

A Crash Course on Complexity Theory

we recall some fundamental notions from complexity theory that will be heavily used in the context of this course - further details can be found in the standard textbooks

Deterministic Turing Machine (DTM)

$$M = (S, \Lambda, \Gamma, \delta, s_0, s_{\text{accept}}, s_{\text{reject}})$$

- S is the set of states
- Λ is the input alphabet, not containing the blank symbol \sqcup
- Γ is the tape alphabet, where $\sqcup \in \Gamma$ and $\Lambda \subseteq \Gamma$
- $\delta : S \times \Gamma \rightarrow S \times \Gamma \times \{L, R\}$
- s_0 is the initial state
- s_{accept} is the accept state
- s_{reject} is the reject state, where $s_{\text{accept}} \neq s_{\text{reject}}$

Deterministic Turing Machine (DTM)

$$M = (S, \Lambda, \Gamma, \delta, s_0, s_{\text{accept}}, s_{\text{reject}})$$

$$\delta(s_1, \alpha) = (s_2, \beta, R)$$

IF at some time instant τ the machine is in state s_1 , the cursor points to cell κ , and this cell contains α

THEN at instant $\tau+1$ the machine is in state s_2 , cell κ contains β , and the cursor points to cell $\kappa+1$

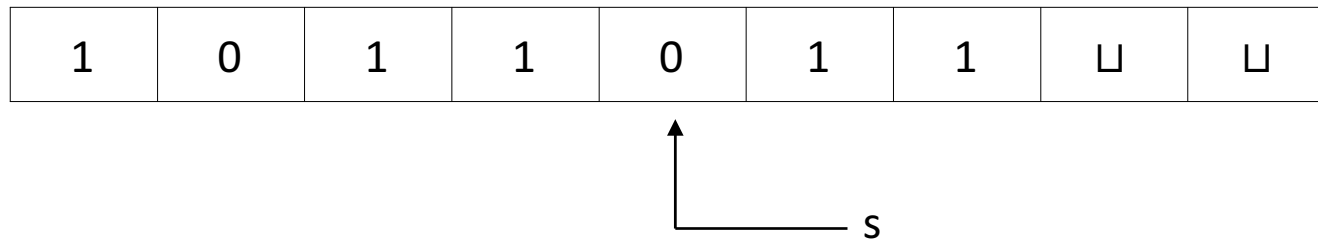
Nondeterministic Turing Machine (NTM)

$$M = (S, \Lambda, \Gamma, \delta, s_0, s_{\text{accept}}, s_{\text{reject}})$$

- S is the set of states
- Λ is the input alphabet, not containing the blank symbol \sqcup
- Γ is the tape alphabet, where $\sqcup \in \Gamma$ and $\Lambda \subseteq \Gamma$
- $\delta : S \times \Gamma \rightarrow \text{power set of } S \times \Gamma \times \{L,R\}$
- s_0 is the initial state
- s_{accept} is the accept state
- s_{reject} is the reject state, where $s_{\text{accept}} \neq s_{\text{reject}}$

Turing Machine Configuration

A perfect description of the machine at a certain point in the computation

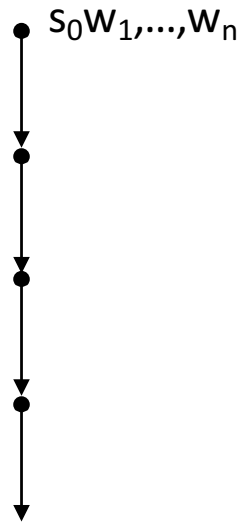


is represented as a string: **1011s011**

- Initial configuration on input w_1, \dots, w_n - $s_0 w_1, \dots, w_n$
- Accepting configuration - $u_1, \dots, u_k s_{\text{accept}} u_{k+1}, \dots, u_{k+m}$
- Rejecting configuration - $u_1, \dots, u_k s_{\text{reject}} u_{k+1}, \dots, u_{k+m}$

