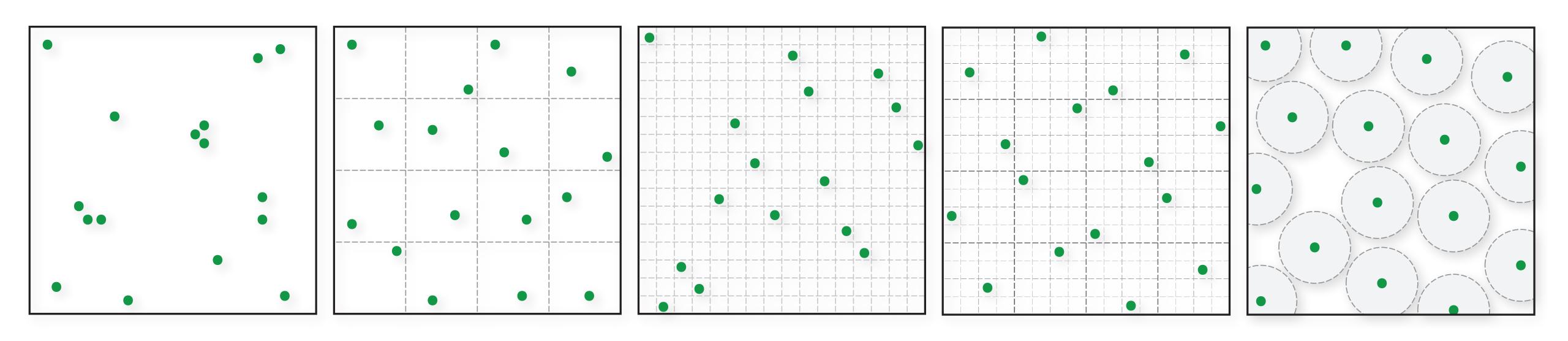
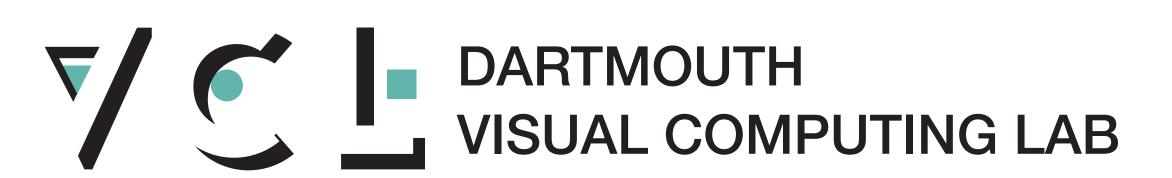
#### POPULAR SAMPLING PATTERNS

Fourier Analysis of Numerical Integration in Monte Carlo Rendering



Wojciech Jarosz wjarosz@dartmouth.edu

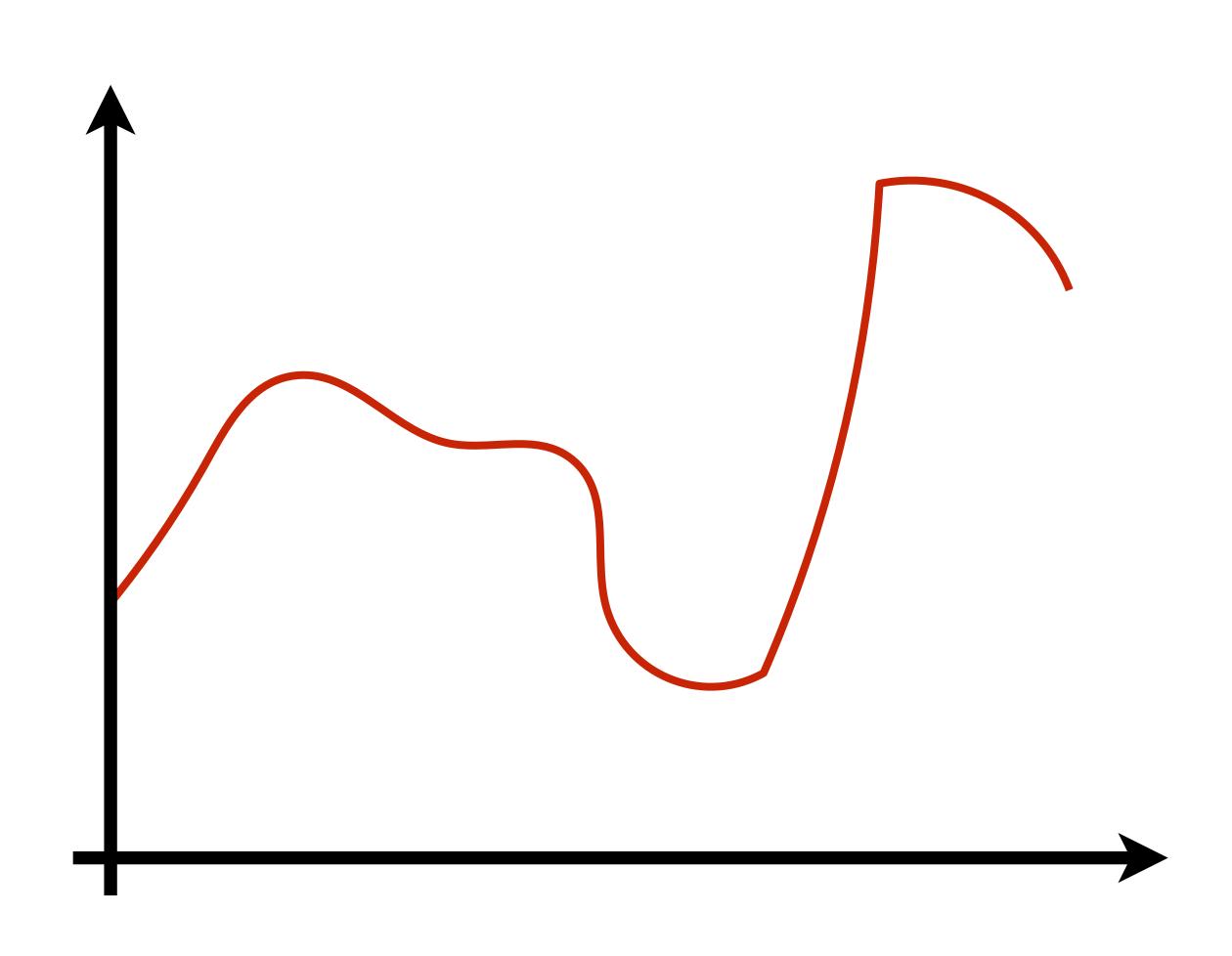




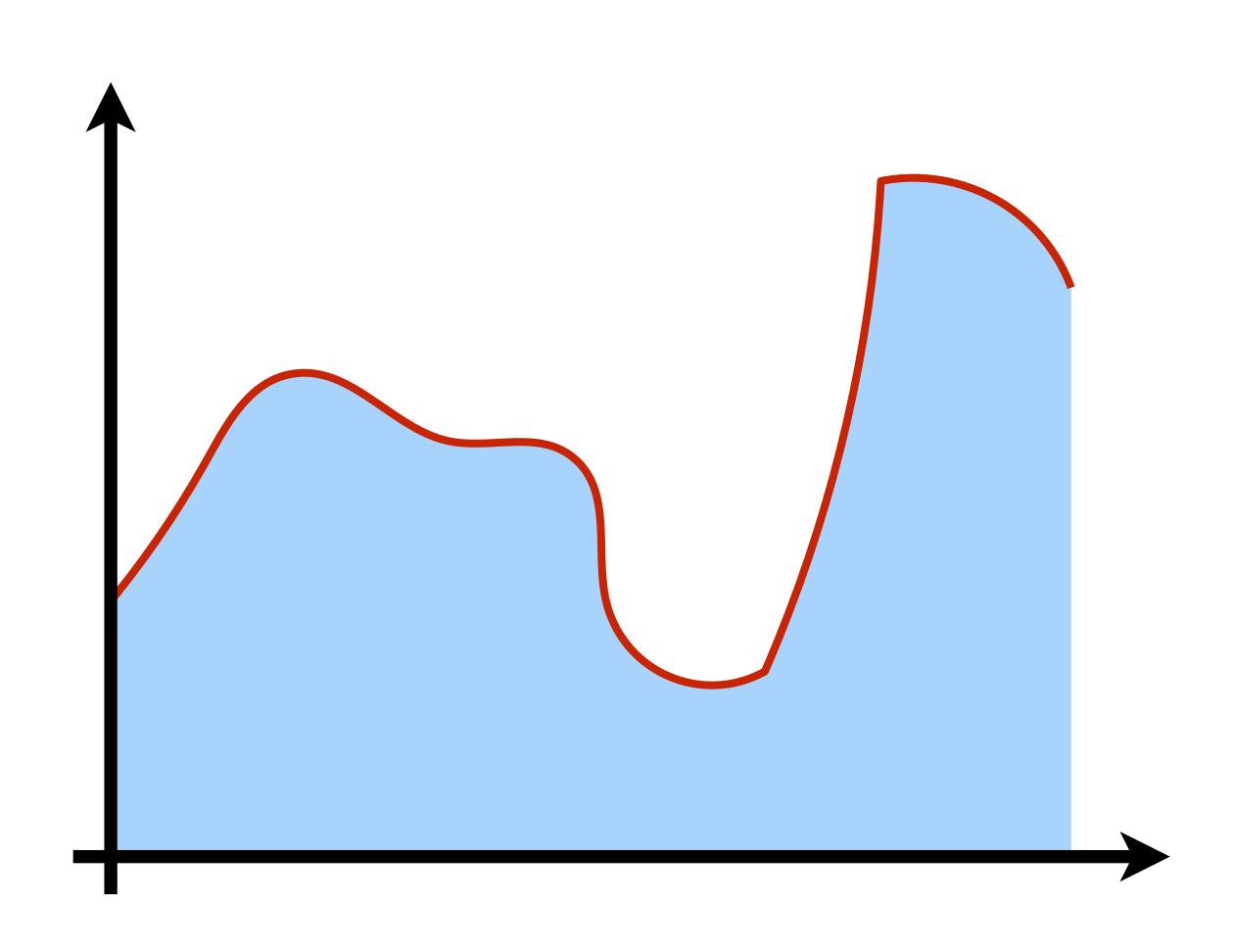
$$I = \int_D f(x) \, \mathrm{d}x$$



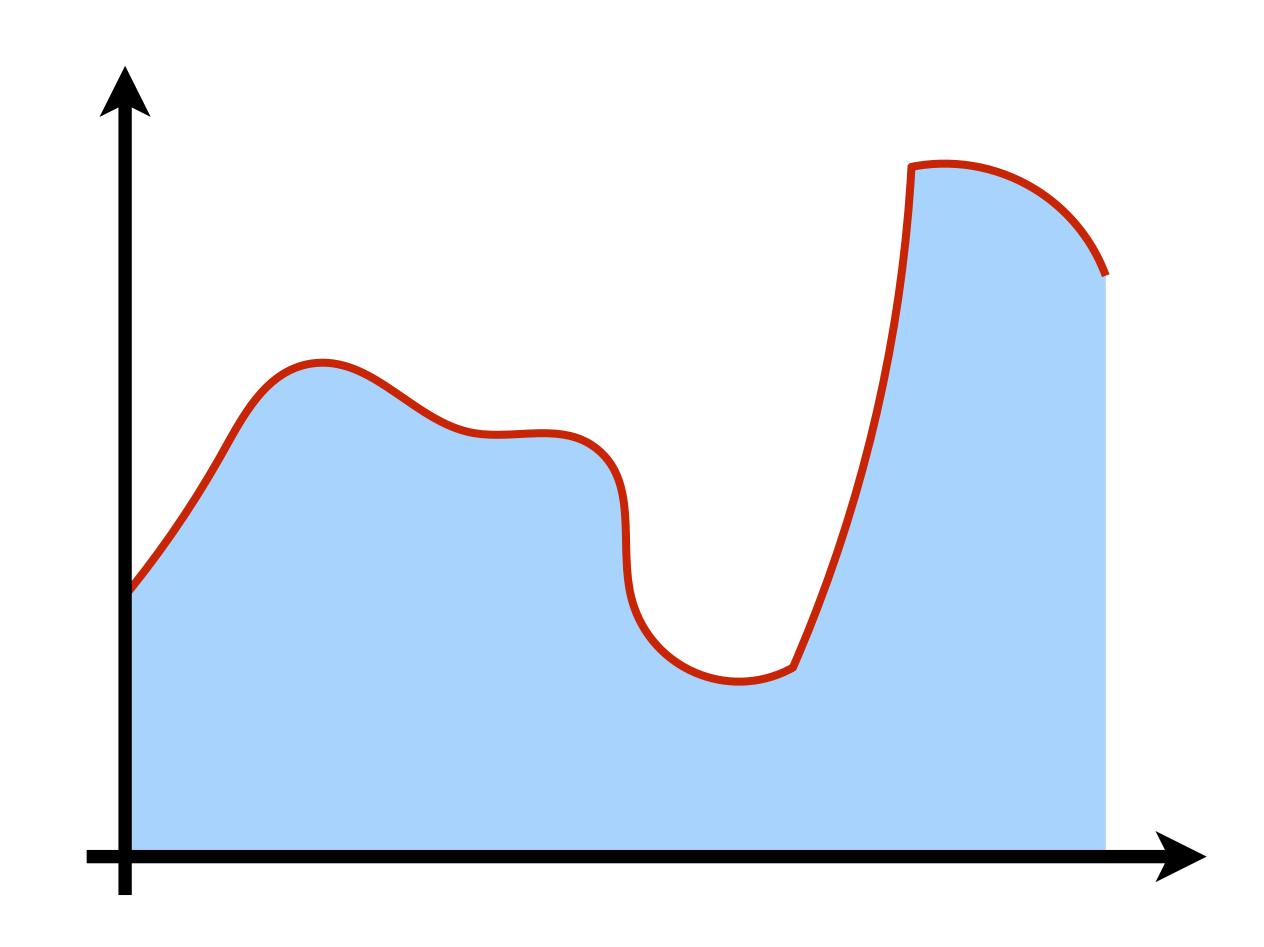
$$I = \int_{D} f(x) \, \mathrm{d}x$$



$$I = \int_{D} f(x) \, \mathrm{d}x$$



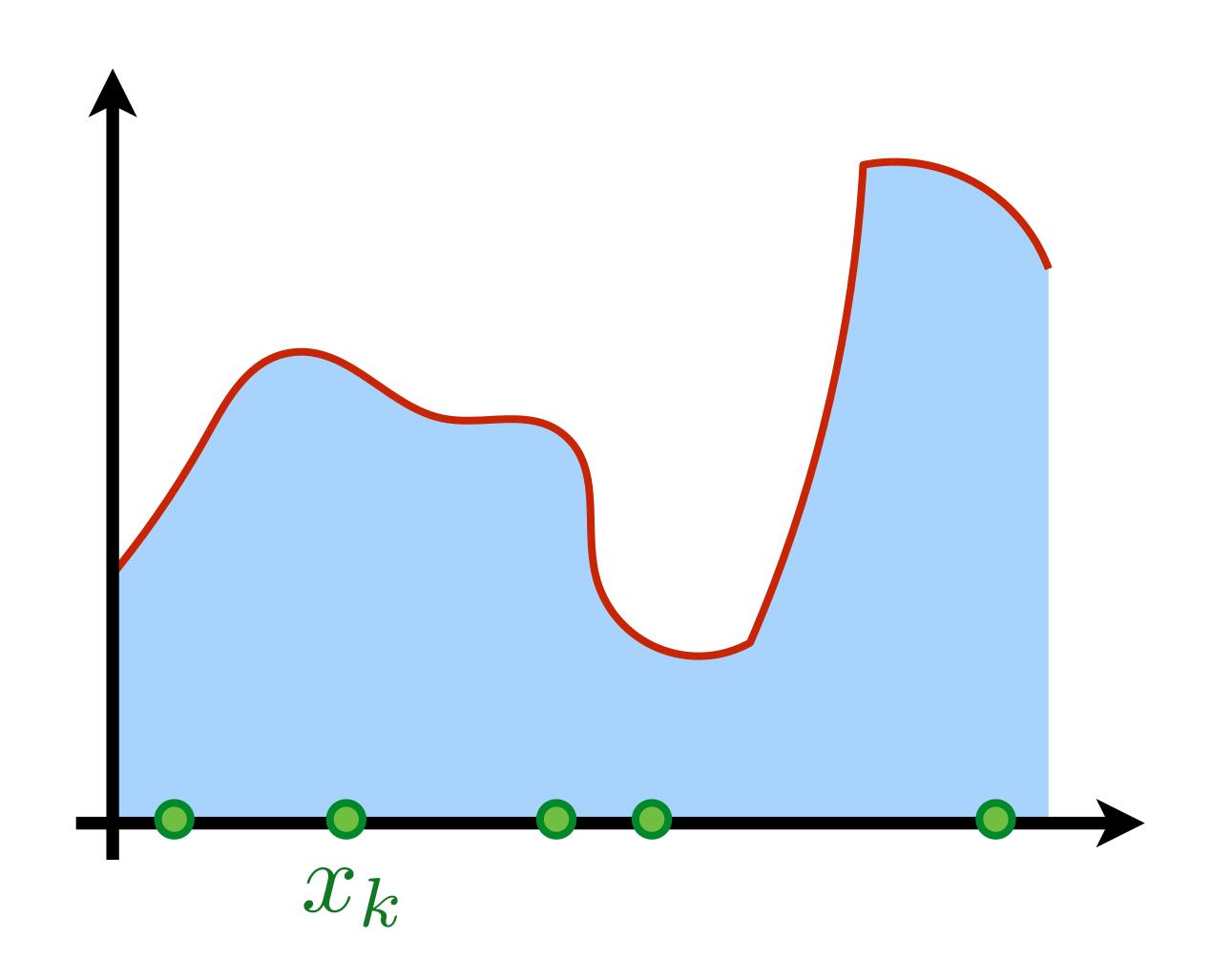
$$I = \int_{D} f(x) dx$$
 $pprox \int_{D} f(x) \mathbf{S}(x) dx$ 



$$I = \int_D f(x) dx$$

$$\approx \int_D f(x) \mathbf{S}(x) dx$$

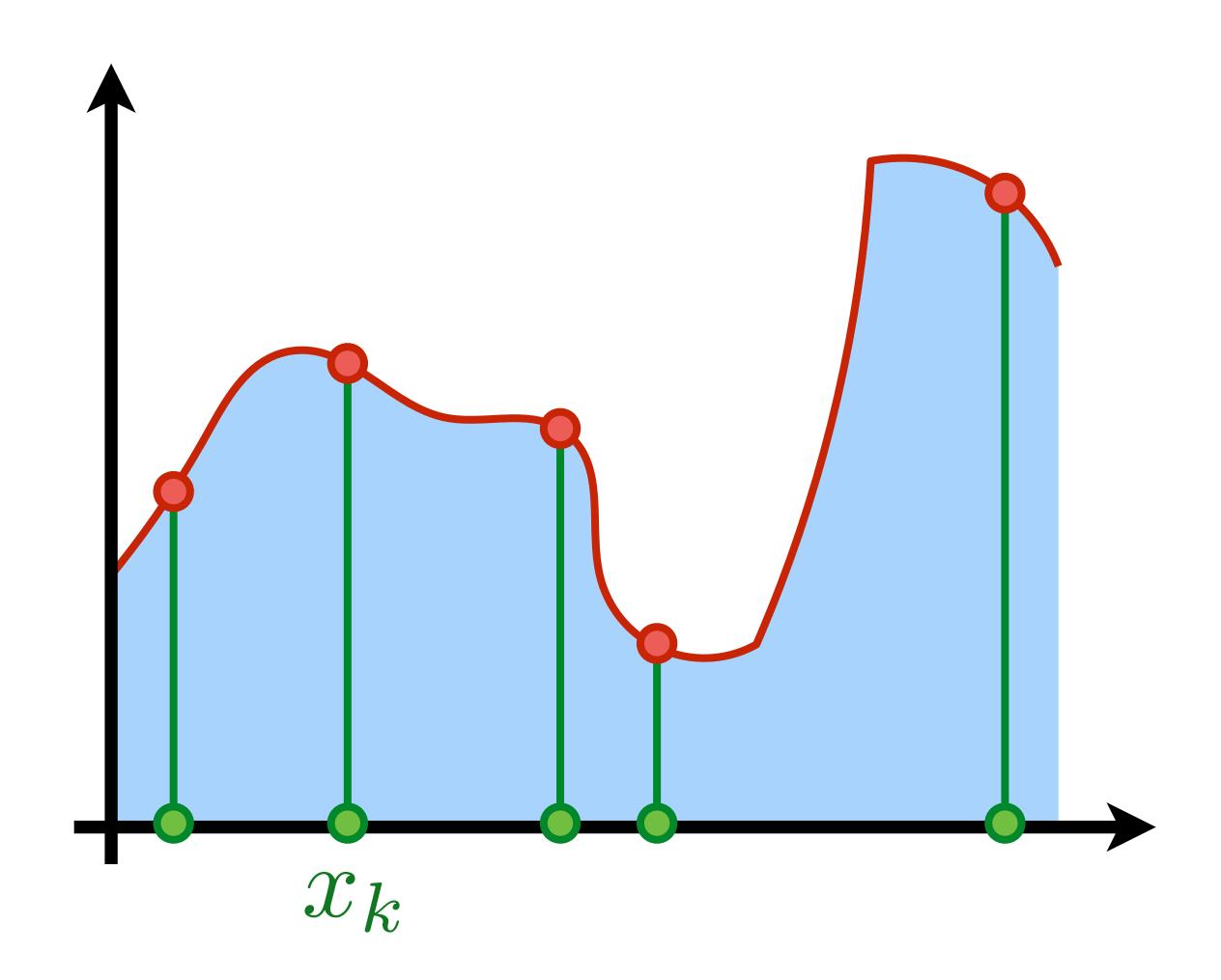
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - x_k)$$



$$I = \int_{D} f(x) dx$$

$$\approx \int_{D} f(x) \mathbf{S}(x) dx$$

$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - x_k)$$

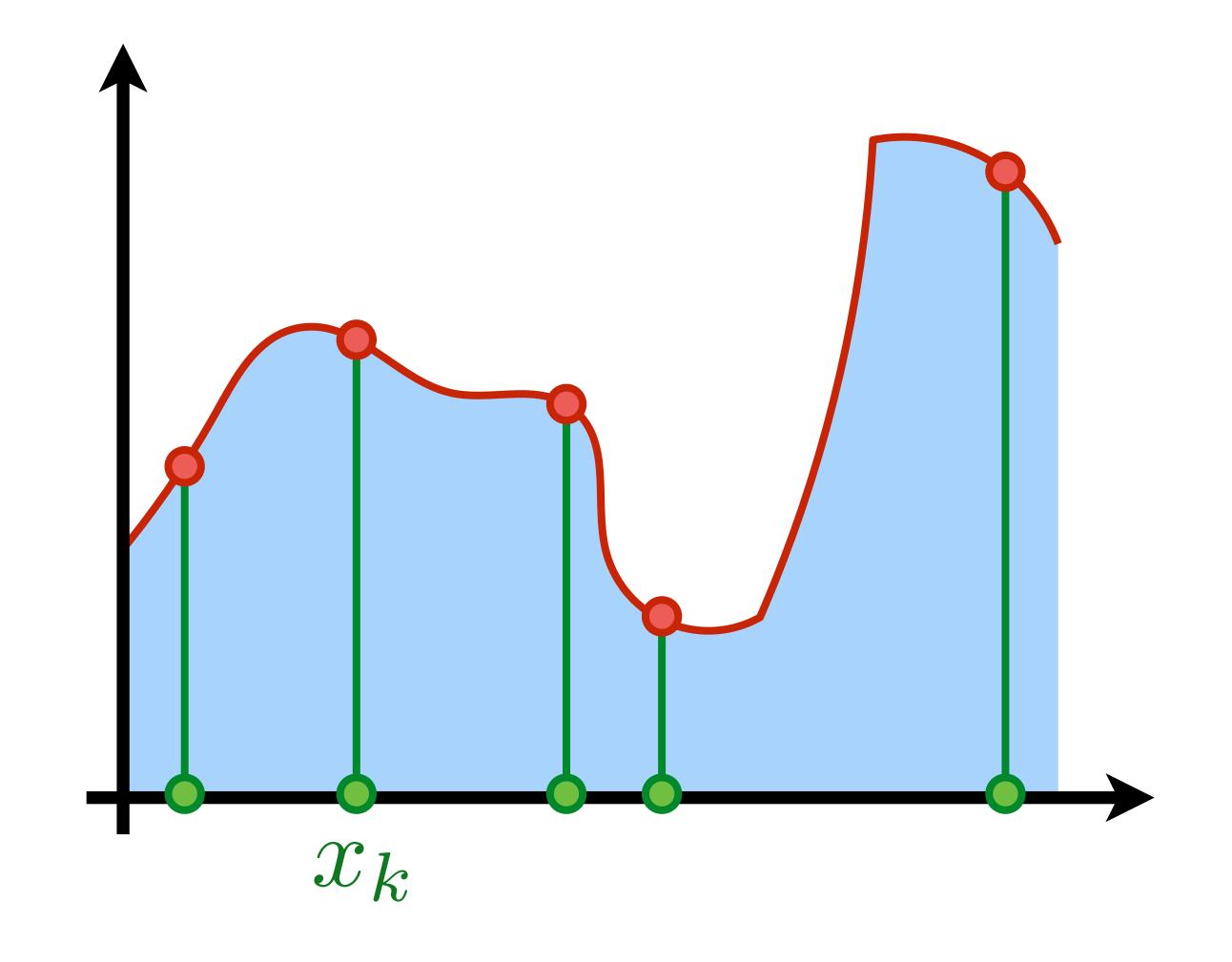


$$I = \int_{D} f(x) dx$$

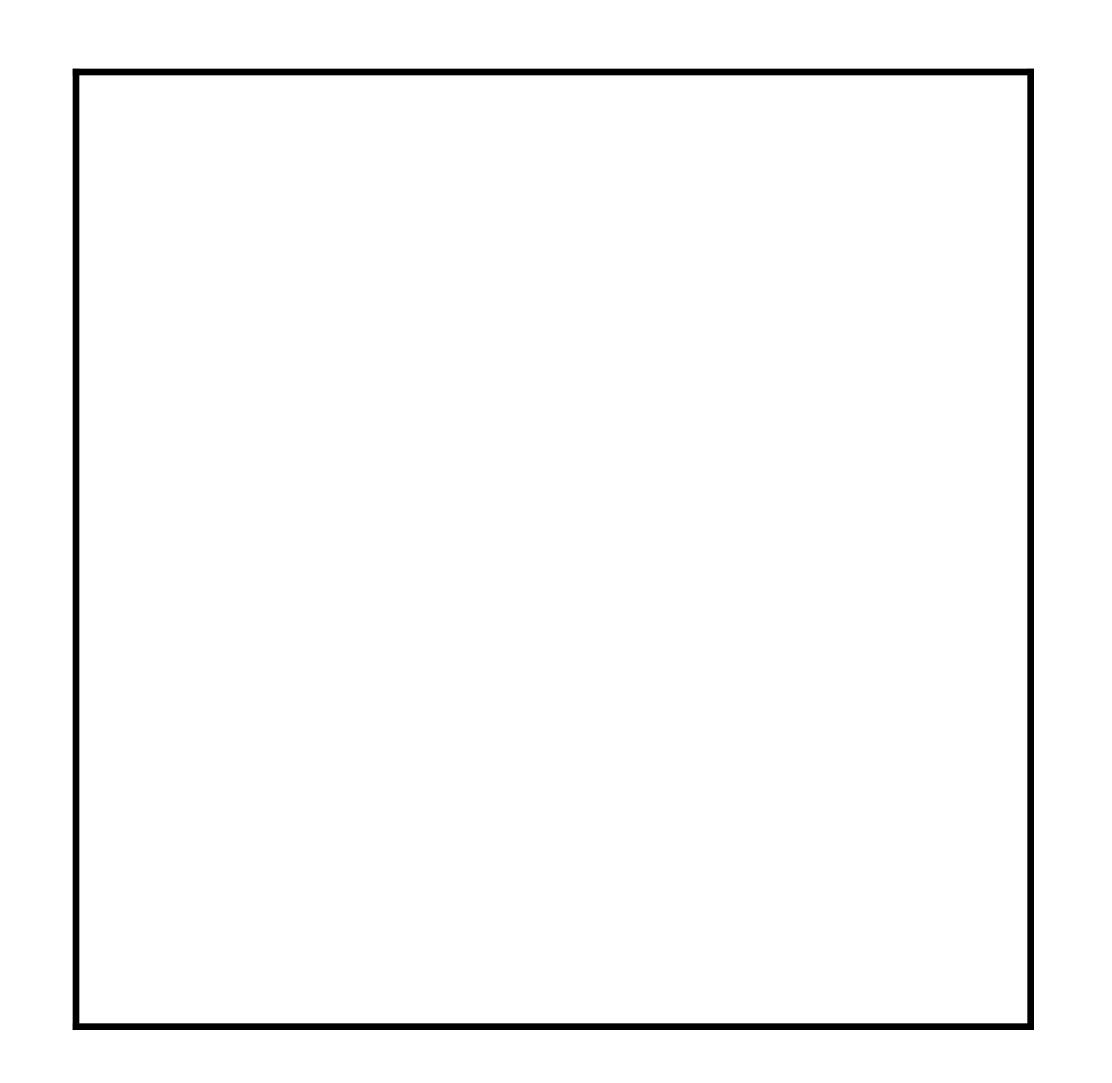
$$\approx \int_{D} f(x) \mathbf{S}(x) dx$$

