

Towards a spatial stochastic process algebra

Vashti Galpin
Laboratory for Foundations of Computer Science
University of Edinburgh

31 July 2008

Introduction

- ▶ spatial concepts in a stochastic process algebra
- ▶ location can affect time taken
- ▶ aims
 - ▶ generality and general results hence wide application
 - ▶ CTMCs and steady state
 - ▶ separation of concerns
 - ▶ performance evaluation
 - ▶ no unnecessary increase in state space
 - ▶ single discovery of state space
 - ▶ efficient experiments

Introduction (cont.)

- ▶ examples of locations
 - ▶ nodes in networks
 - ▶ points in n -dimensional space
- ▶ applications – networks, epidemiology
- ▶ related research
 - ▶ PEPA nets (Gilmore *et al*)
 - ▶ STOKLAIM (de Nicola *et al*)
 - ▶ biological models – BioAmbients, attributed π -calculus
- ▶ work in progress
- ▶ general process algebra then applications and example

Syntax

- ▶ \mathcal{L} set of locations
- ▶ $\mathcal{P}_{\mathcal{L}} = 2^{\mathcal{L}}$ powerset
- ▶ let $L \in \mathcal{P}_{\mathcal{L}}$
- ▶ sequential components

$$S ::= (\alpha @ L, r).S \mid S + S \mid C_s @ L$$

- ▶ model components

$$P ::= P \boxtimes_M P \mid P/M \mid C$$

Location functions

- ▶ process location function
 - ▶ $ploc(C_s@L) = L \cup ploc(S)$ where $C_s@L \stackrel{def}{=} S$
 - ▶ $ploc(P) = \dots$
- ▶ action location function
 - ▶ $aloc((\alpha@L, r).S) = L \cup aloc(S)$
 - ▶ $aloc(P) = \dots$
- ▶ location function
 - ▶ $loc(P) = ploc(P) \cup aloc(P)$
- ▶ all static definitions
- ▶ current location function
 - ▶ needs a dynamic definition

Operational semantics

- ▶ relation for labels from $\mathcal{A} \times \mathcal{P}_{\mathcal{L}} \times \mathbb{R}^+$

- ▶ Prefix
$$\frac{}{(\alpha @ L, r).S \xrightarrow{(\alpha @ L', r)} S} \quad L' = \text{apref}((\alpha @ L, r).S)$$

- ▶ Cooperation
$$\frac{P_1 \xrightarrow{(\alpha @ L_1, r_1)} P'_1 \quad P_2 \xrightarrow{(\alpha @ L_2, r_2)} P'_2}{P_1 \underset{M}{\bowtie} P_2 \xrightarrow{(\alpha @ L, R)} P'_1 \underset{M}{\bowtie} P'_2} \quad \alpha \in M$$

$$L = \text{async}(P_1, P_2, L_1, L_2) \quad R = \text{rsync}(P_1, P_2, L_1, L_2, r_1, r_2)$$

- ▶ other rules defined in the obvious manner
Constant, Choice, Hiding, other two Cooperation rules

Operational semantics (cont.)

- ▶ parameterised by three functions
 - ▶ *apref* – determines location in Prefix rule
 - ▶ *async* – determines location in Cooperation rule
 - ▶ *rsync* – determines rate in Cooperation rule
- ▶ PEPA rate function

$$RPEPA(P_1, P_2, L_1, L_2, r_1, r_2) = \frac{r_1}{r_\alpha(P_1)} \frac{r_2}{r_\alpha(P_2)} \min(r_\alpha(P_1), r_\alpha(P_2))$$

- ▶ can define *apref* and *async* for PEPA as well
- ▶ use of different functions to obtain different process algebras

Possible interpretations

$ ploc(C_S) = 1$	process at one location
$ ploc(C_S) > 1$	process is mobile <i>or</i> process at one of some possible locations
$ aloc(C_S) = 1$	all actions occur at one location
$ aloc(C_S) > 1$	interaction is mobile <i>or</i> actions occur at one of some possible locations
$P \xrightarrow{(\alpha@L,r)} P', L = 1$	synchronisation happens at one location
$P \xrightarrow{(\alpha@L,r)} P', L > 1$	synchronisation involves actions <i>or</i> processes at different locations
...	...

