

Bio-PEPAd: Integrating exponential and deterministic delays

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16th June 2012

Joint work with Giulio Caravagna

Outline

Introduction

Bio-PEPA

Bio-PEPAd

Analysis of Bio-PEPAd

Bio-PEPAd vs. Bio-PEPA

Conclusions

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- The usual interpretation of this delay the **duration** of the action or event.

Actions with delays

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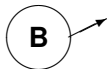
- There may be a delay from the time when an event becomes possible (**enabled**) ;
- When an event occurs there may be a delay until the **effects** of the event become apparent.

Actions with delays in biochemistry

We are interested in modelling intracellular biochemical processes

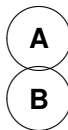
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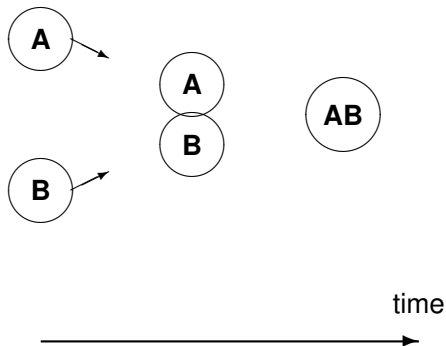
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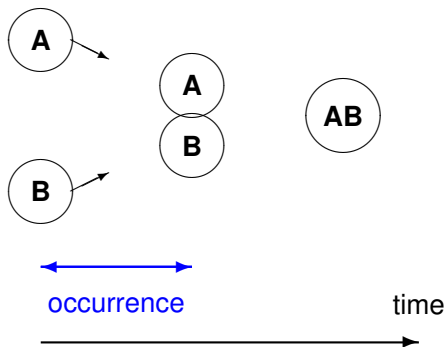
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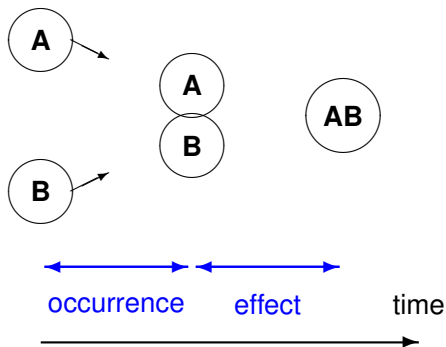
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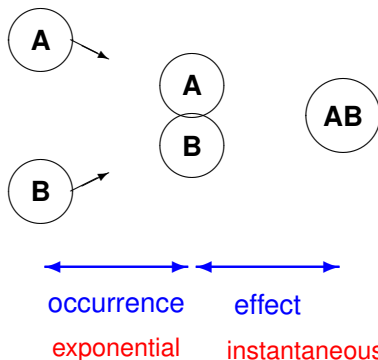
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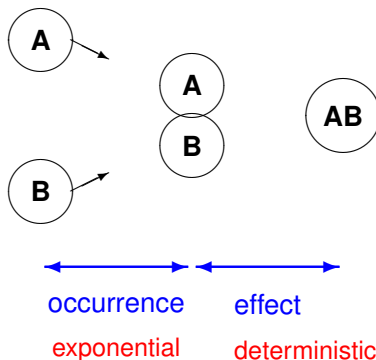
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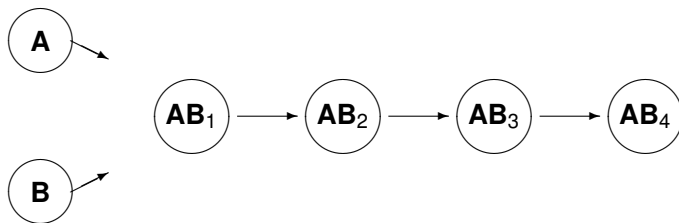


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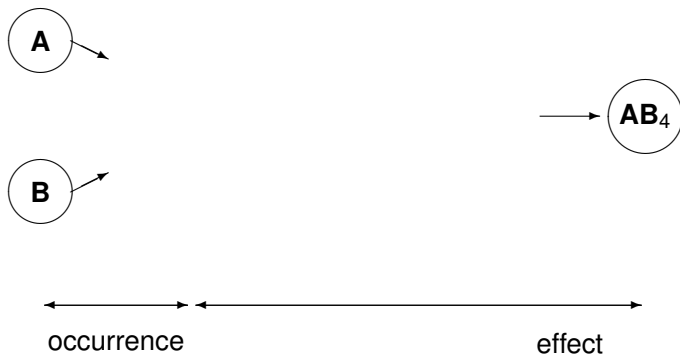
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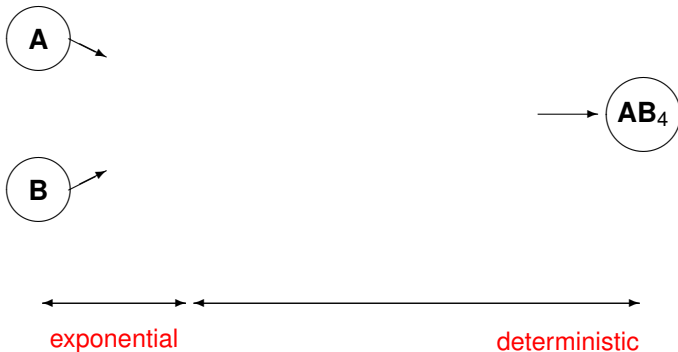
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Bio-PEPA: recap