$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - x_k)$$

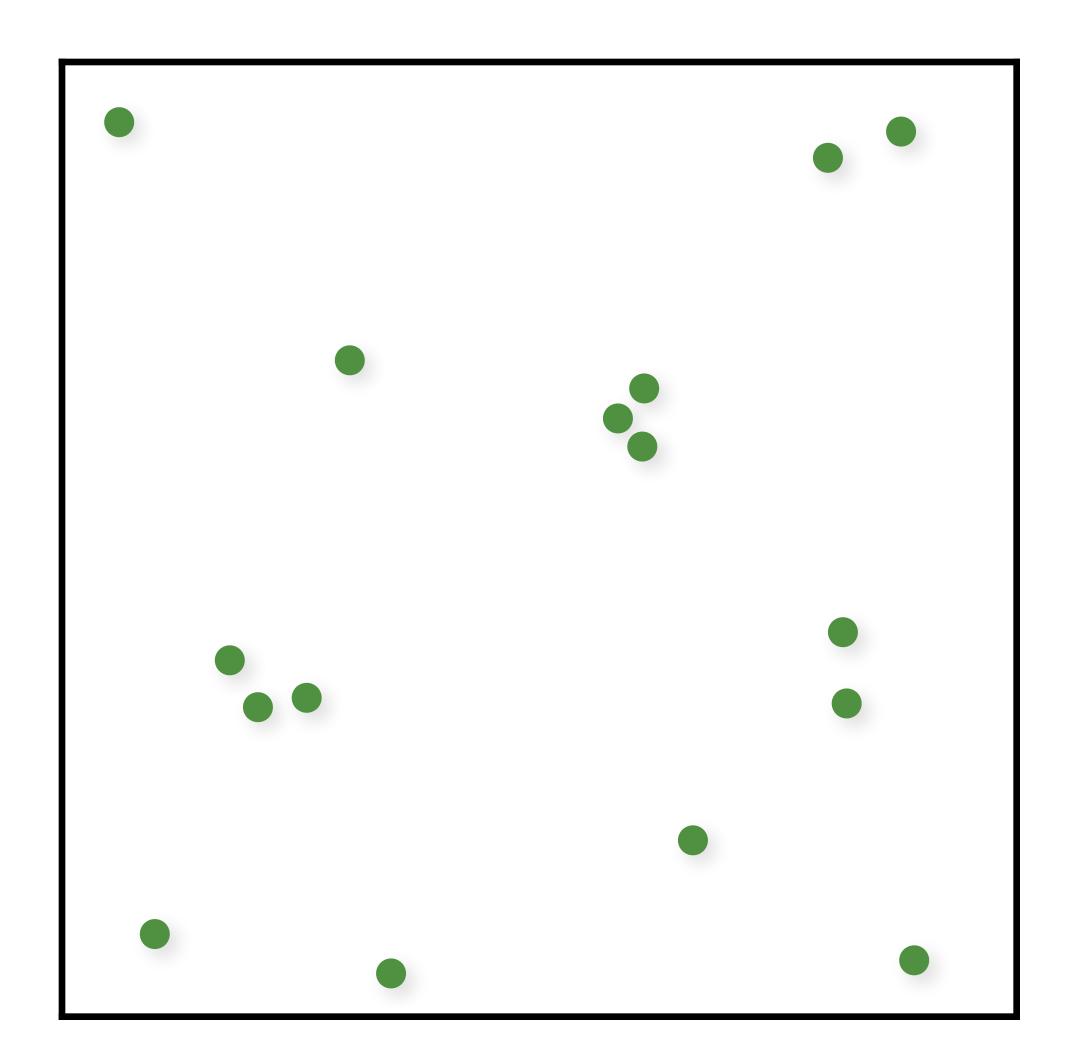
How to generate the locations  $x_k$ ?



```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```

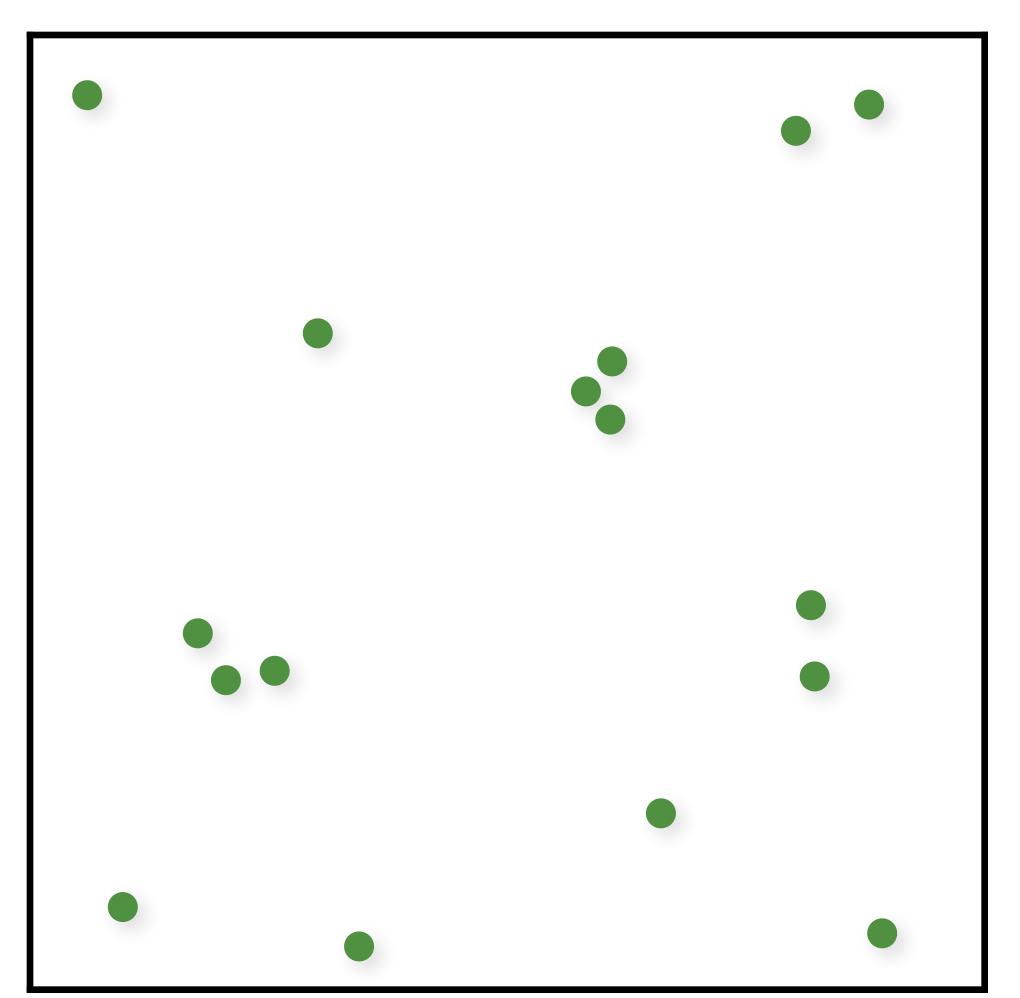


```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```



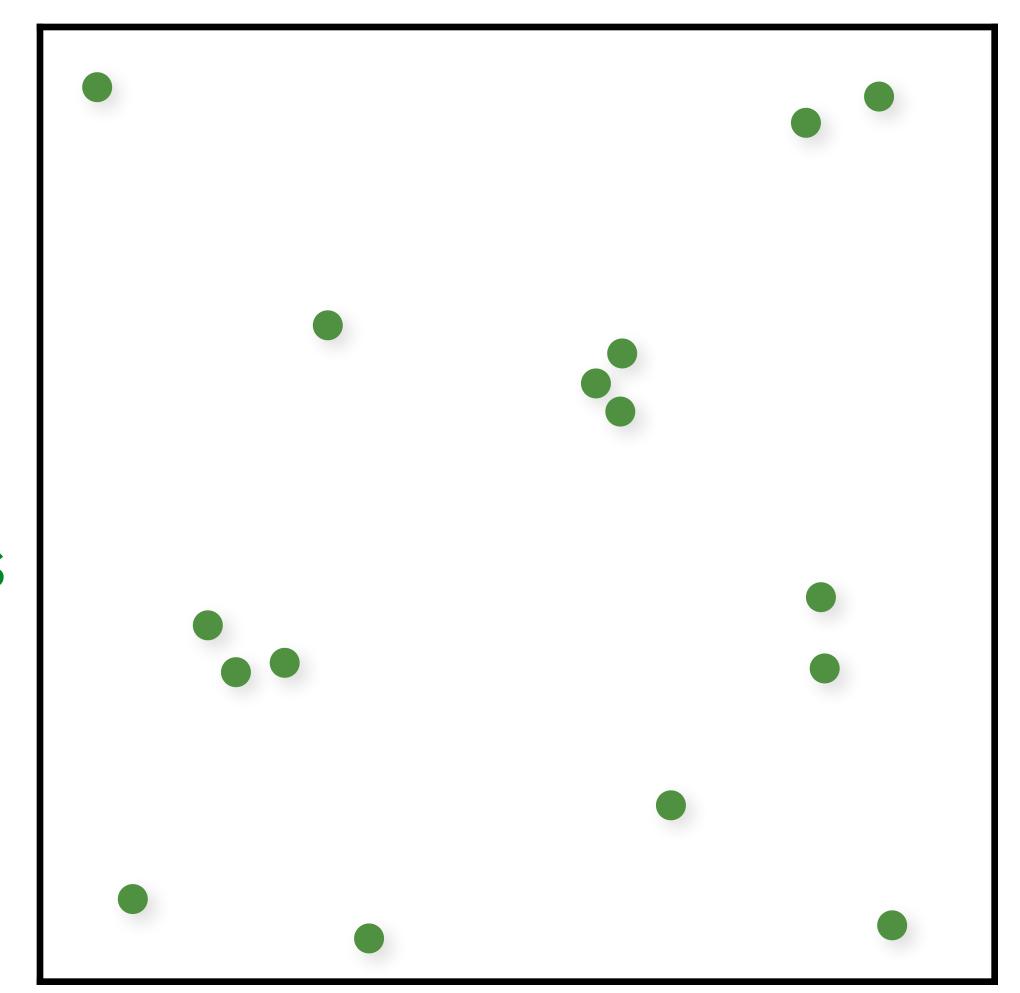
```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```

Trivially extends to higher dimensions



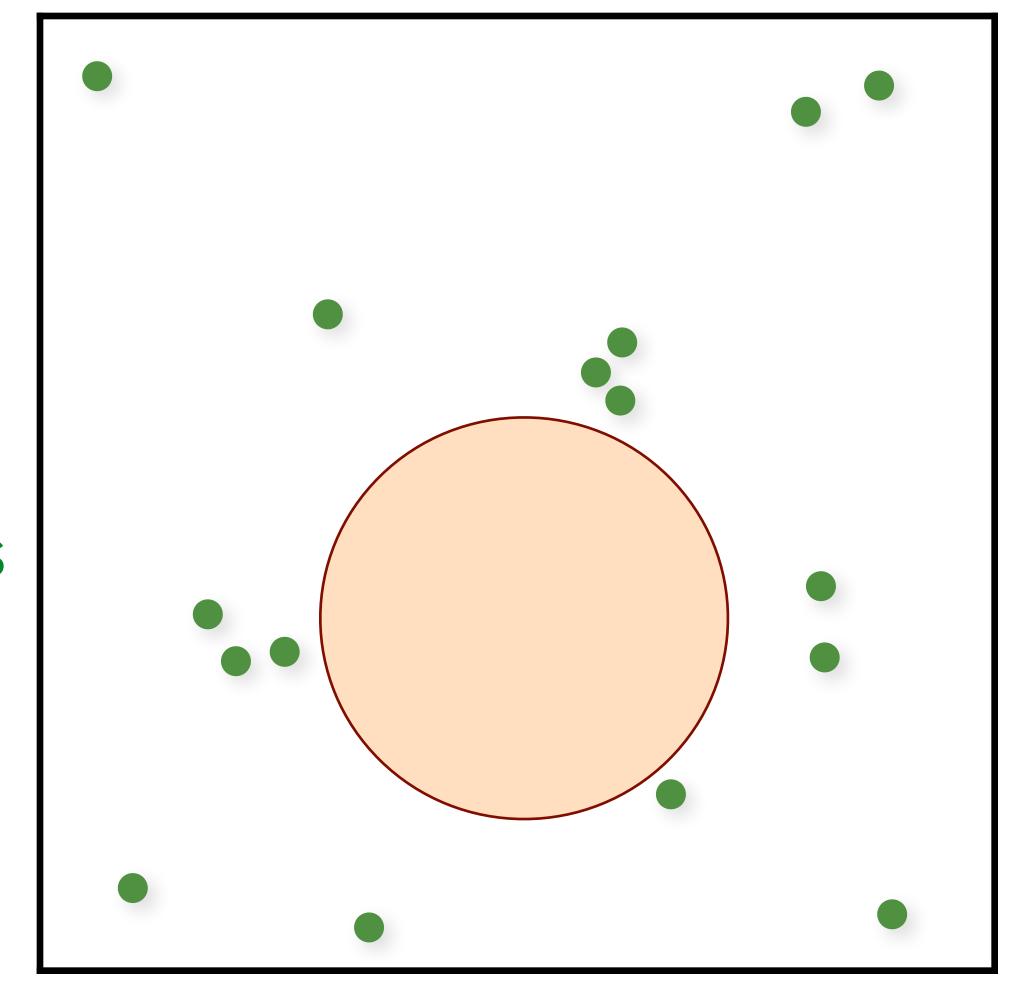
```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```

- Trivially extends to higher dimensions
- Trivially progressive and memory-less



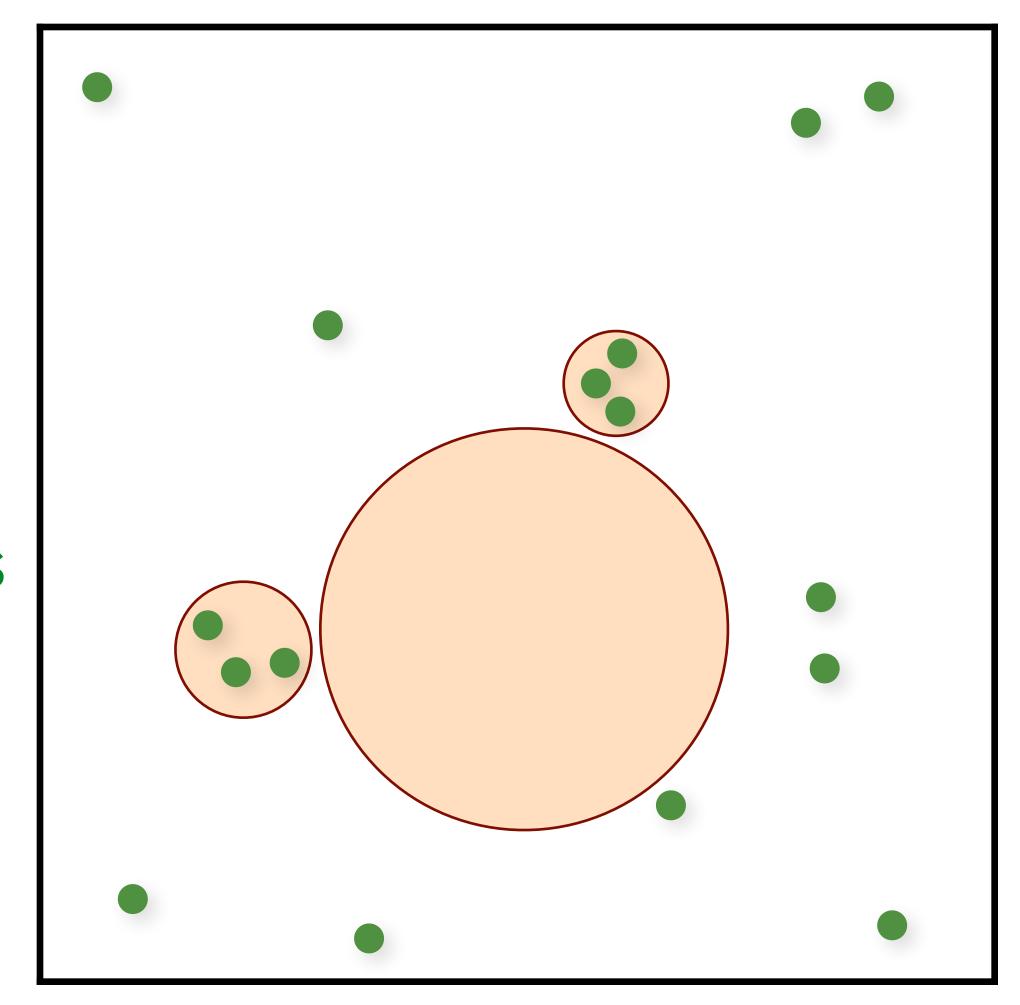
```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```

- Trivially extends to higher dimensions
- Trivially progressive and memory-less
- X Big gaps



