# HYPE applied to the modelling of hybrid biological systems

Vashti Galpin Laboratory for Foundations of Computer Science University of Edinburgh

Joint work with Jane Hillston (University of Edinburgh) and Luca Bortolussi (University of Trieste)

24 May 2008

Introduction

▶ hybrid systems

Introduction

- hybrid systems
  - discrete behaviour

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE

Introduction

- discrete behaviour
- uiscrete benaviour
- continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows

٣

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows
  - hybrid automata

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows
  - hybrid automata
- gene regulatory network

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows
  - hybrid automata
- gene regulatory network
  - view genes as on or off

ď

ackground Operational semantics Hybrid semantics

#### Introduction

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- ► HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows
  - hybrid automata
- gene regulatory network
  - view genes as on or off
  - single gene in the cell with multiple mRNA and proteins

ackground Operational semantics Hybrid semantics

#### Introduction

Introduction

- hybrid systems
  - discrete behaviour
  - continuous behaviour, expressed as ODEs
- HYPE
  - process algebra for hybrid systems
  - inspired by PEPA
  - fine-grained modelling of flows
  - hybrid automata
- gene regulatory network
  - view genes as on or off
  - ▶ single gene in the cell with multiple mRNA and proteins
  - ▶ the Repressilator [Elowitz and Leibler, 2000]

► DNA, genes

- ► DNA, genes
  - transcription of mRNA

- ▶ DNA, genes
  - transcription of mRNA
  - translation to proteins

- ► DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins

- DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins
  - various roles, structural, enzymes

4

- DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins
  - various roles, structural, enzymes
- transcription factors

- DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins
  - various roles, structural, enzymes
- transcription factors
  - inhibitory repressors

- DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins
  - various roles, structural, enzymes
- transcription factors
  - inhibitory repressors
  - promoting activators

- DNA, genes
  - transcription of mRNA
  - translation to proteins
- proteins
  - various roles, structural, enzymes
- transcription factors
  - inhibitory repressors
  - promoting activators
  - feedback loops

synthetic network

- synthetic network
- three genes with three inhibitors

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)
- negative feedback cycle

ð

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)
- negative feedback cycle
  - each gene produces a protein

o"

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)
- negative feedback cycle
  - each gene produces a protein
  - protein inhibits transcription of mRNA by another gene

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)
- negative feedback cycle
  - each gene produces a protein
  - protein inhibits transcription of mRNA by another gene
  - other gene cannot produce its protein

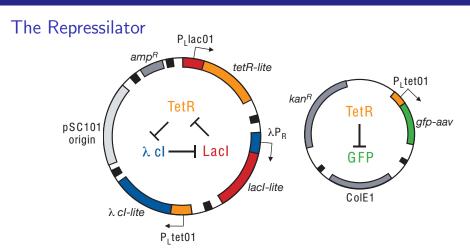
Background Operational semantics Hybrid semantics

### The Repressilator

- synthetic network
- three genes with three inhibitors
- reporter of green flourescent protein (GFP)
- negative feedback cycle
  - each gene produces a protein
  - protein inhibits transcription of mRNA by another gene
  - other gene cannot produce its protein
- quantities of proteins oscillate over time

ď

Background Operational semantics Hybrid semantics Conc



M.B. Elowitz and S. Leibler, A synthetic oscillatory network of transcriptional regulators, *Nature*, 403, 335-338.

Vashti Galpin

MFPS 24

 $Gene_A$ 

$$Gene_A \xrightarrow[trs_A]{} mRNA_A$$

$$Gene_A \xrightarrow{trs_A} mRNA_A \downarrow dm_A$$

$$Gene_A \xrightarrow[trs_A]{} mRNA_A \xrightarrow[trl_A]{} Pr_A$$

$$\downarrow dm_A \qquad trl_A$$

$$Gene_A \xrightarrow{trs_A} mRNA_A \xrightarrow{trl_A} Pr_A \downarrow dp_A \downarrow dp_A$$

$$Gene_A \xrightarrow[trs_A]{} mRNA_A \xrightarrow[trl_A]{} Pr_A$$

$$\downarrow dm_A \qquad \downarrow dp_A$$

$$\begin{array}{ccc} \textit{Gene}_{\textit{B}} \xrightarrow{\textit{trs}_{\textit{B}}} \textit{mRNA}_{\textit{B}} \xrightarrow{\textit{trl}_{\textit{B}}} \textit{Pr}_{\textit{B}} \\ \downarrow \textit{dm}_{\textit{B}} & \downarrow \textit{dp}_{\textit{B}} \end{array}$$

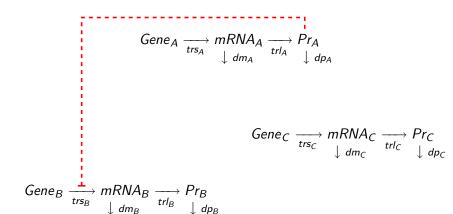
$$Gene_A \xrightarrow{trs_A} mRNA_A \xrightarrow{trl_A} Pr_A$$

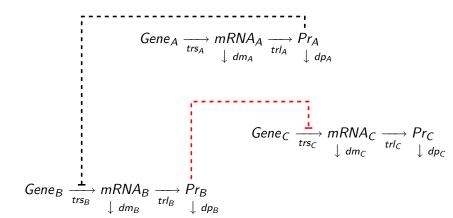
$$\downarrow dm_A \qquad \downarrow dp_A$$

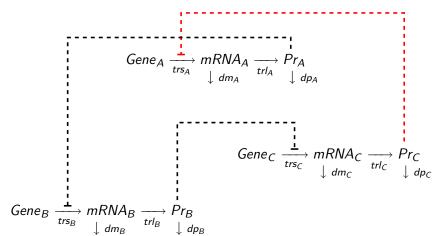
$$\begin{array}{ccc} \textit{Gene}_{\textit{C}} \xrightarrow{\textit{trs}_{\textit{C}}} \textit{mRNA}_{\textit{C}} \xrightarrow{\textit{trl}_{\textit{C}}} \textit{Pr}_{\textit{C}} \\ \downarrow \textit{dm}_{\textit{C}} & \downarrow \textit{dp}_{\textit{C}} \end{array}$$

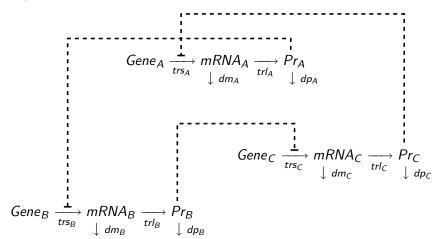
$$Gene_B \xrightarrow{trs_B} mRNA_B \xrightarrow{trl_B} Pr_B$$

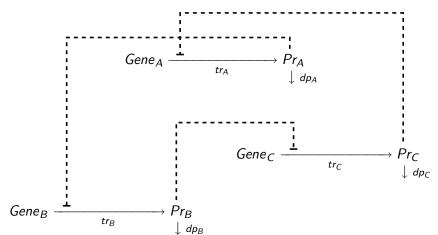
$$\downarrow dm_B \qquad trl_B \qquad \downarrow dp_B$$

