

A unified treatment of concrete sheaf models for higher-order recursion

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Modelling higher-order programs with recursion

Model

- ▶ Cartesian closed category (CCC)
- ▶ Partiality monad, L
- ▶ Interpretation: Type \longleftrightarrow Object
Program \longleftrightarrow Partial morphism

Examples:

- (1) **Probabilistic programming**: partial maps that are measurable
[Heunen et al.'17, Vákár et al.'19]
- (2) **Automatic differentiation**: partial maps that are smooth
[Huot et al.'20, Vákár'20]
- (3) Piecewise differentiable programs [Lew et al.'21]
- (4) **Full abstraction** for a sequential language: definable partial maps
[O'Hearn & Riecke'95], [Matache, Moss, Staton, FSCD'21] 2/26

Goal of this talk

Main Theorem [Matache, Moss, Staton, in preparation]

The examples

- (1) Probabilistic programming
- (2) Automatic differentiation
- (3) Piecewise differentiation
- (4) Full abstraction

} all model higher-order recursion
using the same recipe

- ▶ using **concrete sheaves**
- ▶ using ideas from synthetic domain theory for **recursion**

In each case more domain specific work needs to be done.

Examples of concrete sheaves: subsequential spaces [Johnstone'79], C -spaces [Escardó & Xu'16]

Examples of concrete presheaves: [Rosolini & Streicher'99], finiteness spaces [Ehrhard'07]

Goal of this talk (continued)

Main Theorem [Matache, Moss, Staton, in preparation]

The examples

- (1) Probabilistic programming
- (2) Automatic differentiation
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} all model higher-order recursion
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Corollary: conservativity result for (1), (2), (3)

E.g.(2): Programs $\text{real} \rightarrow \text{real}$ are still interpreted as smooth maps even if they use higher-order recursion.

PCF_v: A call-by-value language

Call-by-value λ -calculus with:

- ▶ base types e.g. `nat`, `real`
- ▶ function types
- ▶ product and sum types
- ▶ recursive functions.

An interpretation looks like:

$$\llbracket \text{nat} \rrbracket = 1 + 1 + \dots \quad \llbracket \tau_1 + \tau_2 \rrbracket = \llbracket \tau_1 \rrbracket + \llbracket \tau_2 \rrbracket \quad \llbracket \tau_1 \times \tau_2 \rrbracket = \llbracket \tau_1 \rrbracket \times \llbracket \tau_2 \rrbracket$$

$$\llbracket \tau \rightarrow \tau' \rrbracket = \llbracket \tau \rrbracket \Rightarrow L[\llbracket \tau' \rrbracket] \quad \llbracket \Gamma \vdash t : \tau \rrbracket : \llbracket \Gamma \rrbracket \rightarrow L[\llbracket \tau \rrbracket]$$

Model

- ▶ Cartesian closed category (CCC)
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- 1 Introduction
- 2 Higher-order computation: categories of concrete sheaves**
- 3 Modelling partiality
- 4 Modelling recursion
- 5 Putting it all together

Why use categories of concrete sheaves?

Example: **first-order probabilistic computation** can be modelled in \mathbf{Sbs} .
 \mathbf{Sbs} is NOT cartesian closed.

The category of **presheaves** on \mathbf{Sbs} is cartesian closed.

Yoneda embedding

$$y : \mathbf{Sbs} \hookrightarrow \mathbf{PSh}(\mathbf{Sbs})$$

Full, faithful, preserves limits.
Does not preserve colimits.

Restricting to **sheaves** on a **site** (\mathbf{Sbs}, J) preserves some colimits from \mathbf{Sbs} .
Concrete sheaves = sets with structure + structure-preserving functions.

$$\mathbf{ConcSh}(\mathbf{Sbs}, J) \hookrightarrow \mathbf{Sh}(\mathbf{Sbs}, J) \hookrightarrow \mathbf{PSh}(\mathbf{Sbs})$$

Well-pointed categories and concrete sites

A category \mathbb{C} is *well-pointed* if

- it has a terminal object \star
- $\mathbb{C}(\star, -) : \mathbb{C} \rightarrow \mathbf{Set}$ is faithful
i.e. maps $h : d \rightarrow c$ are distinguished *functions* $|h| : |d| \rightarrow |c|$

where $|c| = \mathbb{C}(\star, c)$. So \mathbb{C} is a category of sets and certain functions.

