



# Best Paper Runner Up

*Robotics: Science and Systems, 2012*

To

Konrad Rawlik, Marc Toussaint and Sethu Vijayakumar

*for the paper entitled*

On Stochastic Optimal Control and  
Reinforcement Learning by Approximate Inference

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Nick Roy  
General Chair  
RSS2012



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SYDNEY

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Paul Newman  
Program Chair  
RSS2012