# Learning from Data: Density Estimation -Gaussian Distribution

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October 10, 2005

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## The Gaussian Distribution

- Last lecture we talked about density estimation, and gave some examples on binary or Boolean quantities.
- ► This lecture we will be focusing on continuous quantities.
- The most common (and most easily analysed) distribution for continuous quantities is the Gaussian distribution.
- Gaussian distribution is often a reasonable model for many quantities due to various central limit theorems.
- Gaussian is sometimes called a normal distribution.

### Definition

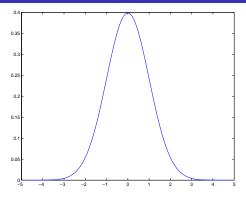
The one dimensional Gaussian distribution is given by

$$P(x|\mu,\sigma^2) = N(x;\mu,\sigma^2) = rac{1}{\sqrt{2\pi\sigma^2}}\exp{-rac{(x-\mu)^2}{2\sigma^2}}$$

- $\mu$  is the *mean* of the Gaussian and  $\sigma^2$  is the *variance*.
- If μ = 1 and σ<sup>2</sup> = 1 then N(x; μ, σ<sup>2</sup>) is called a *standard* Gaussian.

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### Plot

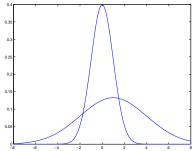


This is a standard one dimensional Gaussian distribution.

- All Gaussians have the same shape subject to scaling and displacement.
- If x is distributed N(x; μ, σ<sup>2</sup>), then y = (x − μ)/σ is distributed N(y; 0, 1).

#### Normalisation

- Remember all distributions must integrate to one. The  $\sqrt{2\pi\sigma^2}$  is called a normalisation constant it ensures this is the case.
- Hence tighter Gaussians have higher peaks:



## Central Limit Theorems (Interest Only)

- >  $X_i$  mean 0, variance  $\Sigma$ , not necessarily Gaussian.
- ► X<sub>i</sub> subject to various conditions (e.g. IID).

$$rac{1}{\sqrt{N}}\sum_{i=1}^N X_i \sim N(0,\Sigma)$$

asymptotically as  $N \to \infty$ .

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## Maximum Likelihood Estimation

- Suppose we have data  $\{x_i, i = 1, 2, ..., n\}$ .
- Suppose we presume the data was generated from a Gaussian with mean μ and variance σ<sup>2</sup>. Call this the model.
- Then the log probability of the data given the model is

$$\log \prod_{i} P(x_{i}|\mu,\sigma^{2}) = -\frac{1}{2} \sum_{i} \frac{(x_{i}-\mu)^{2}}{\sigma^{2}} - \frac{N}{2} \log(2\pi\sigma^{2})$$

Steps left as exercise: hint log  $\prod = \sum \log$ 

## Maximum Likelihood Estimation

▶ Maximum likelihood: Set  $\gamma = 1/\sigma^2$  Take derivatives

$$\log P(X|\mu,\gamma) = -\frac{1}{2} \sum_{i} \gamma(x_{i}-\mu)^{2} - \frac{N}{2} \log(2\pi) + \frac{N}{2} \log \gamma$$
$$\frac{\partial \log P(X|\mu,\gamma)}{\partial \mu} = \gamma \sum_{i} (x_{i}-\mu)$$
$$\frac{\partial \log P(X|\mu,\gamma)}{\partial \gamma} = -\frac{1}{2} \sum_{i} (x_{i}-\mu)^{2} + \frac{N}{2\gamma}$$

- Hence  $\mu = (1/N) \sum_{i} x_{i}$  and  $\sigma^{2} = (1/N) \sum_{i} (x_{i} \mu)^{2}$ .
- Maximum likelihood estimate of σ<sup>2</sup> is biased.

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## Multivariate Gaussian

The vector x is multivariate Gaussian if for mean μ and covariance matrix Σ, it is distributed according to

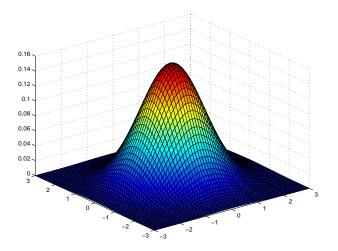
$$P(\mathbf{x}|\boldsymbol{\mu},\boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2}|\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T\boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})\right)$$

- The univariate Gaussian is a special case to this.
- We already met covariance matrices.  $\Sigma$  is the same form.

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**Gaussian Distribution** 

#### Multivariate Gaussian: Picture



#### Multivariate Gaussian: Maximum Likelihood

The Maximum Likelihood estimate can be found in the same way.

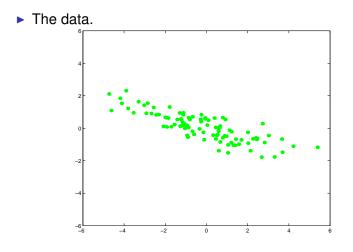
$$\boldsymbol{\mu} = (1/N) \sum_{i=1}^{N} \mathbf{x}_i$$

$$\boldsymbol{\Sigma} = (1/N) \sum_{i=1}^{N} (\mathbf{x}_i - \boldsymbol{\mu}) (\mathbf{x}_i - \boldsymbol{\mu})^T$$

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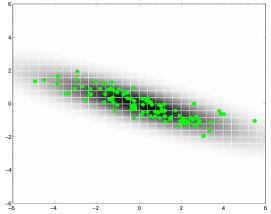
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#### Example



## Example

#### The data. The maximum likelihood fit.



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### Class conditional classification

- Have real valued multivariate data, along with class label for each point.
- Want to predict the value of the class label given some new point.
- Presume that if we take all the points with a particular label, then we believe they were sampled from a Gaussian.
- How should we predict the class at a new point?

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## Class conditional classification

- Learning: Fit Gaussian to data in each class (class conditional fitting). Gives P(position|class)
- Find estimate for probability of each class (see last lecture)
   P(class)
- Inference: Given a new position, we can ask "What is the probability of this point being generated by each of the Gaussians.
- Pick the largest (just like maximum likelihood)
- Better still give probability using Bayes rule

 $P(\text{class}|\text{position}) \propto P(\text{position}|\text{class})P(\text{class})$ 

Then can get ratio

P(class = 1|position)/P(class = 0|position).

Decision boundary for two classes is where this ratio is one.

#### Summary

- Gaussian
- Maximum Likelihood fitting of a Gaussian
- Multivariate Gaussian and covariances again.
- Maximum Likelihood fitting.
- Class conditional classification using Gaussians.

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