INFR10086 Machine Learning (MLG)

Semester 1, 2022/23

Coursework 1

1 Submission

- Submit your coursework on gradescope.¹
- Due: 7 Nov, 2022 at noon, 12:00pm

2 Questions

- 1. Answer the following questions about information theory.
 - a) Variance is defined as $\operatorname{Var}[x] = \mathbb{E}[(x \mathbb{E}[x])^2]$. Show that $\operatorname{Var}[x] = \mathbb{E}[x^2] (\mathbb{E}[x])^2$. [6 marks]
 - b) Entropy of a random variable x is defined as $\mathbb{E}[-\log p(x)]$. Show that if x is Gaussian, i.e., $x \sim \mathcal{N}(\mu, \sigma^2)$, its entropy is

$$\mathbb{E}[-\log p(x)] = \frac{1}{2}\log(2\pi\sigma^2) + \frac{1}{2}.$$
 (1)

(Hint: The derivation is a lot simpler if you use the linearity of expectation and the above fact. In particular, $\sigma^2 = \mathbb{E}[x^2] - \mu^2$.)

[6 marks]

c) Based on the above, can entropy be negative?

[3 marks]

- 2. Answer the following questions about optimization.
 - a) Is it true that if f is convex in x and f has a minimizer, then f has a unique minimizer? If not, provide a counter example.

[5 marks]

b) Is it true that if f is μ -strongly convex in x and f has a minimizer, then f has a unique minimizer? If not, provide a counter example. (Hint: To show that the minimizer is unique, assume there are two, say x_1^* and x_2^* , and show that $x_1^* = x_2^*$.)

[5 marks]

¹https://www.gradescope.com/courses/454792/assignments/2375358

c) Suppose we are trying to find the minimum of $f(x) = x^2$ with gradient descent. What is the gradient at x = 1? Suppose $x_{t-1} = 1$. Based on the gradient update

$$x_t = x_{t-1} - \eta_t \frac{\partial f}{\partial x}(x_{t-1}),\tag{2}$$

could we get a worse value after a gradient update? In other words, could $f(x_t) \ge f(x_{t-1})$? Based on this result, do gradient updates always reduce the objective?

[5 marks]

d) Show that

$$\max(a+b,c+d) \le \max(a,c) + \max(b,d),\tag{3}$$

for any $a, b, c, d \in \mathbb{R}$. Now, use this fact to show that $h(x) = \max(f(x), g(x))$ is convex in x if f and g are both convex.

[5 marks]

3. In this question, we consider the following loss function for binary classification, where $x \in \mathbb{R}^d$ and $y \in \{+1, -1\}$.

$$\ell_{\text{new}}(w; x, y) = \begin{cases} (yw^{\top}\phi(x) - 1)^2 & \text{if } yw^{\top}\phi(x) \le 1\\ 0 & \text{otherwise} \end{cases}$$
(4)

- a) Show that $f(s) = s^2$ is convex in s.
- b) With the fact above, show that $\ell_{\text{new}}(w; x, y)$ is convex in w.

[3 marks]

[3 marks]

[3 marks]

[3 marks]

- c) Is $\ell_{\text{new}}(w; x, y)$ a Lipschitz continuous function? Why or why not?
- d) Derive the gradient of $\ell_{\text{new}}(w; x, y)$ with respect to w.
- e) Show that $\ell_{\text{new}}(w; x, y)$ is an upper bound on the zero-one loss

$$\ell_{01}(w; x, y) = \mathbb{1}_{yw^{\top}\phi(x) < 0},\tag{5}$$

for all w, x, and y.

[8 marks]

- 4. Suppose we want to add a few new operations to a neural network library. The neural network library is implemented as a computation graph, and our goal is to implement the backward operations.
 - a) To allow us to train a regression model, we need to implement the squared loss

$$\ell(y, \hat{y}) = (y - \hat{y})^2, \tag{6}$$

where y is the ground truth and \hat{y} is the prediction. Derive $\frac{\partial \ell}{\partial \hat{y}}$.

[3 marks]

b) Instead of logistic function as the activation function, we could use rectified linear units

$$\operatorname{ReLU}(z) = \max(0, z) \tag{7}$$

i) We just showed that $h(x) = \max(f(x), g(x))$ is convex in x if f and g are convex in x. Use this fact to show that ReLU is convex in z.

[3 marks]

ii) Is ReLU a differentiable function? If so, derive the derivative of ReLU. If not, find the point that is not differentiable and a subgradient at that point.

[6 marks]

iii) Show that ReLU is 1-Lipschitz continuous.

[3 marks]

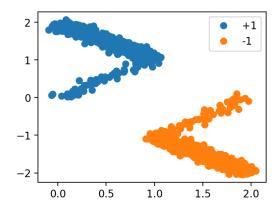
5. There are two common approaches in machine learning that are often compared to each other. One is the **generative approach**, where the distribution of the data points are modeled and hence assumed. The other is the **discriminative approach**, where we do not model the distrubition of data points but only care about achieving a goal, for example, separating data points into two classes.

In this question, we will use an example to illustrate the differences of the two. We are given a 2-dimensional data set.² The following piece of code

```
import pickle
```

```
f = open('two-L.pkl', 'rb')
pos, neg = pickle.load(f)
f.close()
```

shows how you load the data set. The variable **pos** is a list of points from the positive class (+1), while **neg** is a list of points from the other (-1). The points look like the following in the space.



a) To demonstrate the decision boundary learned from a discriminative approach, write a program to train a linear classifier with log loss to separate the two classes. Show a plot of the line (the classifier) after training together with the points.

²Download the data set here https://homepages.inf.ed.ac.uk/htang2/mlg2022/two-L.pkl.

[15 marks]

- b) To demonstrate the decision boundary learned from a generaive approach, we assume points from the positive class is drawn from a Gaussian $\mathcal{N}(\mu_1, \Sigma_1)$, and points from the negative class is drawn from another Gaussian $\mathcal{N}(\mu_2, \Sigma_2)$.
 - i) Write a program to compute

$$\mu = \frac{1}{n} \sum_{i=1}^{n} x_i \tag{8}$$

$$\Sigma = \frac{1}{n} \sum_{i=1}^{n} (x_i - \mu) (x_i - \mu)^{\top}$$
(9)

and estimate μ_1 , Σ_1 , μ_2 , and Σ_2 .

- ii) Find the line that passes through $\frac{\mu_1 + \mu_2}{2}$ while perpendicular to the vector $\mu_2 \mu_1$. Show a plot of the line (the classifier) together with the two means and the points. [12 marks]
- c) Discuss the pros and cons of both approaches based on the observation.

[3 marks]