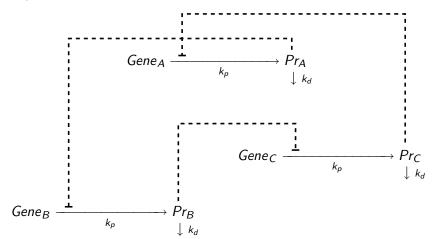












## **HYPE** syntax

two types of action

### HYPE syntax

- two types of action
- events instantaneous, discrete changes

$$\underline{a}\in\mathcal{E}$$

# two types of action

events — instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

activities — influences on continuous aspects, flows

$$\alpha \in \mathcal{A} \qquad \qquad \alpha(\vec{X}) = (\iota, r, I(\vec{X}))$$
 influence name rate influence type with  $\|I(\vec{X})\| = f(\vec{X})$ 

#### **HYPE** syntax

- two types of action
- events instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

activities — influences on continuous aspects, flows

$$\alpha \in \mathcal{A} \qquad \qquad \alpha(\vec{X}) = (\iota, r, I(\vec{X}))$$

$$\text{influence name} \qquad \text{rate} \qquad \text{influence type}$$

$$\text{with } \|I(\vec{X})\| = f(\vec{X})$$

- two types of action
- events instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

activities — influences on continuous aspects, flows

$$\alpha \in \mathcal{A} \qquad \qquad \alpha(\vec{X}) = (\iota, r, I(\vec{X}))$$
 influence name rate influence type with  $\|I(\vec{X})\| = f(\vec{X})$ 

- two types of action
- events instantaneous, discrete changes

$$\mathsf{a} \in \mathcal{E}$$

activities — influences on continuous aspects, flows

$$\alpha \in \mathcal{A} \qquad \qquad \alpha(\vec{X}) = (\iota, r, I(\vec{X}))$$
 influence name rate influence type with  $\|I(\vec{X})\| = f(\vec{X})$ 

#### **HYPE** syntax

- two types of action
- events instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

activities — influences on continuous aspects, flows

$$\alpha \in \mathcal{A} \qquad \qquad \alpha(\vec{X}) = (\iota, r, I(\vec{X}))$$
 influence name rate influence type with  $\|I(\vec{X})\| = f(\vec{X})$ 

where  $\vec{X}$  is a formal parameter.

not stochastic

degradation

$$G_A^{degr}(X) \stackrel{\text{\tiny def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

degradation

$$G_A^{degr}(X) \stackrel{\text{def}}{=} \underbrace{\text{init}} : (d_A, -k_d, Innear(X)).G_A^{degr}(X)$$

degradation

$$G_A^{degr}(X) \stackrel{\text{def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)). G_A^{degr}(X)$$

degradation

$$G_A^{degr}(X) \stackrel{\text{\tiny def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const).G_A^{prod}$ 

degradation

$$G_A^{degr}(X) \stackrel{\text{def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underbrace{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underbrace{\text{express}_A} : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underbrace{\text{inhibit}_A} : (p_A, 0, const).G_A^{prod}$ 

degradation

$$G_A^{degr}(X) \stackrel{\text{def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const). G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const). G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const). G_A^{prod}$ 

degradation

$$G_A^{degr}(X) \stackrel{def}{=} \underline{init} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} init : (p_A, k_p, const).G_A^{prod}$$
  
+  $express_A : (p_A, k_p, const).G_A^{prod}$   
+  $inhibit_A : (p_A, 0, const).G_A^{prod}$ 

degradation

$$G_A^{degr}(X) \stackrel{\text{def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const).G_A^{prod}$ 

degradation

$$G_A^{degr}(X) \stackrel{\text{\tiny def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const).G_A^{prod}$ 

composed

$$Gene_A(X) \stackrel{def}{=} (G_A^{degr}(X) \underset{\text{\{init\}}}{\bowtie} G_A^{prod})$$

degradation

$$G_A^{degr}(X) \stackrel{\text{\tiny def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const).G_A^{prod}$ 

composed

$$Gene_A(X) \stackrel{\text{def}}{=} (G_A^{degr}(X)) \bowtie G_A^{prod})$$

degradation

$$G_A^{degr}(X) \stackrel{\text{\tiny def}}{=} \underline{\text{init}} : (d_A, -k_d, linear(X)).G_A^{degr}(X)$$

production

$$G_A^{prod} \stackrel{\text{def}}{=} \underline{\text{init}} : (p_A, k_p, const).G_A^{prod}$$
 $+ \underline{\text{express}}_A : (p_A, k_p, const).G_A^{prod}$ 
 $+ \underline{\text{inhibit}}_A : (p_A, 0, const).G_A^{prod}$ 

composed

$$Gene_A(X) \stackrel{def}{=} (G_A^{degr}(X) \bowtie_{\text{finit}} G_A^{prod})$$

"controller"

$$Con_A \stackrel{\text{def}}{=} inhibit_A.express_A.Con_A$$

$$Rep \stackrel{\text{def}}{=} (Gene_A(A_B) \underset{\text{init}}{\bowtie} Gene_B(B_C) \underset{\text{init}}{\bowtie} Gene_C(C_A)) \underset{\text{linit}}{\bowtie}$$

$$\underline{init}.(Con_A \parallel Con_B \parallel Con_C)$$

$$L = \{\underline{init}, \underline{inhibit}_A, \underline{inhibit}_B, \underline{inhibit}_C,$$

$$\underline{express}_A, \underline{express}_B, \underline{express}_C\}$$

```
Rep \stackrel{\text{def}}{=} (Gene_A(A_B) \underset{\text{init}}{\bowtie} Gene_B(B_C) \underset{\text{init}}{\bowtie} Gene_C(C_A)) \underset{\text{linit}}{\bowtie} \frac{\text{init}.(Con_A \parallel Con_B \parallel Con_C)}
L = \{ \underbrace{\text{init}, \underbrace{\text{inhibit}}_A, \underbrace{\text{inhibit}}_B, \underbrace{\text{inhibit}}_C, \underbrace{\text{express}}_B, \underbrace{\text{express}}_C \}
```

$$\mathcal{V} = \{A_B, B_C, C_A\}$$

$$\mathcal{V} = \{A_B, B_C, C_A\}$$
 $\llbracket const \rrbracket = 1 \quad \llbracket linear(X) \rrbracket = X$ 

$$\mathcal{V} = \{A_B, B_C, C_A\}$$
 $\llbracket const \rrbracket = 1 \quad \llbracket linear(X) \rrbracket = X$ 