```
for (int k = 0; k < num; k++)
{
    samples(k).x = randf();
    samples(k).y = randf();
}</pre>
```

- Trivially extends to higher dimensions
- Trivially progressive and memory-less
- Big gaps
- **X** Clumping



Fourier transform:  $\hat{f}(\omega) = \int_D f(x) e^{-2\pi \imath \omega x} dx$ 

Fourier transform:  $\hat{f}(\vec{\omega}) = \int_{D} f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ 

Fourier transform:  $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ 

Sampling function:  $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \mathbf{S}(\vec{x}) e^{-2\pi \imath (\vec{\omega} \cdot \vec{x})} d\vec{x}$ 

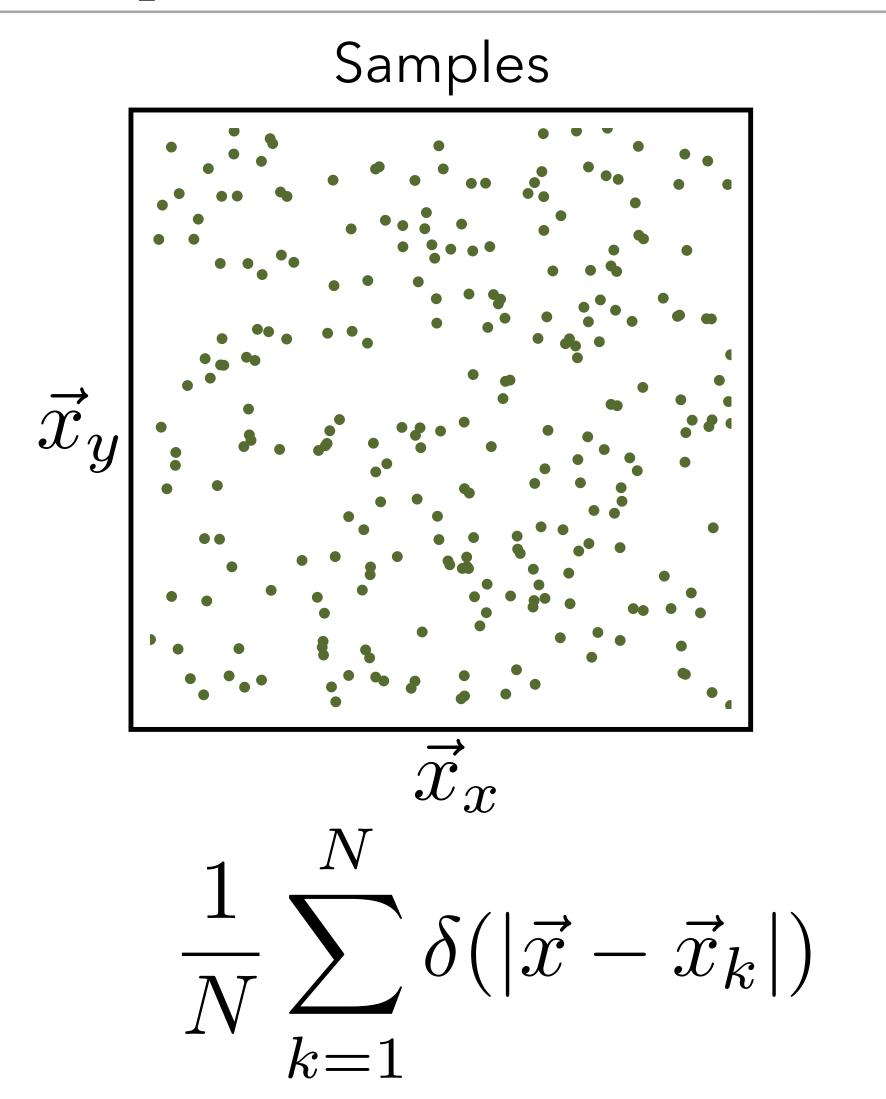
Fourier transform:  $\hat{f}(\vec{\omega}) = \int_{D} f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ 

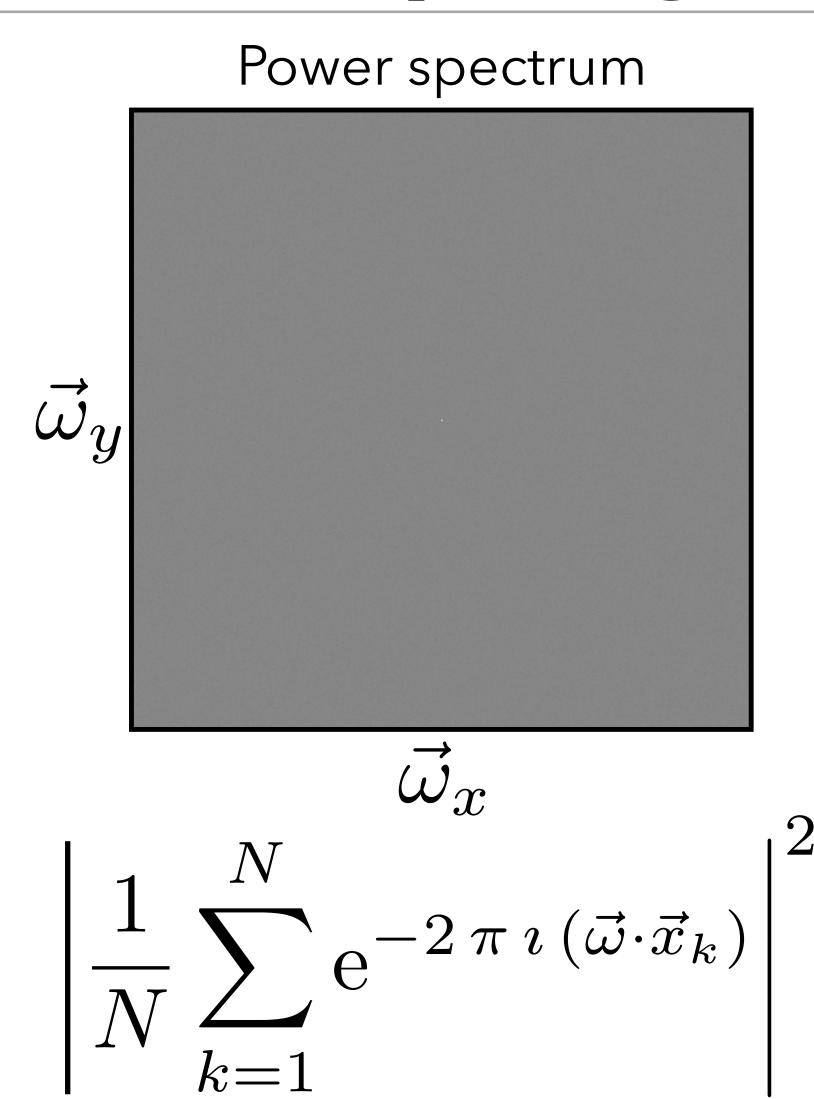
Sampling function:  $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ 

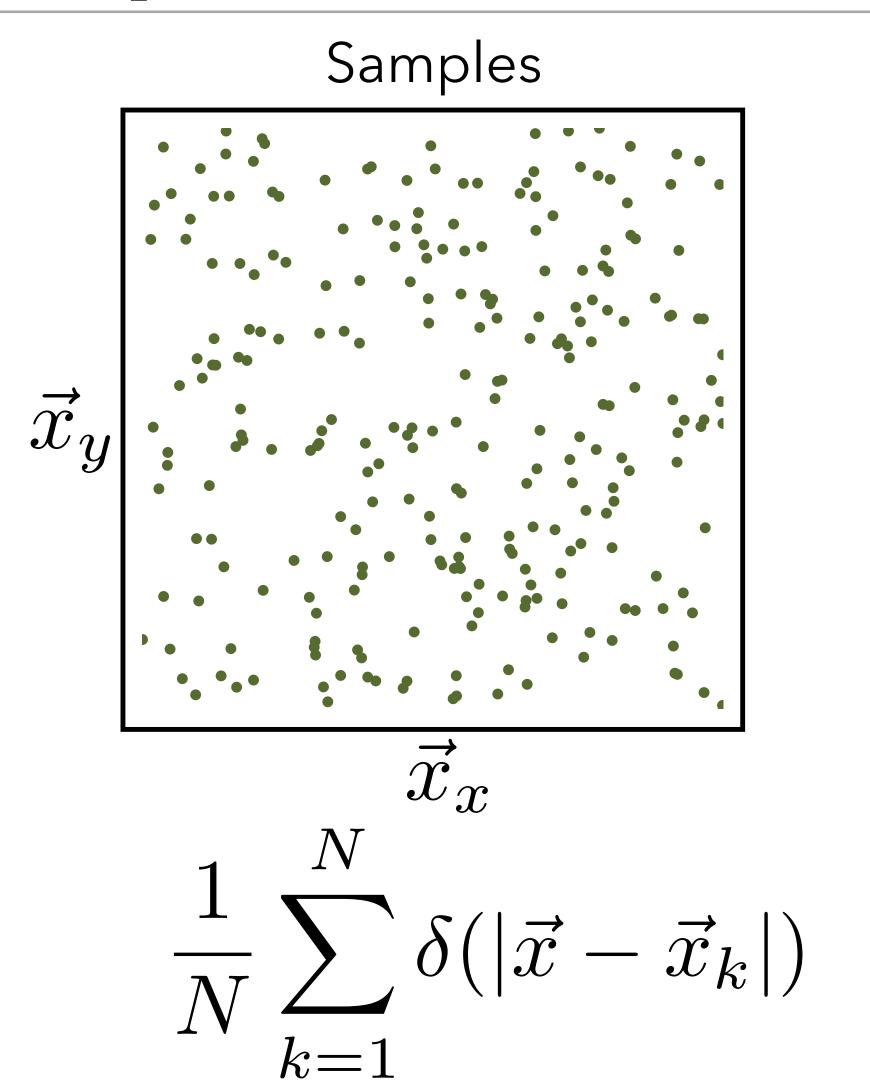
Fourier transform: 
$$\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$$

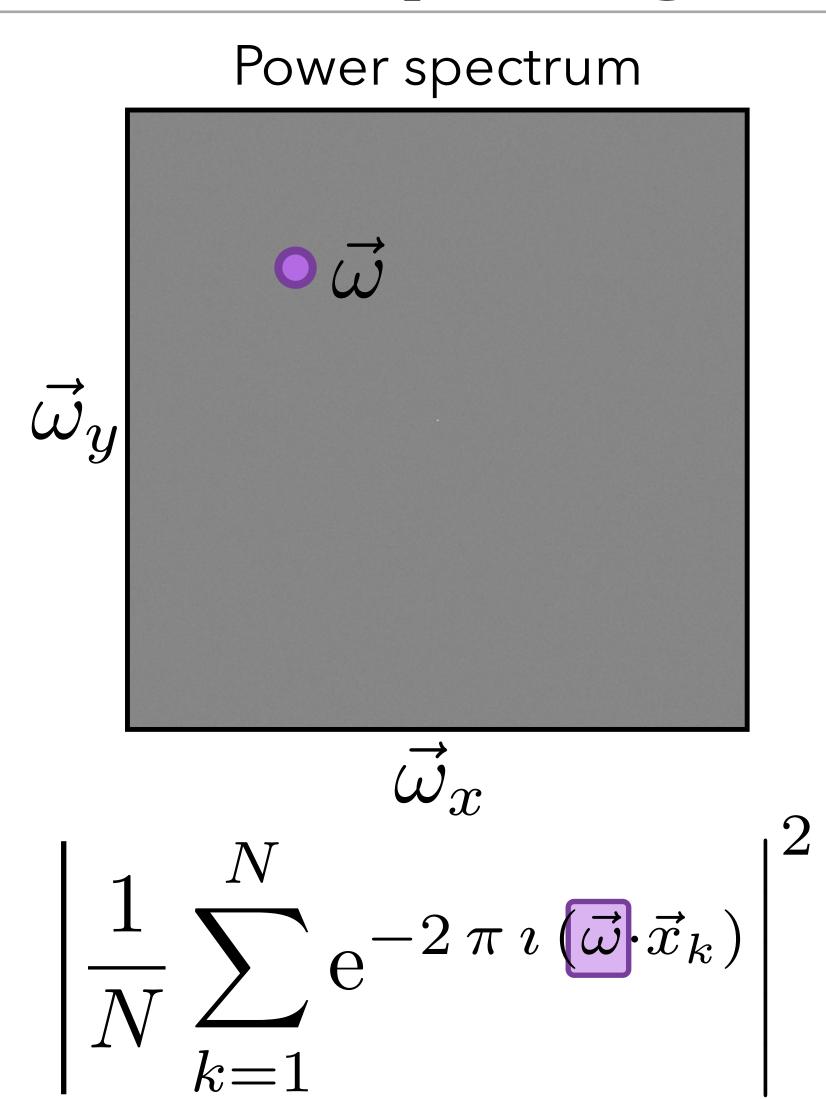
Sampling function: 
$$\hat{\mathbf{S}}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi \imath (\vec{\omega} \cdot \vec{x})} d\vec{x}$$

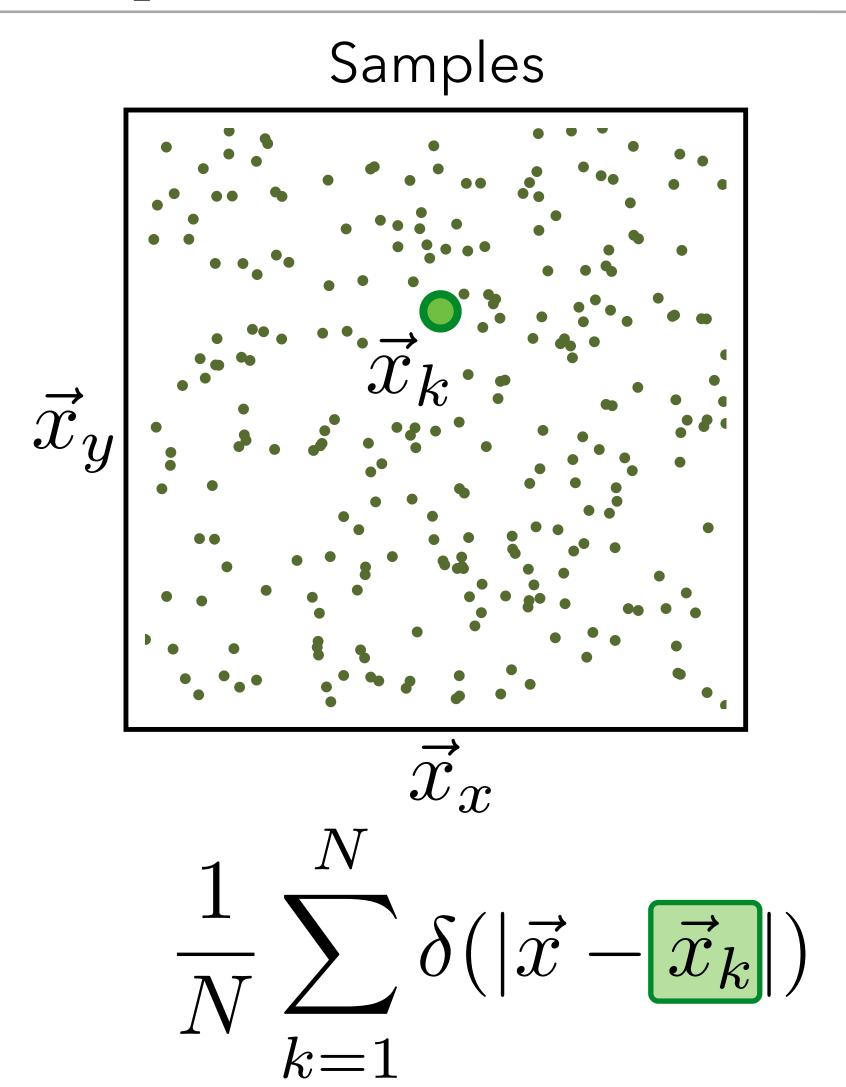
$$= \frac{1}{N} \sum_{k=1}^{N} e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)}$$

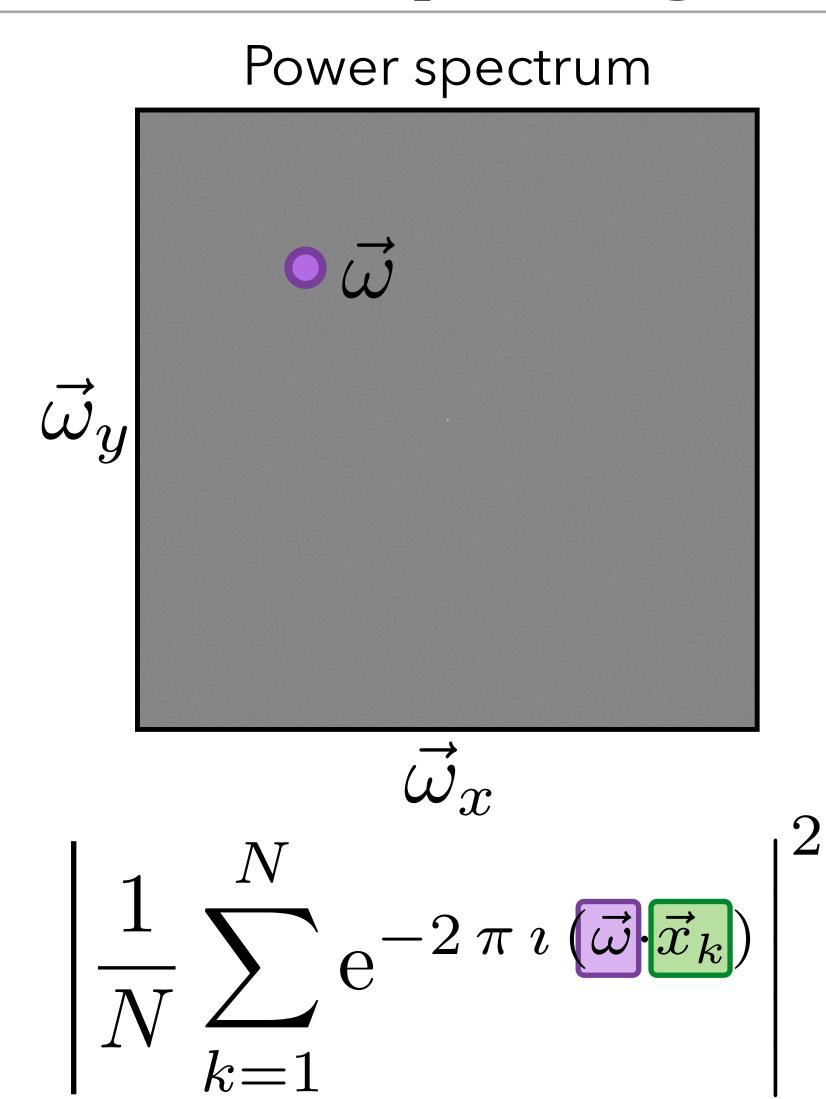




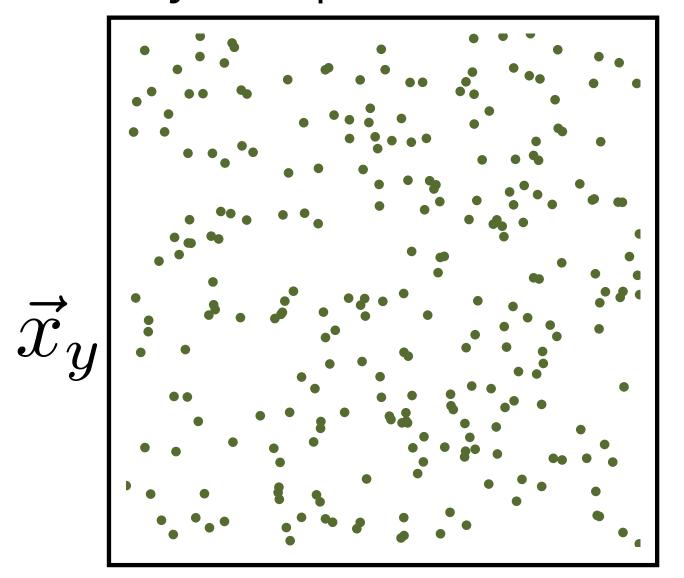






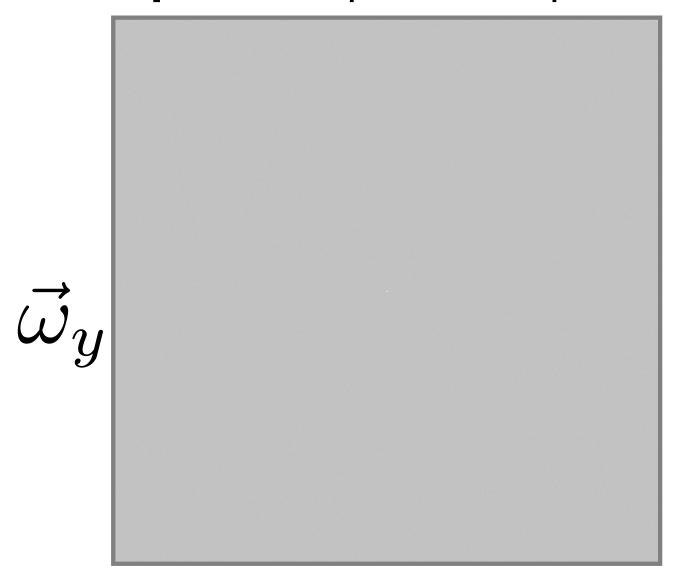


Many sample set realizations



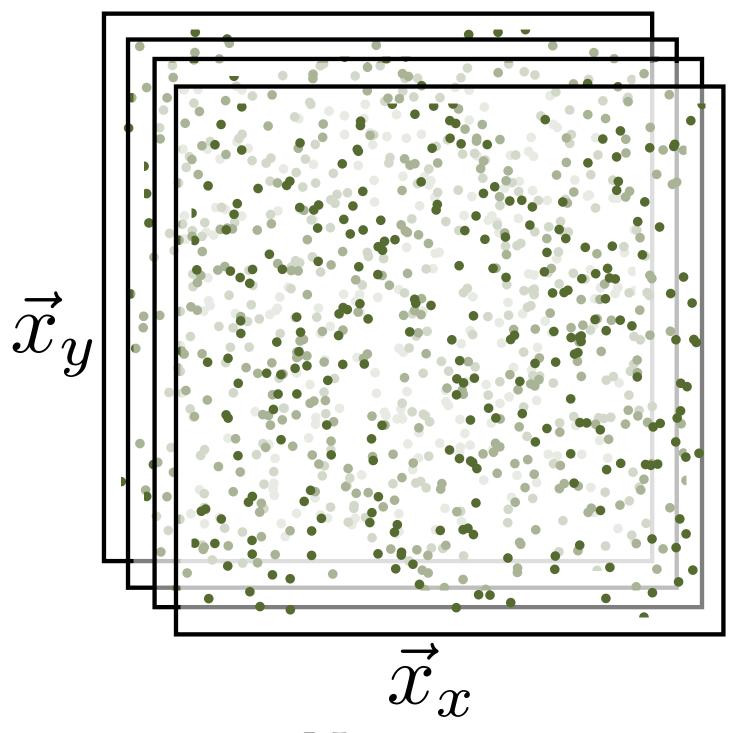
$$\frac{\vec{x}_x}{1} \sum_{k=1}^{N} \delta(|\vec{x} - \vec{x}_k|)$$

Expected power spectrum



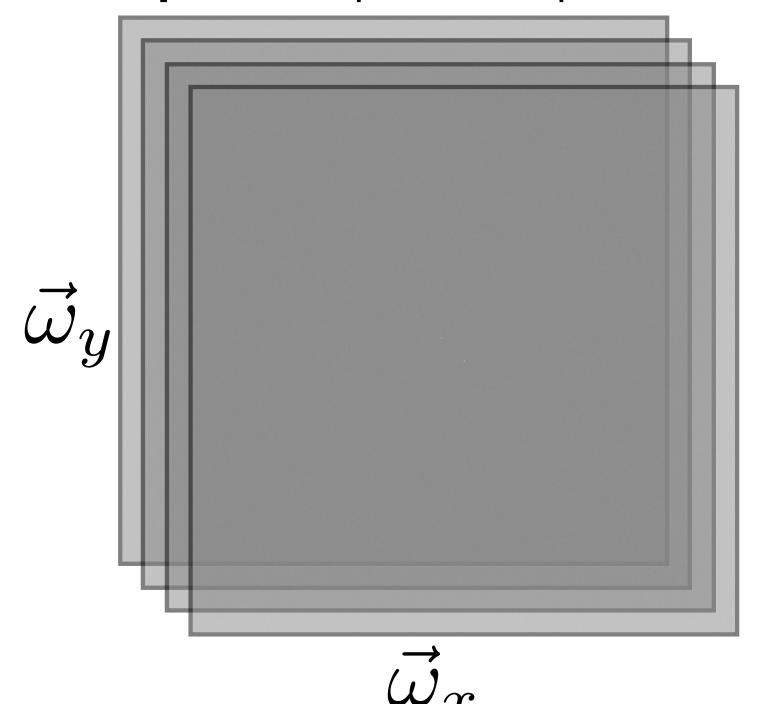
$$\left| \frac{\vec{\omega}_x}{1} \sum_{k=1}^{N} e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2$$

Many sample set realizations



$$\frac{1}{N} \sum_{k=1}^{N} \delta(|\vec{x} - \vec{x}_k|)$$

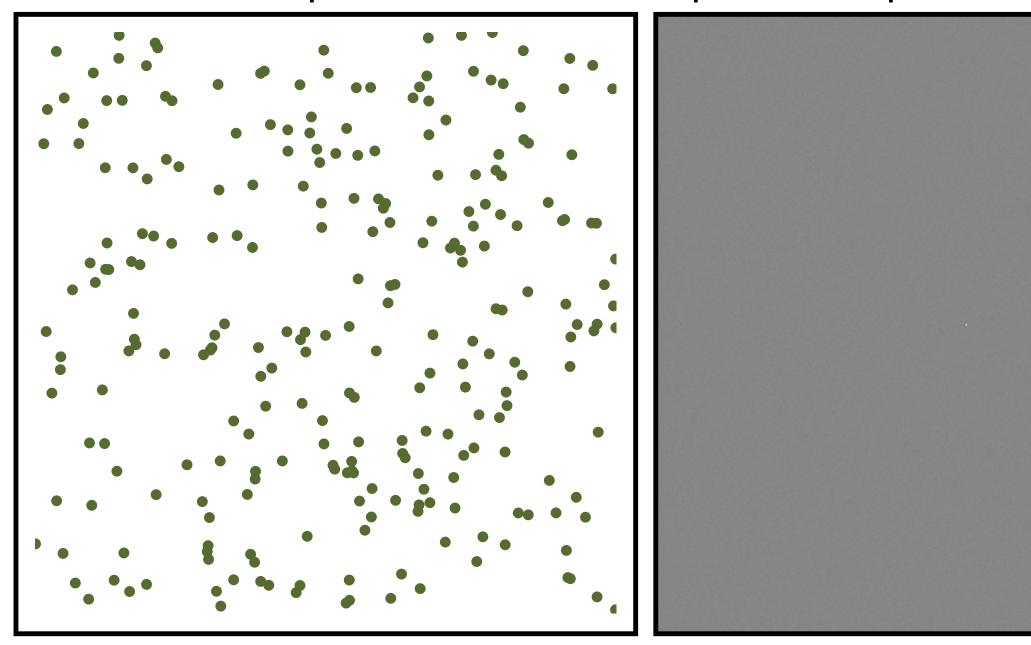
Expected power spectrum



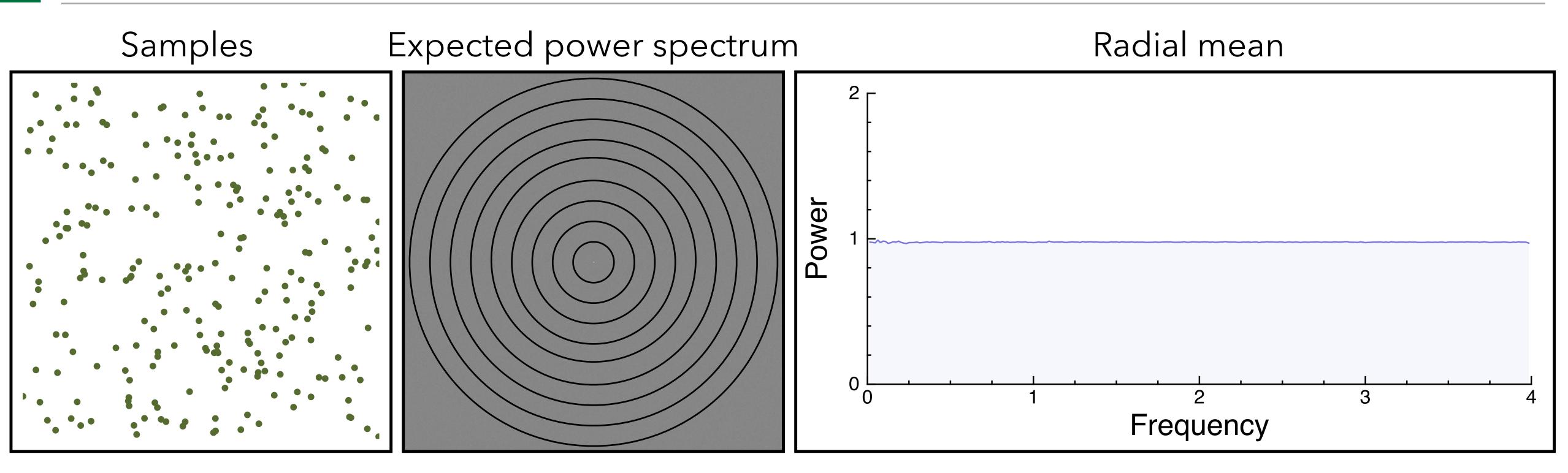
$$\mathbf{E} \left[ \left| \frac{1}{N} \sum_{k=1}^{N} e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

Samples

Expected power spectrum

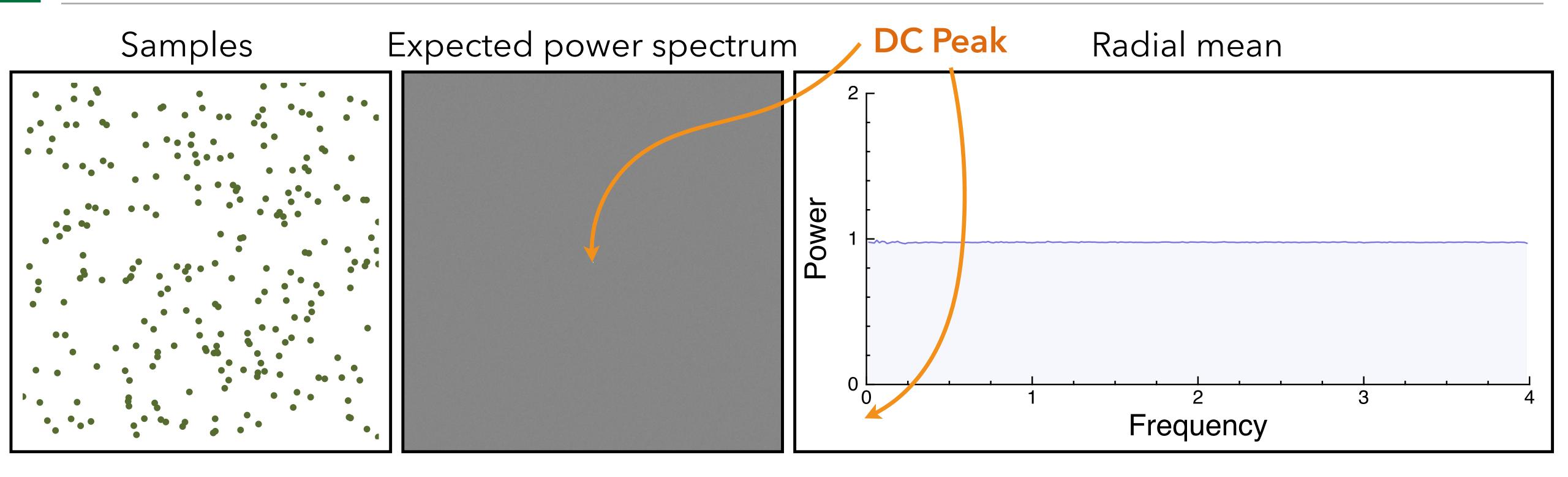


$$\frac{1}{N} \sum_{k=1}^{N} \delta(|\vec{x} - \vec{x}_k|) \quad \mathbf{E} \left[ \left| \frac{1}{N} \sum_{k=1}^{N} e^{-2\pi \imath (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$



$$\frac{1}{N} \sum_{k=1}^{N} \delta(|\vec{x} - \vec{x}_k|) \quad \mathbf{E} \left[ \left| \frac{1}{N} \sum_{k=1}^{N} e^{-2\pi \imath (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

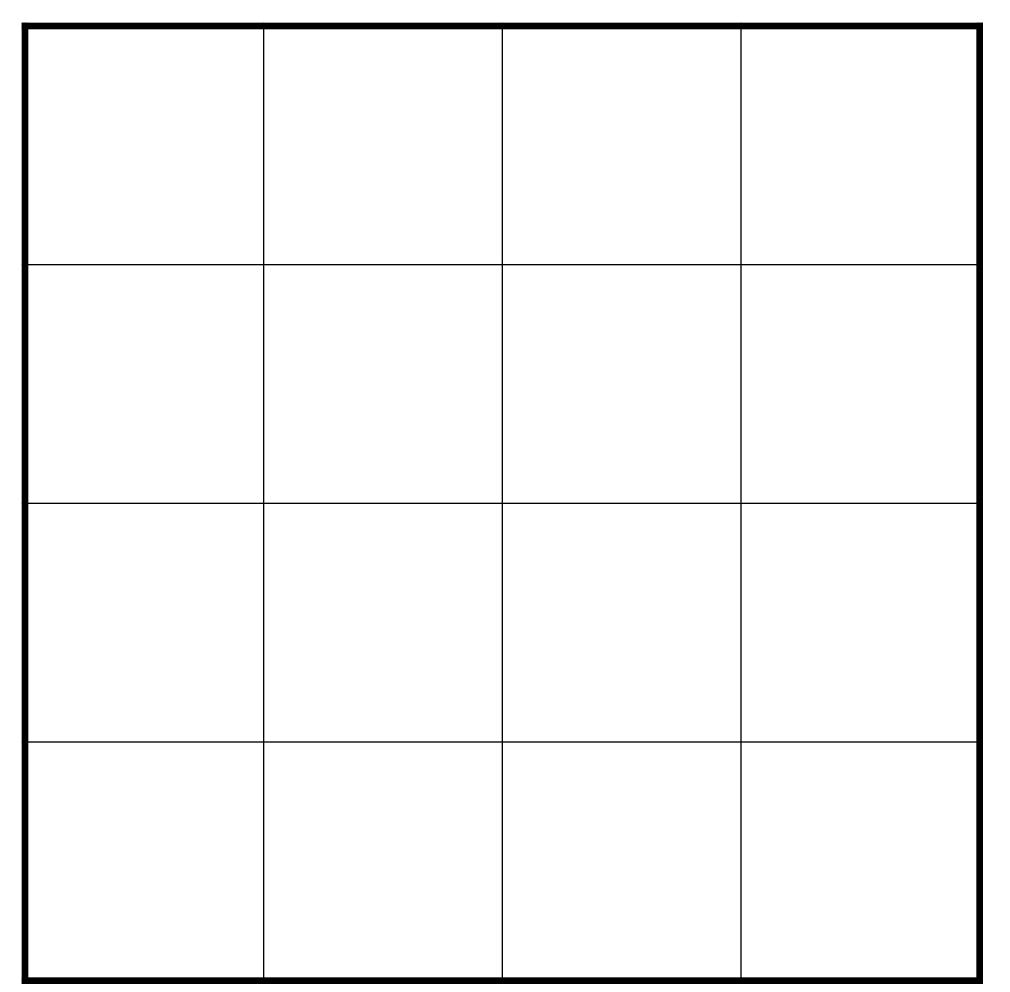




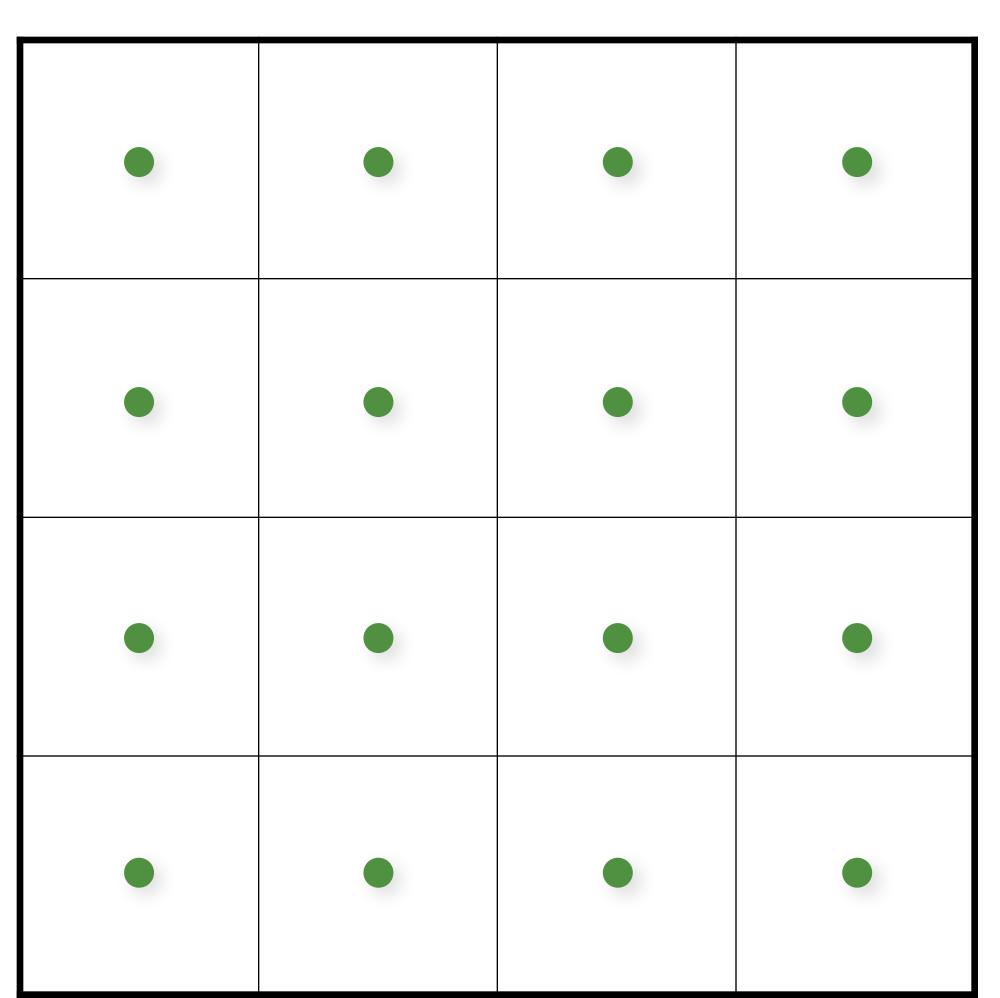
$$\frac{1}{N} \sum_{k=1}^{N} \delta(|\vec{x} - \vec{x}_k|) \quad \mathbf{E} \left[ \left| \frac{1}{N} \sum_{k=1}^{N} e^{-2\pi \imath (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$



```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```

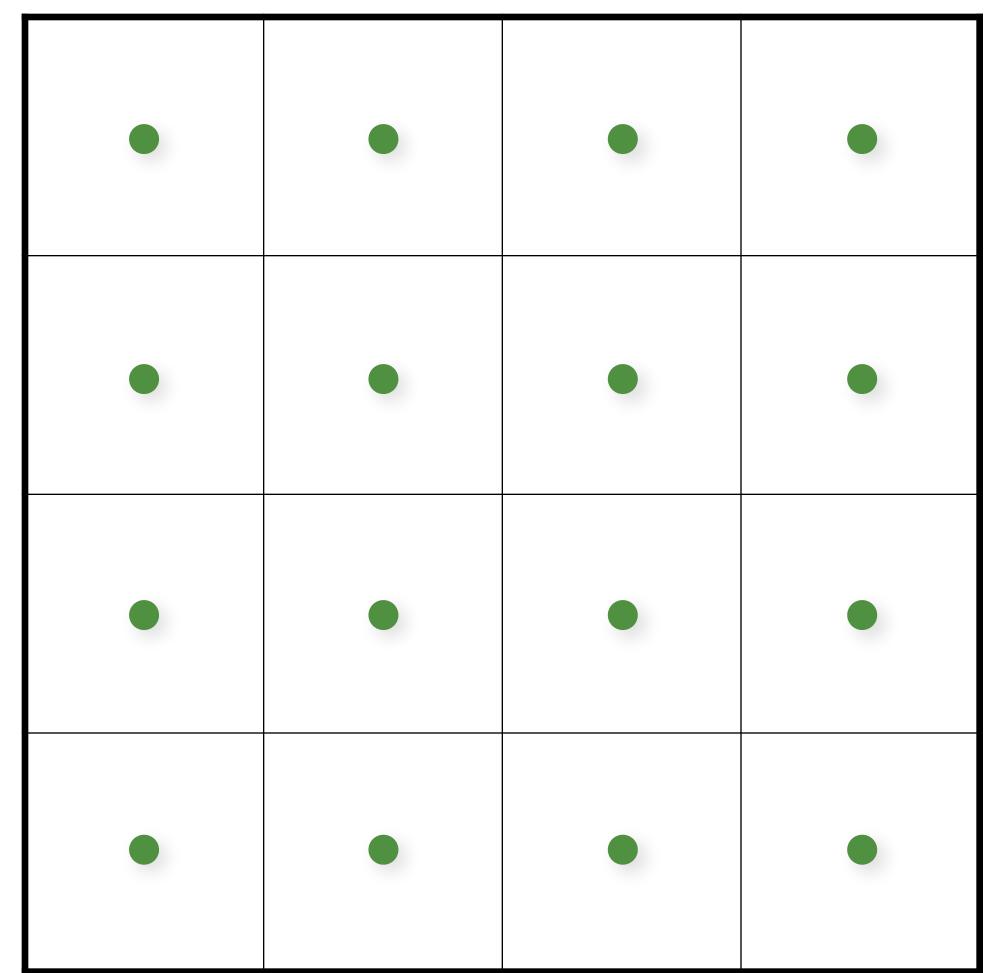


```
for (uint i = 0; i < numX; i++)
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    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```

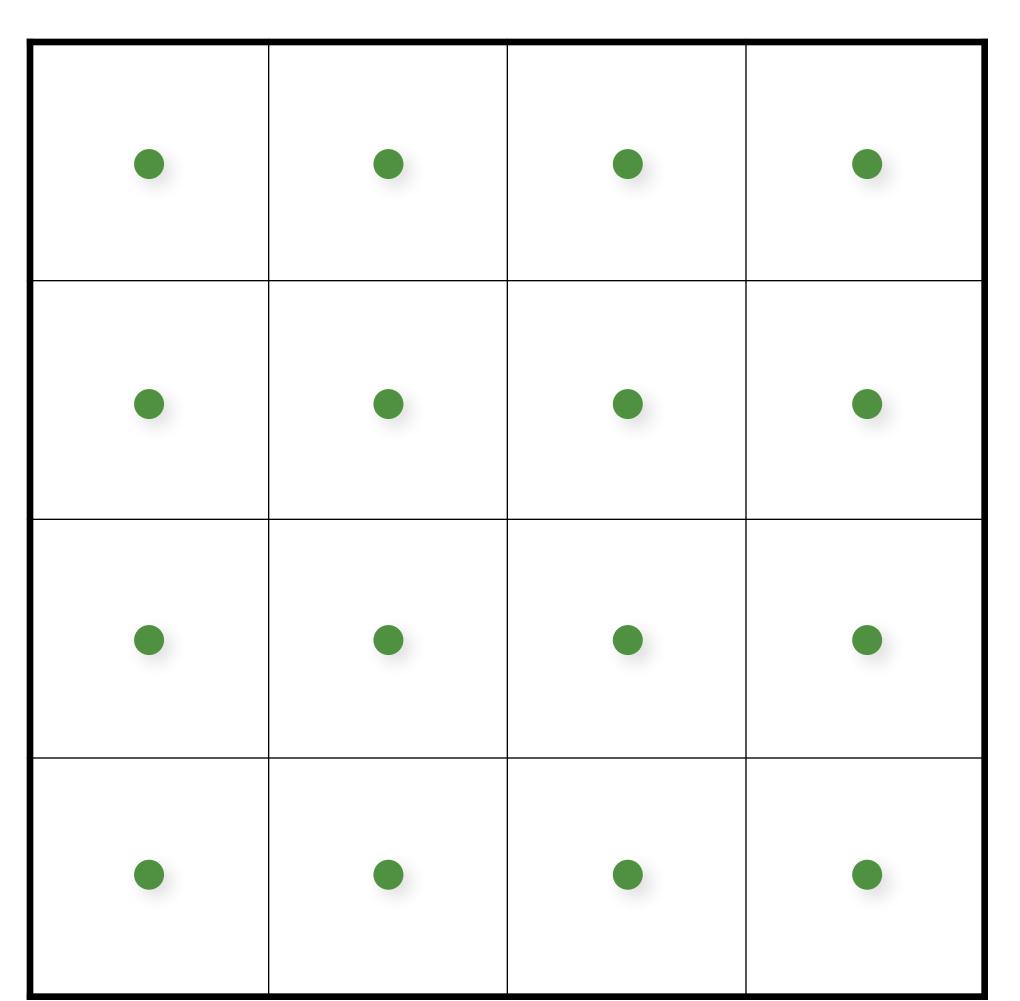


```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```

Extends to higher dimensions, but...

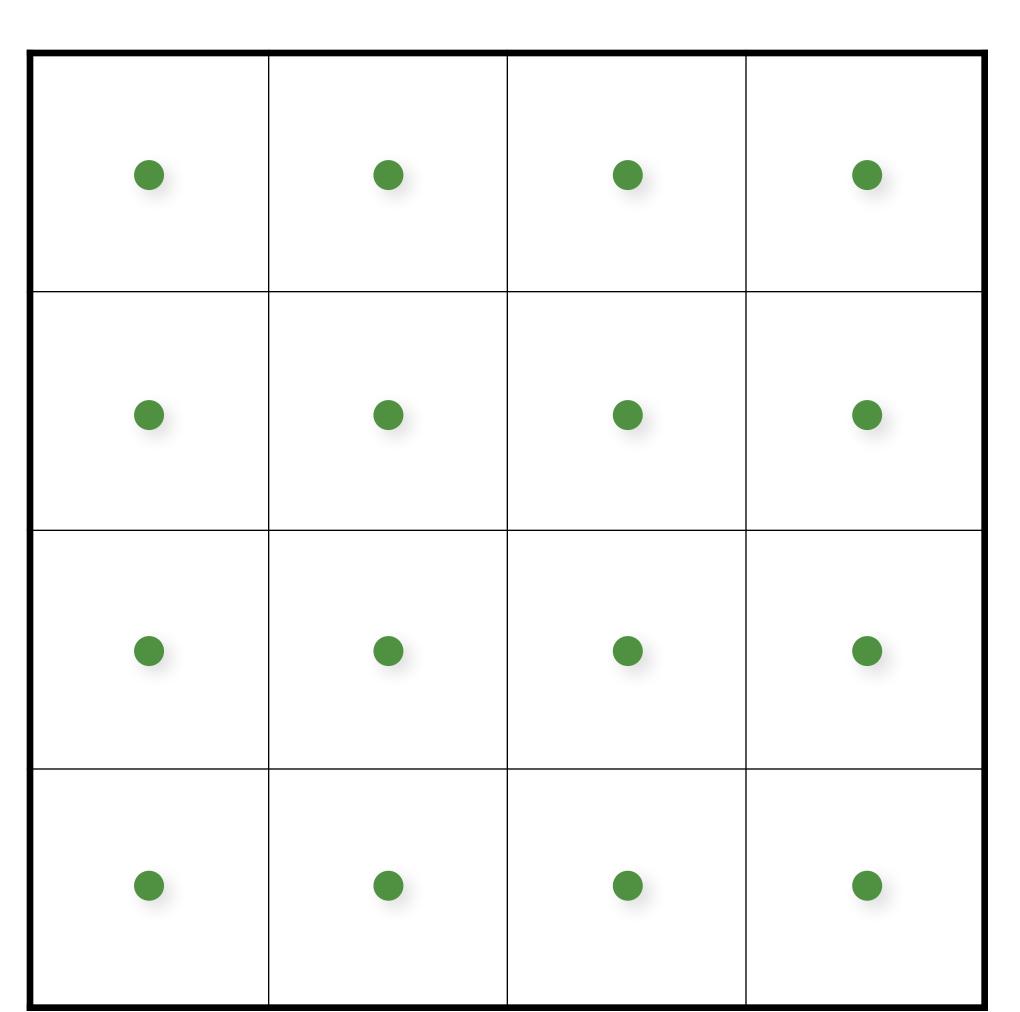


```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```



- Extends to higher dimensions, but...
- X Curse of dimensionality

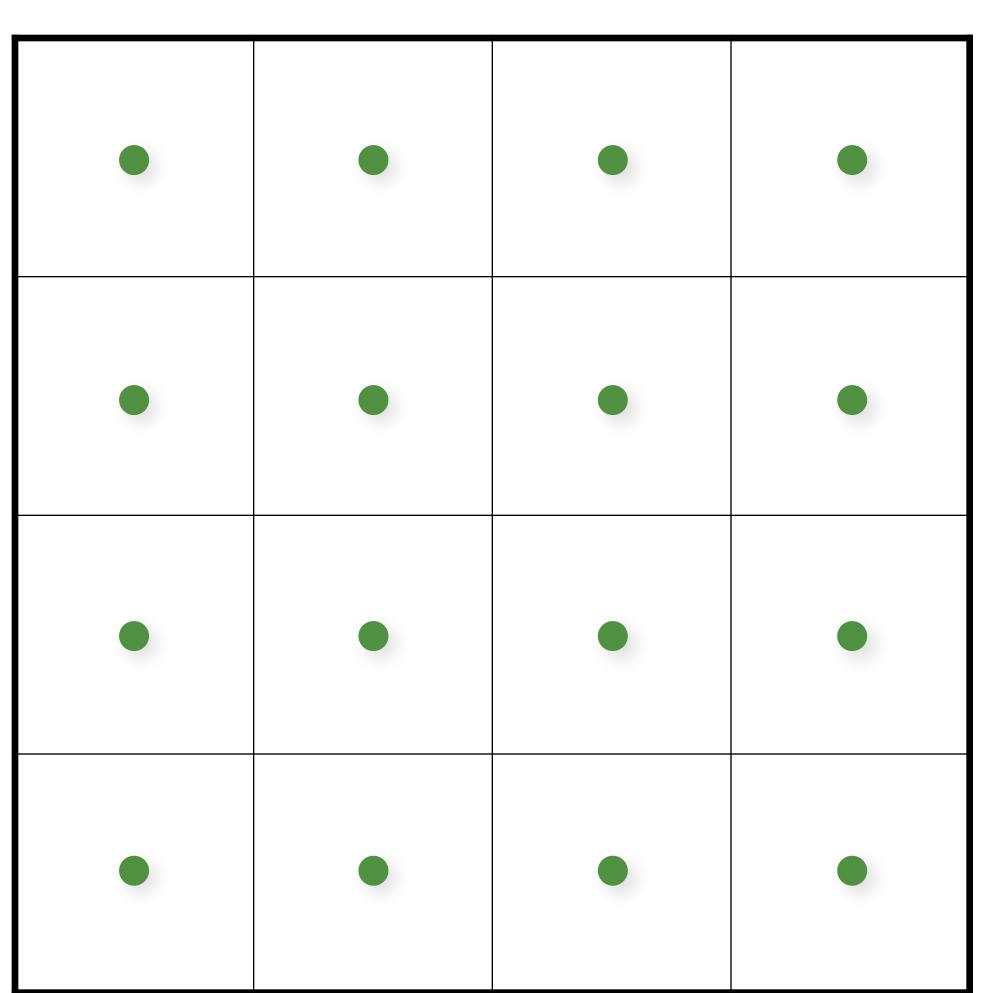
```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```