Bio-PEPA is a recently defined stochastic process algebra for modelling biochemical processes.

Unlike many of the other SPA in use in systems biology which derive from the stochastic π -calculus it is not based on the **molecules as processes** abstraction.

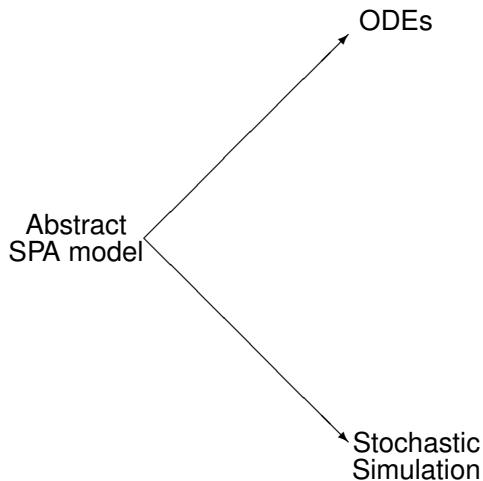
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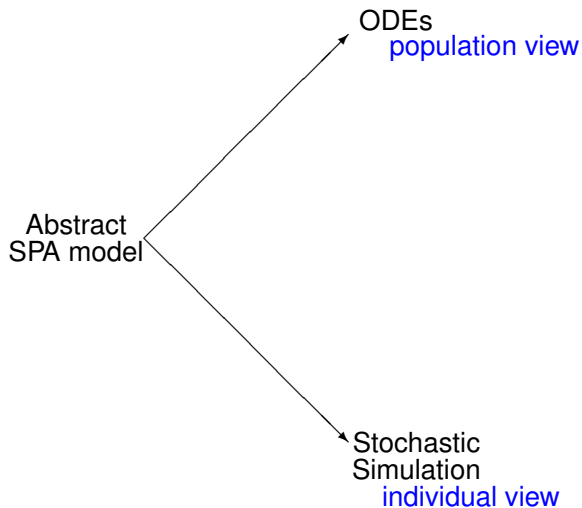
Unlike many of the other SPA in use in systems biology which derive from the stochastic π -calculus it is not based on the **molecules as processes** abstraction.

Instead it is based on the **species as processes** abstraction which means that it readily supports a number of different kinds of analysis.

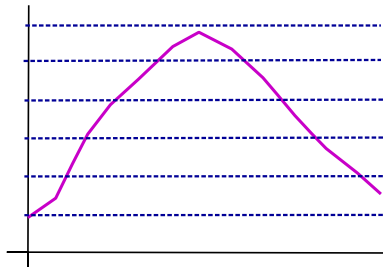
Alternative Representations



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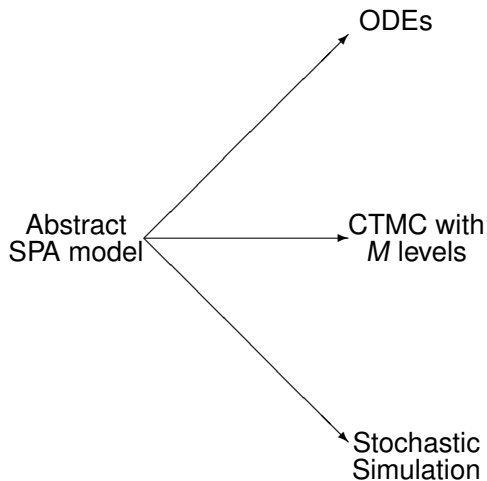


Discretising the population view

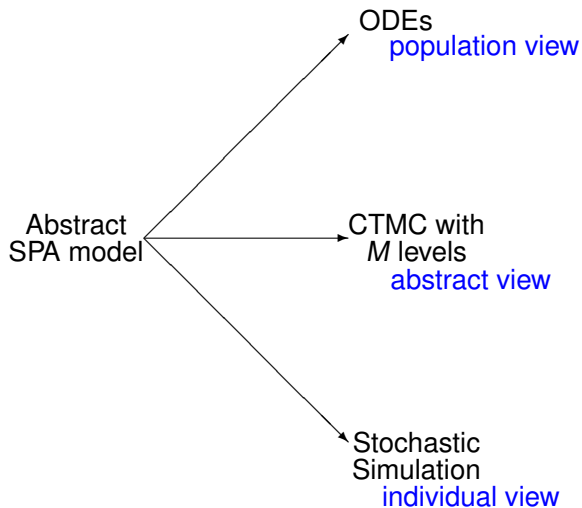


We can discretise the continuous range of possible concentration values into a number of distinct states. These form the possible states of the component representing the reagent.