$$iv(d_A) = A_B$$
  $iv(p_A) = A_B$ 

$$\mathcal{V} = \{A_B, B_C, C_A\}$$
 $\llbracket const \rrbracket = 1$   $\llbracket linear(X) \rrbracket = X$ 
 $iv(d_A) = A_B$   $iv(p_A) = A_B$ 
 $iv(d_B) = B_C$   $iv(p_B) = B_C$ 
 $iv(d_C) = C_A$   $iv(p_C) = C_A$ 

$$V = \{A_B, B_C, C_A\}$$

$$\llbracket const \rrbracket = 1 \qquad \llbracket linear(X) \rrbracket = X$$

$$iv(d_A) = A_B \qquad iv(p_A) = A_B$$

$$iv(d_B) = B_C \qquad iv(p_B) = B_C$$

$$iv(d_C) = C_A \qquad iv(p_C) = C_A$$

$$ec(init) = (true, (A_B = c_A \land B_C = c_B \land C_A = c_C))$$

# The Repressilator in HYPE (cont.) $\mathcal{V} = \{A_B, B_C, C_A\}$

$$\llbracket const \rrbracket = 1$$
  $\llbracket linear(X) \rrbracket = X$   $iv(d_A) = A_B$   $iv(p_A) = A_B$   $iv(p_B) = B_C$   $iv(p_C) = C_A$   $iv(p_C) = C_A$ 

$$ec(\underline{init}) = (true, (A_B = c_A \land B_C = c_B \land C_A = c_C))$$
  
 $ec(\underline{inhibit}_A) = (C_A > p, T) ec(\underline{express}_A) = (C_A \le p, T)$ 

$$\mathcal{V} = \{A_B, B_C, C_A\}$$
 $\llbracket const \rrbracket = 1 \qquad \llbracket linear(X) \rrbracket = X$ 
 $iv(d_A) = A_B \qquad iv(p_A) = A_B$ 

$$iv(d_B) = B_C$$
  $iv(p_B) = B_C$   
 $iv(d_C) = C_A$   $iv(p_C) = C_A$ 

$$\begin{array}{lll} ec(\underline{\mathsf{init}}) &=& (\mathit{true}, (A_B = c_A \land B_C = c_B \land C_A = c_C)) \\ ec(\underline{\mathsf{inhibit}}_A) &=& (C_A > p, T) & ec(\underline{\mathsf{express}}_A) &=& (C_A \leq p, T) \\ ec(\underline{\mathsf{inhibit}}_B) &=& (A_B > p, T) & ec(\underline{\mathsf{express}}_B) &=& (A_B \leq p, T) \\ ec(\underline{\mathsf{inhibit}}_C) &=& (B_C > p, T) & ec(\underline{\mathsf{express}}_C) &=& (B_C \leq p, T) \end{array}$$

▶ state:  $\sigma: IN \to (\mathbb{R} \times IT)$ 

- ▶ state:  $\sigma: IN \to (\mathbb{R} \times IT)$
- configuration:  $\langle ConSys, \sigma \rangle$

- ▶ state:  $\sigma: IN \to (\mathbb{R} \times IT)$
- configuration:  $\langle ConSys, \sigma \rangle$
- ▶ labelled transition system:  $(\mathcal{F}, \mathcal{E}, \rightarrow \subseteq \mathcal{F} \times \mathcal{E} \times \mathcal{F})$

- ▶ state:  $\sigma: IN \to (\mathbb{R} \times IT)$
- ightharpoonup configuration:  $\langle ConSys, \sigma \rangle$
- ▶ labelled transition system:  $(\mathcal{F}, \mathcal{E}, \rightarrow \subseteq \mathcal{F} \times \mathcal{E} \times \mathcal{F})$
- ▶ updating function:  $\sigma[\iota \mapsto (r, I)]$

$$\sigma[\iota \mapsto (r, I)](x) = \begin{cases} (r, I) & \text{if } x = \iota \\ \sigma(x) & \text{otherwise} \end{cases}$$

- ▶ state:  $\sigma: IN \to (\mathbb{R} \times IT)$
- ightharpoonup configuration:  $\langle ConSys, \sigma \rangle$
- ▶ labelled transition system:  $(\mathcal{F}, \mathcal{E}, \rightarrow \subseteq \mathcal{F} \times \mathcal{E} \times \mathcal{F})$
- ▶ updating function:  $\sigma[\iota \mapsto (r, I)]$

$$\sigma[\iota \mapsto (r, I)](x) = \begin{cases} (r, I) & \text{if } x = \iota \\ \sigma(x) & \text{otherwise} \end{cases}$$

change identifying function:  $\Gamma: \mathcal{S} \times \mathcal{S} \times \mathcal{S} \to \mathcal{S}$ 

$$(\Gamma(\sigma, \tau, \tau'))(\iota) = \begin{cases} \tau(\iota) & \text{if } \sigma(\iota) = \tau'(\iota) \\ \tau'(\iota) & \text{if } \sigma(\iota) = \tau(\iota) \\ \text{undefined} & \text{otherwise} \end{cases}$$

Prefix with influence:

$$\frac{}{\langle \underline{\mathsf{a}} : (\iota, r, I) . \mathsf{E}, \sigma \rangle \xrightarrow{\underline{\mathsf{a}}} \langle \mathsf{E}, \sigma [\iota \mapsto (r, I)] \rangle}$$

Prefix without

influence:  $\langle \underline{\underline{a}}.E,\sigma \rangle \xrightarrow{\underline{a}} \langle E,\sigma \rangle$ 

Choice:

$$\frac{\langle E, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle}{\langle E + F, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle} \qquad \frac{\langle F, \sigma \rangle \xrightarrow{\underline{a}} \langle F', \sigma' \rangle}{\langle E + F, \sigma \rangle \xrightarrow{\underline{a}} \langle F', \sigma' \rangle}$$

Constant:

$$\frac{\langle E, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle}{\langle A, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle} (A \stackrel{\text{\tiny def}}{=} E)$$

ď

Prefix with influence:

$$\frac{}{\langle \underline{\mathsf{a}} : (\iota, r, I) . \mathsf{E}, \sigma \rangle \xrightarrow{\underline{\mathsf{a}}} \langle \mathsf{E}, \sigma [\iota \mapsto (r, I)] \rangle}$$

Prefix without

influence:  $\langle a.E, \sigma \rangle \xrightarrow{\underline{a}} \langle E, \sigma \rangle$ 

Choice:

$$\frac{\left\langle E,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E',\sigma'\right\rangle}{\left\langle E+F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E',\sigma'\right\rangle} \qquad \frac{\left\langle F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle F',\sigma'\right\rangle}{\left\langle E+F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle F',\sigma'\right\rangle}$$

Constant:

$$\frac{\langle E, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle}{\langle A, \sigma \rangle \xrightarrow{\underline{a}} \langle E', \sigma' \rangle} (A \stackrel{\text{\tiny def}}{=} E)$$