Concrete site (\mathbb{C}, J)

- A small well-pointed category \mathbb{C}
- For every $c \in \mathbb{C}$ a set $J(c)$ of **covering families** $\{f_i : c_i \rightarrow c\}_{i \in I}$ of c s.t.
 - (C) pullback stability
 - (\star) If $\{f_i : c_i \rightarrow c\}_{i \in I}$ covers c , then $\bigcup_{i \in I} \text{Im}(|f_i|) = |c|$

Concrete sheaf on a concrete site (\mathbb{C}, J)

[Concrete quasitopoi, Dubuc'77]

[Convenient categories of smooth spaces, Baez & Hoffnung'11]

Well-pointed category \mathbb{C}

- has a terminal \star
- a map $h : d \rightarrow c$ is a function between sets $|d| = \mathbb{C}(\star, d)$ etc.

Concrete site (\mathbb{C}, J)

- small well-pointed \mathbb{C}
- For every $c \in \mathbb{C}$ a set $J(c)$ of **covering families** $\{f_i : c_i \rightarrow c\}_{i \in I}$ of c , with axioms (C) and \star .

A concrete sheaf $X : \mathbb{C}^{\text{op}} \rightarrow \mathbf{Set}$ is:

- ▶ a set $X(\star)$
- ▶ $X(c) \subseteq [|c| \rightarrow X(\star)]$

$X(h : d \rightarrow c)$ is precomposition by $|h|$.

Sheaf condition: for each function

$g : |c| \rightarrow X(\star)$ and each covering family $\{f_i : c_i \rightarrow c\}_{i \in I} \in J(c)$, if each $g \circ |f_i| \in X(c_i)$, then $g : |c| \rightarrow X(\star) \in X(c)$.



A morphism $\alpha : X \rightarrow Y$ is a structure-preserving function $\alpha : X(\star) \rightarrow Y(\star)$.

Example: modelling probabilistic programming [Heunen et al.'17, Vákár et al.'19]

A functor $X : \mathbb{C}^{\text{op}} \rightarrow \text{Set}$ is a **concrete sheaf** on a **concrete site** (\mathbb{C}, J) if $X(c) \subseteq [c \rightarrow X(\star)]$ and X satisfies the **sheaf condition**.

Quasi-Borel spaces is the category of concrete sheaves on:

- **Sbs:** objects U are Borel subsets of \mathbb{R}
morphisms are measurable functions between these sets.
- $J(U) =$ countable sets of measurable inclusions $\{U_i \hookrightarrow U\}_{i \in I}$ where $U = \bigcup_{i \in I} U_i$ and the U_i 's are disjoint.

$X(\mathbb{R}) \subseteq [\mathbb{R} \rightarrow X(\star)]$ is the set of “random elements” of $X(\star)$.

Example: modelling probabilistic programming in $\text{ConcSh}(\text{Sbs}, J)$

A functor $X : \mathbb{C}^{\text{op}} \rightarrow \text{Set}$ is a **concrete sheaf** on a **concrete site** (\mathbb{C}, J) if $X(c) \subseteq [|c| \rightarrow X(\star)]$ and X satisfies the **sheaf condition**.

$\text{Sbs} =$ Borel subsets $U \subseteq \mathbb{R} +$ measurable functions

$J(U) =$ sets of inclusions $\{U_i \hookrightarrow U\}_{i \in I}$ where $U = \bigcup_{i \in I} U_i$ and the U_i 's are disjoint.

In $\text{PSh}(\text{Sbs})$, take X concrete. In Sbs , take $\mathbb{R} = \bigcup_{i \in I} U_i$ and U_i 's disjoint:

$$\begin{array}{ccc}
 y\mathbb{R} & & \\
 \uparrow & \dashrightarrow & \\
 \sum_{i \in I} yU_i & & X
 \end{array}
 \quad \text{by Yoneda lemma}
 \quad
 \begin{array}{c}
 (g : \mathbb{R} \rightarrow X(\star)) \in X(\mathbb{R}) \\
 \Updownarrow \\
 \{(f_i : U_i \rightarrow X(\star)) \in X(U_i)\}_{i \in I}
 \end{array}$$