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- The representation of an action within a component (species) records the **stoichiometry** of that entity with respect to that reaction. The **role** of the entity is also distinguished.
- The local states of components are **quantitative** rather than functional, i.e. distinct states of the species are represented as distinct components, not derivatives of a single component.

The syntax

Sequential component (species component)

$$S ::= (\alpha, \kappa) \text{ op } S \mid S + S \mid C \quad \text{where op} = \downarrow \mid \uparrow \mid \oplus \mid \ominus \mid \odot$$

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The parameter I is abstract, recording quantitative information about the species.

Depending on the interpretation, this quantity may be:

- number of molecules (SSA),
- number of molecules (ODE) or
- a level within a semi-quantitative model (CTMC).

The Bio-PEPA system

A Bio-PEPA system \mathcal{P} is a 6-tuple $\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}_R, \text{Comp}, P \rangle$, where:

- \mathcal{V} is the set of compartments;
- \mathcal{N} is the set of quantities describing each species (step size, number of levels, location, ...);
- \mathcal{K} is the set of parameter definitions;
- \mathcal{F}_R is the set of functional rate definitions;
- Comp is the set of definitions of sequential components;
- P is the model component describing the system.

Semantics

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1. **capability relation**, that supports the derivation of quantitative information;
2. **stochastic relation**, that gives the rates associated with each action.

Semantics: prefix rules

$$\text{prefixReac} \quad ((\alpha, \kappa) \downarrow S)(l) \xrightarrow{(\alpha, [S: \downarrow(l, \kappa)])}_c S(l - \kappa) \quad \kappa \leq l \leq N$$

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$$\text{prefixMod} \quad ((\alpha, \kappa) \text{ op } S)(l) \xrightarrow{(\alpha, [S: \text{op}(l, \kappa)])}_c S(l) \\ 0 \leq l \leq N$$

with $\text{op} = \odot, \oplus$, or \ominus

Semantics: constant and choice rules

$$\text{Choice1} \quad \frac{S_1(l) \xrightarrow{(\alpha, \nu)}_c S'_1(l')}{(S_1 + S_2)(l) \xrightarrow{(\alpha, \nu)}_c S'_1(l')}$$

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$$\text{Constant} \quad \frac{S(l) \xrightarrow{(\alpha, S:[op(l, \kappa)])}_c S'(l')}{C(l) \xrightarrow{(\alpha, C:[op(l, \kappa)])}_c S'(l')} \quad \text{with } C \stackrel{\text{def}}{=} S$$

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$$\text{coop1} \quad \frac{P_1 \xrightarrow{(\alpha, \nu)}_c P'_1}{P_1 \boxtimes_{\mathcal{L}} P_2 \xrightarrow{(\alpha, \nu)}_c P'_1 \boxtimes_{\mathcal{L}} P_2} \quad \text{with } \alpha \notin \mathcal{L}$$

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$$\text{coop2} \quad \frac{P_2 \xrightarrow{(\alpha, \nu)}_c P'_2}{P_1 \boxtimes_{\mathcal{L}} P_2 \xrightarrow{(\alpha, \nu)}_c P_1 \boxtimes_{\mathcal{L}} P'_2} \quad \text{with } \alpha \notin \mathcal{L}$$

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$$\text{coopFinal} \quad \frac{P_1 \xrightarrow{(\alpha, v_1)}_c P'_1 \quad P_2 \xrightarrow{(\alpha, v_2)}_c P'_2}{P_1 \boxtimes_{\mathcal{L}} P_2 \xrightarrow{(\alpha, v_1 :: v_2)}_c P'_1 \boxtimes_{\mathcal{L}} P'_2} \quad \text{with } \alpha \in \mathcal{L}$$

Semantics: rates and transition system

In order to derive the rates we consider the **stochastic relation**
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$$\frac{P \xrightarrow{(\alpha_j, \nu)}_c P'}{\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}_R, \text{Comp}, P \rangle \xrightarrow{(\alpha_j, r_{\alpha_j})}_s \langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}_R, \text{Comp}, P' \rangle}$$

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The rate r_{α_j} is defined as $f_{\alpha_j}(\mathcal{V}, \mathcal{N}, \mathcal{K})/h$.