# Operational semantics (cont.)

 $\langle E, \sigma \rangle \stackrel{\underline{\underline{a}}}{\longrightarrow} \langle E', \sigma' \rangle$ Parallel without a ∉ *M*  $\langle E \bowtie F, \sigma \rangle \xrightarrow{\underline{a}} \langle E' \bowtie F, \sigma' \rangle$ synchronisation:

$$\frac{\langle F, \sigma \rangle \xrightarrow{\underline{a}} \langle F', \sigma' \rangle}{\langle E \bowtie_{M} F, \sigma \rangle \xrightarrow{\underline{a}} \langle E \bowtie_{M} F', \sigma' \rangle} \qquad \underline{\underline{a}} \not\in M$$

 $\langle E, \sigma \rangle \stackrel{\underline{\underline{a}}}{\longrightarrow} \langle E', \tau \rangle \quad \langle F, \sigma \rangle \stackrel{\underline{\underline{a}}}{\longrightarrow} \langle F', \tau' \rangle$ Parallel with  $\langle E \bowtie F, \sigma \rangle \xrightarrow{\underline{a}} \langle E' \bowtie F', \Gamma(\sigma, \tau, \tau') \rangle$ synchronisation:

 $a \in M, \Gamma$  defined

Parallel without synchronisation:

$$\frac{\left\langle E,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E',\sigma'\right\rangle}{\left\langle E \bowtie F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E' \bowtie F,\sigma'\right\rangle} \qquad \underline{a} \not\in M$$

$$\frac{\left\langle F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle F',\sigma'\right\rangle}{\left\langle E \bowtie F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E \bowtie F',\sigma'\right\rangle} \qquad \underline{a} \not\in M$$

Parallel with synchronisation:

$$\frac{\left\langle E,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E',\tau\right\rangle \quad \left\langle F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle F',\tau'\right\rangle}{\left\langle E \bowtie_{M} F,\sigma\right\rangle \stackrel{\underline{a}}{\longrightarrow} \left\langle E' \bowtie_{M} F',\Gamma(\sigma,\tau,\tau')\right\rangle}$$

 $a \in M, \Gamma$  defined

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B), \tau_1 \rangle \qquad \langle G_A^{prod}, \tau \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{prod}, \tau_2 \rangle}{\langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau_3 \rangle} \\
\frac{\langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle} \\
\tau = \{ d_A \mapsto *, \ p_A \mapsto *, \ldots \} \\
\tau_1 = \tau [d_A \mapsto (-1, I(A_B))] = \{ d_A \mapsto (-1, I(A_B)), \ p_A \mapsto *, \ldots \} \\
\tau_2 = \tau [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, \ p_A \mapsto (k_p, c), \ldots \} \\
\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{ d_A \mapsto (-1, I(A_B)), \ p_A \mapsto (k_p, c), \ldots \}$$

$$\frac{\langle G_A^{degr}(A_B), \boldsymbol{\tau} \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B), \tau_1 \rangle \qquad \langle G_A^{prod}, \boldsymbol{\tau} \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{prod}, \tau_2 \rangle}{\langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \boldsymbol{\tau} \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau_3 \rangle}$$

$$\frac{\langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \boldsymbol{\tau} \rangle \xrightarrow{\underline{\text{init}}} \langle G_A^{degr}(A_B) \xrightarrow{\underline{\text{init}}} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \boldsymbol{\tau} \rangle \xrightarrow{\underline{\text{init}}} \langle Gene_A(A_B), \tau_3 \rangle}$$

$$\boldsymbol{\tau} = \{ d_A \mapsto *, \ p_A \mapsto *, \ldots \}$$

$$\tau_1 = \boldsymbol{\tau} [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), \ p_A \mapsto *, \ldots \}$$

$$\tau_2 = \boldsymbol{\tau} [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, \ p_A \mapsto (k_p, c), \ldots \}$$

$$\tau_3 = \Gamma(\boldsymbol{\tau}, \tau_1, \tau_2) = \{ d_A \mapsto (-1, l(A_B)), \ p_A \mapsto (k_p, c), \ldots \}$$

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B), \tau_1 \rangle}{\langle G_A^{degr}(A_B) \xrightarrow{\underline{init}} \langle G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{prod}, \tau_2 \rangle} \\
\frac{\langle G_A^{degr}(A_B) \xrightarrow{\underline{\bowtie}} G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B) \xrightarrow{\underline{\bowtie}} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle \xrightarrow{\underline{init}} \langle Gene_A(A_B), \tau_3 \rangle} \\
\tau = \{ d_A \mapsto *, p_A \mapsto *, \ldots \} \\
\tau_1 = \tau [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto *, \ldots \} \\
\tau_2 = \tau [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, p_A \mapsto (k_p, c), \ldots \} \\
\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto (k_p, c), \ldots \}$$

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B), \tau_1 \rangle \qquad \langle G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{prod}, \tau_2 \rangle}{\langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau_3 \rangle}$$

$$\frac{\langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle}$$

$$\tau = \{ d_A \mapsto *, \ p_A \mapsto *, \ldots \}$$

$$\tau_1 = \tau [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), \ p_A \mapsto *, \ldots \}$$

Vashti Galpin

 $\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{d_A \mapsto (-1, I(A_B)), p_A \mapsto (k_p, c), \ldots\}$ 

 $\tau_{\mathcal{D}} = \tau[p_A \mapsto (k_p, c)] = \{d_A \mapsto *, p_A \mapsto (k_p, c), \ldots\}$ 

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B), \tau_1 \rangle}{\langle G_A^{degr}(A_B), \tau_1 \rangle \xrightarrow{\underline{init}} \langle G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{prod}, \tau_2 \rangle} \\
\frac{\langle G_A^{degr}(A_B) \underset{\underline{init}}{\bowtie} G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B) \underset{\underline{init}}{\bowtie} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle \xrightarrow{\underline{init}} \langle Gene_A(A_B), \tau_3 \rangle} \\
\tau = \{ d_A \mapsto *, p_A \mapsto *, \ldots \} \\
\tau_1 = \tau [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto *, \ldots \} \\
\tau_2 = \tau [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, p_A \mapsto (k_p, c), \ldots \} \\
\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto (k_p, c), \ldots \}$$

$$\frac{\langle G_{A}^{degr}(A_{B}), \tau \rangle \xrightarrow{\text{init}} \langle G_{A}^{degr}(A_{B}), \tau_{1} \rangle}{\langle G_{A}^{degr}(A_{B}), \tau_{1} \rangle \xrightarrow{\text{init}} \langle G_{A}^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_{A}^{prod}, \tau_{2} \rangle} \\
\frac{\langle G_{A}^{degr}(A_{B}) \bowtie G_{A}^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_{A}^{degr}(A_{B}) \bowtie G_{A}^{prod}, \tau_{3} \rangle}{\langle Gene_{A}(A_{B}), \tau \rangle \xrightarrow{\text{init}} \langle Gene_{A}(A_{B}), \tau_{3} \rangle} \\
\tau = \{ d_{A} \mapsto *, p_{A} \mapsto *, \ldots \} \\
\tau_{1} = \tau [d_{A} \mapsto (-1, l(A_{B}))] = \{ d_{A} \mapsto (-1, l(A_{B})), p_{A} \mapsto *, \ldots \} \\
\tau_{2} = \tau [p_{A} \mapsto (k_{p}, c)] = \{ d_{A} \mapsto *, p_{A} \mapsto (k_{p}, c), \ldots \} \\
\tau_{3} = \Gamma(\tau, \tau_{1}, \tau_{2}) = \{ d_{A} \mapsto (-1, l(A_{B})), p_{A} \mapsto (k_{p}, c), \ldots \}$$