- Extends to higher dimensions, but...
- X Curse of dimensionality
- **X** Aliasing

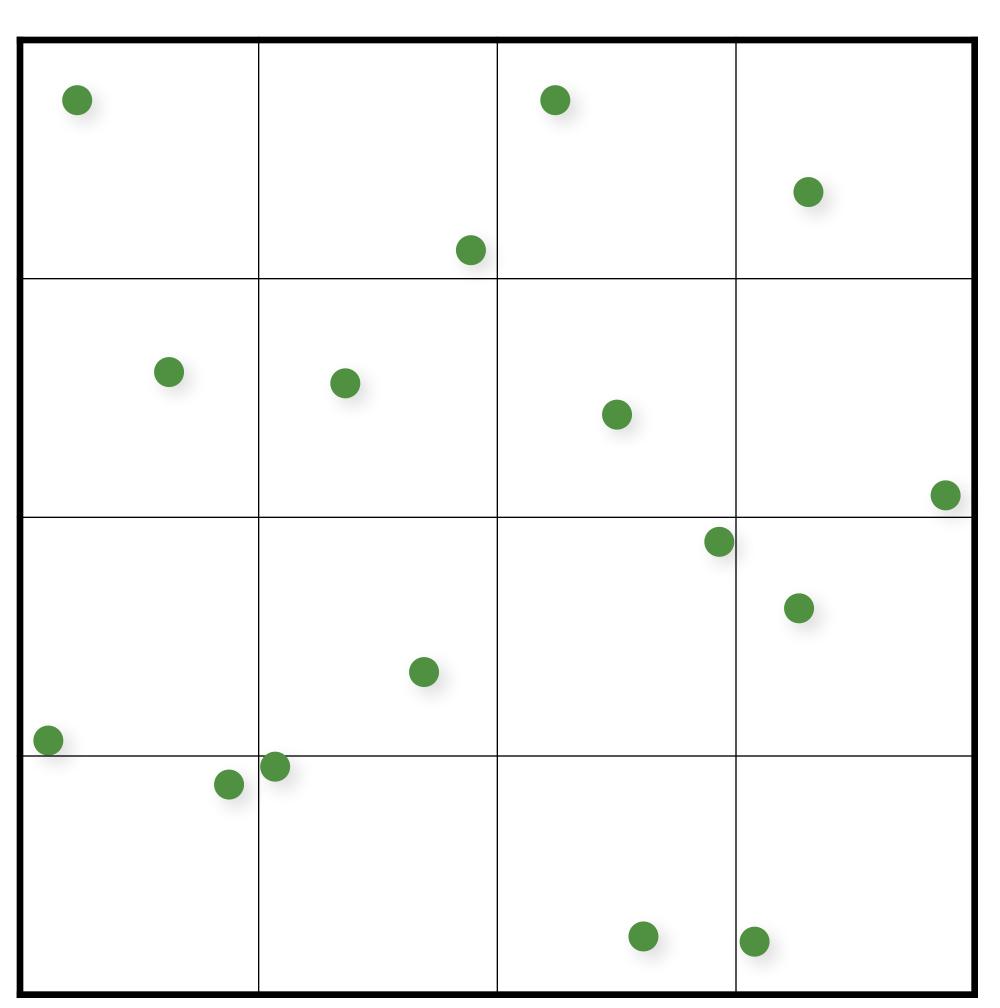


```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + 0.5)/numX;
        samples(i,j).y = (j + 0.5)/numY;
    }</pre>
```



#### Jittered/Stratified Sampling

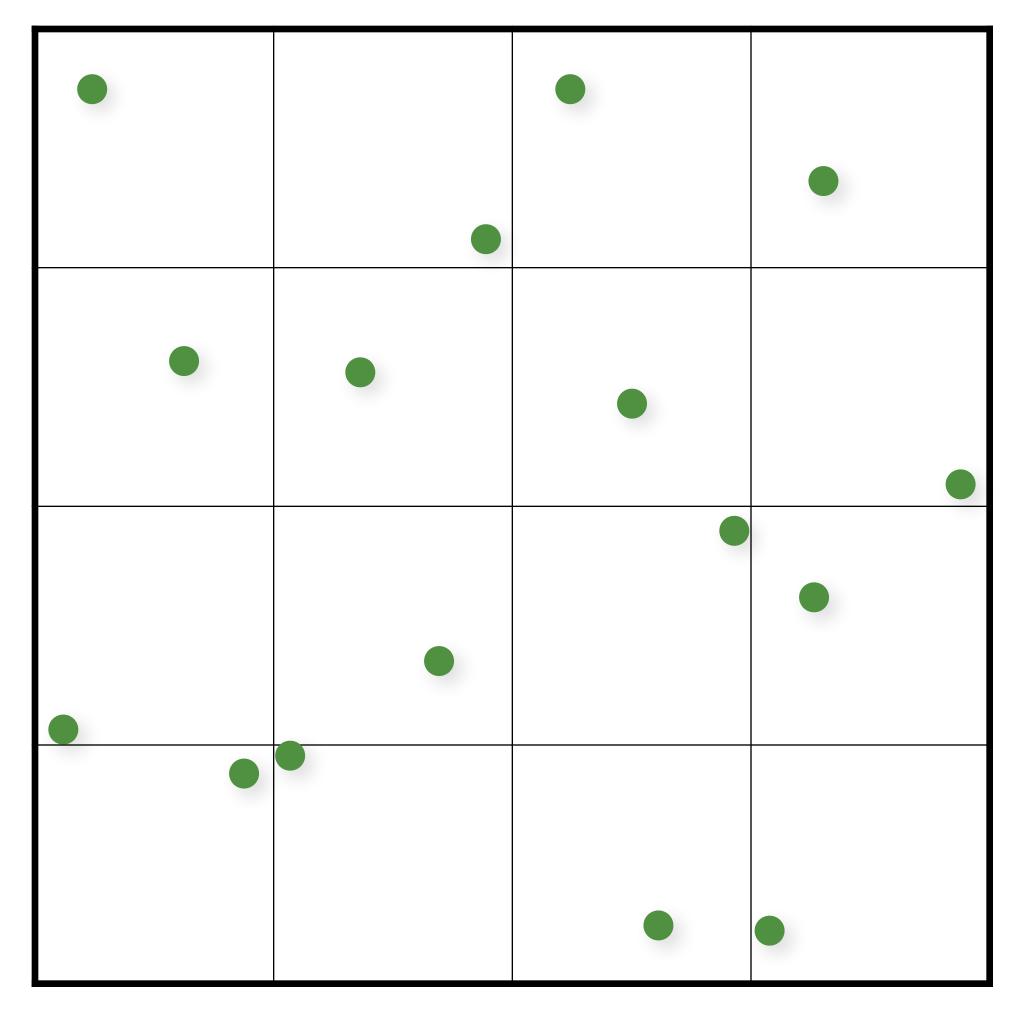
```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
}</pre>
```



#### Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
    }</pre>
```

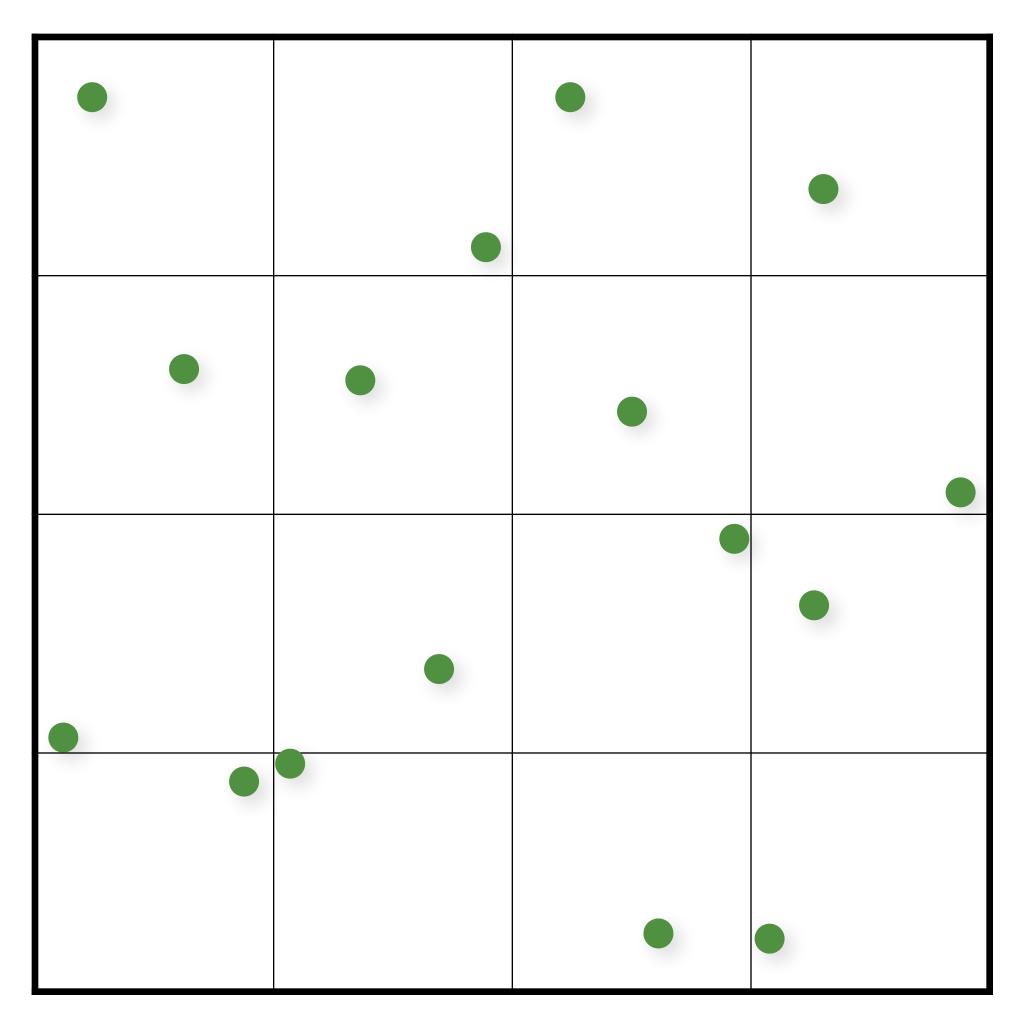
Provably cannot increase variance



#### Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
}</pre>
```

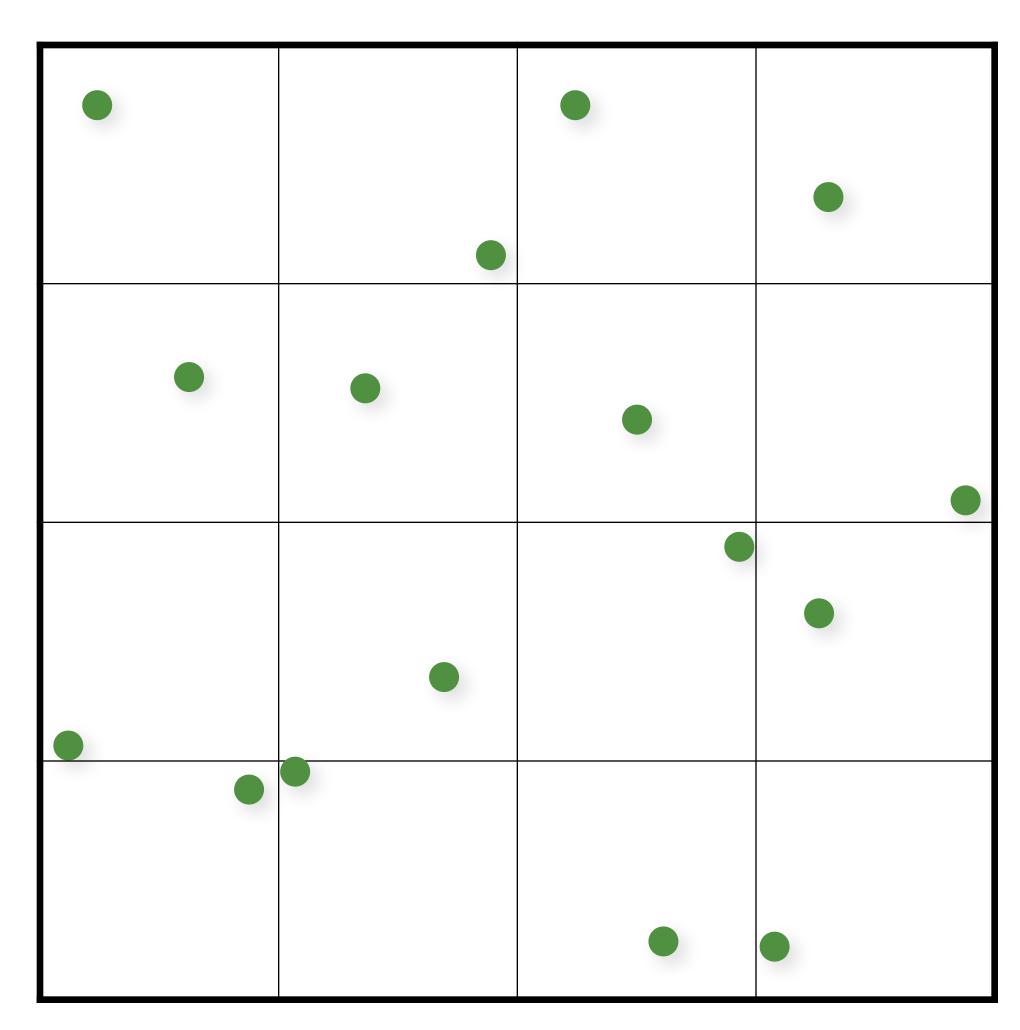
- Provably cannot increase variance
- Extends to higher dimensions, but...



### Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
}</pre>
```

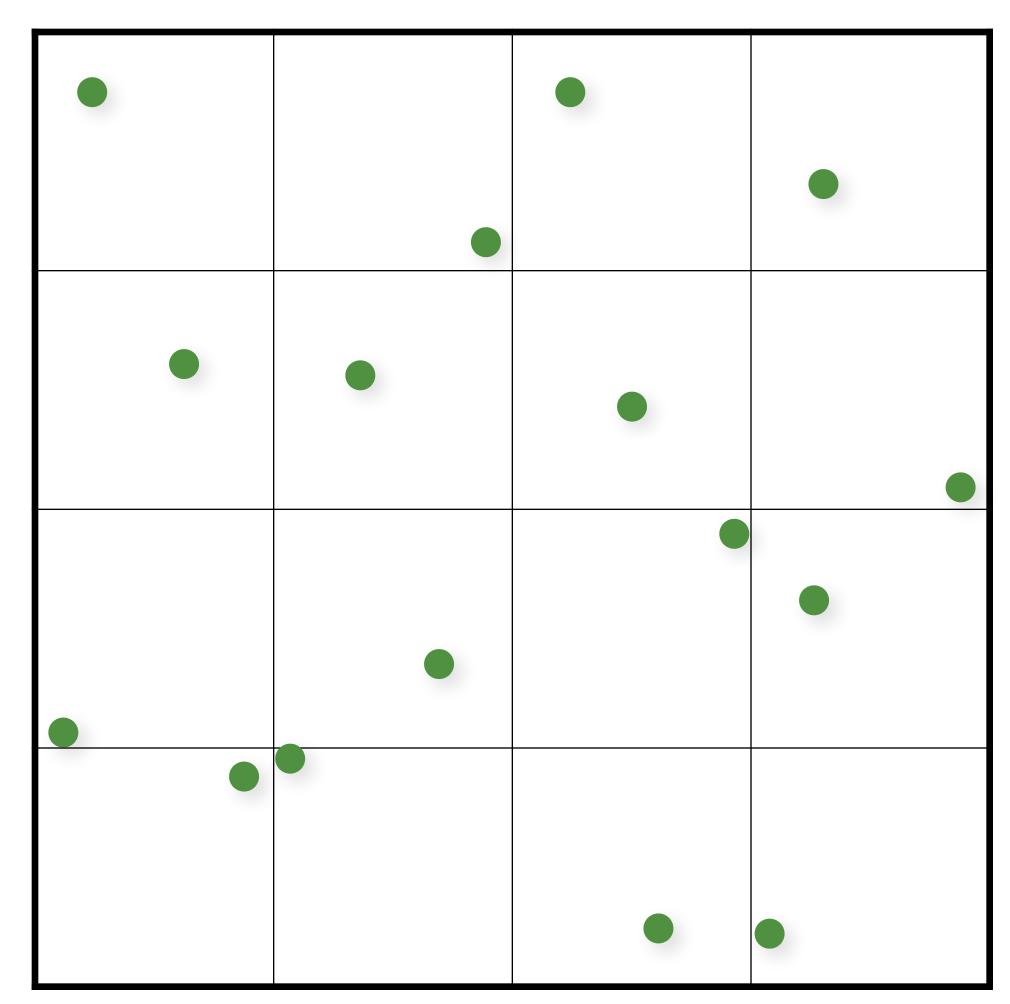
- Provably cannot increase variance
- Extends to higher dimensions, but...
- X Curse of dimensionality



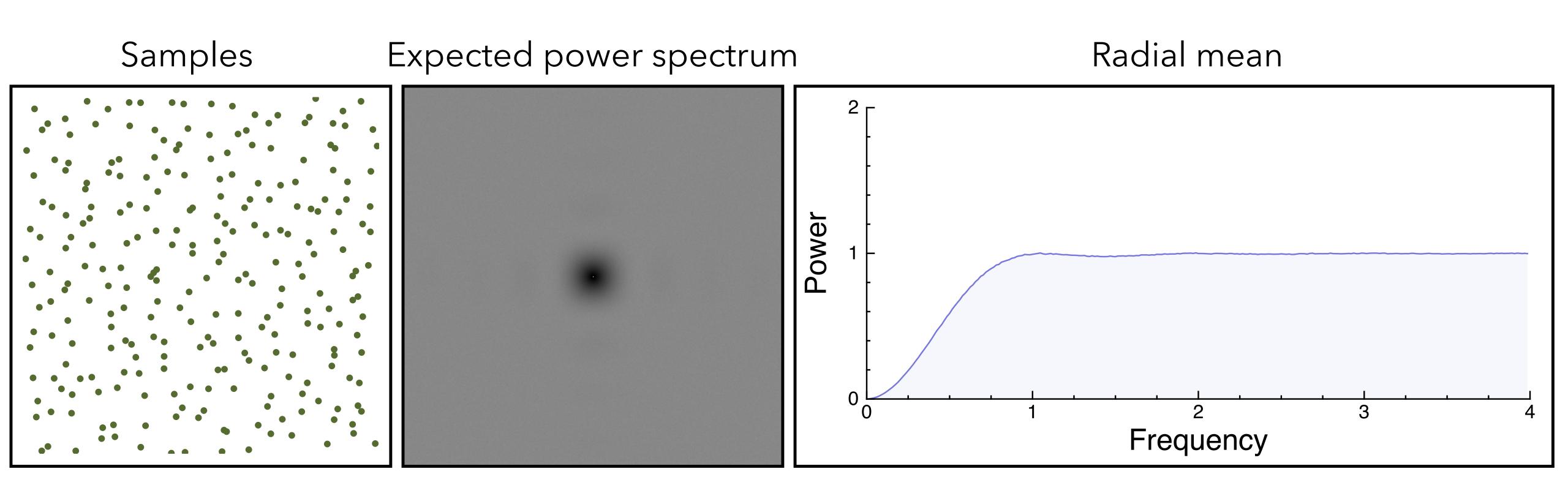
### Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
}</pre>
```

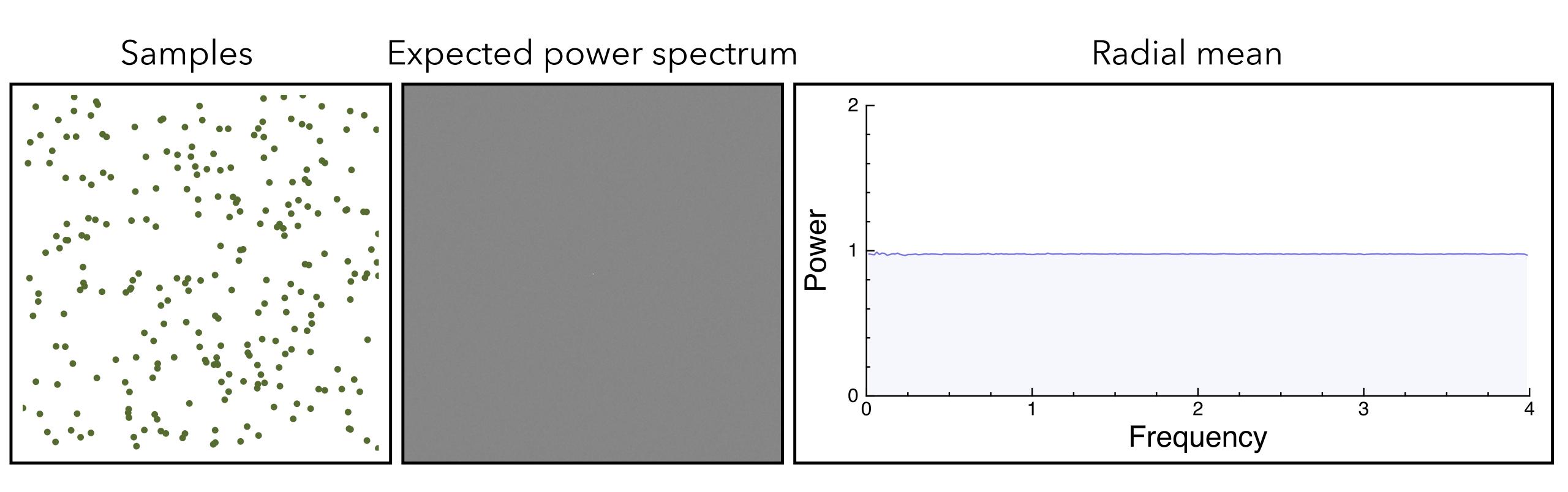
- Provably cannot increase variance
- Extends to higher dimensions, but...
- X Curse of dimensionality
- X Not progressive



# Jittered Sampling

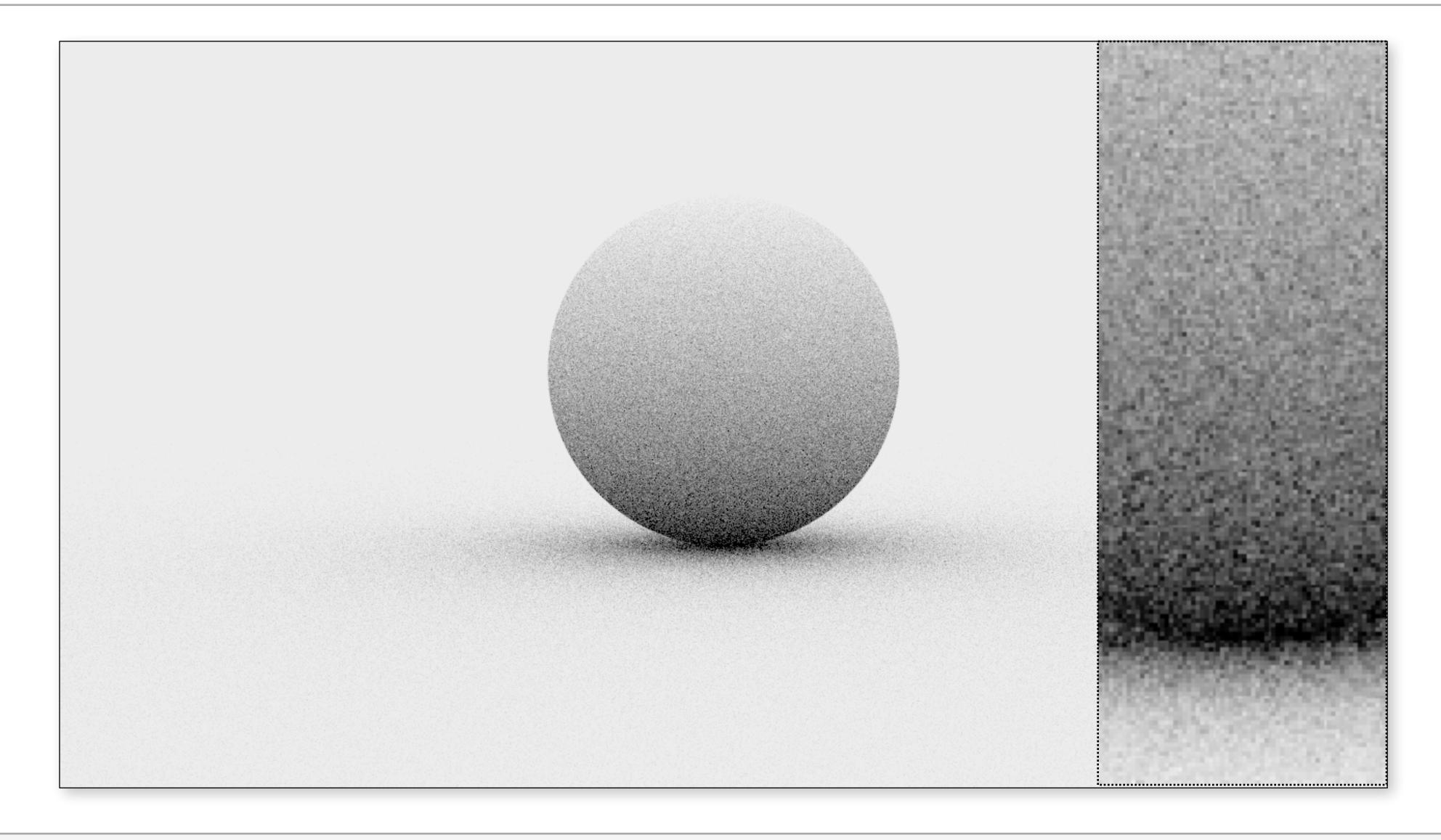


# Independent Random Sampling



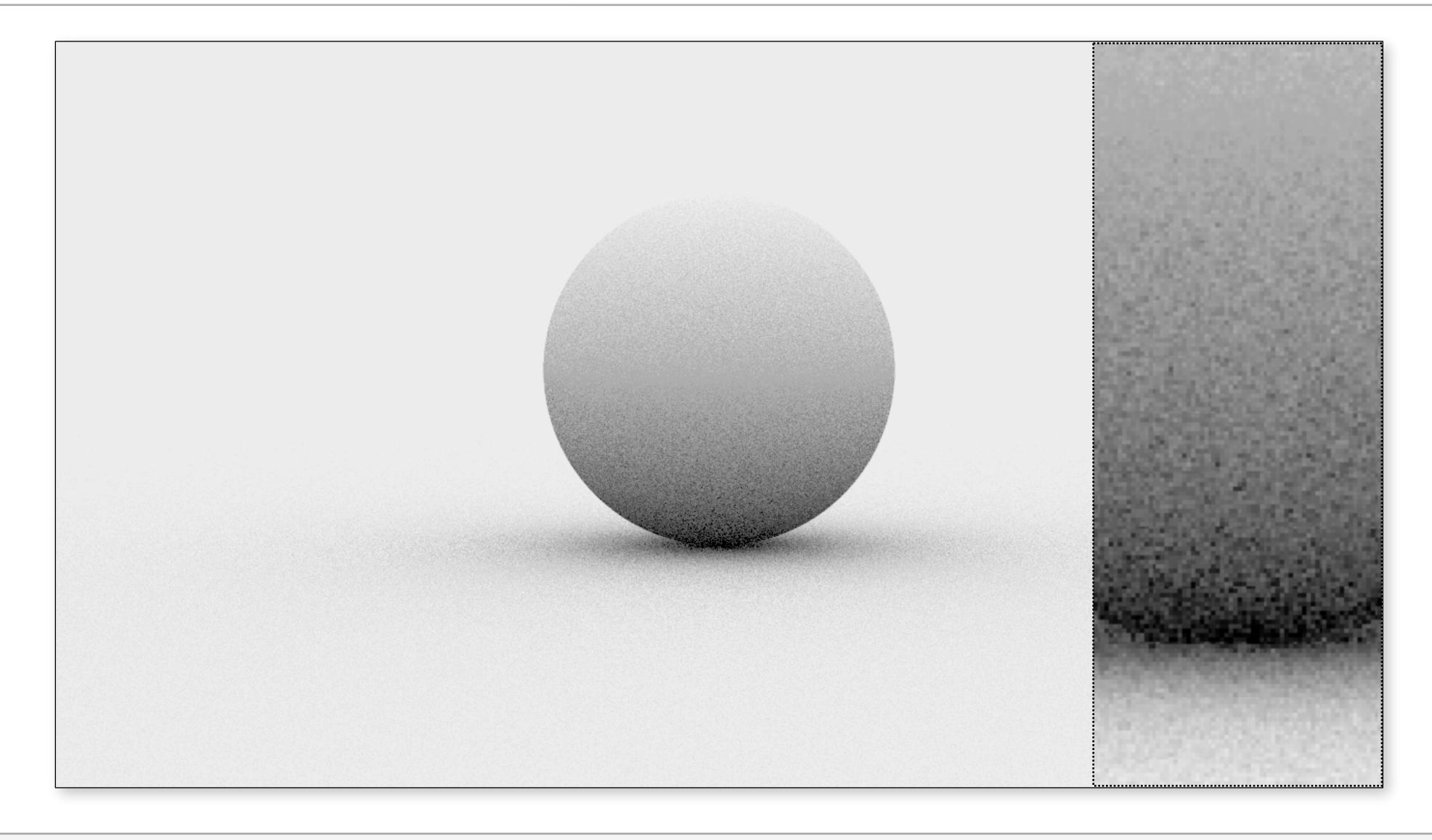


### Monte Carlo (16 random samples)





## Monte Carlo (16 jittered samples)





### Stratifying in Higher Dimensions

#### Stratification requires $O(N^d)$ samples

- e.g. pixel (2D) + lens (2D) + time (1D) = 5D

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- e.g. pixel (2D) + lens (2D) + time (1D) = 5D
  - splitting 2 times in  $5D = 2^5 = 32$  samples
  - splitting 3 times in  $5D = 3^5 = 243$  samples!



### Stratifying in Higher Dimensions

#### Stratification requires $O(N^d)$ samples

- e.g. pixel (2D) + lens (2D) + time (1D) = 5D
  - splitting 2 times in  $5D = 2^5 = 32$  samples
  - splitting 3 times in  $5D = 3^5 = 243$  samples!