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- Transformation happens at a rate k and obeys a mass-action kinetic law.
- Such a model is constituted by a single reaction channel of the form $A \xrightarrow{k} B$.
- We assume the initial state contains three elements of species A and no elements of species B ;
- Formally it is described by the 2-dimensional vector $\mathbf{x}_0 = (3, 0)^T$.

Small example in Bio-PEPA

The Bio-PEPA processes modelling the species are

$$A \stackrel{\text{def}}{=} (\alpha, 1)\downarrow A \qquad B \stackrel{\text{def}}{=} (\alpha, 1)\uparrow B$$

where α is the action corresponding to the reaction and $f_\alpha = f_{MA}(k)$.

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The initial configuration of the process is

$$A(3) \boxtimes_{\{\alpha\}} B(0).$$

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The components of the system in which this process is embedded are:

$$\mathcal{V} = \{\text{cell} : 1\}$$

$$\mathcal{K} = \{k' = k\}$$

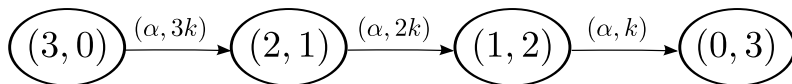
$$\mathcal{N} = \begin{array}{l} \{A \text{ in cell} : N_A = 3, h_A = 1; \\ \quad B \text{ in cell} : N_B = 3, h_A = 1\} \end{array}$$

$$\mathcal{F} = \{f_\alpha = f_{MA}(k')\}$$

$$Comp = \{A \stackrel{def}{=} (\alpha, 1) \downarrow A, B \stackrel{def}{=} (\alpha, 1) \uparrow B\}$$

$$P = A(3) \boxtimes_{\{\alpha\}} B(0).$$

The SLTS for the Bio-PEPA example



Starting from the initial configuration $\mathbf{X}(t_0) = 0$ the process eventually reaches the final state $(0, 3)$, which corresponds to the process $A(0) \boxtimes_{\{\alpha\}} B(3)$.

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Currently we assume **all** actions have a non-zero delay.

Bio-PEPAd system

A Bio-PEPAd system is a 7-tuple $\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, \sigma, P \rangle$ where:

- $\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, P \rangle$ is a Bio-PEPA system;
- $\sigma \in \Delta$ is a function used to specify the delays of the actions.

Process configuration

Bio-PEPAd **process configurations** are defined by the following syntax:

$$\begin{aligned}
 C_S &::= (\alpha, \kappa) op \ C_S \mid C_S + C_S \mid C \\
 C_P &::= C_P \boxtimes_{\mathcal{L}} C_P \mid C_S(l, L)
 \end{aligned}$$

where L is a list of 4-tuples $(l', \kappa', \alpha', op')$ with $l, \kappa \in \mathbb{N}$, $\alpha \in \mathcal{A}$ and $op \in \{\downarrow, \uparrow, \odot, \oplus, \ominus\}$.

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For example, if $(I', \kappa, \alpha, op) \in L$ there are κ levels of concentration of species S involved in a currently running action α which fired when the level of S was I' , and its role was op .

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- In this case the end of the **exponentially distributed event** corresponds to the **start** of the action, denoted α^+ .
- Whereas the end of the **deterministically timed delay** corresponds to **terminating** the action, denoted α^- .
- As usual for the ST style, we have **two transition relations** over **process configurations**.

Initial process configuration

From Bio-PEPAd process P we derive its corresponding process configuration P_C using a function $\mu : \mathcal{P} \rightarrow \mathcal{C}$ such that

$$\begin{aligned} \mu((\alpha, \kappa)op S) &= (\alpha, \kappa)op S & \mu(P_1 \boxtimes_{\mathcal{L}} P_2) &= \mu(P_1) \boxtimes_{\mathcal{L}} \mu(P_2) \\ \mu(S_1 + S_2) &= S_1 + S_2 & \mu(S(l)) &= S(l, []). \end{aligned}$$

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For example, the process $S(l_1) \mathbin{\boxtimes}_{\mathcal{L}_1} S(l_2) \mathbin{\boxtimes}_{\mathcal{L}_2} S(l_3)$ is transformed into the configuration $S(l_1, []) \mathbin{\boxtimes}_{\mathcal{L}_1} S(l_2, []) \mathbin{\boxtimes}_{\mathcal{L}_2} S(l_3, [])$.

Auxiliary functions

We define four auxiliary functions to examine and manipulate the scheduling lists:

- *pick*: given α and a scheduling list, select the first α action entry in the list.
- *del*: given α and a scheduling list, remove the first α action entry in the list.
- *prod*: given a scheduling list for species S , select those entries in which S is involved as a product.
- *pend*: given a scheduling list find how many levels are involved.