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B), \tau_1 \rangle \qquad \langle G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{prod}, \tau_2 \rangle}{\langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau_3 \rangle}$$

$$\frac{\langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau \rangle \xrightarrow{\text{init}} \langle G_A^{degr}(A_B) \xrightarrow{\text{init}} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle \xrightarrow{\text{init}} \langle Gene_A(A_B), \tau_3 \rangle}$$

$$\tau = \{ d_A \mapsto *, p_A \mapsto *, \ldots \}$$

$$\tau_1 = \tau [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto *, \ldots \}$$

$$\tau_2 = \tau [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, p_A \mapsto (k_p, c), \ldots \}$$

$$\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto (k_p, c), \ldots \}$$

$$\frac{\langle G_A^{degr}(A_B), \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B), \tau_1 \rangle \qquad \langle G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{prod}, \tau_2 \rangle}{\langle G_A^{degr}(A_B) \underset{\underline{init}}{\boxtimes} G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B) \underset{\underline{init}}{\boxtimes} G_A^{prod}, \tau_3 \rangle} \\
\frac{\langle G_A^{degr}(A_B) \underset{\underline{init}}{\boxtimes} G_A^{prod}, \tau \rangle \xrightarrow{\underline{init}} \langle G_A^{degr}(A_B) \underset{\underline{init}}{\boxtimes} G_A^{prod}, \tau_3 \rangle}{\langle Gene_A(A_B), \tau \rangle} \\
\tau = \{ d_A \mapsto *, p_A \mapsto *, \ldots \} \\
\tau_1 = \tau [d_A \mapsto (-1, l(A_B))] = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto *, \ldots \} \\
\tau_2 = \tau [p_A \mapsto (k_p, c)] = \{ d_A \mapsto *, p_A \mapsto (k_p, c), \ldots \} \\
\tau_3 = \Gamma(\tau, \tau_1, \tau_2) = \{ d_A \mapsto (-1, l(A_B)), p_A \mapsto (k_p, c), \ldots \}$$

## The Repressilator – labelled transition system

8 configurations represent all possibilities with 8 distinct states

$$\sigma_{0} = D \cup \{p_{A} \mapsto (0, c), p_{B} \mapsto (0, c), p_{C} \mapsto (0, c)\} 
\sigma_{1} = D \cup \{p_{A} \mapsto (0, c), p_{B} \mapsto (0, c), p_{C} \mapsto (k_{p}, c)\} 
\sigma_{2} = D \cup \{p_{A} \mapsto (0, c), p_{B} \mapsto (k_{p}, c), p_{C} \mapsto (0, c)\} 
\sigma_{3} = D \cup \{p_{A} \mapsto (0, c), p_{B} \mapsto (k_{p}, c), p_{C} \mapsto (k_{p}, c)\} 
\sigma_{4} = D \cup \{p_{A} \mapsto (k_{p}, c), p_{B} \mapsto (0, c), p_{C} \mapsto (0, c)\} 
\sigma_{5} = D \cup \{p_{A} \mapsto (k_{p}, c), p_{B} \mapsto (0, c), p_{C} \mapsto (k_{p}, c)\} 
\sigma_{6} = D \cup \{p_{A} \mapsto (k_{p}, c), p_{B} \mapsto (k_{p}, c), p_{C} \mapsto (0, c)\} 
\sigma_{7} = D \cup \{p_{A} \mapsto (k_{p}, c), p_{B} \mapsto (k_{p}, c), p_{C} \mapsto (0, c)\} 
\text{where} 
$$D = \{d_{A} \mapsto (-1, l(A_{B})), d_{B} \mapsto (-1, l(B_{C})), d_{C} \mapsto (-1, l(C_{A}))\}$$$$

何

 $\triangleright$  extract ODEs from each state  $\sigma$  in the lts of CS

$$\mathit{CS}_\sigma = \left\{ \mathsf{ODE} \; \mathsf{for} \; \mathsf{variable} \; V \; \middle| \; V \in \mathcal{V} \right\} \; \; \mathsf{where} \;$$

$$\frac{dV}{dt} = \sum \left\{ r[I(\vec{W})] \mid iv(\iota) = V \text{ and } \sigma(\iota) = (r, I(\vec{W})) \right\}$$

 $\triangleright$  extract ODEs from each state  $\sigma$  in the lts of CS

$$extit{CS}_{\sigma} = \left\{ ext{ODE for variable } V \; \middle| \; V \in \mathcal{V} 
ight\} \; ext{where}$$

$$\frac{dV}{dt} = \sum \left\{ r[I(\vec{W})] \mid iv(\iota) = V \text{ and } \sigma(\iota) = (r, I(\vec{W})) \right\}$$

▶ for any influence name associated with *V* 

ð

 $\triangleright$  extract ODEs from each state  $\sigma$  in the lts of CS

$$\mathit{CS}_\sigma = \left\{ \mathsf{ODE} \; \mathsf{for} \; \mathsf{variable} \; V \; \middle| \; V \in \mathcal{V} \right\} \; \; \mathsf{where} \;$$

$$\frac{dV}{dt} = \sum \left\{ r[I(\vec{W})] \mid iv(\iota) = V \text{ and } \sigma(\iota) = (r, I(\vec{W})) \right\}$$

- for any influence name associated with V
- $\blacktriangleright$  determine from  $\sigma$  its rate and influence type

 $\blacktriangleright$  extract ODEs from each state  $\sigma$  in the lts of *CS* 

$$extit{CS}_{\sigma} = \left\{ ext{ODE for variable } V \; \middle| \; V \in \mathcal{V} 
ight\} \; ext{where}$$

$$\frac{dV}{dt} = \sum \left\{ \frac{r[I(\vec{W})]}{r[I(\vec{W})]} \mid iv(\iota) = V \text{ and } \sigma(\iota) = (r, I(\vec{W})) \right\}$$

- ▶ for any influence name associated with *V*
- determine from  $\sigma$  its rate and influence type
- multiply its rate and influence function together

ď

 $\blacktriangleright$  extract ODEs from each state  $\sigma$  in the lts of *CS* 

$$extit{CS}_{\sigma} = \left\{ ext{ODE for variable } V \; \middle| \; V \in \mathcal{V} 
ight\} \; ext{ where}$$

$$\frac{dV}{dt} = \sum \{ r[I(\vec{W})] \mid iv(\iota) = V \text{ and } \sigma(\iota) = (r, I(\vec{W})) \}$$