#### Inconvenient for large d

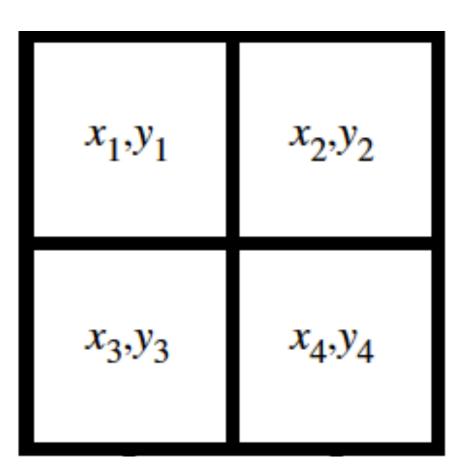
- cannot select sample count with fine granularity



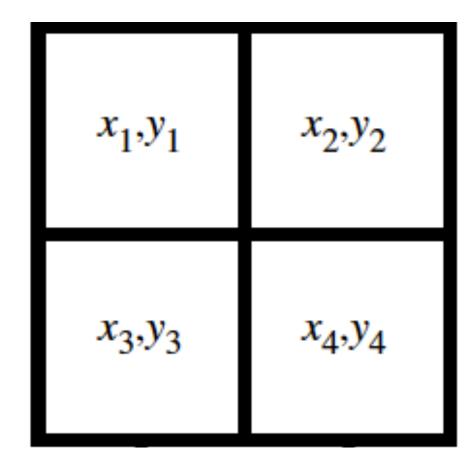


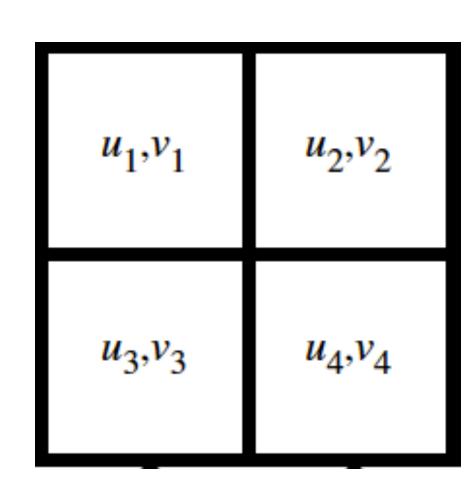
#### Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel

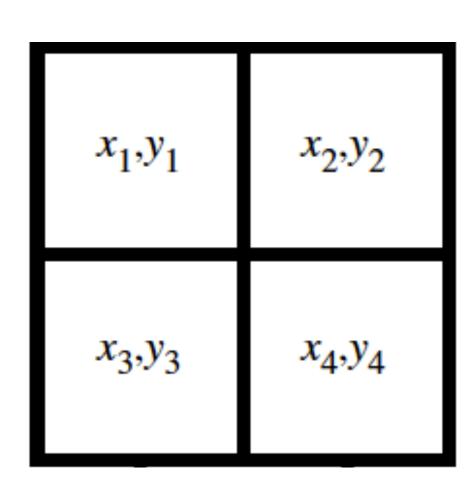


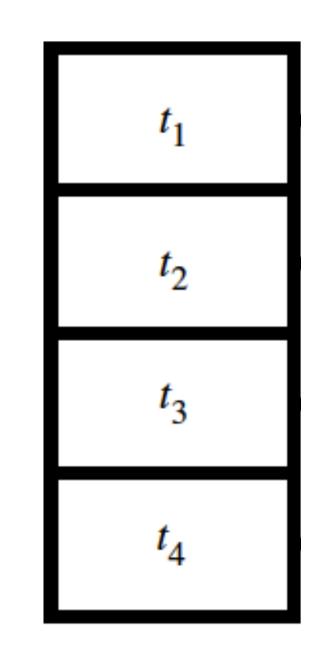
- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens  $x_1,y_1$

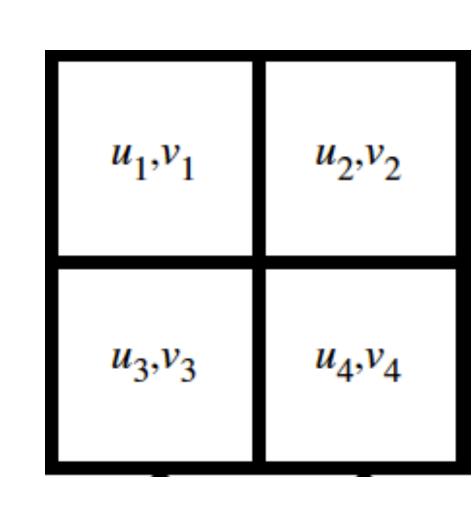




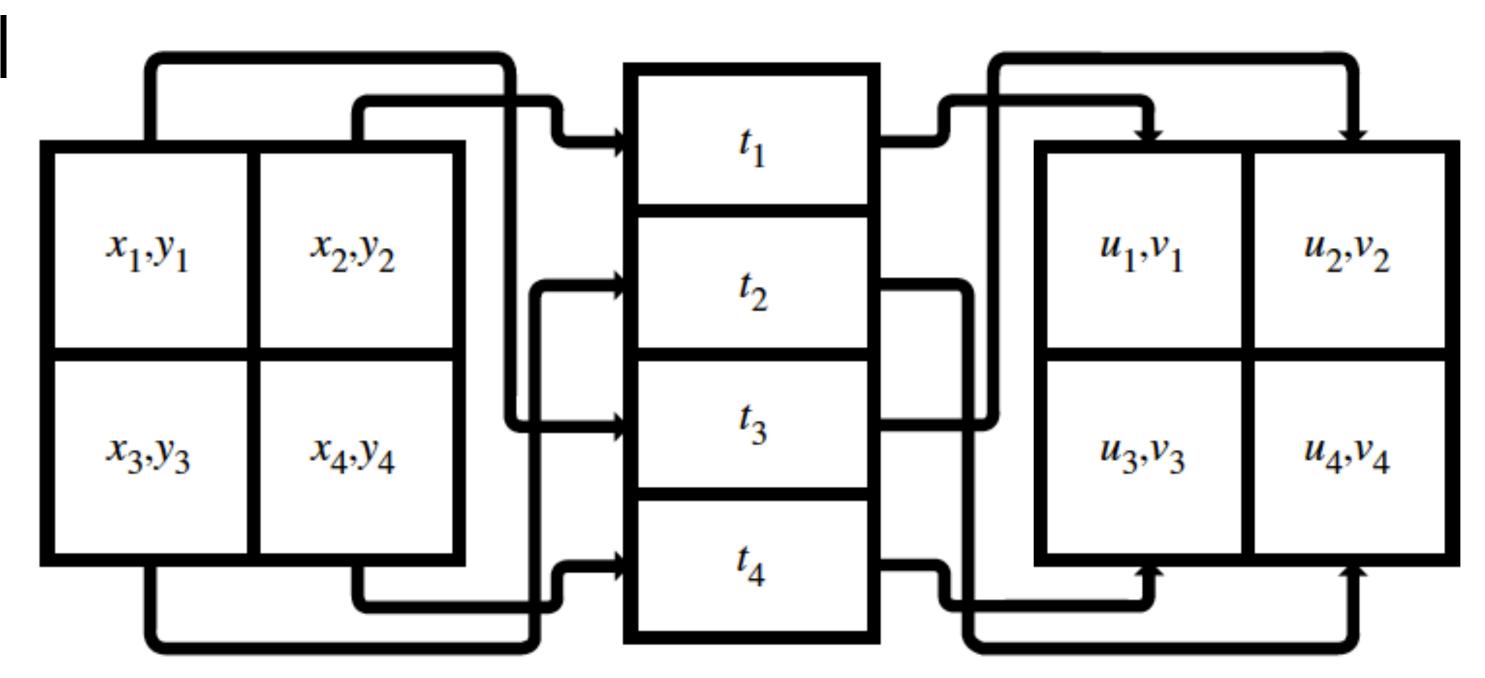
- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
- 1D jittered (t) for time







- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
- 1D jittered (t) for time
- combine dimensions in random order



# Depth of Field (4D)

Reference Uncorrelated Jitter Random Sampling

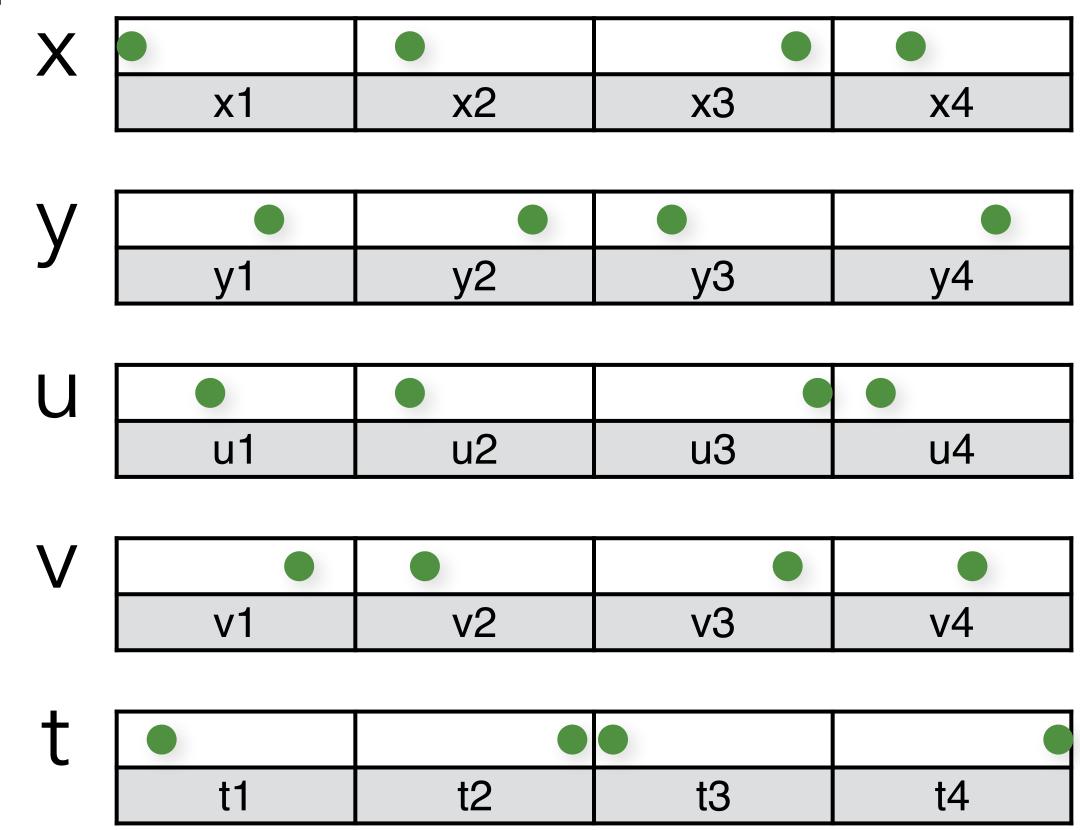
### Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

### Uncorrelated Jitter -> Latin Hypercube

#### Stratify samples in each dimension separately

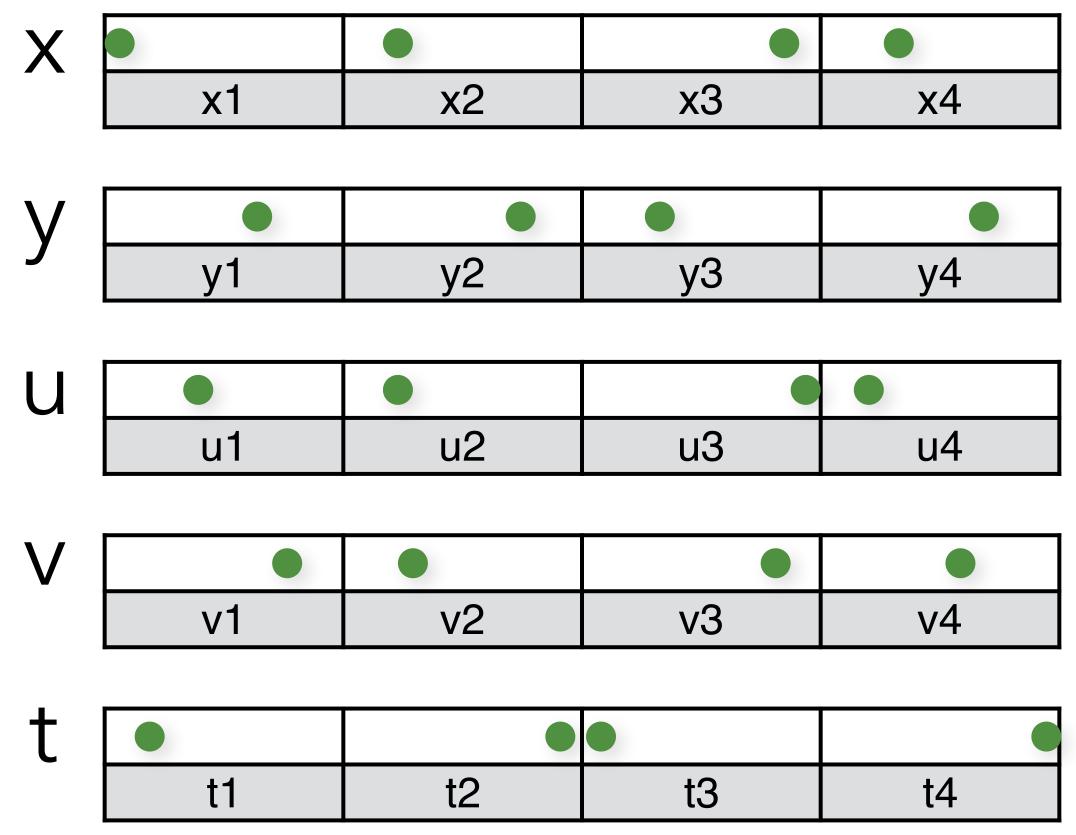
- for 5D: 5 separate 1D jittered point sets



### Uncorrelated Jitter -> Latin Hypercube

#### Stratify samples in each dimension separately

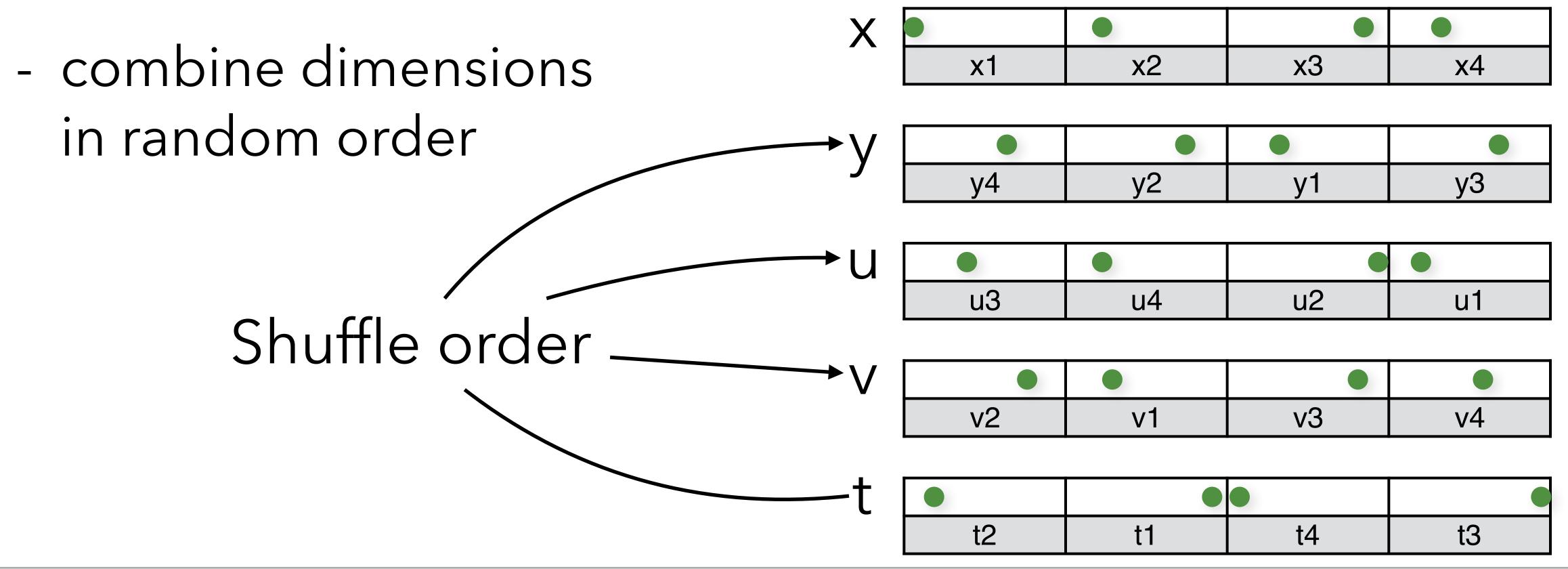
- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order



### Uncorrelated Jitter → Latin Hypercube

#### Stratify samples in each dimension separately

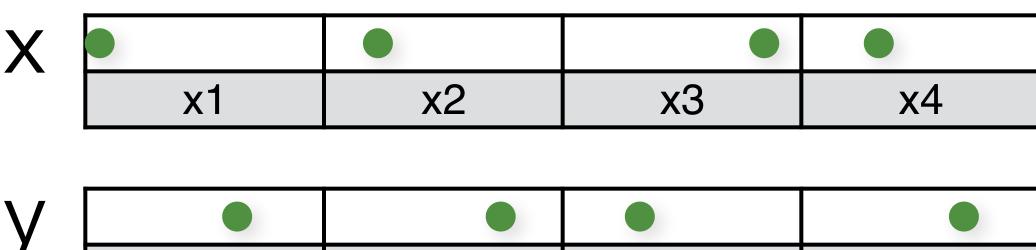
- for 5D: 5 separate 1D jittered point sets



### N-Rooks = 2D Latin Hypercube [Shirley 91]

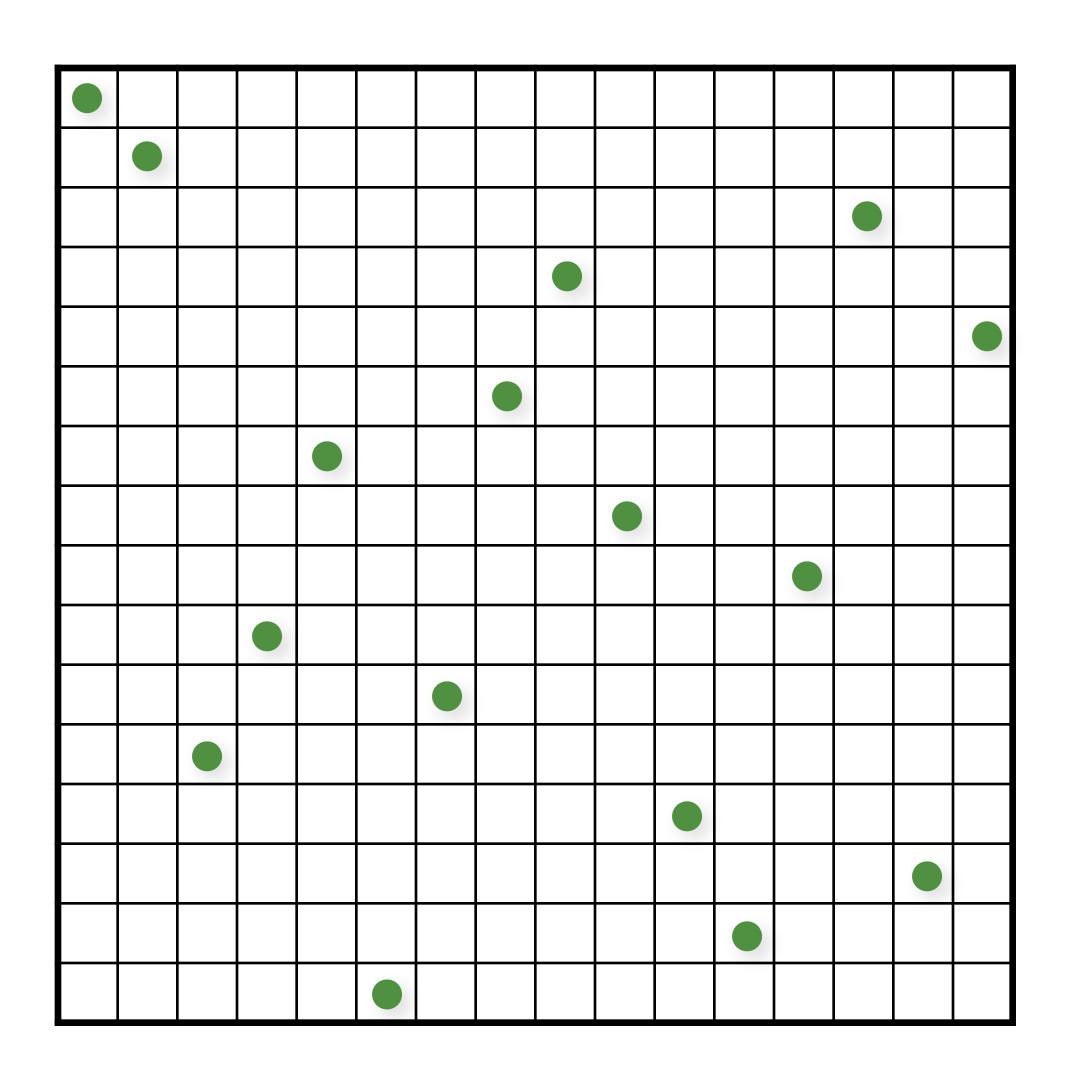
#### Stratify samples in each dimension separately

- for 2D: 2 separate 1D jittered point sets
- combine dimensions in random order





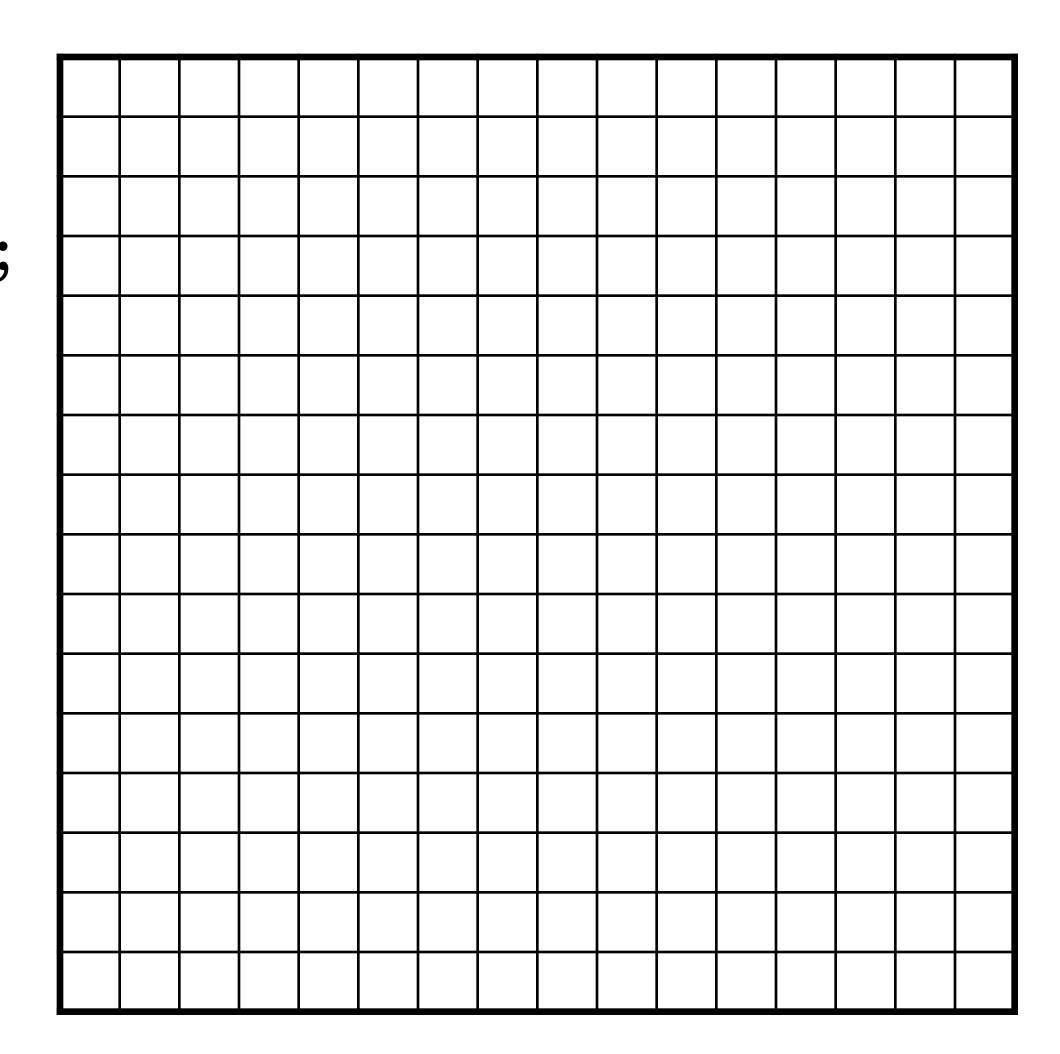
[Shirley 91]





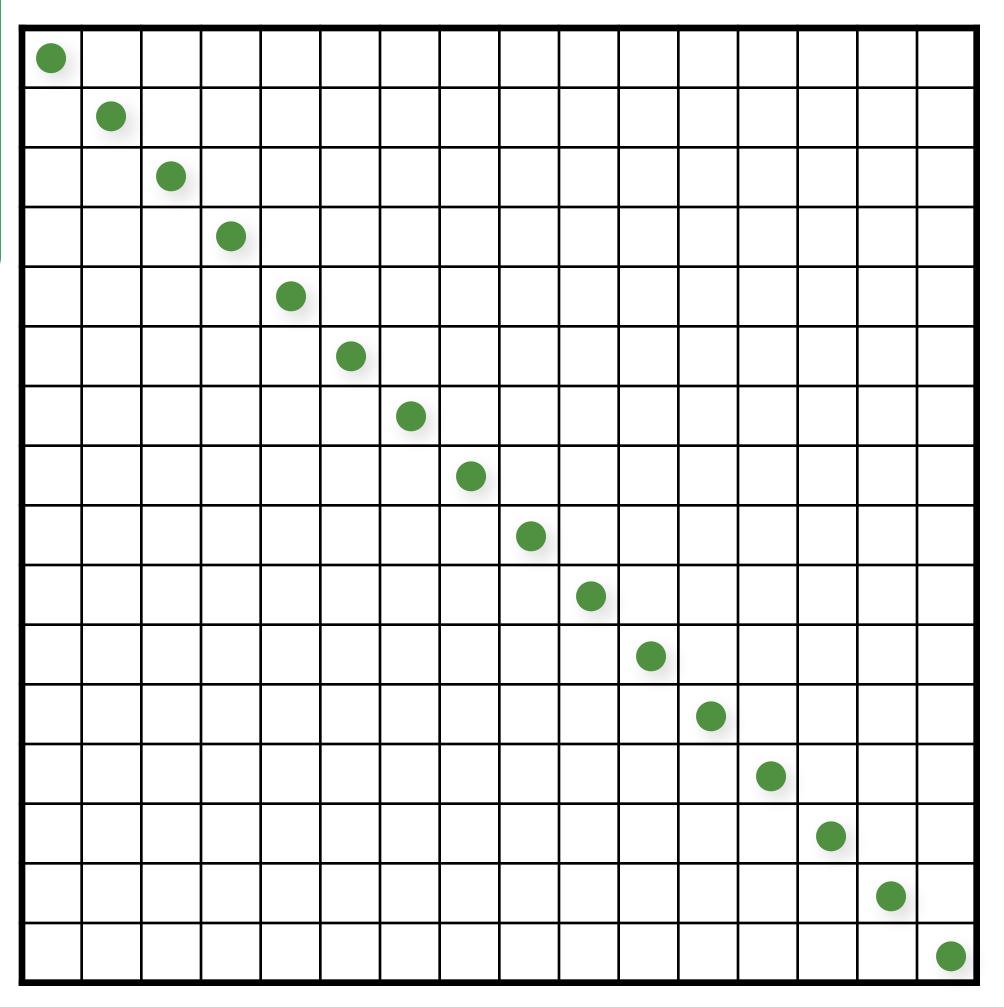
```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
// shuffle each dimension independently</pre>
```

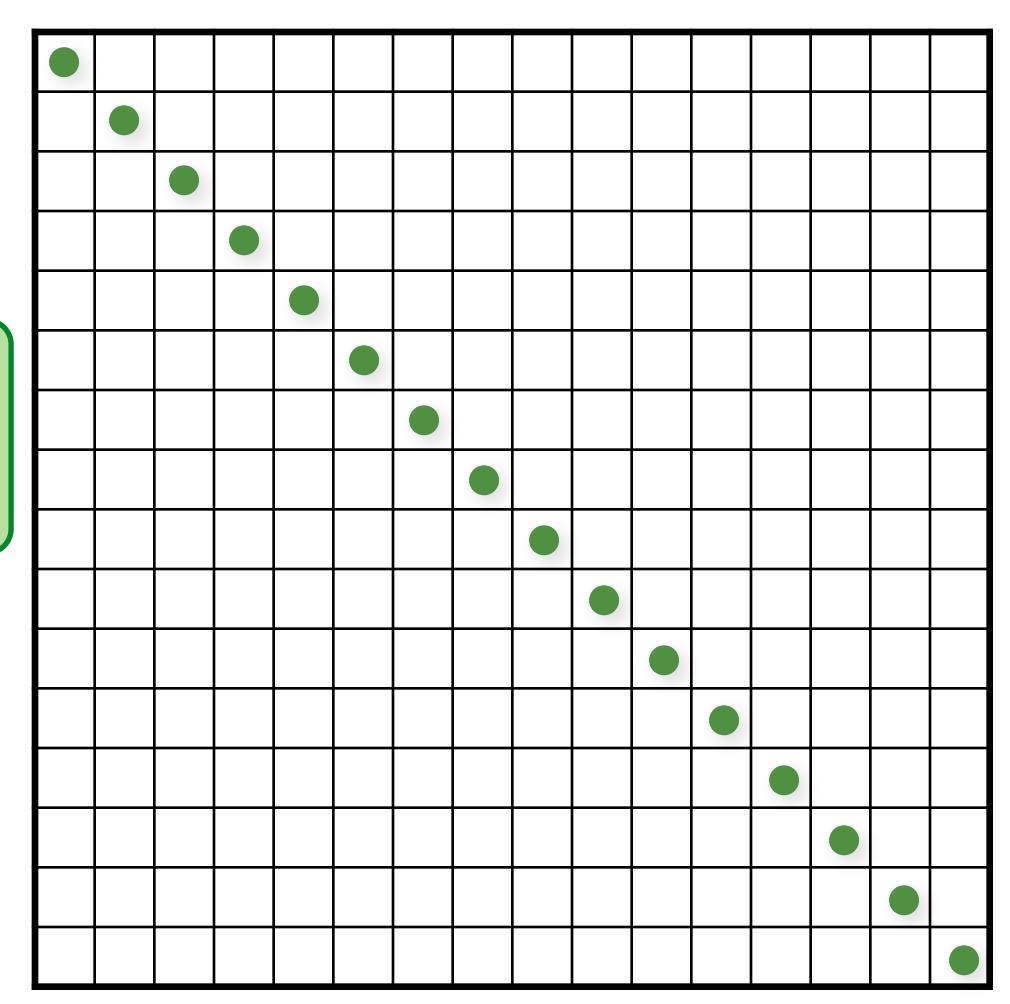
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
 shuffle(samples(d,:));</pre>