The start relation: Prefix

$$(\alpha, \kappa) \downarrow S(l, L) \xrightarrow{(\alpha^+, [S: \downarrow(l, \kappa)])}_{st} S(l - \kappa, L @ [(l, \kappa, \alpha, \downarrow)]) \quad \kappa \leq l \leq N$$

$$(\alpha, \kappa) \uparrow S(l, L) \xrightarrow{(\alpha^+, [S: \uparrow(l, \kappa)])}_{st} S(l, L @ [(l, \kappa, \alpha, \uparrow)]) \quad 0 \leq l + \text{pend prod } L \leq N$$

$$(\alpha, \kappa) \oplus S(l, L) \xrightarrow{(\alpha^+, [S: \oplus(l, \kappa)])}_{st} S(l, L @ [(l, \kappa, \alpha, \oplus)]) \quad \kappa \leq l \leq N$$

$$(\alpha, \kappa) op S(l, L) \xrightarrow{(\alpha^+, [S: op(l, \kappa)])}_{st} S(l, L @ [(l, \kappa, \alpha, op)]) \quad 1 \leq l \leq N, \quad op \in \{\odot, \ominus\}$$

The start relation: Choice and Constant

$$\frac{S_1(l, L) \xrightarrow{(\alpha^+, w)}_{st} S'_1(l', L')}{(S_1 + S_2)(l, L) \xrightarrow{(\alpha^+, w)}_{st} S'_1(l', L')}$$

$$\frac{S_2(l, L) \xrightarrow{(\alpha^+, w)}_{st} S'_2(l', L')}{(S_1 + S_2)(l, L) \xrightarrow{(\alpha^+, w)}_{st} S'_2(l', L')}$$

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$$\frac{S(l, L) \xrightarrow{(\alpha^+, w)}_{st} S'(l', L') \quad C \stackrel{def}{=} S(l, L)}{C \xrightarrow{(\alpha^+, w)}_{st} S'(l', L')}$$

The start relation: Cooperation

$$\frac{P_1 \xrightarrow{(\alpha^+, w)}_{st} P'_1 \quad \alpha \notin \mathcal{L}}{P_1 \boxtimes_{\mathcal{L}} P_2 \xrightarrow{(\alpha^+, w)}_{st} P'_1 \boxtimes_{\mathcal{L}} P_2}$$

$$\frac{P_2 \xrightarrow{(\alpha^+, w)}_{st} P'_2 \quad \alpha \notin \mathcal{L}}{P_1 \boxtimes_{\mathcal{L}} P_2 \xrightarrow{(\alpha^+, w)}_{st} P_1 \boxtimes_{\mathcal{L}} P'_2}$$

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The completion relation: Ongoing actions

$$\frac{\text{pick } \alpha L = (l, \kappa, \alpha, \uparrow)}{S(l', L) \xrightarrow{(\alpha^-, [S:\uparrow(l, \kappa)])}_{co} S(l' + \kappa, \text{del } \alpha L)}$$

$$\frac{\text{pick } \alpha L = (l, \kappa, \alpha, op) \quad op \in \{\downarrow, \odot, \oplus, \ominus\}}{S(l', L) \xrightarrow{(\alpha^-, [S:op(l, \kappa)])}_{co} S(l', \text{del } \alpha L)}$$

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$$\frac{S_1(l, L) \xrightarrow{(\alpha^-, w)}_{co} S'_1(l', L')}{(S_1 + S_2)(l, L) \xrightarrow{(\alpha^-, w)}_{co} S'_1(l', L')} \quad \frac{S_2(l, L) \xrightarrow{(\alpha^-, w)}_{co} S'_2(l', L')}{(S_1 + S_2)(l, L) \xrightarrow{(\alpha^-, w)}_{co} S'_2(l', L')}$$

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 \end{array}$$

The stochastic relation

$$\frac{P \xrightarrow{(\alpha^+, w)}_{st} P' \quad r_\alpha = f_\alpha[w, \mathcal{N}, \mathcal{K}]h^{-1}}{\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, \sigma, P \rangle \xrightarrow{(\alpha^+, r_\alpha, \sigma(\alpha))}_s \langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, \sigma, P' \rangle}$$

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Timing aspects of Bio-PEPAd

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- By means of the ST semantics, in Bio-PEPAd a qualitative notion of time can be retrieved by observing state changes induced by either the start or the completion of an action.
- Moreover, by construction, instances of an action complete while **respecting their starting order**.
- However note that the SLTS contains **all the potential behaviours** for a process configuration but some of these **may not be possible** given the kinetic information of the system.

Small example revisited

To illustrate Bio-PEPAd we consider again the small example earlier modelled in Bio-PEPA:

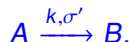


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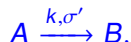


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We again assume the initial state described by the vector $\mathbf{x}_0 = (3, 0)^T$.

