent'$$

## A mobile agent system (6)



$$Agent' \stackrel{def}{=} (interrogate, r_i).Agent''$$

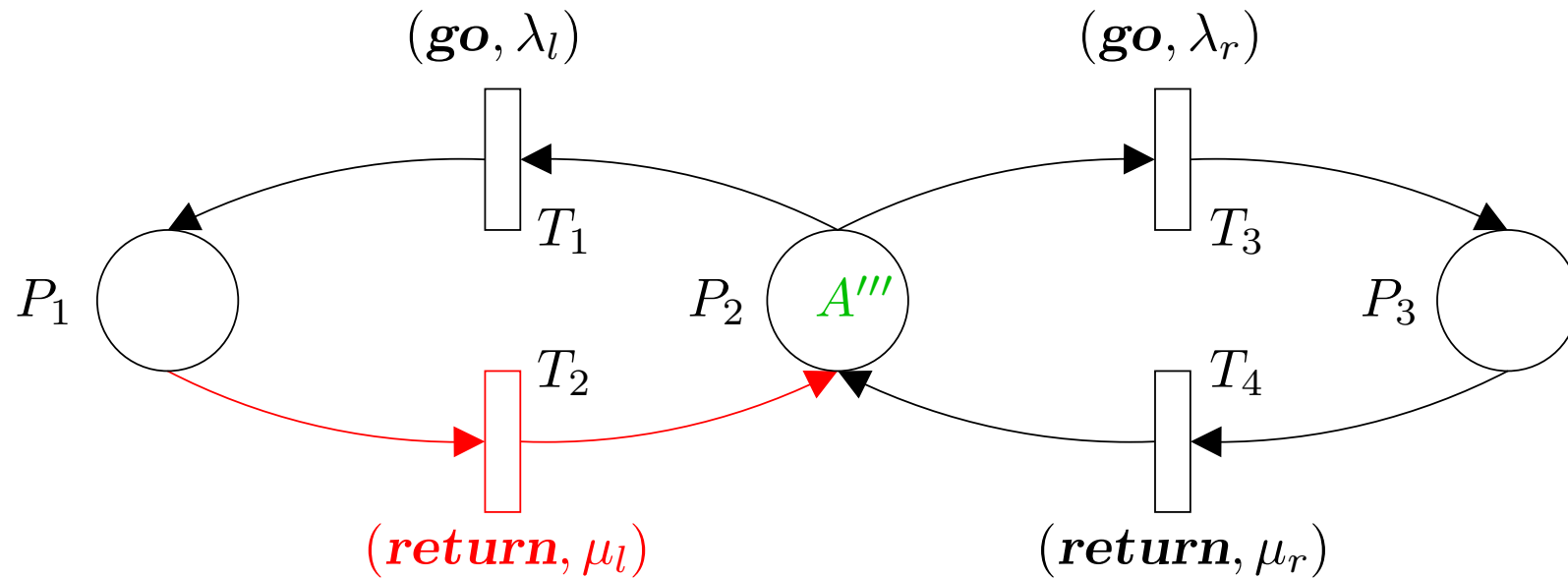
## A mobile agent system (7)



$$Agent'' \stackrel{def}{=} (return, \mu).Agent'''$$

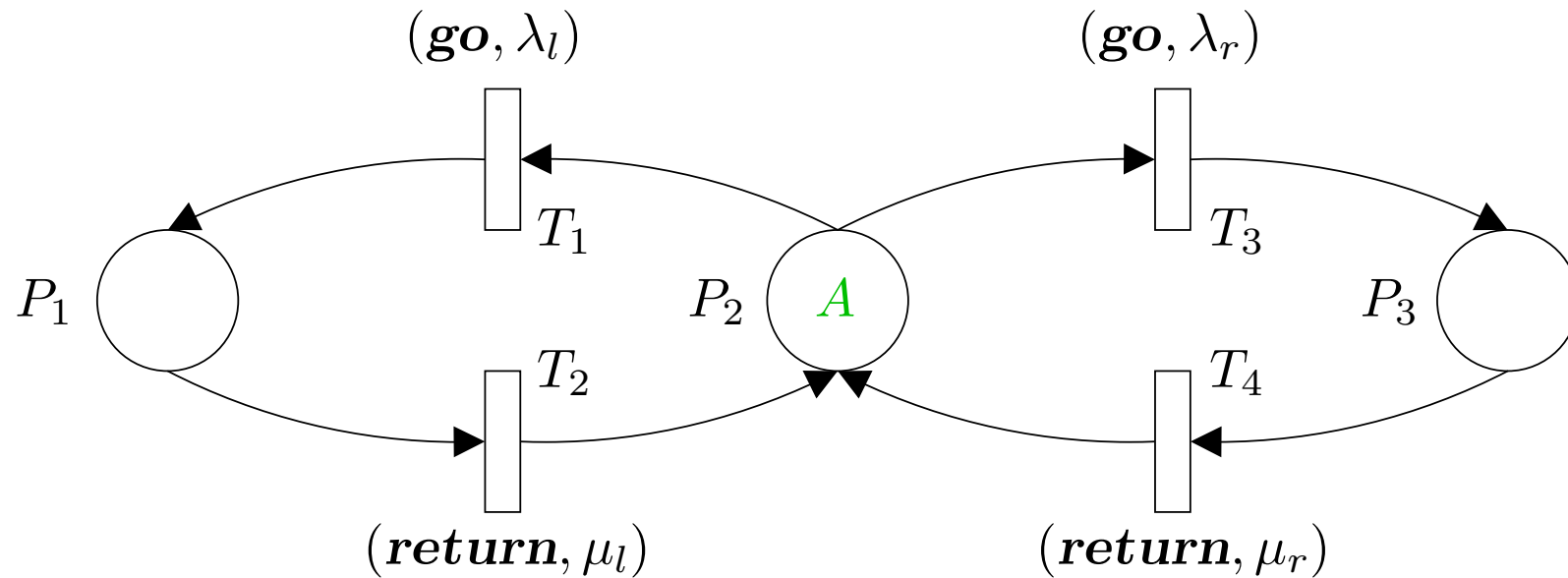


## A mobile agent system (8)



$$Agent''' \stackrel{def}{=} (dump, r_d).Agent$$

## A mobile agent system (9)



$$Agent \stackrel{def}{=} (go, \lambda).Agent'$$

## Conclusions

- Having a small, stable core language has facilitated many possibilities for us — compiling PEPA and PEPA net models to other formalisms seems to be a very profitable activity.
- However, there are typically many small details in the translation which need to be taken care of.
- It is tempting to lift features of the host tool back to the PEPA level but sometimes desirable properties of the PEPA language are lost.
- It is important to strike a balance between exploiting opportunities and losing theoretical properties.

---

## Acknowledgements

This work has been supported by the **DEGAS (Design Environments for Global ApplicationS)** project IST-2001-32072 funded by the FET Proactive Initiative on Global Computing.