Sheaf condition at \mathbb{R} : for each function $g : \mathbb{R} \rightarrow X(\star)$ and each covering family $\{f_i : U_i \rightarrow \mathbb{R}\}_{i \in I} \in J(c)$, if each $g \circ f_i \in X(U_i)$, then $g : \mathbb{R} \rightarrow X(\star) \in X(\mathbb{R})$.

$$\begin{array}{ccc}
 & & \\
 & \searrow & \\
 U_i & \xleftarrow{f_i} & \mathbb{R} \xrightarrow{g} X(\star) \\
 & \swarrow & \\
 & &
 \end{array}$$

Example: modelling differentiable programs [Huot et al.'20, Vákár'20]

A functor $X : \mathbb{C}^{\text{op}} \rightarrow \text{Set}$ is a **concrete sheaf** on a **concrete site** (\mathbb{C}, J) if $X(c) \subseteq [|c| \rightarrow X(\star)]$ and X satisfies the **sheaf condition**.

Diffeological spaces is the category of concrete sheaves on:

- Site: objects are open subsets $U \subseteq \mathbb{R}^n$ for any n
morphisms are smooth maps.
- $J(U) =$ countable sets of open inclusions $\{U_i \hookrightarrow U\}_{i \in I}$ where $U = \bigcup_{i \in I} U_i$.

$X(U) \subseteq [U \rightarrow X(\star)]$ is the set of “plots” of $X(\star)$.

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Partial maps

In any category, a **partial map** $X \rightharpoonup Y$ is a pair (m, f) :

$$\begin{array}{ccc} X' & \xrightarrow{f} & Y \\ \downarrow m \in \mathcal{N} & & \\ X & & \end{array}$$

where \mathcal{N} is **stable class of monos**:

- contains all isomorphisms
- closed under composition
- stable under pullback (with arbitrary maps)

(1) **Quasi-Borel spaces**: partial maps that are measurable, with Borel domain

(2) **Diffeological spaces**: partial maps that are smooth, with open domain

From partial maps to a lifting monad

How do we get a monad L with the following property?

For every
$$\begin{array}{ccc} X' & \xrightarrow{f} & Y \\ \downarrow_{m \in \mathcal{N}} & & \\ X & & \end{array}$$
, where \mathcal{N} is a stable class of monos

there is exactly one corresponding total map $X \rightarrow LY$ such that

$$\begin{array}{ccc} X' & \xrightarrow{f} & Y \\ \downarrow_{m \in \mathcal{N}} & \lrcorner & \downarrow_{\eta_Y} \\ X & \xrightarrow{\exists!} & LY \end{array}$$

and conversely.

L might not exist in general.

From partial maps to a lifting monad (continued)

In a sheaf category $\text{Sh}(\mathbb{C}, J)$:

Theorem

\mathcal{N} has an associated lifting monad L if the class of monos \mathcal{N} “comes from” a **class of pre-admissible monos \mathcal{M} in \mathbb{C}** .

\mathcal{M} is a class of pre-admissible monos in \mathbb{C} if:

- stable class
- $\Delta_{\mathcal{M}} : \mathbb{C}^{\text{op}} \rightarrow \text{Set}$ is a J -sheaf, where:
 $\Delta_{\mathcal{M}}(c) = \text{iso. classes of } c' \twoheadrightarrow c \in \mathcal{M}$
 $\Delta_{\mathcal{M}}(f : d \rightarrow c) = \text{pullback along } f$

\mathcal{N} stable class of monos:

- contains all isomorphisms
- closed under composition
- stable under pullback

Lifting monad:

for every $(m, f) : X \twoheadrightarrow Y$ with $m \in \mathcal{N}$, there is exactly one total map $X \rightarrow LY$.

$$\begin{array}{ccc} d' & \xrightarrow{\in \mathcal{M}} & d \\ \downarrow & \lrcorner & \downarrow f \\ c' & \xrightarrow{\in \mathcal{M}} & c \end{array}$$

From partial maps to a lifting monad (continued)

In a sheaf category $\text{Sh}(\mathbb{C}, J)$:

Theorem

\mathcal{N} has an associated lifting monad L if the class of monos \mathcal{N} “comes from” a **class of pre-admissible monos \mathcal{M} in \mathbb{C}** .