Small example in Bio-PEPAd

We are able to fully reuse the Bio-PEPA specification for this model:

$$A \stackrel{\text{def}}{=} (\alpha, 1)\downarrow A, \quad B \stackrel{\text{def}}{=} (\alpha, 1)\uparrow B.$$

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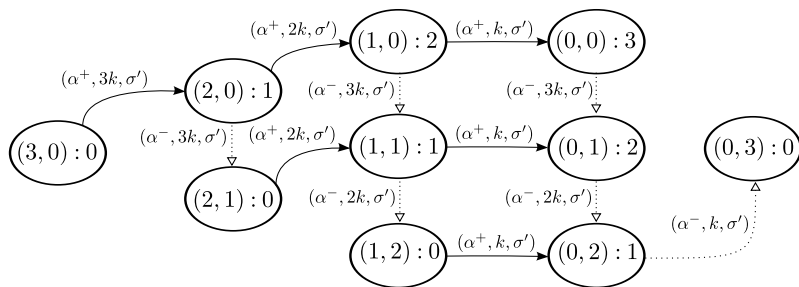
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The initial configuration of the process, obtained by applying the function μ is

$$A(3, []) \boxtimes_{\{\alpha\}} B(0, []).$$

The SLTS for the Bio-PEPAd example



Starting from the initial configuration $(3, 0) : 0$, we eventually reach the final state $(0, 3) : 0$, which corresponds to the final configuration $A(0, []) \boxtimes_{\{\alpha\}} B(3, [])$.

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Just as in Bio-PEPA, we can subject Bio-PEPAd models to different analyses based on the different views of the system:

Population view:

Individual view:

Abstract view:

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The simplest form of DDE considers constant delays

$\sigma_1 > \dots > \sigma_n \geq 0$ and consists of an equation of the form

$$\frac{dX}{dt} = \varphi_X(t, \{X(t - \sigma_i) \mid i = 1, \dots, n\})$$

where $X(t - \sigma_i)$ denotes the state of the system at the past time $t - \sigma_i$.

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As in the translation from Bio-PEPA to ODE, the mapping consists of three steps:

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Only Step 2 differs from the Bio-PEPAd/DDE case.

Moreover, the initial conditions must be defined in the interval $[t_0 - \sigma(\alpha); t_0]$ where α is the action with maximum delay.

This is left to the modeller.

DSSA

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Luckily, based on DDEs, variants of SSA which incorporate deterministic delays have previously been defined [Barrio et al 2006; Barbuti et al 2009].

These algorithms work for the [delay-as-duration](#) abstraction (cf. the [purely delayed](#) abstraction), which is what we use for Bio-PEPAd.

Mapping Bio-PEPAd to DSSA

To prepare a Bio-PEPAd system for simulation using DSSA

1. Define the algebraic representation of the process:

$$\{(\cdot)_n : C \cup \mathcal{P} \rightarrow \mathbb{N}^n \mid n \in \mathbb{N}\}$$

encodes a Bio-PEPA process/Bio-PEPAd process configuration as a population vector:

$$(\mathbb{S}_1(l_1) \underset{\mathcal{L}_1}{\boxtimes} \dots \underset{\mathcal{L}_m}{\boxtimes} \mathbb{S}_m(l_m))_m = (l_1, \dots, l_m)^T$$

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2. Create the reactions to simulate: The actual rates of the reactions have to be defined, case by case, using the parameters in \mathcal{F} (as for Bio-PEPA).

DSS Algorithm

```

1:  $t \leftarrow t_0; \mathbf{x} \leftarrow \mathbf{x}_0; S \leftarrow \emptyset;$ 
2: while  $t < T$  do
3:    $a_0(\mathbf{x}) \leftarrow \sum_{j=1}^M a_j(\mathbf{x});$ 
4:   let  $r_1, r_2 \sim U[0, 1];$ 
5:    $\tau \leftarrow a_0(\mathbf{x})^{-1} \ln(r_1^{-1});$ 
6:   let  $S_{t,\tau} = \{(t'', v'') \in S \mid t'' \in (t, t + \tau]\};$ 
7:   if  $S_{t,\tau} \neq \emptyset$  then
8:      $(t', v') \leftarrow \min\{S_{t,\tau}\};$ 
9:      $\mathbf{x} \leftarrow \mathbf{x} + v'; t \leftarrow t'; S \leftarrow S \setminus \{(t', v')\};$ 
10:  else
11:    let  $j$  such that  $\sum_{i=1}^{j-1} a_i(\mathbf{x}) < r_2 \cdot a_0(\mathbf{x}) \leq \sum_{i=1}^j a_i(\mathbf{x});$ 
12:     $\mathbf{x} \leftarrow \mathbf{x} + v_j^r; t \leftarrow t + \tau; S \leftarrow S \cup \{(t + \tau + \sigma_j, v_j^p)\};$ 
13:  end if
14: end while

```


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- When a clock expires the state is updated according to an **event-dependent probability distribution**.
- For all other events it is known whether the completion of this event **cancels**, **creates** or **maintains** the event.