Initialize

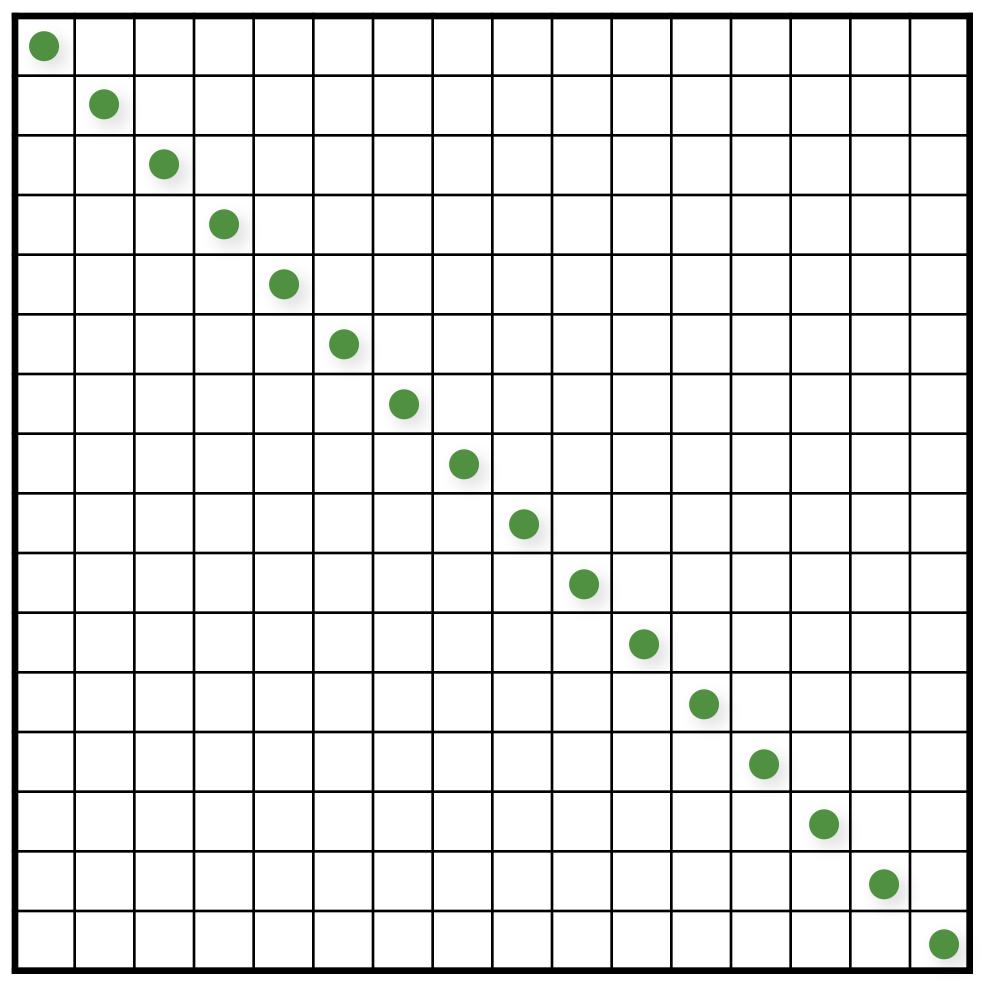
```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
   for (uint i = 0; i < numS; i++)
     samples(d,i) = (i + randf())/numS;</pre>
```

```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

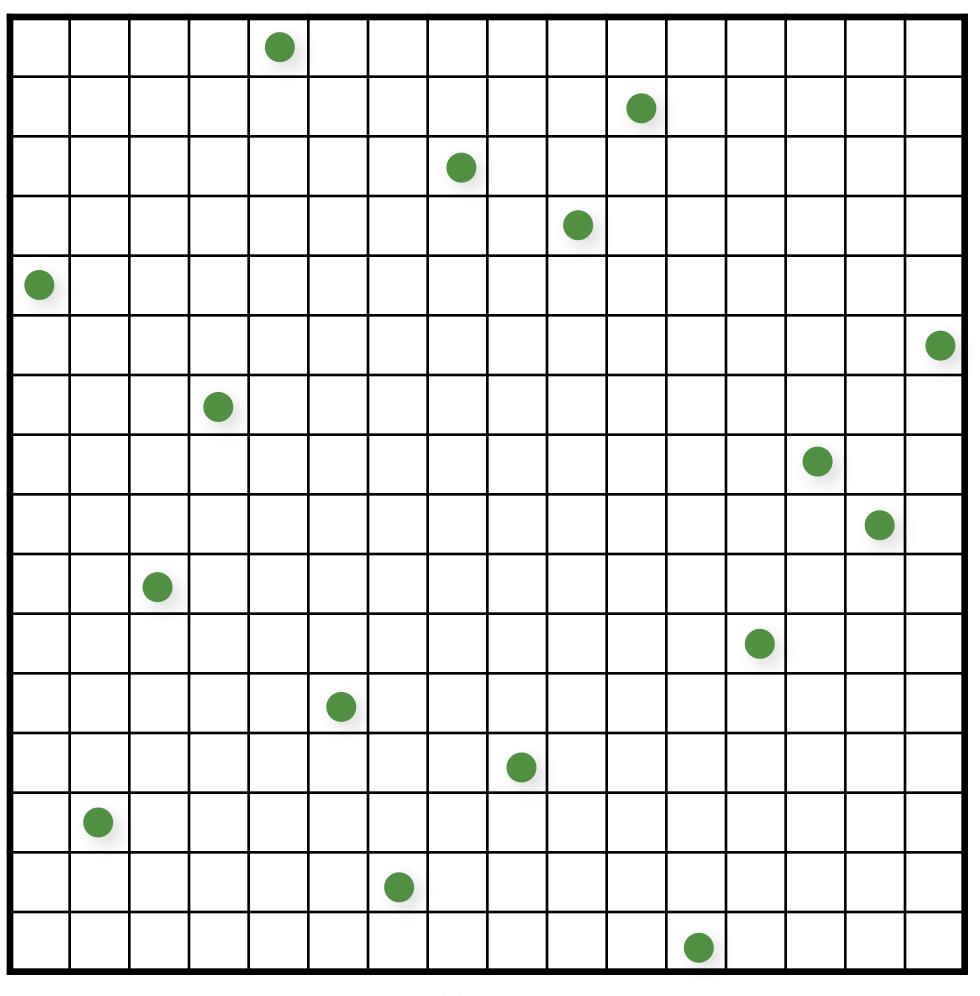
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



Shuffle rows

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

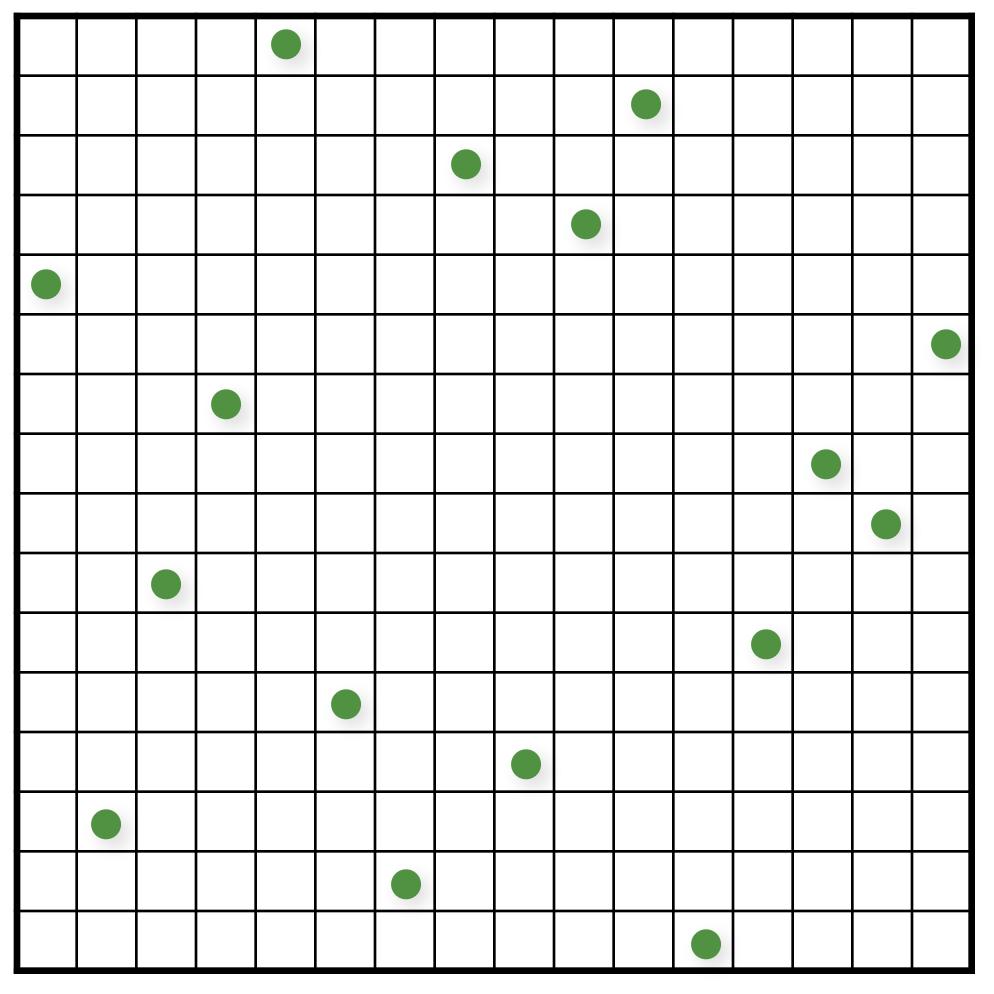
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



Shuffle rows

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

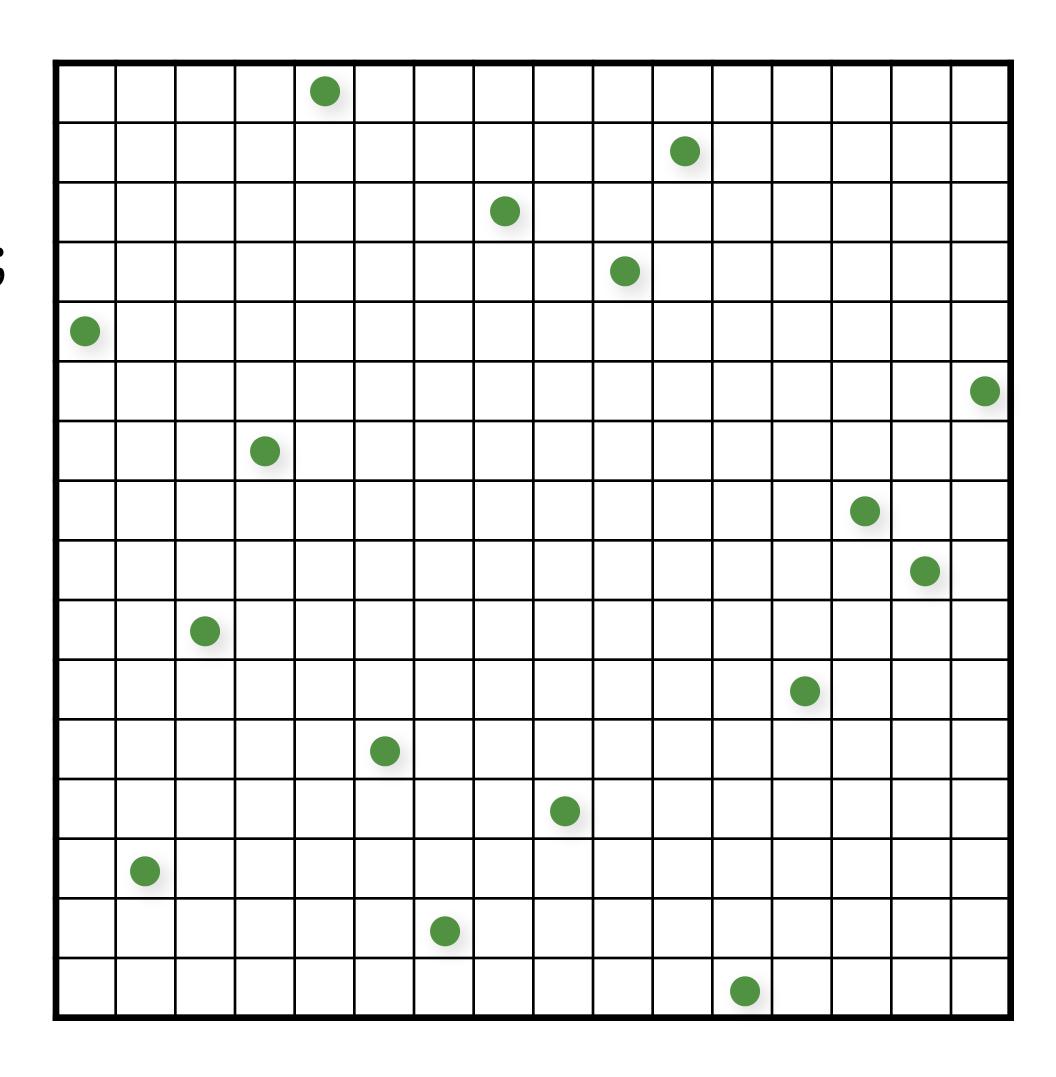
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



Shuffle rows

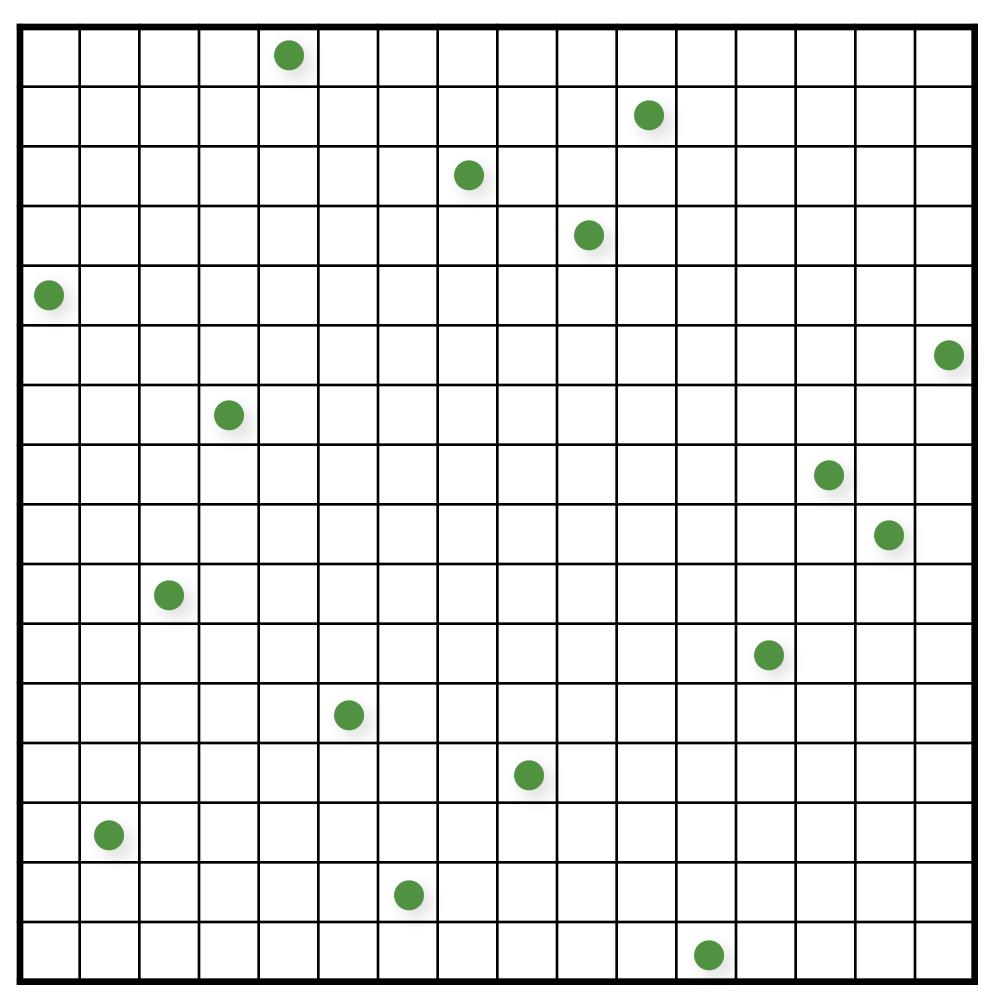
```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```

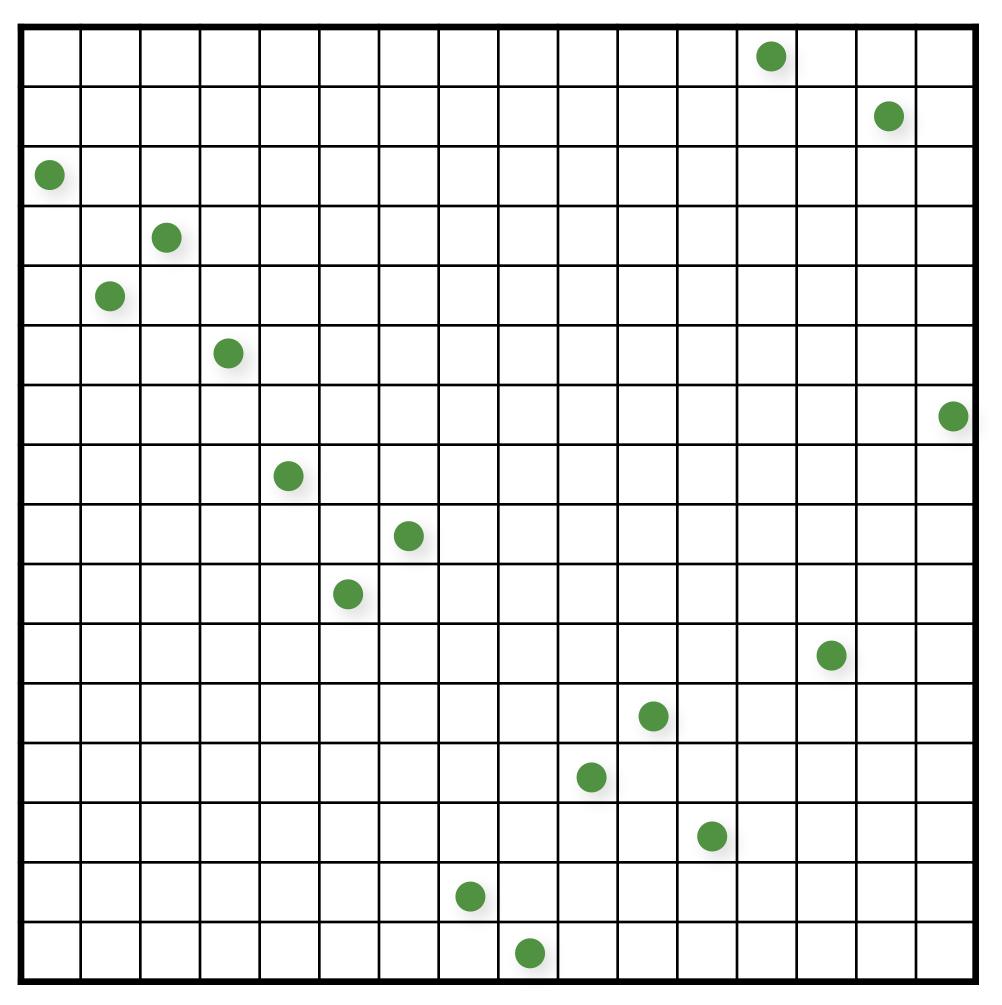


Shuffle columns



```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

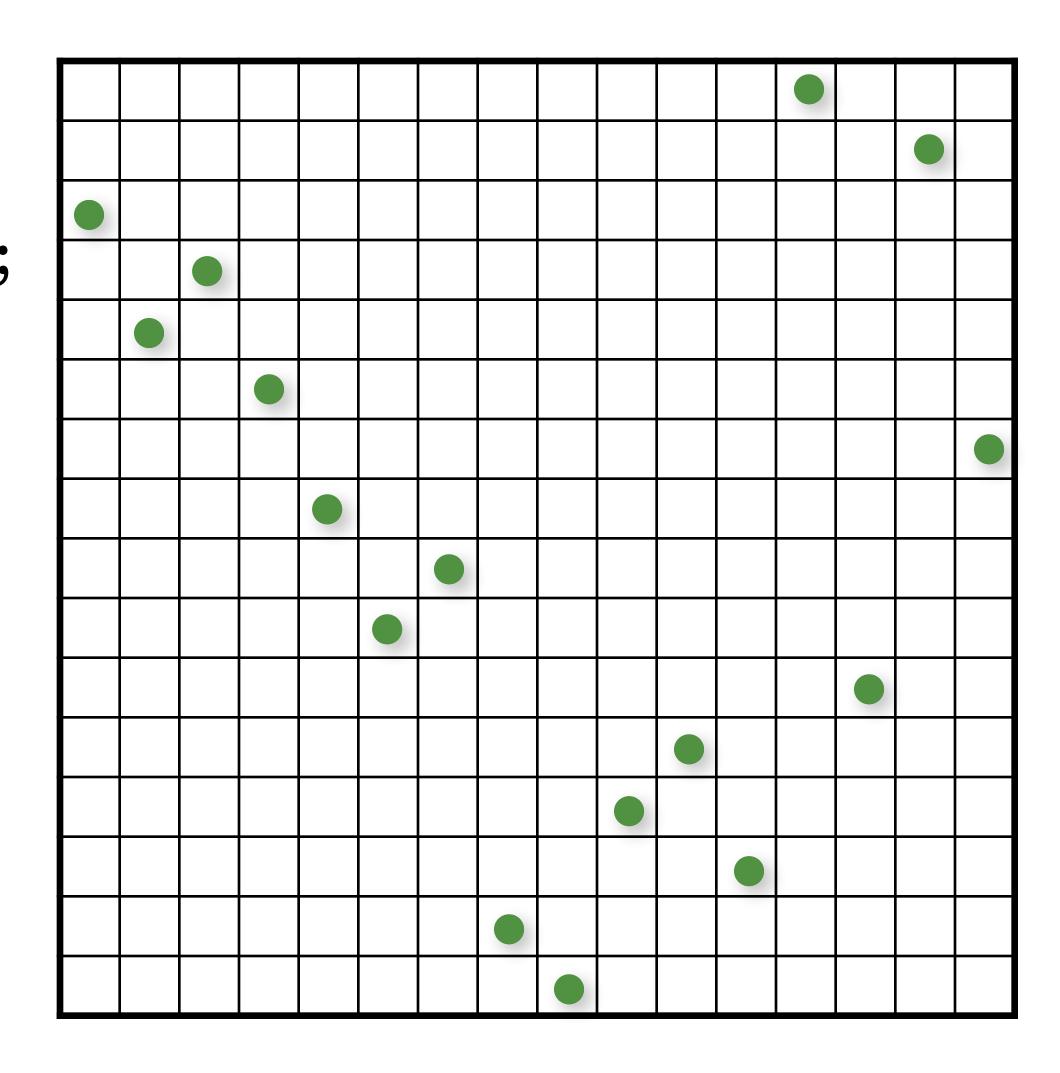
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```

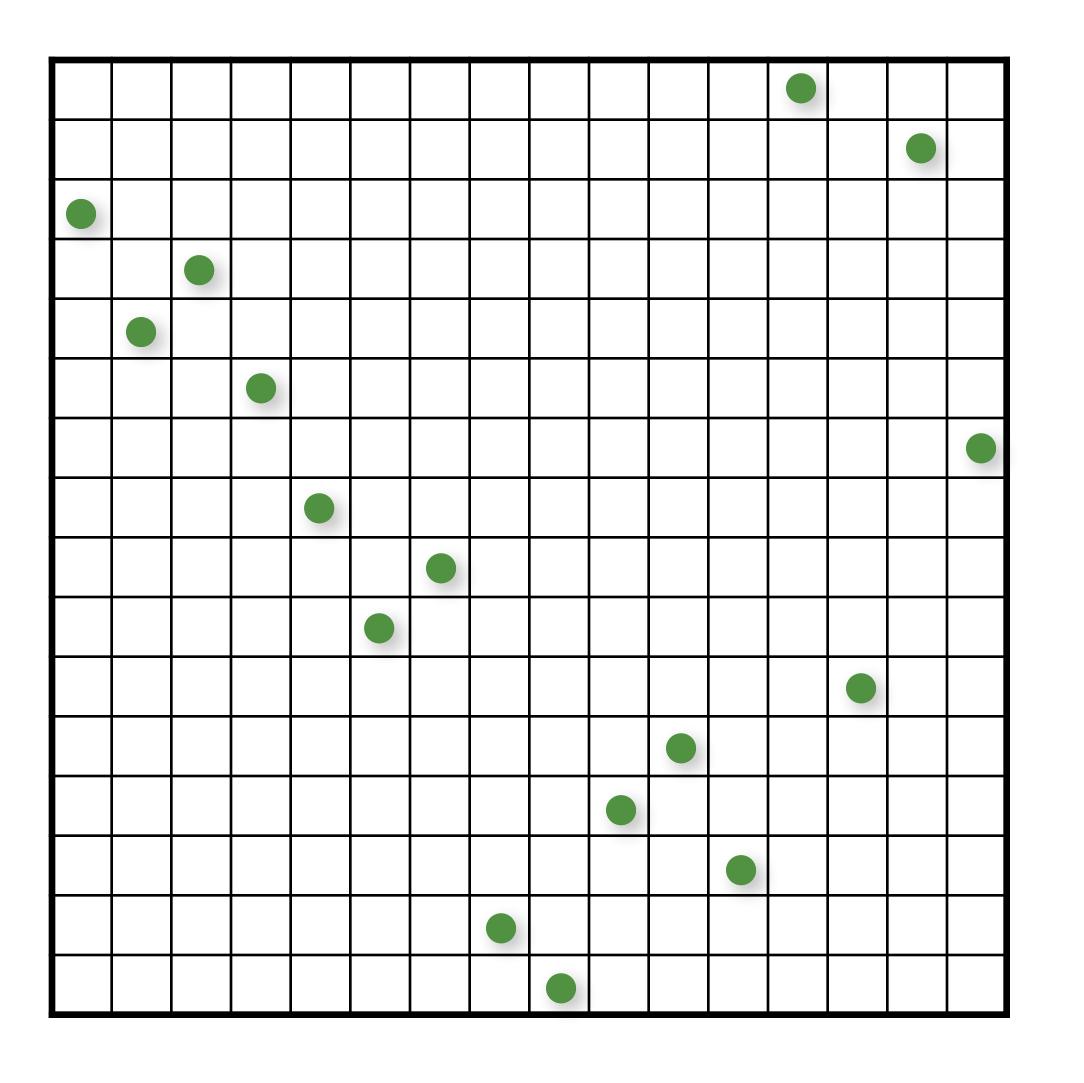


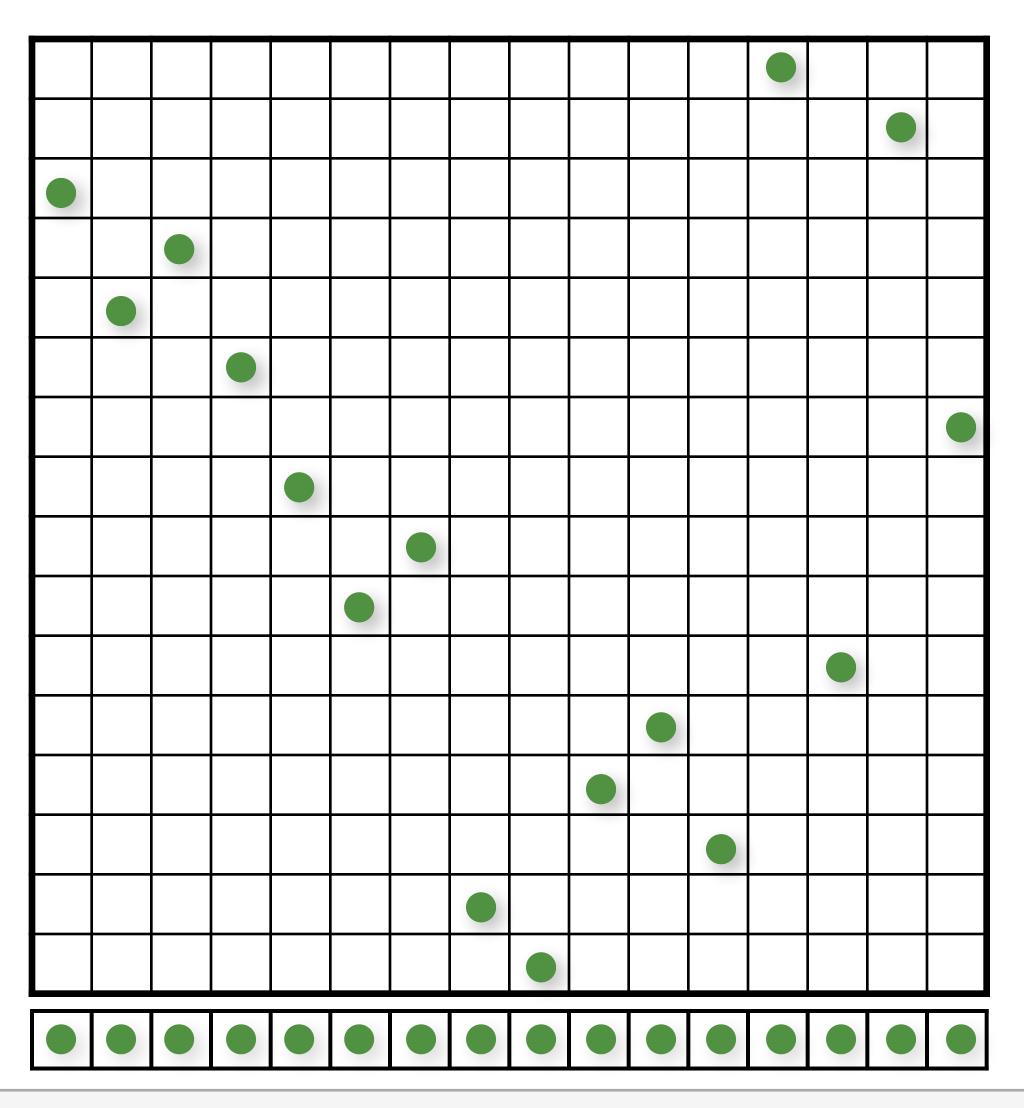
Shuffle columns

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;

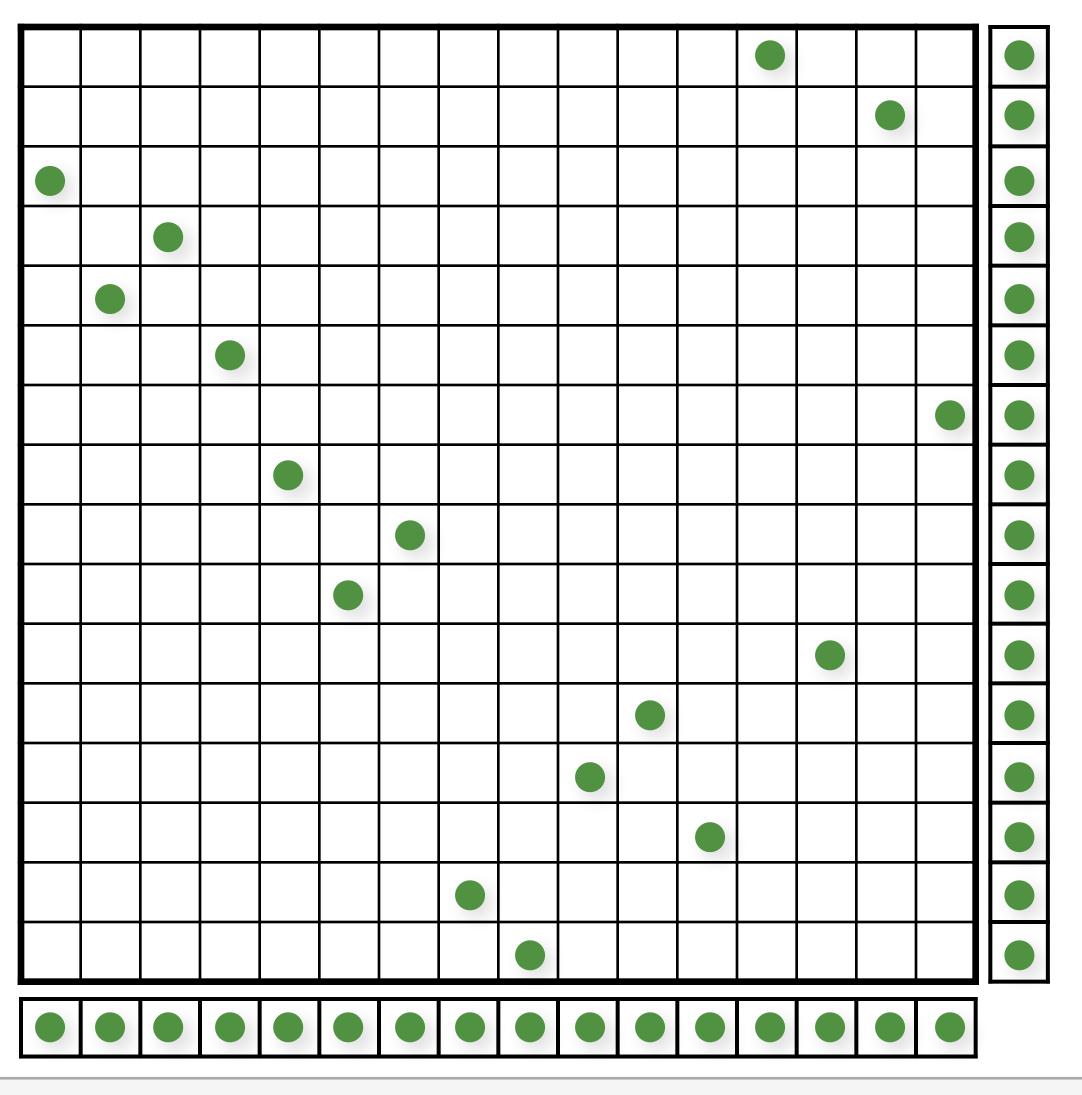
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));</pre>
```