\mathcal{N} “comes from” \mathcal{M} if

$\mathcal{N} =$ all pullbacks of $\top : 1 \rightarrow \Delta_{\mathcal{M}}$,

where $\top_c = [\text{id}_c]$

$$\begin{array}{ccc} X' & \xrightarrow{!} & 1 \\ \in \mathcal{N} \downarrow & \lrcorner & \downarrow \top \\ X & \xrightarrow{x} & \Delta_{\mathcal{M}} \end{array}$$

\mathcal{N} stable class of monos:

- contains all isomorphisms
- closed under composition
- stable under pullback

Lifting monad:

for every $(m, f) : X \rightarrow Y$ with $m \in \mathcal{N}$, there is exactly one total map $X \rightarrow LY$.

\mathcal{M} stable class

$\Delta_{\mathcal{M}} : \mathbb{C}^{\text{op}} \rightarrow \text{Set}$ a J -sheaf

$\Delta_{\mathcal{M}}(c) =$ iso. classes of $c' \twoheadrightarrow c \in \mathcal{M}$

$\Delta_{\mathcal{M}}(f : d \rightarrow c) =$ pullback along f

see e.g [Rosolini'86] for dominance, [Mulry'94],
[Fiore&Plotkin'97] for constructing a lifting monad

Examples: classes of pre-admissible monos

Quasi-Borel spaces:

Site: objects U are Borel subsets of \mathbb{R} ,
morphisms are measurable functions.

\mathcal{M} = for every U , the measurable
monos with codomain U

Diffeological spaces:

Site: objects are open subsets $U \subseteq \mathbb{R}^n$ for any n ,
morphisms are smooth maps.

\mathcal{M} = for every U , the open inclusion
maps into U

For a concrete sheaf X , the lifting monad:

$$LX(\star) = X(\star) \uplus \{\perp\}$$

$$LX(U) = \{g : U \rightarrow X(\star) \uplus \{\perp\} \mid \exists U' \twoheadrightarrow U \in \mathcal{M} \text{ s.t. } \text{dom}(g) = U' \\ \text{and } g|_{U'} \in X(U')\}$$

In general, having the lifting monad is not enough to model recursion.

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The ωcpo model of PCF_v

Types = partially ordered sets with least upper bounds of ω -chains

Terms = continuous functions

To model recursive functions:

- a lifting monad on ωcpo
- Tarski's fixed point theorem

We want to recover this model as presheaves with a class of admissible monos in the site.

vSet: A concrete presheaf model of PCF_v

$V = \{0 < 1 < 2 < \dots < \infty\}$ = poset of vertical nat. numbers

See the category \mathcal{H} from [Fiore & Rosolini'97, '01].

\mathbb{V} = two-object category

$vSet = [\mathbb{V}^{op}, Set]$ = presheaves on \mathbb{V}

Concrete presheaf on \mathbb{V}

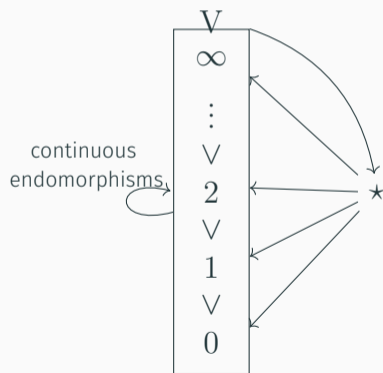
► a set $X(\star)$

► a set of functions $X(V) \subseteq [V \rightarrow X(\star)]$

$x \in X(V)$ is a **completed chain** of elements in $X(\star)$.
Map $X \rightarrow Y$ = function $X(\star) \rightarrow Y(\star)$ that **preserves chains**.

ωcpo is a full subcategory of $vSet$:

$D \mapsto (|D|, \omega cpo(V, D))$



Lifting in vSet

\mathbb{V} = vertical naturals as a two-object category
 \mathbf{vSet} = presheaves on \mathbb{V}

Theorem:

A class of pre-admissible monos \mathcal{M} in \mathbb{C} induces a lifting monad L on the sheaf category $\mathbf{Sh}(\mathbb{C}, J)$.

