
Eriskay: a programming language based on game semantics

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Motivation

The Eriskay project: Use a simple mathematical model of computation (a game model) to guide the design of a full-scale programming language.

We have in mind a strongly typed, higher order, polymorphic, class-based, object-oriented language, inspired by languages such as Java and ML. Some motivations:

- Reasoning about programs. Logical full abstraction means that logics derived from the model can be understood in terms of the language.
- “Hygiene” properties. Semantically based language design promises to yield properties like type safety and security for exceptions, continuations, name generation.
- Expressive new constructs suggested by model.

OO

Game semantics is intuitively a good match for object-oriented languages:

- Can model stateful computation.
- Good for *data abstraction*. We can interpret an object as a strategy for its externally observable behaviour, and gain a full abstraction result.
- Captures the idea of *reactive* computation (an ongoing interaction rather than a final result)

We consider a *core language* which can be interpreted simply in our game model, and a *full language* including more problematic features (references with equality) which require some extra effort to model. (Also cut-down language Lingay)

Introduction to Eriskay

Eriskay is a strongly typed class-based object-oriented language, with

- Objects with mutable state
- Functions (and recursion), sums, (labelled) products
- Recursive types, structural subtyping and System F style polymorphism (and F-bounded)
- Linear type system
- A form of continuations

Game model

We work in the simple category of Lamarche games—games are just trees of alternating Opponent/Player moves, with no restrictions such as well-bracketing. Define games \otimes , \multimap , etc.

There are two linear exponentials ‘!’ of particular interest:

- Hyland exponential— $!A$ is simply an infinitary (ordered) product of the game A .
- Backtracking exponential—each move in $!A$ may continue play in some copy of A , or backtrack to some move and open a new copy.

Basic language features

Types:

$$\sigma ::= \text{int} \mid \sigma_1 * \sigma_2 \mid \sigma_1 + \sigma_2 \mid \sigma_1 \rightarrow \sigma_2 \mid !\sigma_1 \mid \{l_1 : \sigma_1, \dots, l_n : \sigma_n\}$$

Language is strict, plain functions are linear and not reusable:

$$\llbracket \sigma_1 \rightarrow \sigma_2 \rrbracket = \llbracket \sigma_1 \rrbracket \multimap \llbracket \sigma_2 \rrbracket_{\perp}$$

Records are labelled products:

$$\llbracket l_1 : \sigma_1, \dots, l_n : \sigma_n \rrbracket = \llbracket \sigma_1 \rrbracket \otimes \dots \otimes \llbracket \sigma_n \rrbracket$$

Catchcont

We define a control operator `catchcont` providing a form of resumable exceptions (in various flavours). Where ρ, τ are ground types:

$$\frac{x : \rho \rightarrow \sigma \vdash e : \tau}{\vdash \text{catchcont}_1 x \Rightarrow e}$$
$$: \{\text{result} : \tau\} +$$
$$\{\text{arg} : \rho, \text{resume} : \sigma \rightarrow \tau\}$$

$$\frac{x : !(\rho \rightarrow \sigma) \vdash e : \tau}{\vdash \text{catchcont}_2 x \Rightarrow e}$$
$$: \{\text{result} : \tau\} +$$
$$\{\text{arg} : \rho, \text{resume} : \sigma \rightarrow !(\rho \rightarrow \sigma) \rightarrow \tau\}$$

Catchcont, continued

Semantic considerations suggest a more general operator:

$$\frac{x : !(\rho \rightarrow \sigma) \vdash e : \tau * \tau'}{\vdash \text{catchcont}_3 x \Rightarrow e} \quad \rho, \tau \text{ ground}$$
$$: \{\text{result} : \tau, \text{more} : !(\rho \rightarrow \sigma) \rightarrow \tau'\} +$$
$$\{\text{arg} : \rho, \text{resume} : \sigma \rightarrow !(\rho \rightarrow \sigma) \rightarrow \tau * \tau'\}$$

To show definability and full abstraction we consider the *universal game* $U = \llbracket !(\text{int} \rightarrow \text{int}) \rrbracket$. All computable strategies of U are language-definable, and basic types, $U \otimes U$, $U \oplus U$, $U \multimap U$, $!U$ and U_{\perp} are all definable retracts of U .

Coding the retraction $(U \multimap U) \rightarrow U \triangleleft U$ makes use of the power of catchcont_3 .

Catchcopy

Under the backtracking interpretation of ‘!’, we additionally have a reusable version:

$$\frac{x : !(\rho \rightarrow \sigma) \vdash e : \tau * \tau'}{\vdash \text{catchcopy } x \Rightarrow e} \quad \rho, \tau \text{ ground}$$

$$: \{ \text{result} : \tau, \text{more} : !(!(\rho \rightarrow \sigma) \rightarrow \tau') \} +$$

$$\{ \text{arg} : \rho, \text{resume} : \sigma !(- \rightarrow !(\rho \rightarrow \sigma) \rightarrow \tau * \tau') \}$$

Again, this is required for definability.