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- When an exponentially timed clock expires the state is updated according to the probability distribution given by the relative rates of all the possible start actions in that state.
- When a deterministically timed clock expires there is only one possible next state.

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Relating Bio-PEPAd and Bio-PEPA

In order to relate Bio-PEPAd and Bio-PEPA we start by defining the inverse of function μ .

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$$\mu^{-1}(S(I, L)) = S(I).$$

Note that function μ is **not** a bijection.

Specifically $\forall L \in \mathcal{L}_{\mathcal{D}}. \mu^{-1}(S(I, L)) = S(I)$,

i.e. we lose information about the structure of L , namely the actions started and not yet completed in $S(I, L)$.

Interchangeability

A Bio-PEPA process $P \in \mathcal{P}$ and a Bio-PEPAd process configuration $P_C \in \mathcal{C}$ are said to be **interchangeable** if and only if

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If P and P_C are interchangeable, then by definition $\mu(P) = P_C$ and all the lists appearing in P_C must be empty, i.e. there must be no uncompleted actions running.

Theorem: Relating processes and configurations

If P and P_C are interchangeable, then for any possible action derivable from P and leading to a state P' , there exists a sequence of start and completion transitions, from P_C through P'_C to P''_C , such that P' and P''_C are interchangeable.

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Let $\mathcal{I} = \{(P, P_C) \mid P \in \mathcal{P}, P_C \in \mathcal{C}, \mu(P) = P_C, \mu^{-1}(P_C) = P\}$, then

$$\forall (P, P_C) \in \mathcal{I}. \forall P' \in \mathcal{P}. P \xrightarrow{(\alpha, w)}_c P' \implies \\ \exists P'_C, P''_C \in \mathcal{C}. P_C \xrightarrow{(\alpha^+, w)}_{st} P'_C \xrightarrow{(\alpha^-, w)}_{co} P''_C \wedge (P', P''_C) \in \mathcal{I}$$

Theorem: Relating processes and configurations

If P and P_C are interchangeable, then for any possible action derivable from P and leading to a state P' , there exists a sequence of start and completion transitions, from P_C through P'_C to P''_C , such that P' and P''_C are interchangeable.

Let $\mathcal{I} = \{(P, P_C) \mid P \in \mathcal{P}, P_C \in \mathcal{C}, \mu(P) = P_C, \mu^{-1}(P_C) = P\}$, then

$$\begin{aligned} \forall (P, P_C) \in \mathcal{I}. \forall P' \in \mathcal{P}. P \xrightarrow{(\alpha, w)}_c P' \implies \\ \exists P'_C, P''_C \in \mathcal{C}. P_C \xrightarrow{(\alpha^+, w)}_{st} P'_C \xrightarrow{(\alpha^-, w)}_{co} P''_C \wedge (P', P''_C) \in \mathcal{I} \end{aligned}$$

Thus we can think of interchangeability as a **simulation**.

Theorem: Relating Bio-PEPA and Bio-PEPAd Systems

For any Bio-PEPA system $\langle \mathcal{T}, P \rangle$ there exists $P_C \in C. (P, P_C) \in \mathcal{I}$ such that

$$\begin{aligned}
 \forall P' \in \mathcal{P}. \langle \mathcal{T}, P \rangle &\xrightarrow{(\alpha, r)}_s \langle \mathcal{T}, P' \rangle \\
 \implies \forall \sigma \in \Delta. \langle \mathcal{T}, \sigma, P_C \rangle &\xrightarrow{(\alpha^+, r, \sigma(\alpha))}_s \langle \mathcal{T}, \sigma, P'_C \rangle \\
 &\wedge \langle \mathcal{T}, \sigma, P'_C \rangle \xrightarrow{(\alpha^-, r, \sigma(\alpha))}_s \langle \mathcal{T}, \sigma, P''_C \rangle \\
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where $\langle \mathcal{T}, P \rangle$ denotes $\langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, P \rangle$ whenever we are not concerned with the elements of the system specifically, and similarly for $\langle \mathcal{T}, \sigma, P \rangle$.

Implications of Interchangeability

If a process and process configuration are interchangeable, then any of the possible Bio-PEPA systems is interchangeable to an infinity of different Bio-PEPAd systems.

This happens because any Bio-PEPAd system with the same \mathcal{T} simulates the Bio-PEPA system, independently of the delays.

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The Bio-PEPA stochastic semantics are **embedded** in the Bio-PEPAd stochastic semantics.