And that's not all

- ▶ beyond just adding locations, want to use them for performance evaluation
- ▶ aims
 - ▶ relate locations to each other
 - ▶ want interesting theoretical results
 - ▶ want to minimise time in analysis
- ▶ graph structure over locations
- ▶ weighted hypergraph: $G = (\mathcal{L}, E, w)$ with $E \subseteq \mathcal{P}_{\mathcal{L}}$ and $w : E \rightarrow \mathbb{R}$ or weighted directed graph
- ▶ weights modify rates on actions between locations
- ▶ weights assigned or calculated

Theoretical results – aim

- ▶ combine graph and known structures to obtain new results quickly

Analysis	PEPA model	Modified by G	Form of result
PEPA model	P	P_G	
↓			
LMTS	\mathcal{M}	\mathcal{M}_G	$\mathcal{M} \odot G = \mathcal{M}_G$
↓			
CTMC	\mathcal{Q}	\mathcal{Q}_G	$\mathcal{Q} \boxtimes G = \mathcal{Q}_G$
↓			
steady state	Π	Π_G	$\Pi \boxtimes G = \Pi_G$

Application – plant epidemiology

- ▶ epidemiology with spatial aspects
- ▶ grapevine diseases in vineyards
- ▶ mealy bug insect – vector for leaf roll disease
- ▶ two separate issues
 - ▶ delay before vector arrives at uninfected plant – dependent on distance between plants, hence dependent on vineyard layout
 - ▶ delay before newly arrived vector infects plant
- ▶ three distinct patterns of infection
- ▶ build models to explain this

Application – networking

- ▶ networking performance
- ▶ scenario
 - ▶ arbitrary topology
 - ▶ single packet traversal through network
 - ▶ processes can be colocated
- ▶ want to model different traffic situations
- ▶ choose functions to create process algebra
 - ▶ each sequential component must have single fixed location
 - ▶ communication must be pairwise and directional

Application – networking (cont.)

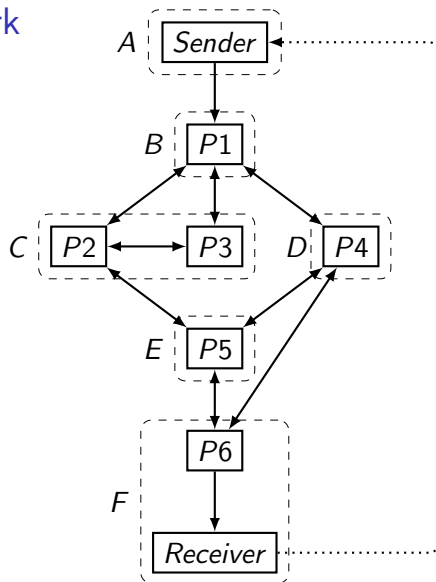
► functions

$$\text{apref}(S) = \begin{cases} I & \text{if } \text{ploc}(S) = \{I\} \\ \perp & \text{otherwise} \end{cases}$$

$$\text{async}(P_1, P_2, L_1, L_2) = \begin{cases} (l_1, l_2) & \text{if } L_1 = \{l_1\}, L_2 = \{l_2\} \\ \perp & \text{otherwise} \end{cases}$$

$$\begin{aligned} & \text{rsync}(P_1, P_2, L_1, L_2, r_1, r_2) \\ &= \begin{cases} \frac{r_1}{r_\alpha(P_1)} \frac{r_2}{r_\alpha(P_2)} \min(r_\alpha(P_1), r_\alpha(P_2)) \cdot w((l_1, l_2)) & \text{if } L_1 = \{l_1\}, L_2 = \{l_2\}, (l_1, l_2) \in E \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

Example network



PEPA model

$$Sender@A \stackrel{def}{=} (prepare, \rho).Sending@A$$

$$Sending@A \stackrel{def}{=} (cSto1, r_1).(ack, r_{ack}).Sender@A$$

$$Receiver@F \stackrel{def}{=} (c6toR, r_6).Receiving@F$$

$$Receiving@F \stackrel{def}{=} (consume, \gamma).(ack, r_{ack}).Receiver@F$$

...

$$P2@C \stackrel{def}{=} (c1to2, r).(P2'@C + (c3to2, r).P2'@C + (c5to2, r).P2'@C$$

$$P2'@C \stackrel{def}{=} (c2to1, r).P2@C + (c2to3, r).P2@C + (c2to5, r).P2@C$$

...

$$Network \stackrel{def}{=} (Sender@A \underset{L_5}{\boxtimes} (P1@B \underset{L_1}{\boxtimes} (P2@C \underset{L_2}{\boxtimes} (P3@C \underset{L_3}{\boxtimes} \\ (P4@D \underset{L_4}{\boxtimes} (P5@E \underset{L_5}{\boxtimes} (P6@F \underset{L_R}{\boxtimes} Receiver@F))))))$$