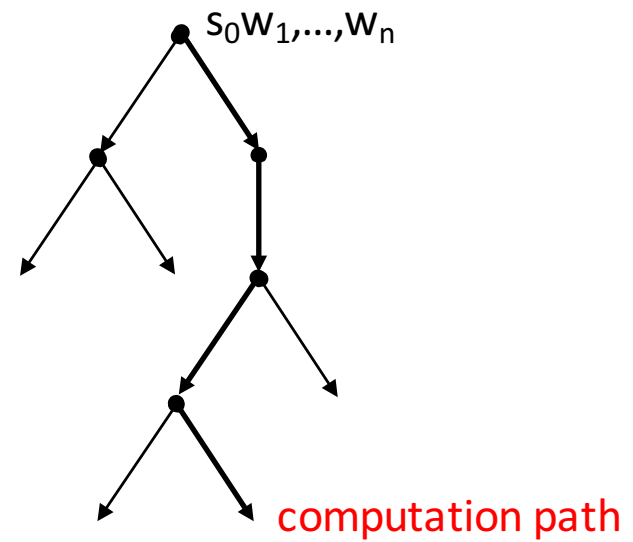
Turing Machine Computation

Deterministic



the next configuration is unique

Nondeterministic



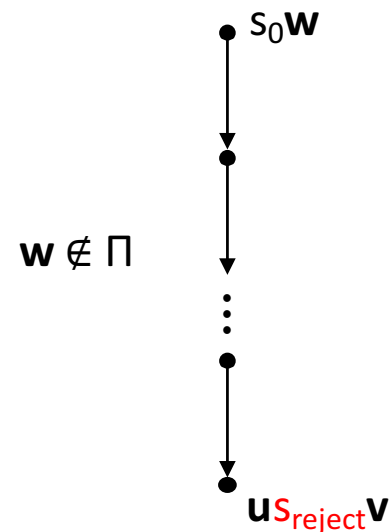
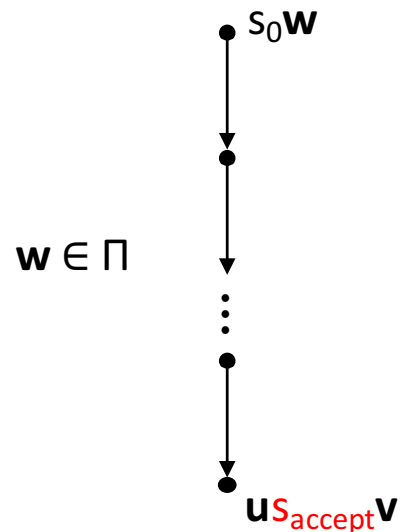
computation tree

Deciding a Problem

(recall that an instance of a decision problem Π is encoded as a word over a certain alphabet Λ - thus, Π is a set of words over Λ , i.e., $\Pi \subseteq \Lambda^*$)

A DTM $M = (S, \Lambda, \Gamma, \delta, s_0, s_{\text{accept}}, s_{\text{reject}})$ **decides** a problem Π if, for every $w \in \Lambda^*$:

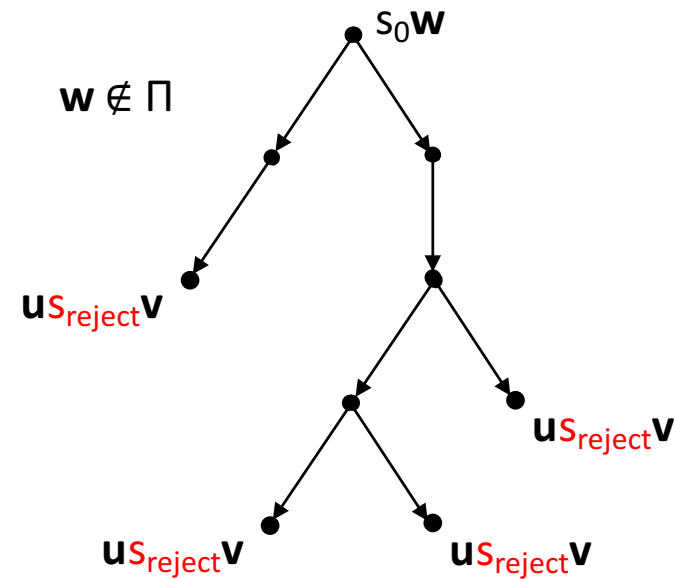
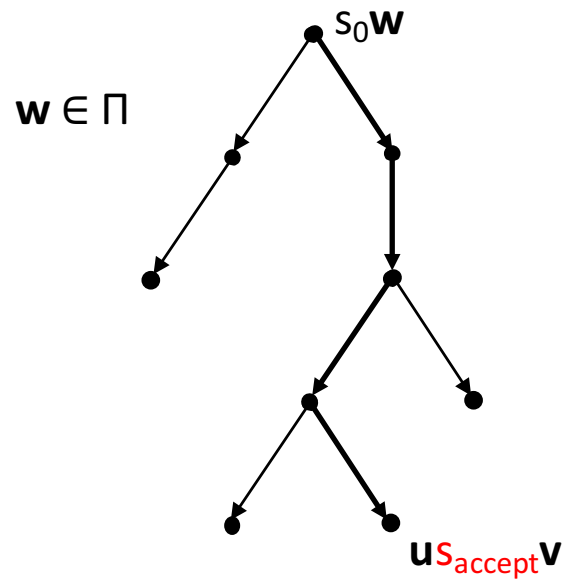
- M on input w halts in s_{accept} if $w \in \Pi$
- M on input w halts in s_{reject} if $w \notin \Pi$



Deciding a Problem

A NTM $M = (S, \Lambda, \Gamma, \delta, s_0, s_{\text{accept}}, s_{\text{reject}})$ **decides** a problem Π if, for every $w \in \Lambda^*$:

- The computation tree of M on input w is finite
- There exists **at least one** accepting computation path if $w \in \Pi$
- There is **no** accepting computation path if $w \notin \Pi$