\mathbb{V} has a class of pre-admissible monos:

$$\mathcal{M}_{\mathbb{V}} = \{(\lambda x.x + n) \in \mathbb{V}(\mathbb{V}, \mathbb{V}) \mid n \in \mathbb{N}\} \cup \{\text{id}_{\star} : \star \rightarrow \star\}$$

which induces a **lifting monad** L on \mathbf{vSet} , where for a concrete presheaf X :

$$(LX)(\star) = X(\star) \uplus \{\perp\} \qquad (LX)(\mathbb{V}) = \{\perp\} \uplus \coprod_{n \in \mathbb{N}} (X(\mathbb{V}))_n$$

$(X(\mathbb{V}))_n \approx$ chains from $X(\mathbb{V})$ with n \perp 's added at the beginning.

Modelling PCF_V in vSet

Fixed point theorem in vSet

We can construct a fixed point of a map $(A \Rightarrow LB) \rightarrow (A \Rightarrow LB)$ if LB is “complete”.

$$\begin{array}{ccc} \omega \times X & \xrightarrow{h} & LB \\ \downarrow & \dashrightarrow & \\ yV \times X & & \end{array}$$

see also [Fiore & Plotkin'97]

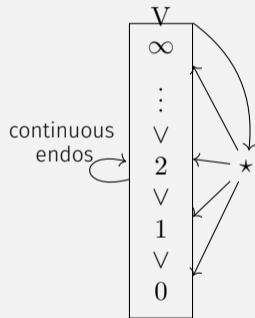
ω = greatest subobject of yV without ∞

Theorem

vSet is an adequate model of PCF_V where types are concrete presheaves.

The interpretation of PCF_V commutes with the inclusion $\omega\text{cpo} \hookrightarrow \text{vSet}$.

\mathbb{V} = two-object category



$\text{vSet} = [\mathbb{V}^{\text{op}}, \text{Set}]$

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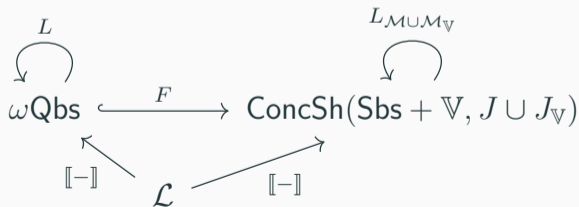
Modelling PCF_v in a category of concrete sheaves

Main Theorem [Matache, Moss, Staton, in preparation]

Given a **concrete site** with a **class of admissible monos** $(\mathbb{C}, J, \mathcal{M})$,
“combine” it with the site for $v\text{Set}$, $(\mathbb{V}, J_{\mathbb{V}}, \mathcal{M}_{\mathbb{V}})$.

The category of **concrete sheaves** on the combined concrete site
 $(\mathbb{C} + \mathbb{V}, J \cup J_{\mathbb{V}}, \mathcal{M} \cup \mathcal{M}_{\mathbb{V}})$ is an adequate model of PCF_v .

Example: we recover the ωQbs model



Concrete site for Qbs:

Sbs: objects U are Borel subsets of \mathbb{R} ,
morphisms are measurable functions.
 $J(U)$ = countable sets of inclusions
 $\{U_i \hookrightarrow U\}_{i \in I}$ where $U = \bigcup_{i \in I} U_i$
and the U_i 's are disjoint.
 \mathcal{M} = all monos.

Summary

Main Theorem [Matache, Moss, Staton, in preparation]

Given a **concrete site** with a **class of admissible monos** $(\mathbb{C}, J, \mathcal{M})$, “combine” it with the site for \mathbf{vSet} , $(\mathbb{V}, J_{\mathbb{V}}, \mathcal{M}_{\mathbb{V}})$.

The category of **concrete sheaves** on the combined concrete site $(\mathbb{C} + \mathbb{V}, J \cup J_{\mathbb{V}}, \mathcal{M} \cup \mathcal{M}_{\mathbb{V}})$ is an adequate model of $\mathbf{PCF}_{\mathbb{V}}$.

Model higher-order recursion for:

- (1) **Probabilistic programming**
- (2) **Automatic differentiation**
- (3) Piecewise differentiation
- (4) Full abstraction

Using:

- sheaves on a concrete site
- class of admissible monos in the site
- presheaves on the vertical naturals