- ▶ for any influence name associated with *V*
- determine from  $\sigma$  its rate and influence type
- multiply its rate and influence function together
- sum these over all associated influence names

ď

## The Repressilator – ODEs

$$\sigma_{4} = \{d_{A} \mapsto (-1, linear(A_{B})), p_{A} \mapsto (k_{p}, const), \\ d_{B} \mapsto (-1, linear(B_{C})), p_{B} \mapsto (0, const), \\ d_{C} \mapsto (-1, linear(C_{A})), p_{C} \mapsto (0, const)\}$$

The ODEs for this state are

$$\frac{dA_B}{dt} = -k_d A_B + k_p, \quad \frac{dB_C}{dt} = -k_d B_C, \quad \frac{dC_A}{dt} = -k_d C_A$$

## The Repressilator – ODEs

$$\sigma_{4} = \{d_{A} \mapsto (-1, linear(A_{B})), p_{A} \mapsto (k_{p}, const), \\ d_{B} \mapsto (-1, linear(B_{C})), p_{B} \mapsto (0, const), \\ d_{C} \mapsto (-1, linear(C_{A})), p_{C} \mapsto (0, const)\}$$

The ODEs for this state are

$$\frac{dA_B}{dt} = -k_d A_B + k_p, \quad \frac{dB_C}{dt} = -k_d B_C, \quad \frac{dC_A}{dt} = -k_d C_A$$

Use ABC for this set of ODEs

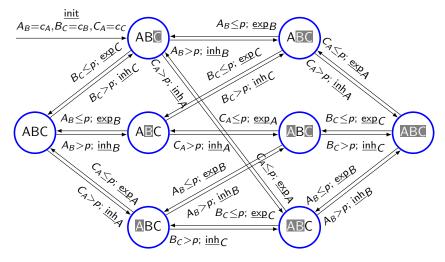
$$\sigma_{4} = \{d_{A} \mapsto (-1, linear(A_{B})), p_{A} \mapsto (k_{p}, const), \\ d_{B} \mapsto (-1, linear(B_{C})), p_{B} \mapsto (0, const), \\ d_{C} \mapsto (-1, linear(C_{A})), p_{C} \mapsto (0, const)\}$$

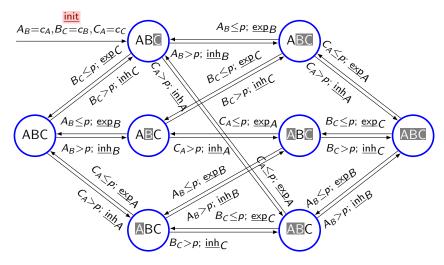
The ODEs for this state are

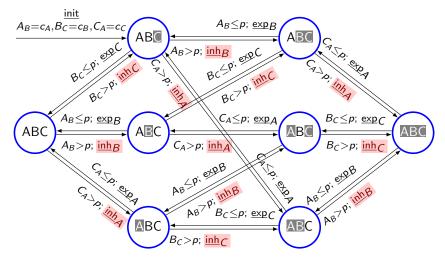
$$\frac{dA_B}{dt} = -k_d A_B + k_p, \quad \frac{dB_C}{dt} = -k_d B_C, \quad \frac{dC_A}{dt} = -k_d C_A$$

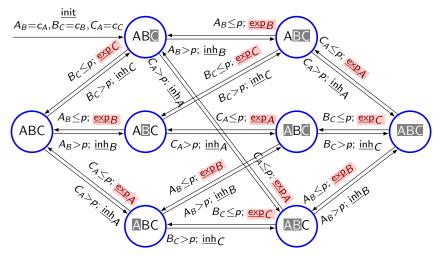
Use ABC for this set of ODEs

Likewise the ODEs for  $\sigma_3$  would be ABC and for  $\sigma_7$ , ABC

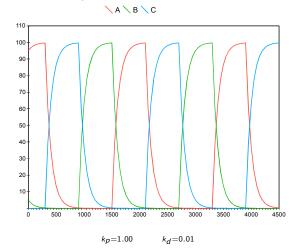








## The Repressilator – protein levels over time



- different style of modelling
- explicit ODEs

GeneA 
$$\stackrel{def}{=} (dA_B = c_A) \land \mathbf{A} \text{ OnA}$$

OnA  $\stackrel{def}{=} (dA_B/dt = -k_dA_B + k_p) \land \mathbf{v} \sigma_{\text{rel}}^*$ 

$$((C_A > p) : \rightarrow ((A_B^{\bullet} = {}^{\bullet}A_B) \land \mathbf{v} \text{ inhibit} \cdot \text{OffA}))$$

OffA  $\stackrel{def}{=} (dA_B/dt = -k_dA_B) \land \mathbf{v} \sigma_{\text{rel}}^*$ 

$$((C_A \le p) : \rightarrow ((A_B^{\bullet} = {}^{\bullet}A_B) \land \mathbf{v} \text{ express} \cdot \text{OnA}))$$

 $\stackrel{def}{=}$  GeneA || GeneB || GeneC Rep

# The Repressilator in ACP<sub>hs</sub><sup>srt</sup>

- different style of modelling
- explicit ODEs

GeneA 
$$\stackrel{\text{def}}{=} (dA_B = c_A) \land \mathbf{A} \text{ OnA}$$

OnA  $\stackrel{\text{def}}{=} (dA_B/dt = -k_dA_B + k_p) \land \mathbf{V} \sigma_{\text{rel}}^*$ 

$$((C_A > p) : \rightarrow ((A_B^{\bullet} = {}^{\bullet}A_B) \land \mathbf{V} \text{ inhibit} \cdot \text{OffA}))$$

OffA  $\stackrel{\text{def}}{=} (dA_B/dt = -k_dA_B) \land \mathbf{V} \sigma_{\text{rel}}^*$ 

$$((C_A \le p) : \rightarrow ((A_B^{\bullet} = {}^{\bullet}A_B) \land \mathbf{V} \text{ express} \cdot \text{OnA}))$$

$$\mathsf{Rep} \quad \stackrel{\scriptscriptstyle def}{=} \quad \mathsf{GeneA} \parallel \mathsf{GeneB} \parallel \mathsf{GeneC}$$

#### Further work and conclusions

further work

Vashti Galpin

Conclusion

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"

Vashti Galpin

Conclusion

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters

Vashti Galpin

Conclusion

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models
  - more biological modelling

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models
  - more biological modelling
- conclusions

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models
  - more biological modelling
- conclusions
  - ► HYPE for modelling hybrid biological systems

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models
  - more biological modelling
- conclusions
  - HYPE for modelling hybrid biological systems
  - use of flows to obtain ODEs

#### Further work and conclusions

- further work
  - less abstract model including mRNA and "leakiness"
  - more realistic parameters
  - equivalence between more abstract and more concrete models
  - more biological modelling
- conclusions
  - HYPE for modelling hybrid biological systems
  - use of flows to obtain ODEs
  - separation of modelling concerns