Graphs

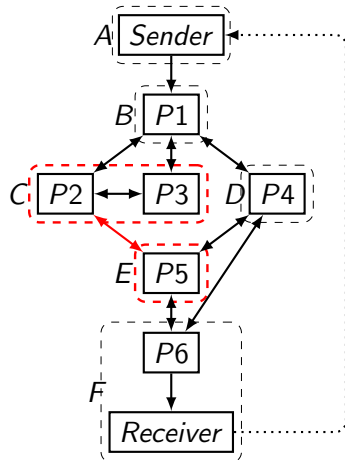
- ▶ rates: $r = r_1 = r_6 = 10$
- ▶ the weighted graph G has no effect on the rates in the model

	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>
<i>A</i>	1	1				
<i>B</i>			1	1		
<i>C</i>		1	1		1	
<i>D</i>		1			1	1
<i>E</i>			1	1		1
<i>F</i>	1			1	1	1

Graphs

- ▶ G_1 represents heavy traffic between C and E

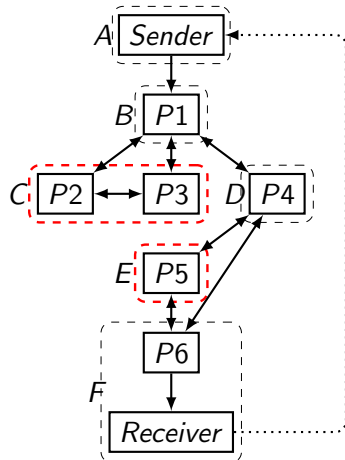
	A	B	C	D	E	F
A	1	1				
B			1	1		
C		1	1		0.1	
D		1			1	1
E			0.1	1		1
F	1			1	1	1



Graphs

- ▶ G_2 represents no connectivity between C and E

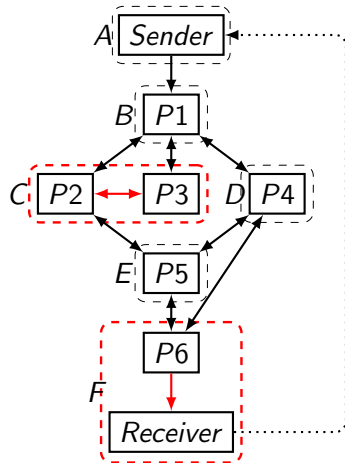
	A	B	C	D	E	F
A	1	1				
B			1	1		
C		1	1		0	
D		1			1	1
E			0	1		1
F	1			1	1	1



Graphs

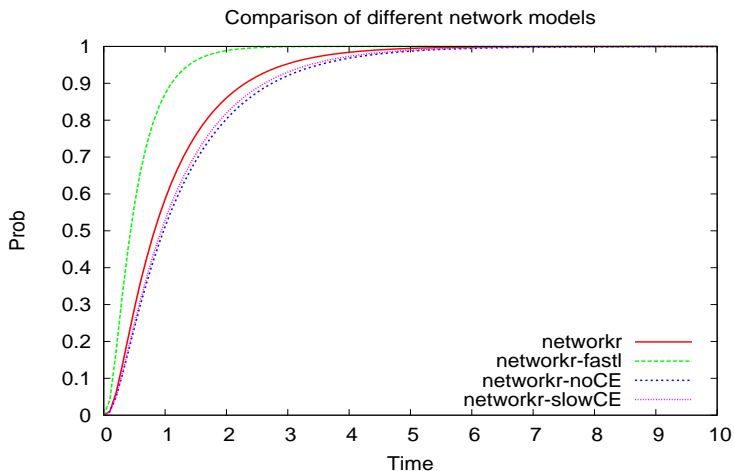
- G_3 represents high connectivity between colocated processes

	A	B	C	D	E	F
A	1	1				
B			1	1		
C		1	10		1	
D		1			1	1
E			1	1		1
F	1			1	1	10



Analysis

- cumulative density function of passage time



Further work and conclusions

- ▶ further work
 - ▶ finalise general process algebra
 - ▶ more specific applications
 - ▶ theoretical results
 - ▶ semantic equivalences
- ▶ conclusions
 - ▶ first steps towards a very general stochastic process algebra with locations
 - ▶ most important aspect is that locations affect rates

Thank you

This research was funded by the EPSRC SIGNAL Project