Classes

For now assume that methods are *public*, and fields are *protected*. A class implementation is a first-class expression of type `classimpl` τ_f, τ_m, τ_k , where:

- τ_f is a record type for the fields,
- $\tau_m = \{m_1 : !(\rho_1 \rightarrow \rho'_1), \dots, m_n : !(\rho_n \rightarrow \rho'_n)\}$ is the type for objects of the class
- τ_k is the argument type for the (single) constructor

Given such a class implementation c , we can construct an object via the expression `constr` $c : \tau_k \rightarrow \tau_m$.

But what does one look like?

Method bodies

For object type τ_m , with fields of type τ_f , the method bodies will have type $\tau_m \Downarrow \tau_f$.

In the case of the Hyland !, there is a 'functional' treatment of state:

$$\tau_m \Downarrow \tau_f = \{m_1 : !(\rho_1 * \tau_f \rightarrow \rho'_1 * \tau_f), \dots, m_n : !(\rho_n * \tau_f \rightarrow \rho'_n * \tau_f)\}$$

With the backtracking !, we can introduce more flexible *read* and *write* operations:

$$\tau_m \Downarrow \tau_f = !(!(\{\} \rightarrow \tau_f) \rightarrow !(\tau_f \rightarrow \{\}) \rightarrow \tau_m)$$

(Note: not every expression of either of these types is a suitable method body)

Class implementations

In a class body, we leave ‘open’ the method implementations, via a parameter $self : \tau_m \# \tau_f$, allowing for *method overriding*.

A class is interpreted via the resulting approximation operator $\tau_m \# \tau_f \rightarrow \tau_m \# \tau_f$. The fixed point of this is taken at object creation time.

An additional parameter *super* can be added, and to allow for additional fields in subclasses we can replace τ_f by $\tau_f * \delta$ (unfortunately not $\alpha <: \tau_f$).

$$\begin{array}{c}
 c : \text{classimpl } \tau_f, \tau_m, \tau_k \\
 e_m : \text{polytype } \delta \Rightarrow \tau_{super} \rightarrow \tau_{self} \rightarrow \tau_{self} \\
 e_k : \tau'_k \rightarrow \tau_k * (\tau_f \rightarrow \tau'_f) \\
 \hline
 \text{extend } c \text{ with } e_m, e_k : \text{classimpl } \tau''_f, \tau''_m, \tau'_k
 \end{array}
 \qquad
 \begin{array}{l}
 \tau_{super} = \tau_m \# (\tau''_f * \delta) \\
 \tau_{self} = \tau'_m \# (\tau''_f * \delta) \\
 \tau''_f = \tau_f \# \tau'_f \\
 \tau''_m = \tau_m \# \tau'_m \\
 \tau_f, \tau'_f \text{ have disjoint labels}
 \end{array}$$

Restrictions on higher-order store

Our class implementations seem to allow us to define a higher-order store cell. Suppose s is a store cell for $(\text{int} \rightarrow \text{int})$, and we run

$$s.put(\text{fn } x \Rightarrow x); s.get() \ 5$$

We get ‘bad’ behaviour:

	$put: (\text{int} \rightarrow \text{int}) \rightarrow \{\}$	$get: \{\} \rightarrow (\text{int} \rightarrow \text{int})$	
O	?		
P	!		
O		?	
P		!	
O			?5
P	?5		

Argument safety

Problematic behaviour occurs when a method argument is accessed via the state after the method returns. The type system ensures the property of *argument safety*, that this does not occur.

New judgement forms such as $\Gamma \vdash e : \tau \text{ safe}$.

Fundamental principle: information from an argument may only flow into the state via an expression of ground type.

This means that our language does not permit arbitrary uses of higher-order store; on the other hand, we are not restricted to ground type store.

What do we have

- Can create objects with higher-type fields (f): $\text{new } C (x:\text{int}\rightarrow\text{int})$ can set $f := x$
- Cannot store a non-ground-type argument: $m(x:\text{int}\rightarrow\text{int})\{f := x\}$.
- Cannot store a non-ground-type value obtained from argument:

$$m(x:\text{int}\rightarrow\text{int}\rightarrow\text{int})\{f := x\ 5\}$$

- Can interact with fields: $m()\{\text{return } (f\ 5)\}$
- Update non-ground fields: $m()\{f := \lambda n. f\ n + 1\}$
- Make use of ground type info from argument $m()\{p := x\ 5; f := \lambda n. p\}$
- Use fields and arguments unrestrictedly in return values:

$$m(x:\text{int}\rightarrow\text{int})\{\text{return } (f, x)\}$$

Exception safety

Argument safety has applications to statically controlled exceptions.

- In ML, it is possible for an exception to escape its static scope.
- Conversely, Java's typing of exceptions can be too restrictive.

Consider the Java program:

```
interface Function {Element f (Element x);}
interface List {void add (Element x);
               void map (Function F);
               Element nth (int n);}
```

Intuitively, map is argument safe, while add is not.

Future work

- Implementation (coming soon)
- Soundness proof (extension of proof for smaller language)
- Details of full language
- Program logics etc.

Conclusions