## Thank you

This research was funded by the EPSRC SIGNAL Project

► two types of actions

- two types of actions
- ▶ events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

- two types of actions
- events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

▶ activities: influences on continuous aspect of system, flows

$$\alpha \in \mathcal{A}$$
  $\alpha(\vec{X}) = (\iota, r, I(\vec{X}))$ 

- two types of actions
- events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

▶ activities: influences on continuous aspect of system, flows

$$\alpha \in \mathcal{A}$$
  $\alpha(\vec{X}) = (\iota, r, I(\vec{X}))$ 

▶ influence name  $\iota \in \mathit{IN}$ 

- two types of actions
- events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

▶ activities: influences on continuous aspect of system, flows

$$\alpha \in \mathcal{A}$$
  $\alpha(\vec{X}) = (\iota, r, I(\vec{X}))$ 

- ▶ influence name  $\iota \in IN$
- ▶ rate  $r \in \mathbb{R}$

- two types of actions
- events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

▶ activities: influences on continuous aspect of system, flows

$$\alpha \in \mathcal{A}$$
  $\alpha(\vec{X}) = (\iota, r, I(\vec{X}))$ 

- ▶ influence name  $\iota \in IN$
- ▶ rate  $r \in \mathbb{R}$
- influence type  $I(\vec{X})$  with  $[I(\vec{X})] = f(\vec{X})$

- two types of actions
- events: instantaneous, discrete changes

$$\underline{\mathsf{a}} \in \mathcal{E}$$

▶ activities: influences on continuous aspect of system, flows

$$\alpha \in \mathcal{A}$$
  $\alpha(\vec{X}) = (\iota, r, I(\vec{X}))$ 

- ▶ influence name  $\iota \in IN$
- ▶ rate  $r \in \mathbb{R}$
- influence type  $I(\vec{X})$  with  $[I(\vec{X})] = f(\vec{X})$
- parameterised by formal variables  $\vec{X}$

▶ subcomponents:  $S := \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 

- ▶ subcomponents:  $S := \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{\text{def}}{=} S$

- ▶ subcomponents:  $S ::= \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{\text{def}}{=} S$
- ▶ components:  $P ::= C(\vec{X}) \mid P \bowtie_L P$   $L \subseteq \mathcal{E}$

- ▶ subcomponents:  $S := \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{def}{=} S$
- ▶ components:  $P ::= C(\vec{X}) \mid P \bowtie_{L} P$   $L \subseteq \mathcal{E}$ 
  - component names:  $C(\vec{X}) \stackrel{def}{=} P$  or subcomponent name

- ▶ subcomponents:  $S := \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{\text{def}}{=} S$
- ▶ components:  $P ::= C(\vec{X}) \mid P \bowtie_{L} P$   $L \subseteq \mathcal{E}$ 
  - component names:  $C(\vec{X}) \stackrel{def}{=} P$  or subcomponent name
- ▶ uncontrolled system:  $\Sigma ::= C(\vec{V}) \mid \Sigma \bowtie_{L} \Sigma$   $L \subseteq \mathcal{E}$

\_\_\_

- ▶ subcomponents:  $S := \underline{a} : \alpha . C_s \mid S + S$   $\underline{a} \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{\text{def}}{=} S$
- ▶ components:  $P ::= C(\vec{X}) \mid P \bowtie_{L} P$   $L \subseteq \mathcal{E}$ 
  - ▶ component names:  $C(\vec{X}) \stackrel{def}{=} P$  or subcomponent name
- ▶ uncontrolled system:  $\Sigma ::= C(\vec{V}) \mid \Sigma \bowtie_{L} \Sigma \qquad L \subseteq \mathcal{E}$
- ► controller:  $M := \underline{a}.M \mid 0 \mid M + M$   $\underline{a} \in \mathcal{E}$  $Con := M \mid Con \bowtie Con$   $L \subseteq \mathcal{E}$

ъ,

- ▶ subcomponents:  $S ::= a : \alpha . C_s \mid S + S$   $a \in \mathcal{E}, \alpha \in \mathcal{A}$ 
  - subcomponent names:  $C_s(\vec{X}) \stackrel{def}{=} S$
- ▶ components:  $P ::= C(\vec{X}) \mid P \bowtie P$   $L \subseteq \mathcal{E}$ 
  - component names:  $C(\vec{X}) \stackrel{def}{=} P$  or subcomponent name
- ▶ uncontrolled system:  $\Sigma ::= C(\vec{V}) \mid \Sigma \bowtie \Sigma$   $L \subseteq \mathcal{E}$
- ▶ controller:  $M := a.M \mid 0 \mid M + M$   $a \in \mathcal{E}$  $Con ::= M \mid Con \bowtie Con \qquad L \subseteq \mathcal{E}$
- ▶ controlled system:  $ConSys ::= \Sigma \bowtie \underline{init}.Con$   $L \subseteq \mathcal{E}$

► HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 

- ▶ HYPE model: (ConSys, V, X, IN, IT, E, A, ec, iv, EC, ID)
  - ▶ *IN* influence names, *IT* influence types

- ► HYPE model: (ConSys, V, X, IN, IT, E, A, ec, iv, EC, ID)
  - ► *IN* influence names, *IT* influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)

Vashti Galpin

HYPE for biological systems

MFPS 24

- ▶ HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► *IN* influence names, *IT* influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $iv : IN \rightarrow V$ , association of influence names with variables

Vashti Galpin

HYPE for biological systems

MFPS 24

- ► HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► IN influence names, IT influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $\qquad \qquad \text{$i$} \textit{$v:IN} \rightarrow \mathcal{V} \text{, association of influence names with variables}$
  - ► *ID* influence descriptions,  $[I(\vec{X})] = f(\vec{X})$ ,

- ► HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► *IN* influence names, *IT* influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $\qquad \qquad \text{$i$} \textit{$v:IN} \rightarrow \mathcal{V} \text{, association of influence names with variables}$
  - ► *ID* influence descriptions,  $[I(\vec{X})] = f(\vec{X})$ ,
- well-defined HYPE model

\_\_\_

- ► HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► IN influence names, IT influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $lacktriangleright iv: \mathit{IN} 
    ightarrow \mathcal{V}$ , association of influence names with variables
  - ► *ID* influence descriptions,  $[I(\vec{X})] = f(\vec{X})$ ,
- well-defined HYPE model
  - subcomponents:

$$\mathcal{C}_s(\vec{X}) \stackrel{\text{def}}{=} \underline{\mathbf{a}}_1 : \alpha_1 . \mathcal{C}_s(\vec{X}) + \ldots + \underline{\mathbf{a}}_n : \alpha_n . \mathcal{C}_s(\vec{X}) \quad \underline{\mathbf{a}}_i \neq \underline{\mathbf{a}}_j$$