Relating the stochastic semantics

The Bio-PEPA stochastic relation \rightarrow_s is equivalently defined by the following inference rule

$$\frac{
 \begin{array}{l}
 \langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, \sigma, \mu(P) \rangle \xrightarrow{(\alpha^+, r_\alpha, \sigma(\alpha))}_s \langle \mathcal{V}, \mathcal{N}, \mathcal{K}, \mathcal{F}, \text{Comp}, \sigma, P'_C \rangle \\
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 \end{array}
 }{
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where σ is a generic function from Δ .

Relating trajectories

There are trajectories in the DSSA which are **close** to the SSA trajectory in the sense that no more than one delay is running at a time.

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$$\forall \alpha \in \mathcal{A}. \langle \sigma, \mu(P) \rangle \xrightarrow{(\alpha^+, r_\alpha, \sigma(\alpha))}_s \langle \sigma, P'_C \rangle \xrightarrow{(\alpha^-, r_\alpha, \sigma(\alpha))}_s \langle \sigma, \mu(P') \rangle.$$

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Let $(\mu(P)) = \mathbf{x}$, $(P'_C) = \mathbf{x} + \nu_\alpha^r$, $(\mu(P')) = \mathbf{x} + \nu_\alpha^r + \nu_\alpha^p = \mathbf{x} + \nu_\alpha$ where ν_α^r and ν_α^p denote the stoichiometry vector for the reactants and the products and are such that $\nu_\alpha = \nu_\alpha^r + \nu_\alpha^p$.

Relating trajectories

- In state \mathbf{x} , the next value for $\tau \sim \text{Exp}(a_0(\mathbf{x}))$ is sampled and reaction R_j is chosen to fire with probability $a_j(\mathbf{x})/a_0(\mathbf{x})$; (the scheduling list is empty since $P_C \equiv \mu(P)$.)

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- If $\tau' > \sigma_\alpha$ then the state changes to $\mathbf{x} + \nu_\alpha$ and time to $t + \sigma_\alpha$, otherwise a new reaction is scheduled.
- The case $\tau' > \sigma_\alpha$ has probability $\exp(-a_0(\mathbf{x} + \nu_\alpha^r)\sigma_\alpha)$.

Relating trajectories

Since events are independent, if we generalize among all possible reactions we get equation

$$p(\mathbf{x}) = \sum_{i=1}^m \frac{a_i(\mathbf{x})}{a_0(\mathbf{x})} e^{-a_0(\mathbf{x} + \nu_i^r) \sigma_i}.$$

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In systems where $\forall R_i. f_{\alpha_i}[w, \mathcal{N}, \mathcal{K}] = a_i(\mathbf{x}) = r_{\alpha_i}$, we can write a probability which is logically equivalent to $p(\mathbf{x})$ for $\mu(P)$ as

$$\mathbb{P}(\mu(P)) = \sum_{i=1}^m \frac{f_{\alpha_i}[w, \mathcal{N}, \mathcal{K}]}{\text{ExitRate}(\mu(P))} e^{-\text{ExitRate}(\mu(P)) \sigma(\alpha_i)}.$$

Relating trajectories

Note that

$$\lim_{\sigma \rightarrow \infty} \mathbb{P}(\mu(P)) = 0 \qquad \lim_{\sigma \rightarrow 0} \mathbb{P}(\mu(P)) = \sum_{i=1}^m \frac{f_{\alpha_i}[w, \mathcal{N}, \mathcal{K}]}{\text{ExitRate}(\mu(P))}$$

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In particular, in the limit $\sigma \rightarrow 0$ the probability of making the stochastic transition reduces to the probability of leaving P , in its associated CTMC.

Thus the probability of observing, during a simulation of a Bio-PEPAd model, a series of steps which correspond to the interchangeable Bio-PEPA process is the **closure of $\mathbb{P}(\mu(P))$** .

Outline

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Bio-PEPA

Bio-PEPAd

Analysis of Bio-PEPAd

Bio-PEPAd vs. Bio-PEPA

Conclusions

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- Bio-PEPAd is a **conservative** extension of Bio-PEPA.
- The firing of actions with delays is assumed to follow the **delay-as-duration** abstraction.

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- Based on the semantics, the encoding of Bio-PEPAd systems in **GSMP** has been given and mapping to other analysis frameworks have been demonstrated.
- The expressiveness of Bio-PEPA and Bio-PEPAd have been compared at a semantic level, and results proved about the probabilities of performing actions in the two algebras.

On-going work

There are several strands of possible further development of Bio-PEPAd:

- It could be interesting to consider the alternative interpretation of delays, the so-called **purely delayed** abstraction, rather than the **delay as duration** abstraction.
- We could consider the combination of delayed and non-delayed actions.
- Based on the developed semantics we could equip Bio-PEPAd with **equivalence relations**, perhaps based on the previously defined relations for Bio-PEPA.
- And course there is always more work to do on **case studies** and **tool development**!

Thank you!