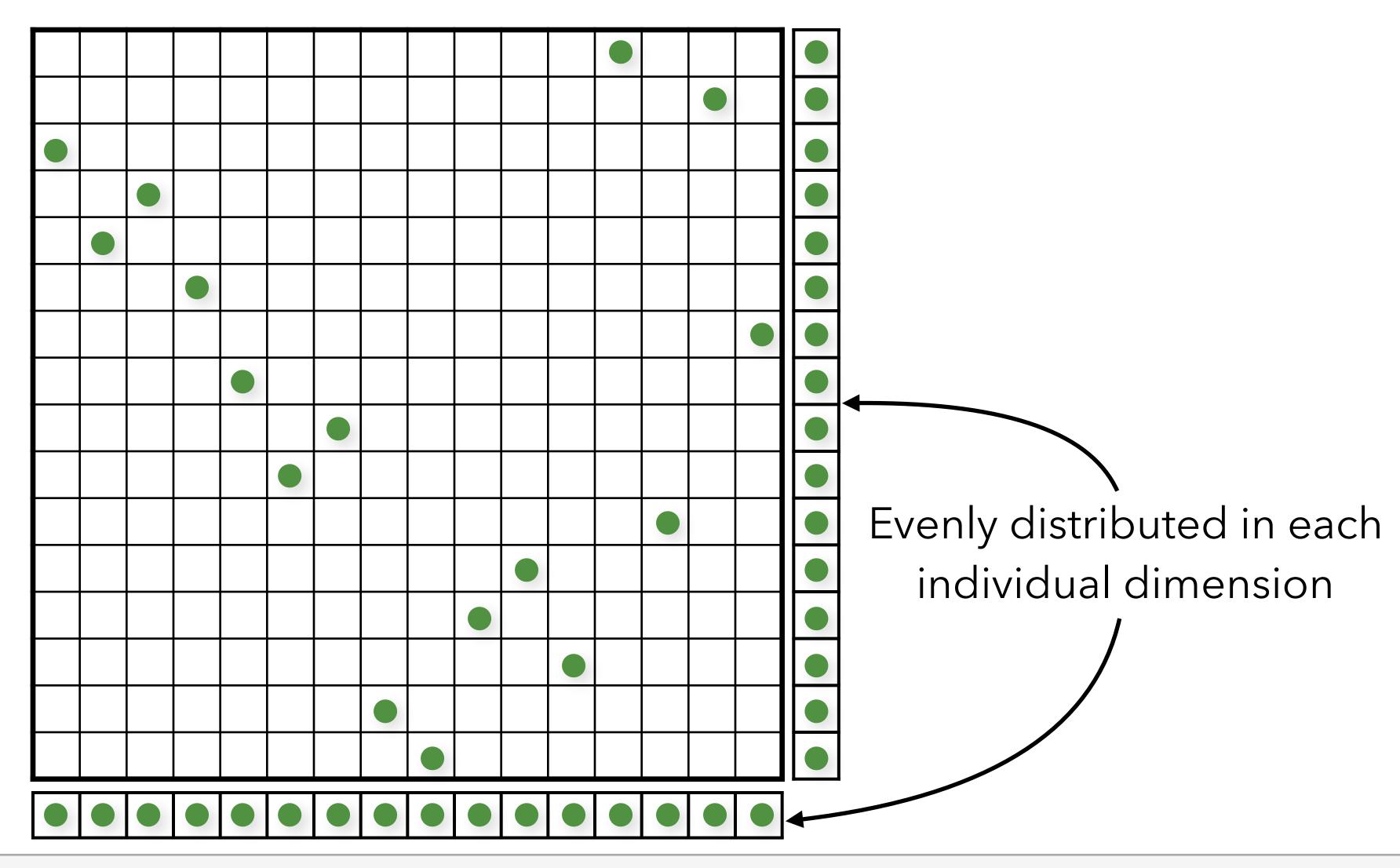






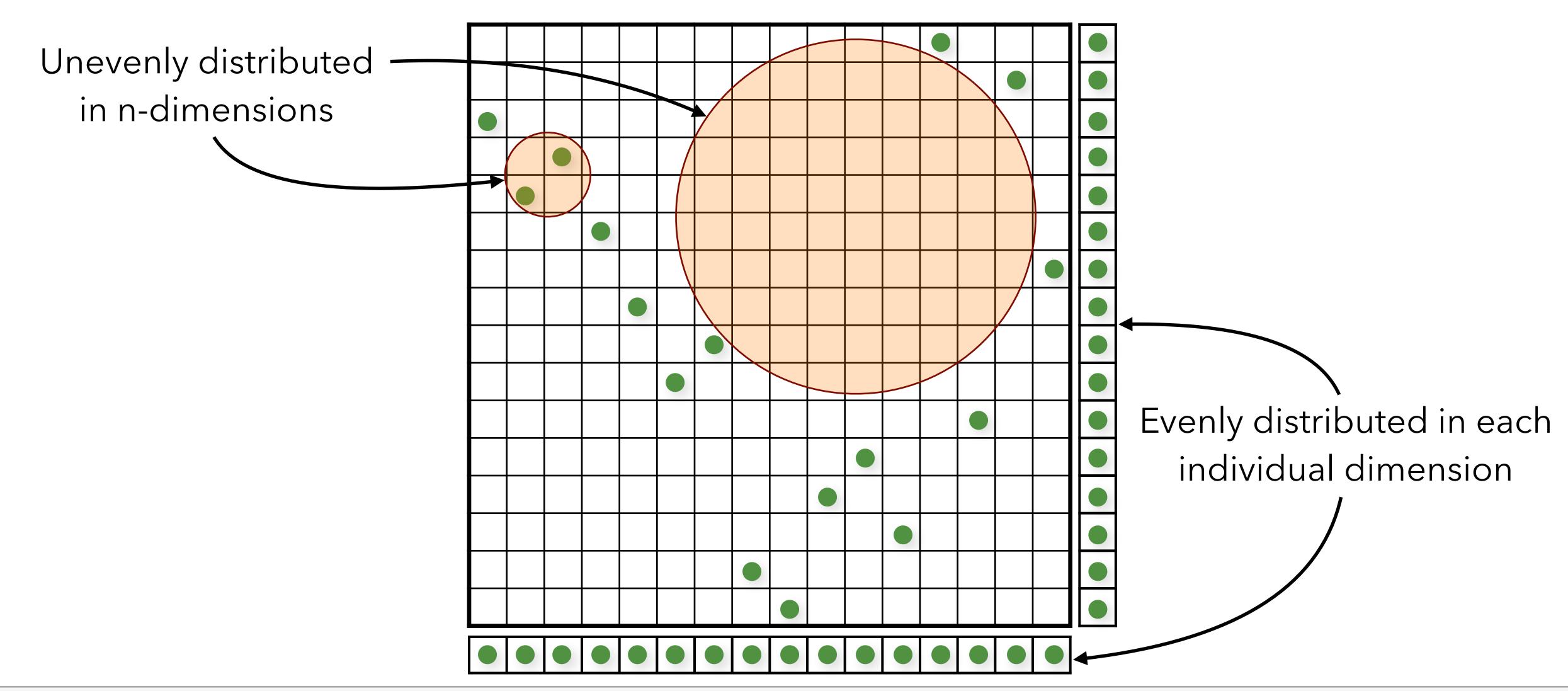






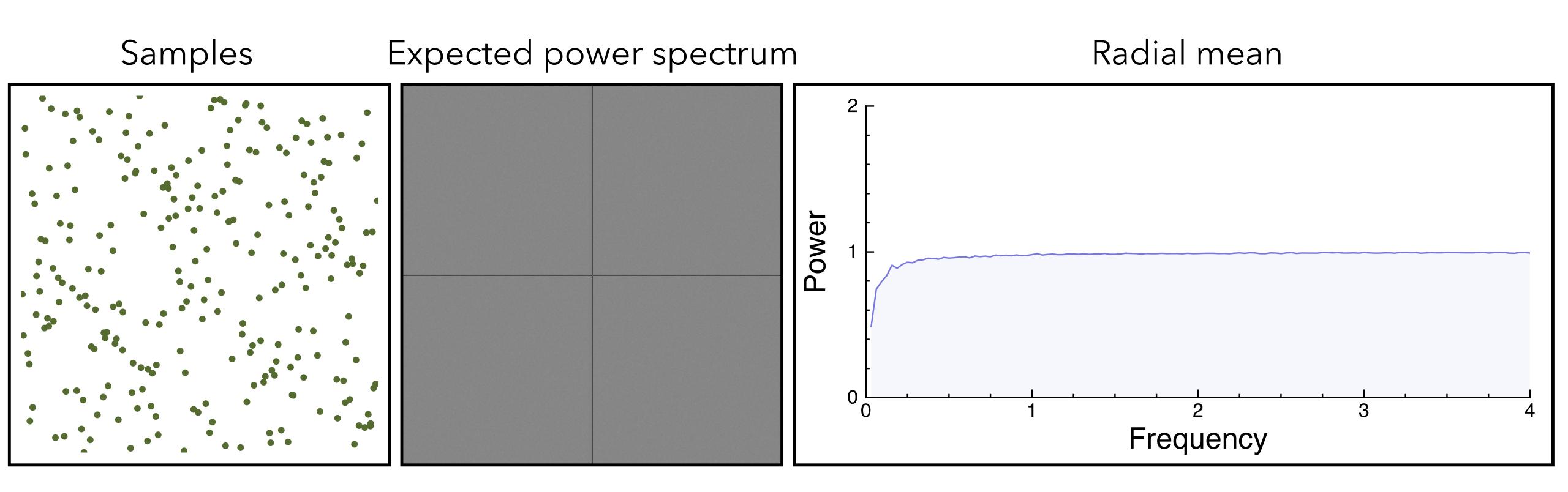


## Latin Hypercube (N-Rooks) Sampling





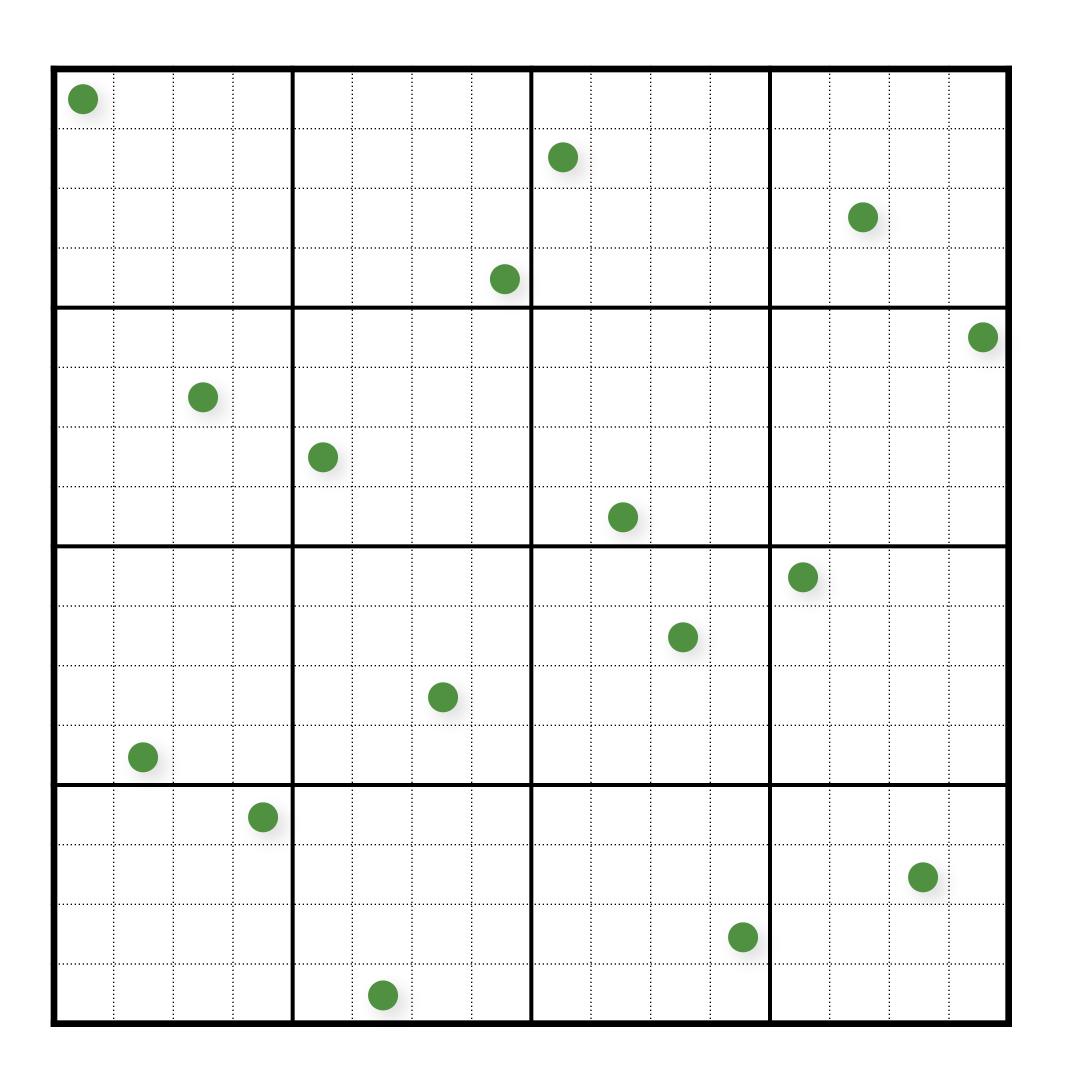
# N-Rooks Sampling



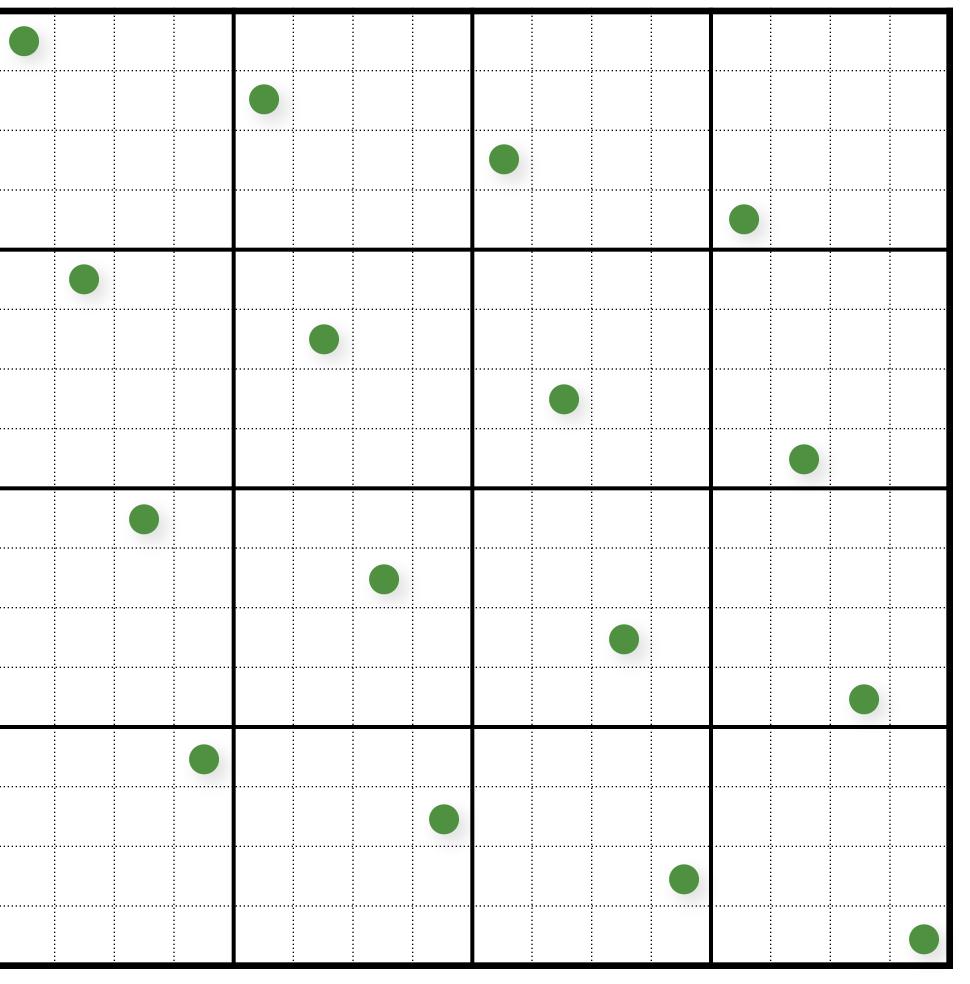


Kenneth Chiu, Peter Shirley, and Changyaw Wang. "Multi-jittered sampling." In *Graphics Gems IV*, pp. 370–374. Academic Press, May 1994.

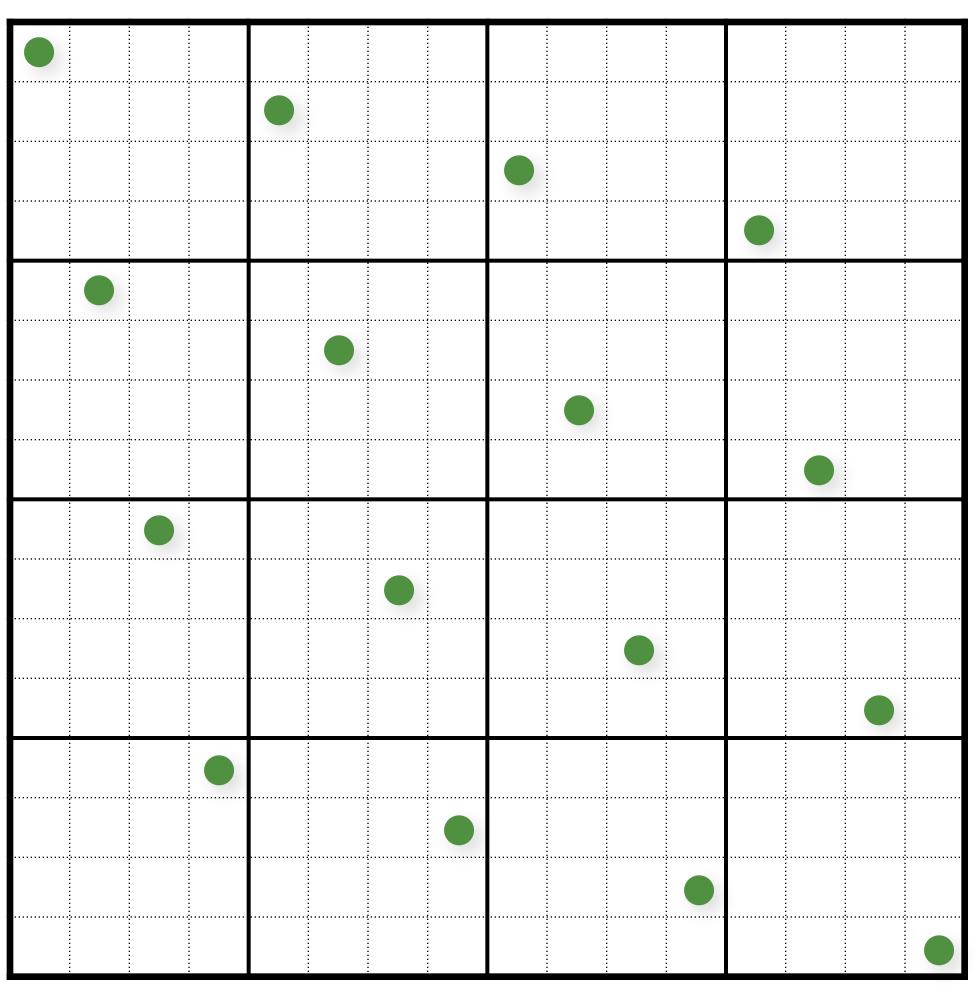
- combine N-Rooks and Jittered stratification constraints



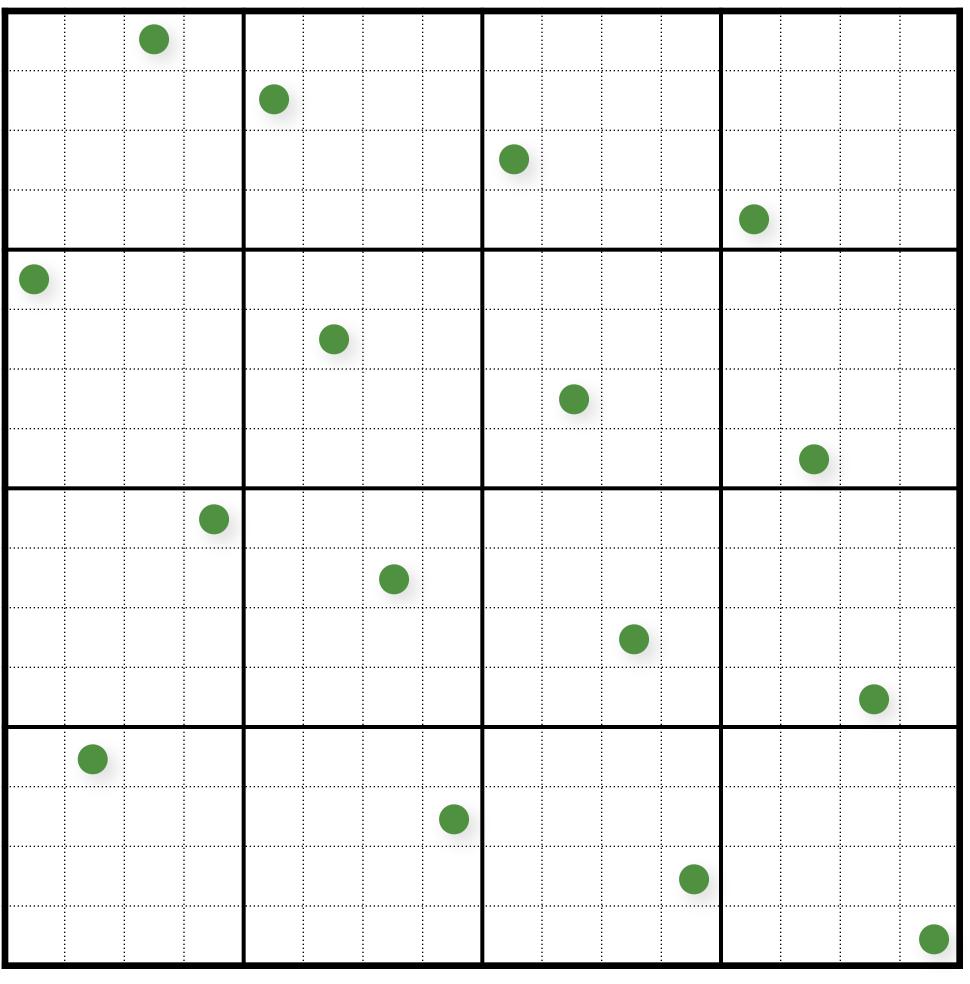
```
// initialize
float cellSize = 1.0 / (resX*resY);
for (uint i = 0; i < resX; i++)
    for (uint j = 0; j < resY; j++)
         samples(i,j).x = i/resX + (j+randf()) / (resX*resY);
         samples(i,j).y = j/resY + (i+randf()) / (resX*resY);
  shuffle x coordinates within each column of cells
for (uint i = 0; i < resX; i++)
    for (uint j = resY-1; j >= 1; j--)
         swap(samples(i, j).x, samples(i, randi(0, j)).x);
// shuffle y coordinates within each row of cells
for (unsigned j = 0; j < resY; j++)
    for (unsigned i = resX-1; i >= 1; i--)
         swap(samples(i, j).y, samples(randi(0, i), j).y);
```