- ▶ HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► *IN* influence names, *IT* influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $iv : IN \rightarrow V$ , association of influence names with variables
  - ▶ *ID* influence descriptions,  $[I(\vec{X})] = f(\vec{X})$ ,
- well-defined HYPE model
  - subcomponents:

$$C_s(\vec{X}) \stackrel{\text{def}}{=} \underline{a}_1 : \alpha_1.C_s(\vec{X}) + \ldots + \underline{a}_n : \alpha_n.C_s(\vec{X}) \quad \underline{a}_i \neq \underline{a}_j$$

- $\underline{init}$ :  $(\iota, \_, \_)$  appears exactly once
- ▶  $\underline{a}$ :  $(\iota, -, -)$  appears at most once

- ► HYPE model:  $(ConSys, V, X, IN, IT, \mathcal{E}, A, ec, iv, EC, ID)$ 
  - ► *IN* influence names, *IT* influence types
  - $ec: \mathcal{E} \to EC$ , association of events with event conditions
  - EC, event conditions, (activation condition, reset)
  - $iv : IN \rightarrow V$ , association of influence names with variables
  - ▶ *ID* influence descriptions,  $[I(\vec{X})] = f(\vec{X})$ ,
- well-defined HYPE model
  - subcomponents:

$$C_s(\vec{X}) \stackrel{\text{def}}{=} \underline{a}_1 : \alpha_1.C_s(\vec{X}) + \ldots + \underline{a}_n : \alpha_n.C_s(\vec{X}) \quad \underline{a}_i \neq \underline{a}_j$$

- $\underline{init}$ :  $(\iota, \_, \_)$  appears exactly once
- ▶  $\underline{a}$ :  $(\iota, \_, \_)$  appears at most once
- synchronisation on shared events

ď

 $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$ 

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup {f X} = \{X_1, \dots, X_n\}, \ \dot{X}_j, \ X'_j$

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ightharpoonup control graph: G = (V, E)

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ▶ control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$

- $\triangleright$  (V, E, X, E, flow, init, inv, event, jump, reset, urgent)
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ightharpoonup control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$ 
  - associated ODEs:  $\dot{\mathbf{X}} = flow(v)$
  - initial conditions: init(v)
  - ▶ invariants: inv(v)

Vashti Galpin MFPS 24

- $\triangleright$  ( $V, E, X, \mathcal{E}$ , flow, init, inv, event, jump, reset, urgent)
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ▶ control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$ 
  - associated ODEs:  $\dot{\mathbf{X}} = flow(v)$
  - ▶ initial conditions: init(v)
  - ▶ invariants: inv(v)
- ▶ (control) switches:  $e \in E$

\_\_\_

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ▶ control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$ 
  - associated ODEs:  $\dot{\mathbf{X}} = flow(v)$
  - ▶ initial conditions: init(v)
  - ▶ invariants: inv(v)
- ▶ (control) switches:  $e \in E$ 
  - events:  $event(e) \in \mathcal{E}$

\_\_\_

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ▶ control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$ 
  - associated ODEs:  $\dot{\mathbf{X}} = flow(v)$
  - ▶ initial conditions: init(v)
  - ▶ invariants: inv(v)
- ▶ (control) switches:  $e \in E$ 
  - events:  $event(e) \in \mathcal{E}$
  - predicate on X: jump(e)
  - ▶ predicate on X ∪ X': reset(e)

ď

- $ightharpoonup (V, E, X, \mathcal{E}, flow, init, inv, event, jump, reset, urgent)$
- $ightharpoonup X = \{X_1, ..., X_n\}, \dot{X}_j, X'_j$
- ightharpoonup control graph: G = (V, E)
- ▶ (control) modes:  $v \in V$ 
  - associated ODEs:  $\dot{\mathbf{X}} = flow(v)$
  - ▶ initial conditions: init(v)
  - ▶ invariants: inv(v)
- ▶ (control) switches:  $e \in E$ 
  - events:  $event(e) \in \mathcal{E}$
  - predicate on X: jump(e)
  - ▶ predicate on  $X \cup X'$ : reset(e)
  - boolean: urgent(e)

▶ modes *V*: set of reachable configurations

- ▶ modes *V*: set of reachable configurations
- edges E: transitions between configurations

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$
- ▶ if  $v_j = \langle P_j, \sigma_j \rangle$  then

$$flow(v_j)[X_i] = \sum \{r[I(\vec{W})] \mid iv(\iota) = X_i \text{ and } \sigma_j(\iota) = (r, I(\vec{W}))\}$$

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$
- ▶ if  $v_j = \langle P_j, \sigma_j \rangle$  then  $flow(v_j)[X_i] = \sum \{r[[I(\vec{W})]] \mid iv(\iota) = X_i \text{ and } \sigma_j(\iota) = (r, I(\vec{W}))\}$
- ightharpoonup inv(v) = true

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$
- ▶ if  $v_j = \langle P_j, \sigma_j \rangle$  then  $flow(v_j)[X_i] = \sum \{r[[I(\vec{W})]] \mid iv(\iota) = X_i \text{ and } \sigma_j(\iota) = (r, I(\vec{W}))\}$
- ightharpoonup inv(v) = true
- ▶ let e be an edge associated with  $\underline{a}$  and let  $ec(\underline{a}) = (act_{\underline{a}}, res_{\underline{a}})$

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$
- if  $v_j = \langle P_j, \sigma_j \rangle$  then  $flow(v_j)[X_i] = \sum \{r[I(\vec{W})] \mid iv(\iota) = X_i \text{ and } \sigma_j(\iota) = (r, I(\vec{W}))\}$
- ightharpoonup inv(v) = true
- ▶ let e be an edge associated with  $\underline{a}$  and let  $ec(\underline{a}) = (act_{\underline{a}}, res_{\underline{a}})$ 
  - $event(e) = \underline{a}$  and  $reset(e) = res_{\underline{a}}$
  - if  $act_{\underline{a}} \neq \bot$  then  $jump(e) = act_{\underline{a}}$  and urgent(e) = true else jump(e) = true and urgent(e) = false

- modes V: set of reachable configurations
- edges E: transitions between configurations
- ightharpoonup variables  $m m{X}$ : variables  $m m{\mathcal{V}}$
- if  $v_j = \langle P_j, \sigma_j \rangle$  then  $flow(v_j)[X_i] = \sum \{r[[I(\vec{W})]] \mid iv(\iota) = X_i \text{ and } \sigma_j(\iota) = (r, I(\vec{W}))\}$
- ightharpoonup inv(v) = true
- ▶ let e be an edge associated with  $\underline{a}$  and let  $ec(\underline{a}) = (act_{\underline{a}}, res_{\underline{a}})$ 
  - $event(e) = \underline{a}$  and  $reset(e) = res_{\underline{a}}$
  - if  $act_{\underline{a}} \neq \bot$  then  $jump(e) = act_{\underline{a}}$  and urgent(e) = true else jump(e) = true and urgent(e) = false
- $init(v) = \begin{cases} res_{\underline{init}} & \text{if } v = \langle P, \sigma \rangle \text{ with primes removed} \\ false & otherwise \end{cases}$

۳.