Complexity Classes

Consider a function $f : \mathbb{N} \rightarrow \mathbb{N}$

$$\text{TIME}(f(n)) = \{\Pi \mid \Pi \text{ is decided by some DTM in time } O(f(n))\}$$

$$\text{NTIME}(f(n)) = \{\Pi \mid \Pi \text{ is decided by some NTM in time } O(f(n))\}$$

$$\text{SPACE}(f(n)) = \{\Pi \mid \Pi \text{ is decided by some DTM using space } O(f(n))\}$$

$$\text{NSPACE}(f(n)) = \{\Pi \mid \Pi \text{ is decided by some NTM using space } O(f(n))\}$$

Complexity Classes

- We can now recall the standard time and space complexity classes:

PTIME	=	$\bigcup_{k>0} \text{TIME}(n^k)$	
NP	=	$\bigcup_{k>0} \text{NTIME}(n^k)$	
EXPTIME	=	$\bigcup_{k>0} \text{TIME}(2^{n^k})$	
NEXPTIME	=	$\bigcup_{k>0} \text{NTIME}(2^{n^k})$	
LOGSPACE	=	$\text{SPACE}(\log n)$	} these definitions are relying on two-tape Turing machines with a read-only and a read/write tape
NLOGSPACE	=	$\text{NSPACE}(\log n)$	
PSPACE	=	$\bigcup_{k>0} \text{SPACE}(n^k)$	
EXPSPACE	=	$\bigcup_{k>0} \text{SPACE}(2^{n^k})$	

- For every complexity class C we can define its **complementary class** $\text{co}C$

$$\text{co}C = \{\Lambda^* \setminus \Pi \mid \Pi \in C\}$$

An Alternative Definition for NP

Theorem: Consider a problem $\Pi \subseteq \Lambda^*$. The following are equivalent:

- $\Pi \in \text{NP}$
- There is a relation $R \subseteq \Lambda^* \times \Lambda^*$ that is *polynomially decidable* such that

$$\Pi = \{\mathbf{u} \mid \text{there exists } \mathbf{w} \text{ such that } |\mathbf{w}| \leq |\mathbf{u}|^k \text{ and } (\mathbf{u}, \mathbf{w}) \in R\}$$

witness or certificate

$$\{\mathbf{xy} \in \Lambda^* \mid (\mathbf{x}, \mathbf{y}) \in R\} \in \text{PTIME}$$

Example:

$$3\text{SAT} = \{\phi \mid \phi \text{ is a 3CNF formula that is satisfiable}\}$$

$$= \{\phi \mid \phi \text{ is a 3CNF for which there is an assignment } \alpha \text{ such that } |\alpha| \leq |\phi| \text{ and } (\phi, \alpha) \in R\}$$

where $R = \{(\phi, \alpha) \mid \alpha \text{ is a satisfying assignment for } \phi\} \in \text{PTIME}$

Relationship Among Complexity Classes

$\text{LOGSPACE} \subseteq \text{NLOGSPACE} \subseteq \text{PTIME} \subseteq \text{NP}, \text{coNP} \subseteq$

$\text{PSPACE} \subseteq \text{EXPTIME} \subseteq \text{NEXPTIME}, \text{coNEXPTIME} \subseteq \dots$

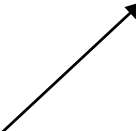
Some useful notes:

- For a deterministic complexity class C , $\text{co}C = C$
- $\text{coNLOGSPACE} = \text{NLOGSPACE}$
- It is generally believed that $\text{PTIME} \neq \text{NP}$, but we don't know
- $\text{PTIME} \subset \text{EXPTIME} \Rightarrow$ at least one containment between them is strict
- $\text{PSPACE} = \text{NPSPACE}$, $\text{EXSPACE} = \text{NEXSPACE}$, etc.
- But, we don't know whether $\text{LOGSPACE} = \text{NLOGSPACE}$

Complete Problems

- These are the hardest problems in a complexity class
- A problem that is complete for a class C, it is unlikely to belong in a lower class
- A problem Π is **complete** for a complexity class C, or simply **C-complete**, if:
 1. $\Pi \in C$
 2. Π is C-hard, i.e., every problem $\Pi' \in C$ can be **efficiently reduced** to Π

there exists a logspace algorithm that computes a function f such that
 $w \in \Pi' \text{ iff } f(w) \in \Pi$ - in this case we write $\Pi' \leq_L \Pi$



- To show that Π is C-hard it suffices to reduce some C-hard problem Π' to it

Some Complete Problems

- **NP-complete**
 - SAT (satisfiability of propositional formulas)
 - Many graph-theoretic problems (e.g., 3-colorability)
 - Traveling salesman
 - etc.
- **PSPACE-complete**
 - Quantified SAT (or simply QSAT)
 - Equivalence of two regular expressions
 - Many games (e.g., Geography)
 - etc.