Initialize

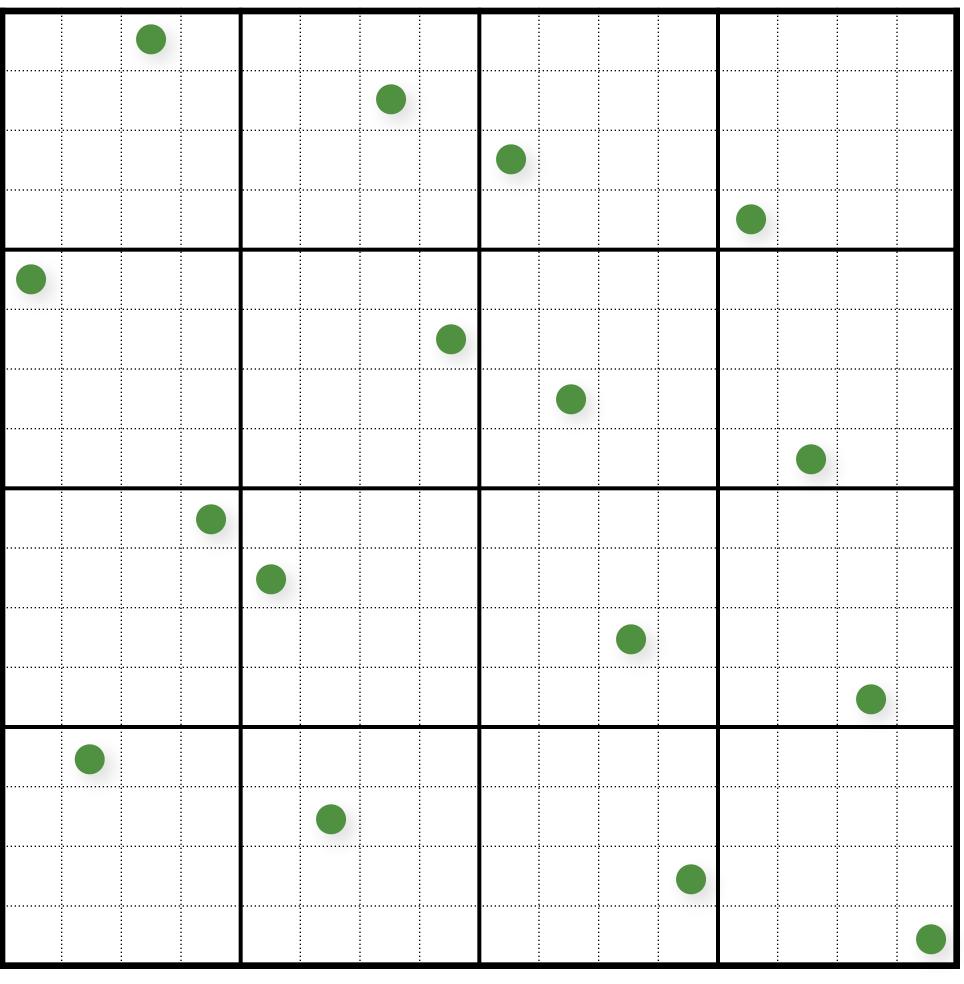


Shuffle x-coords

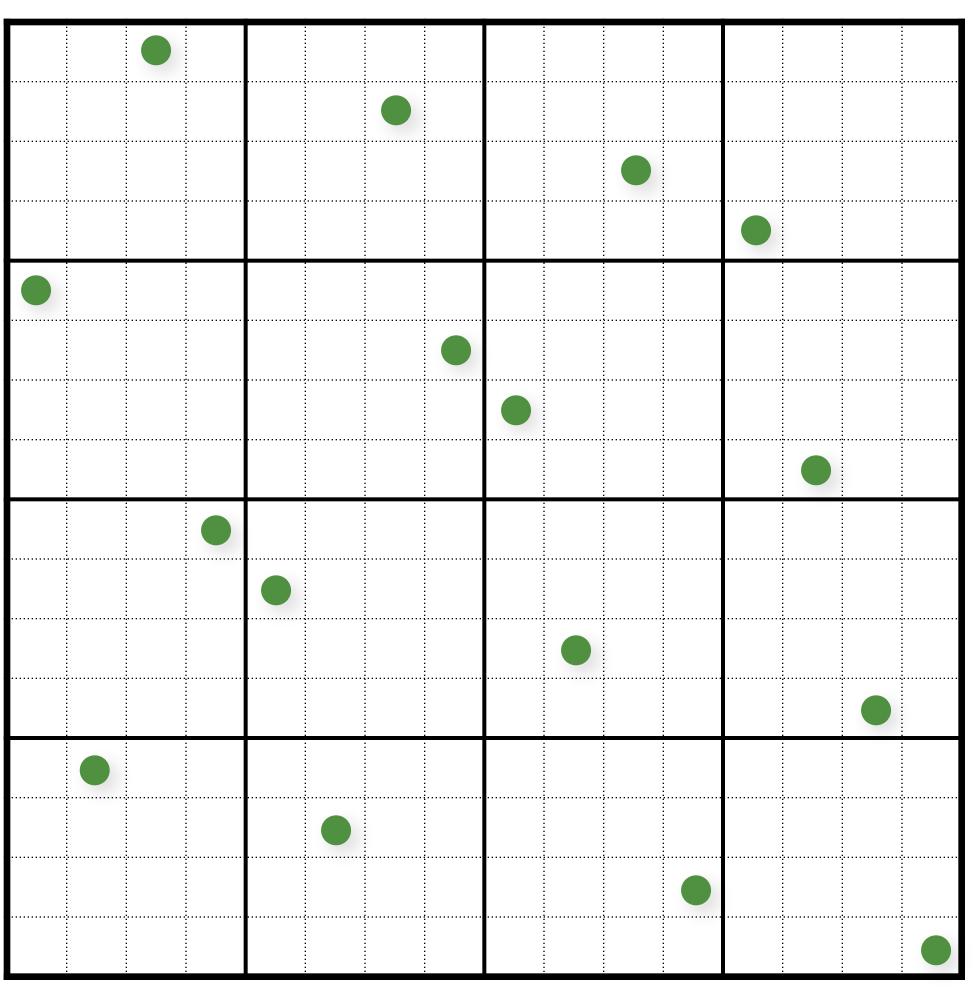


Shuffle x-coords

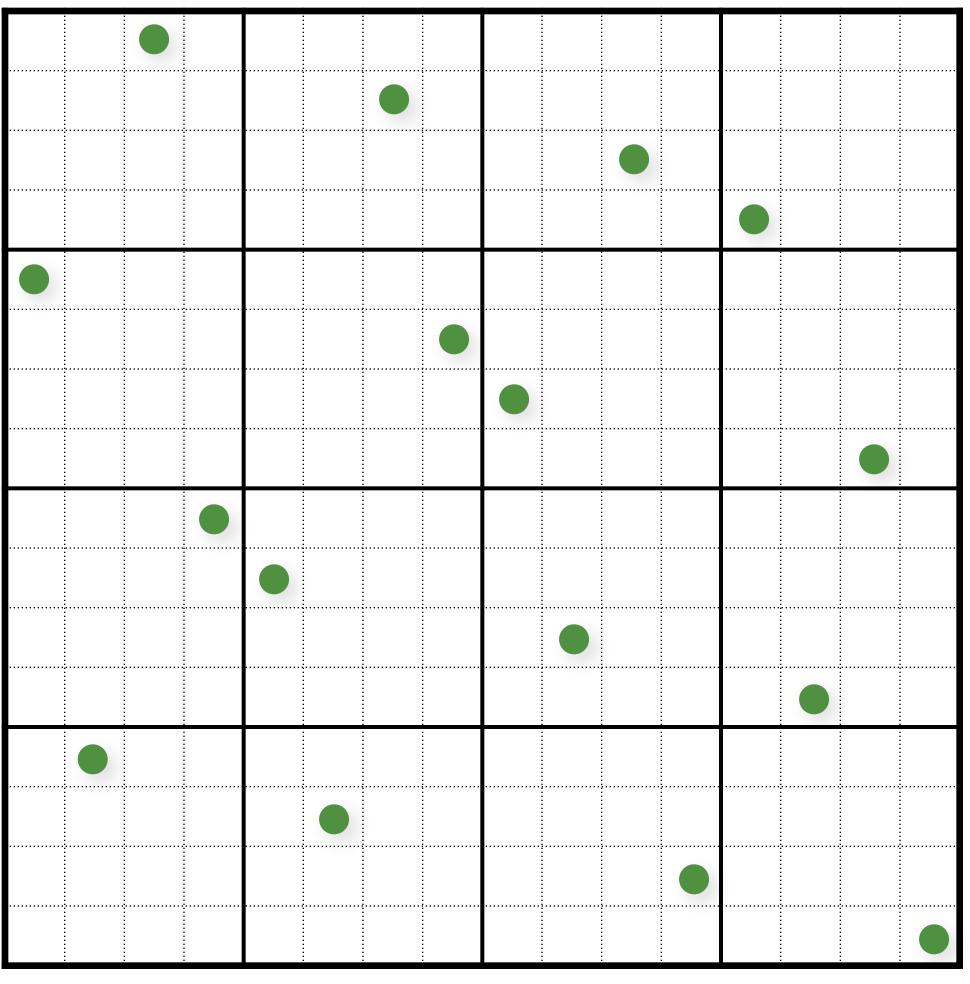




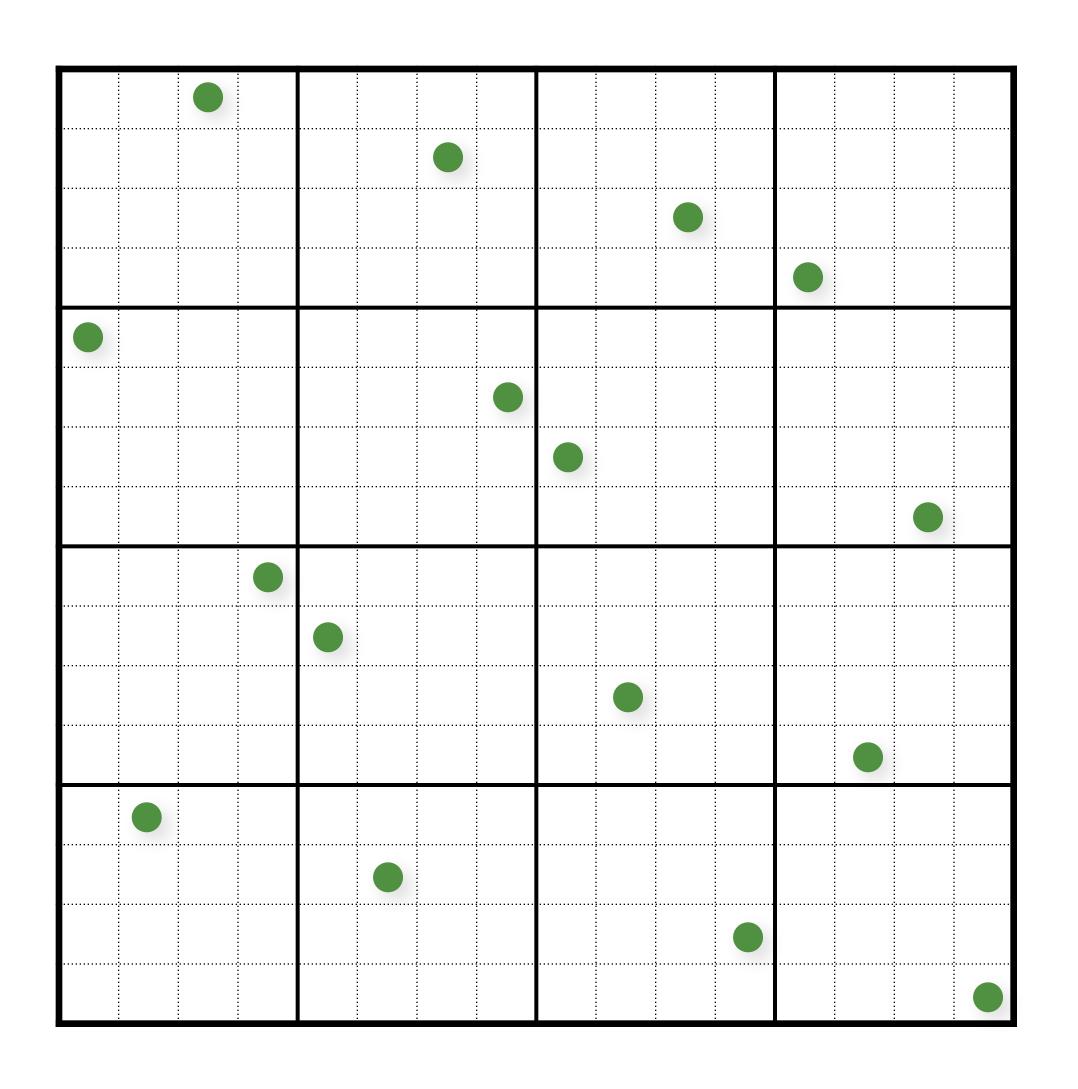
Shuffle x-coords

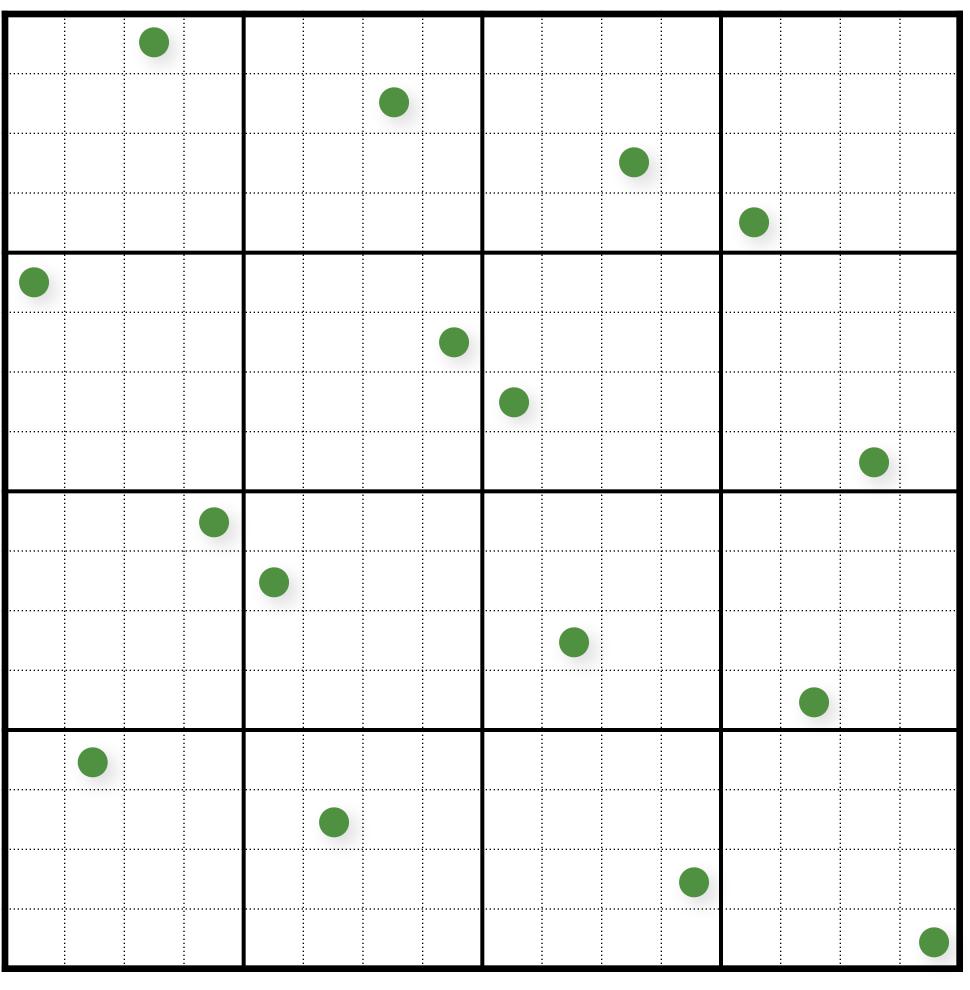


Shuffle x-coords



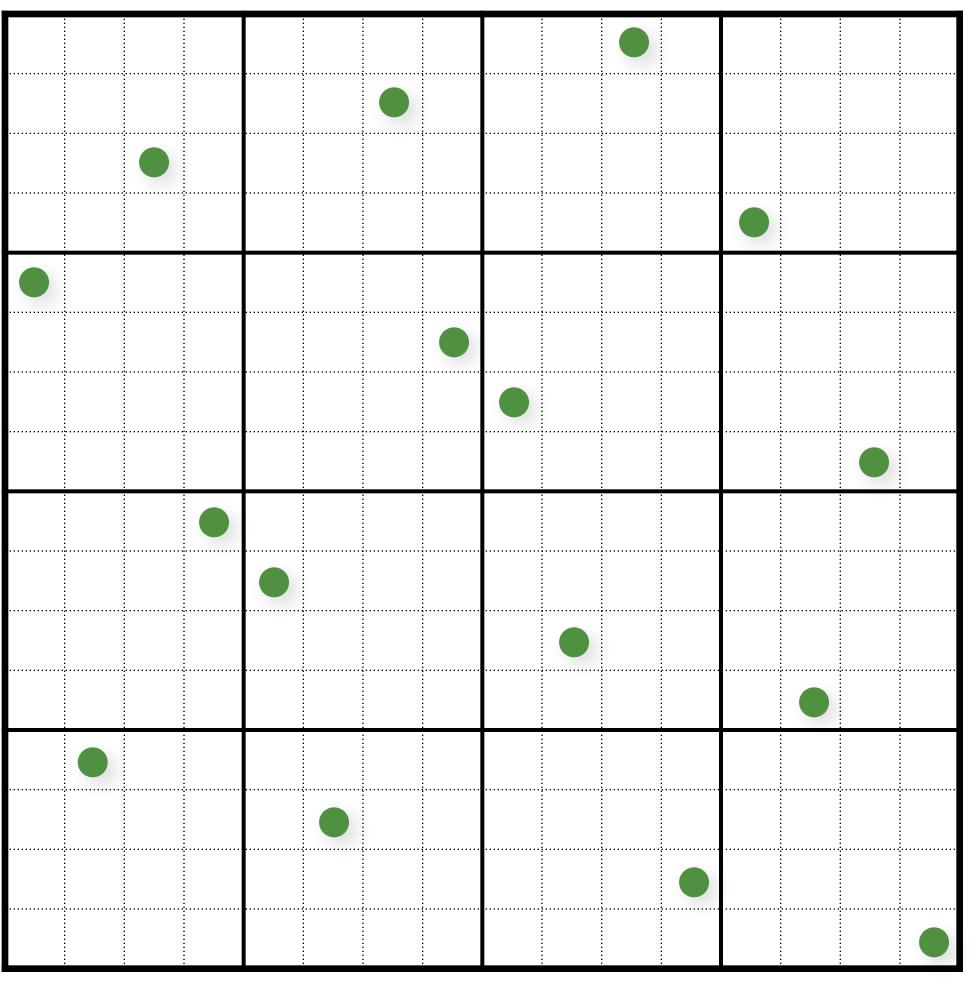
Shuffle x-coords





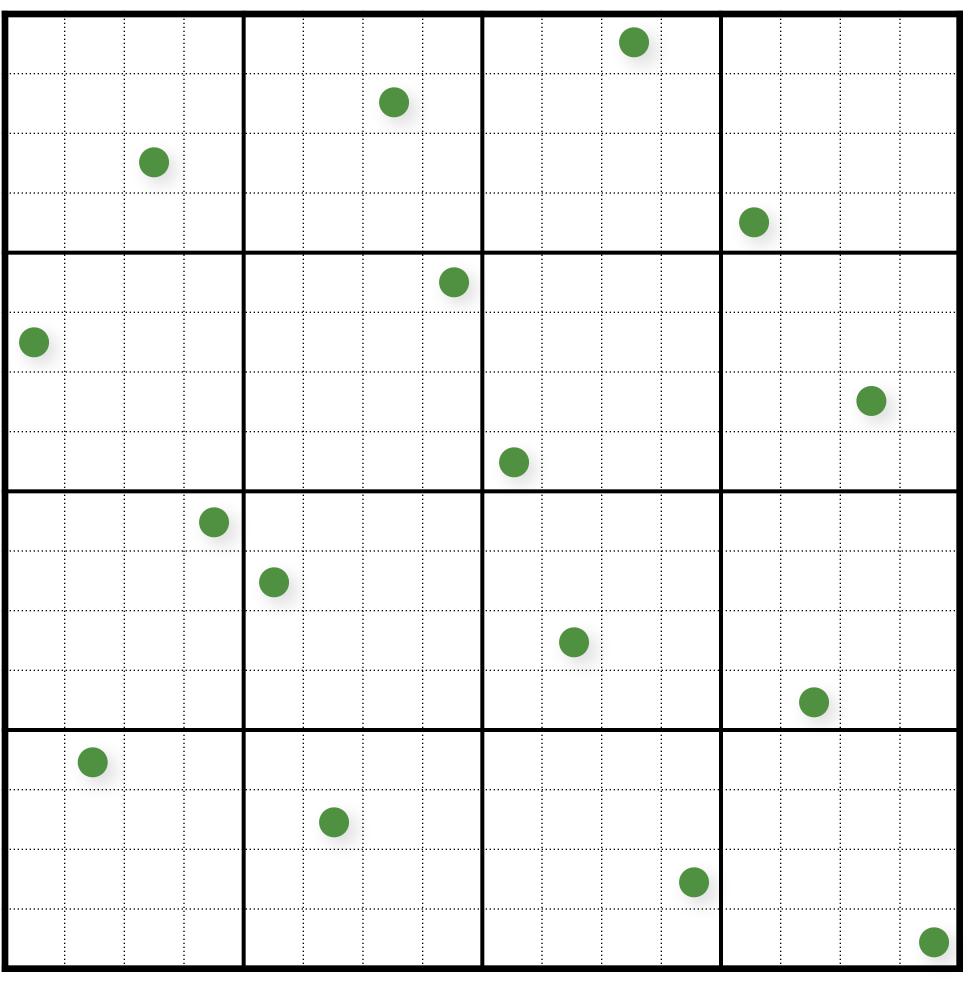
Shuffle y-coords





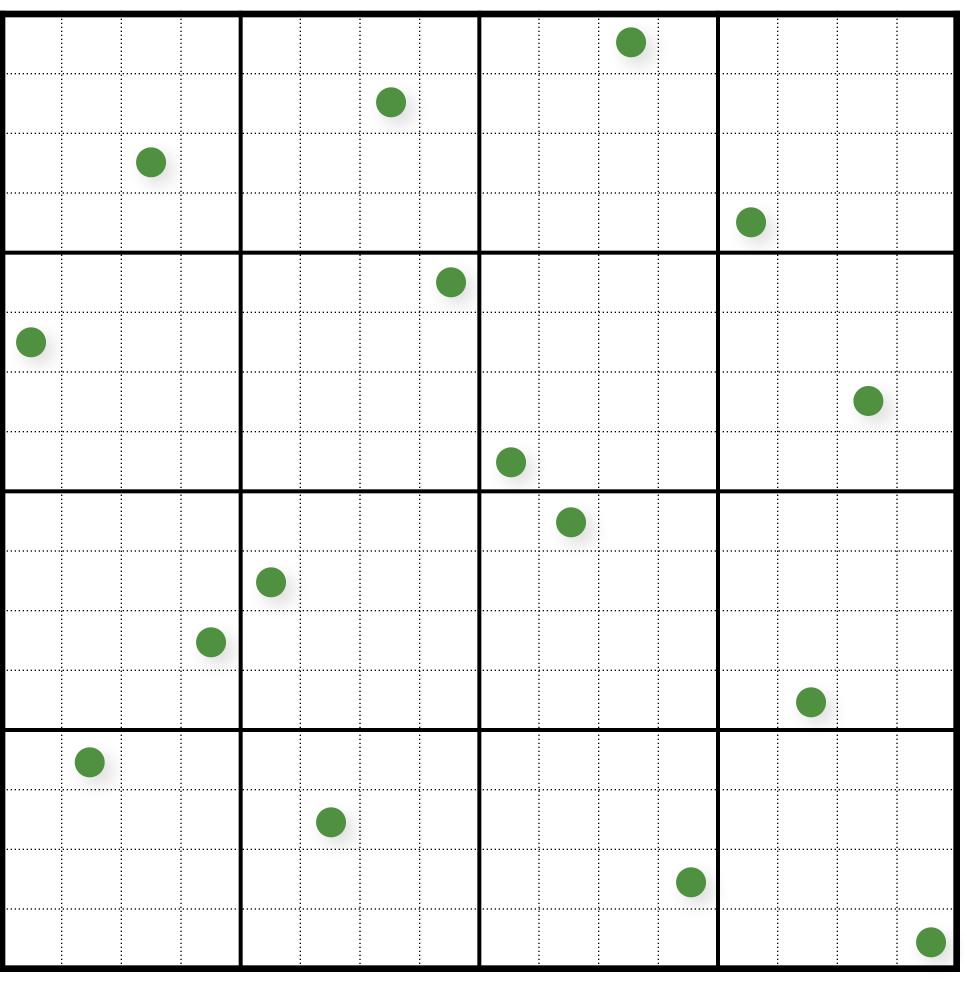
Shuffle y-coords





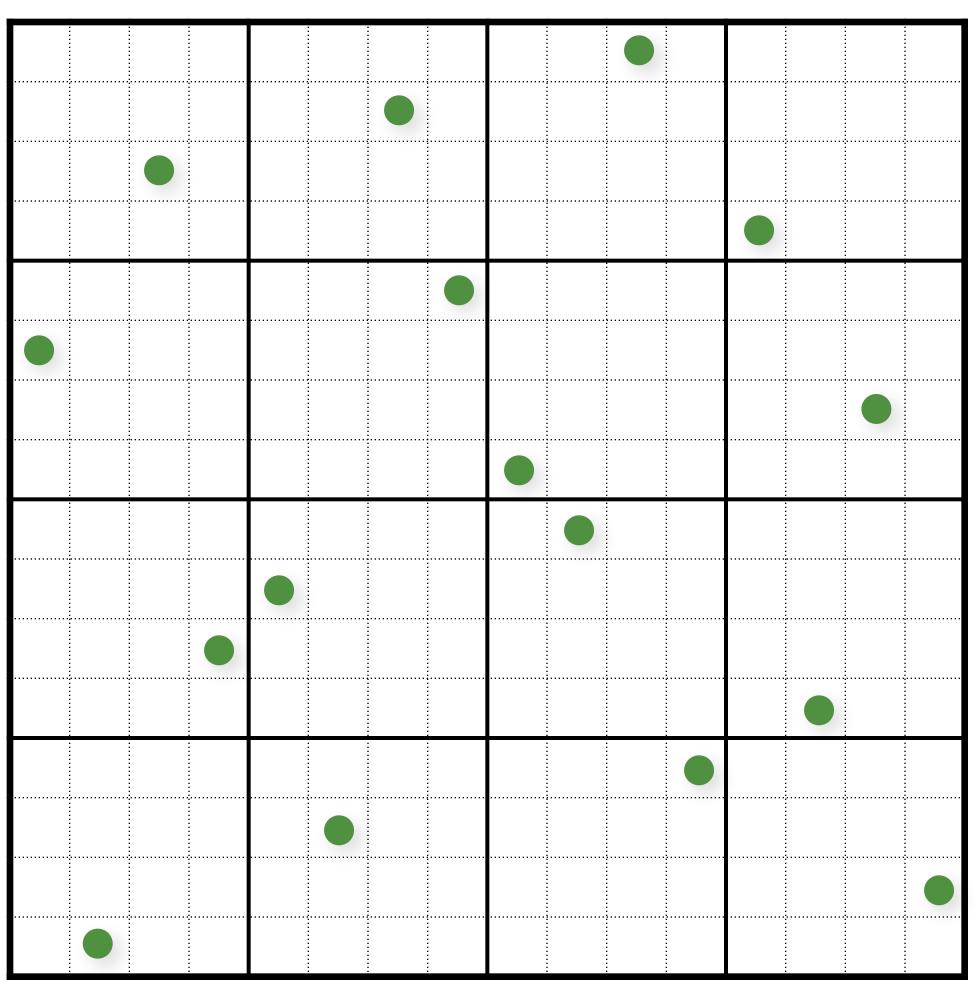
Shuffle y-coords





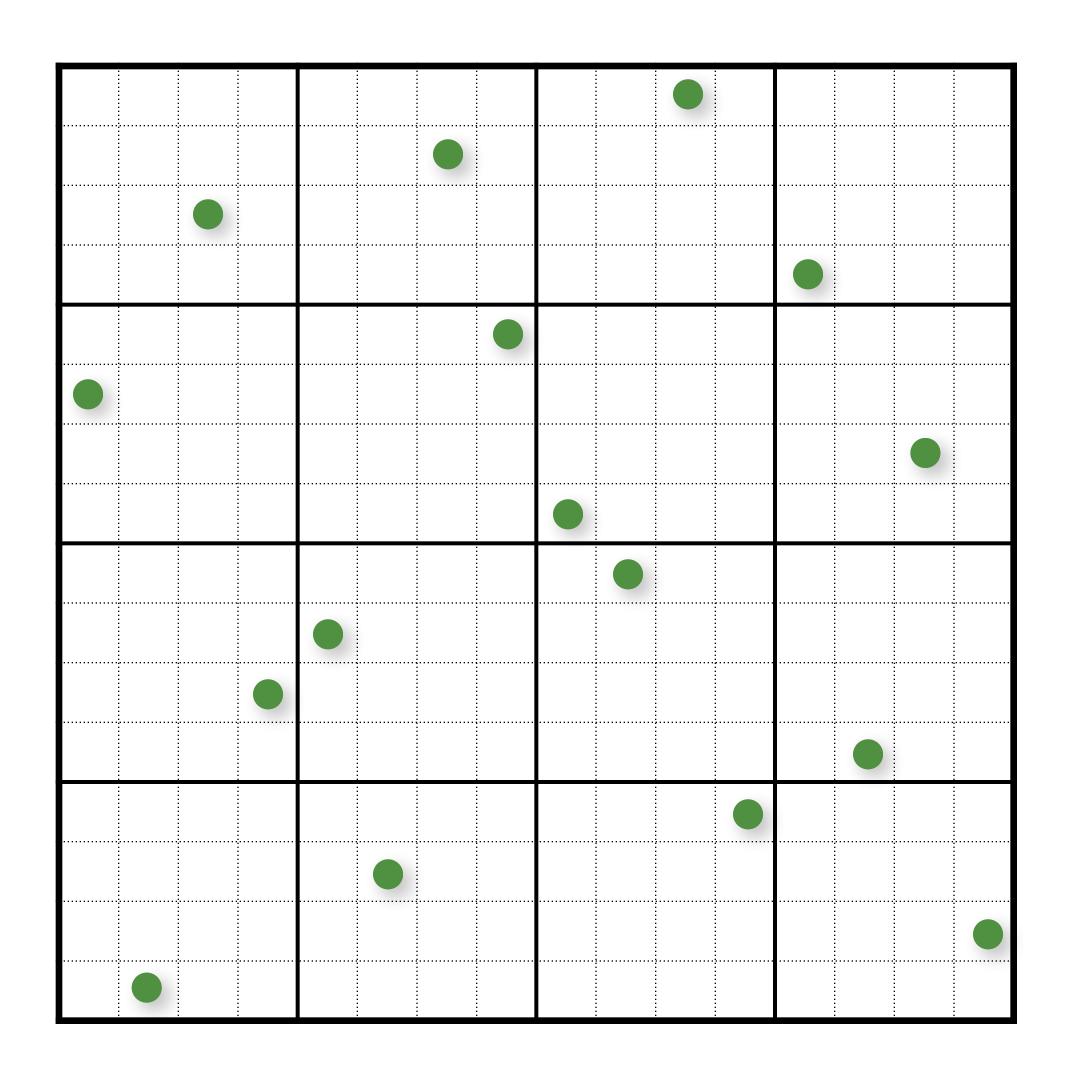
Shuffle y-coords



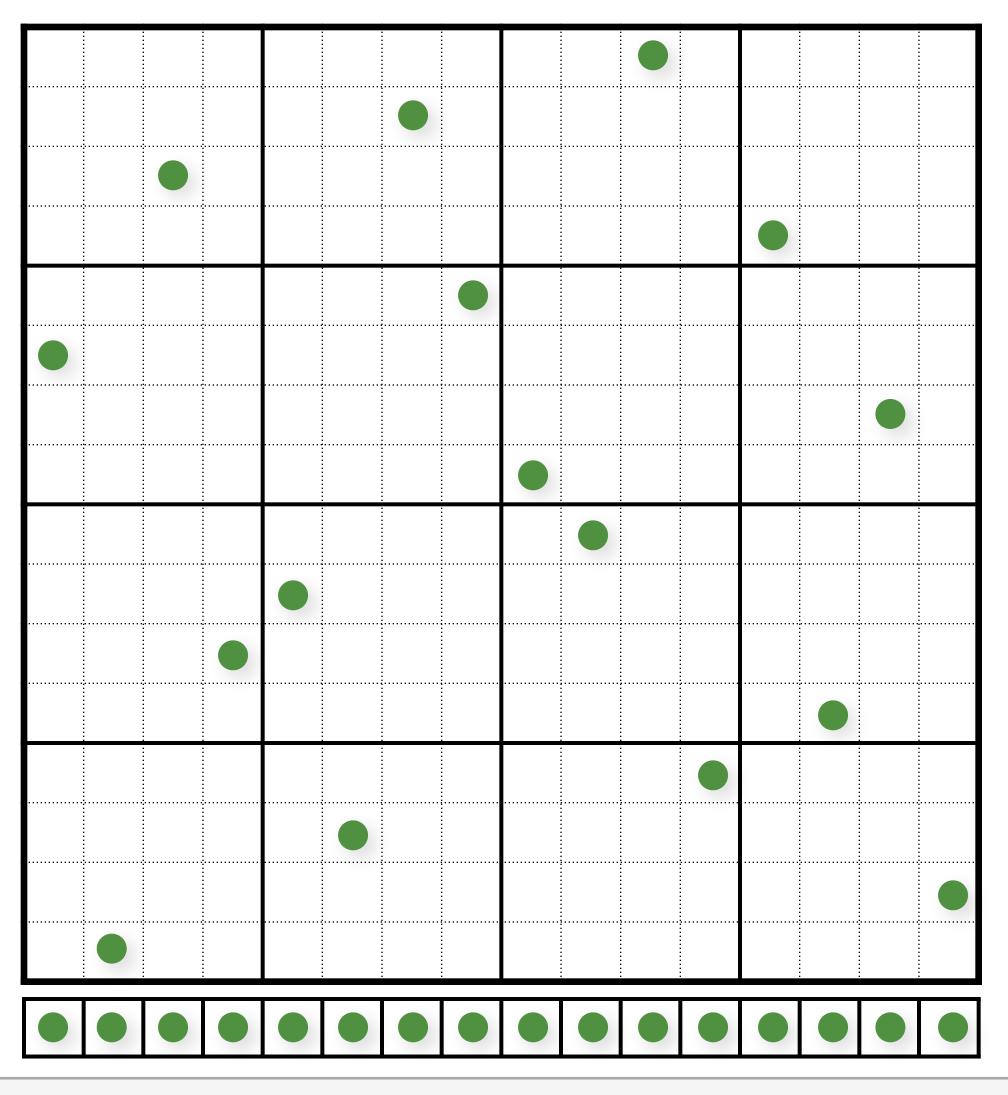


Shuffle y-coords

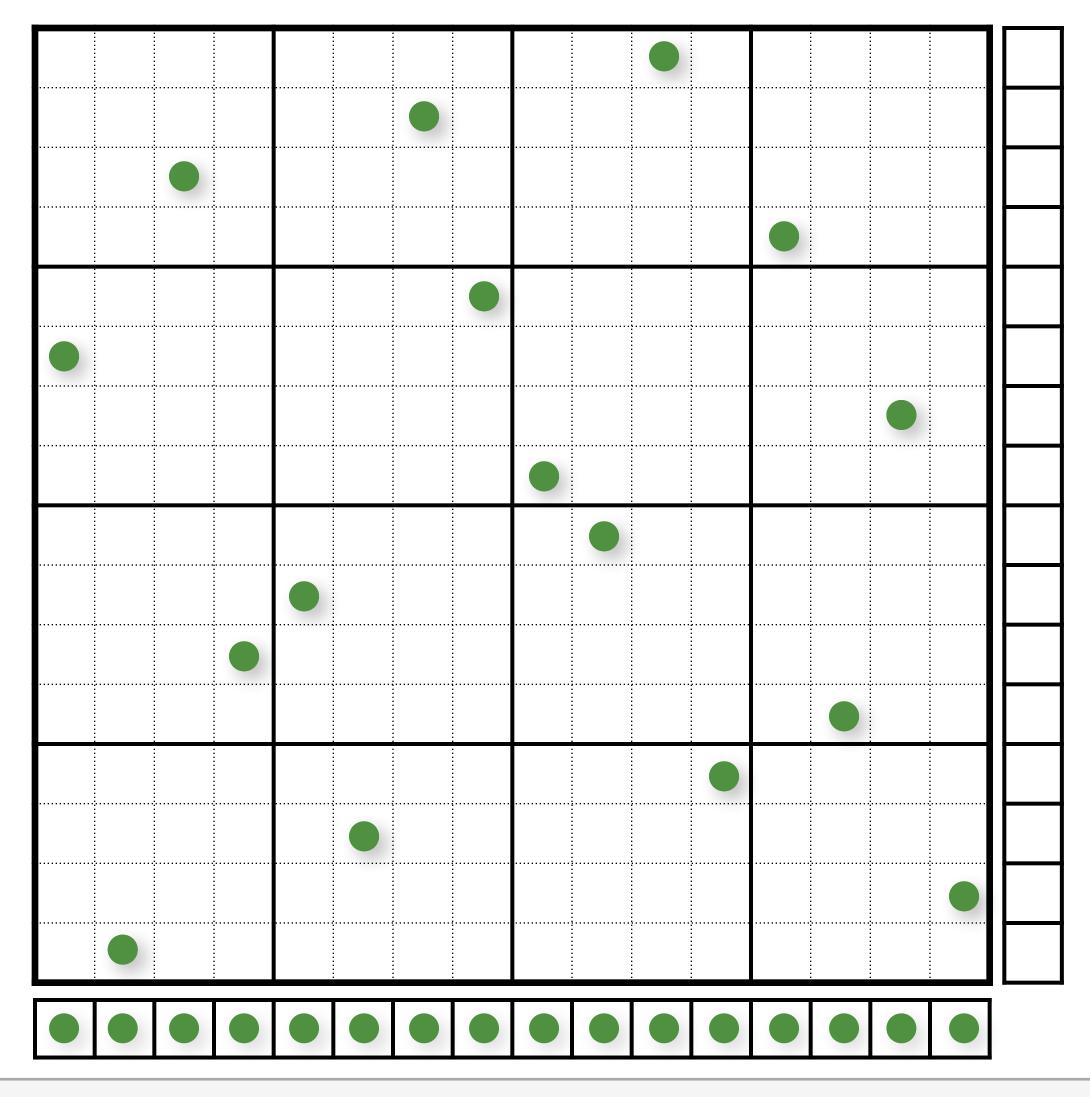




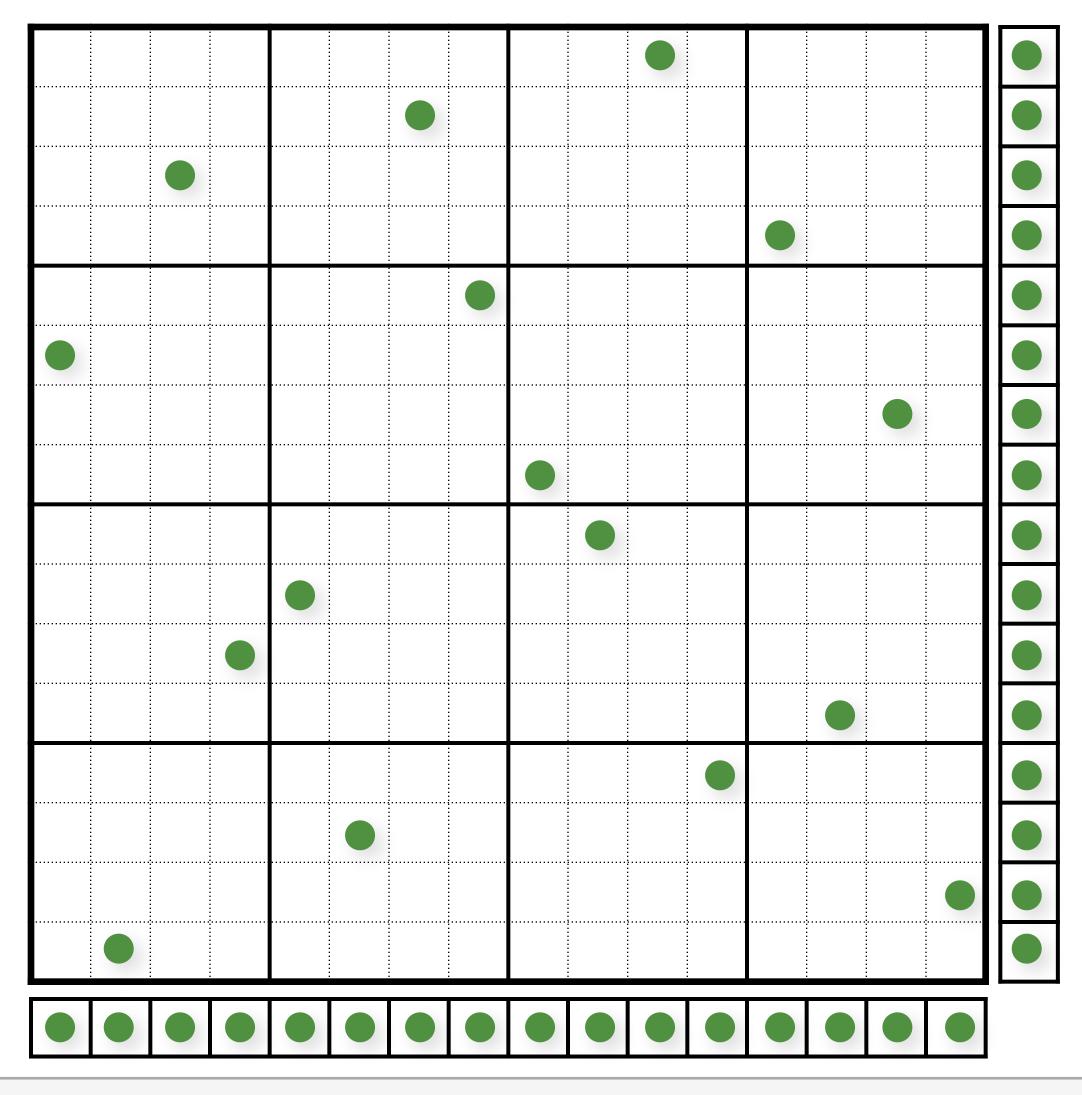




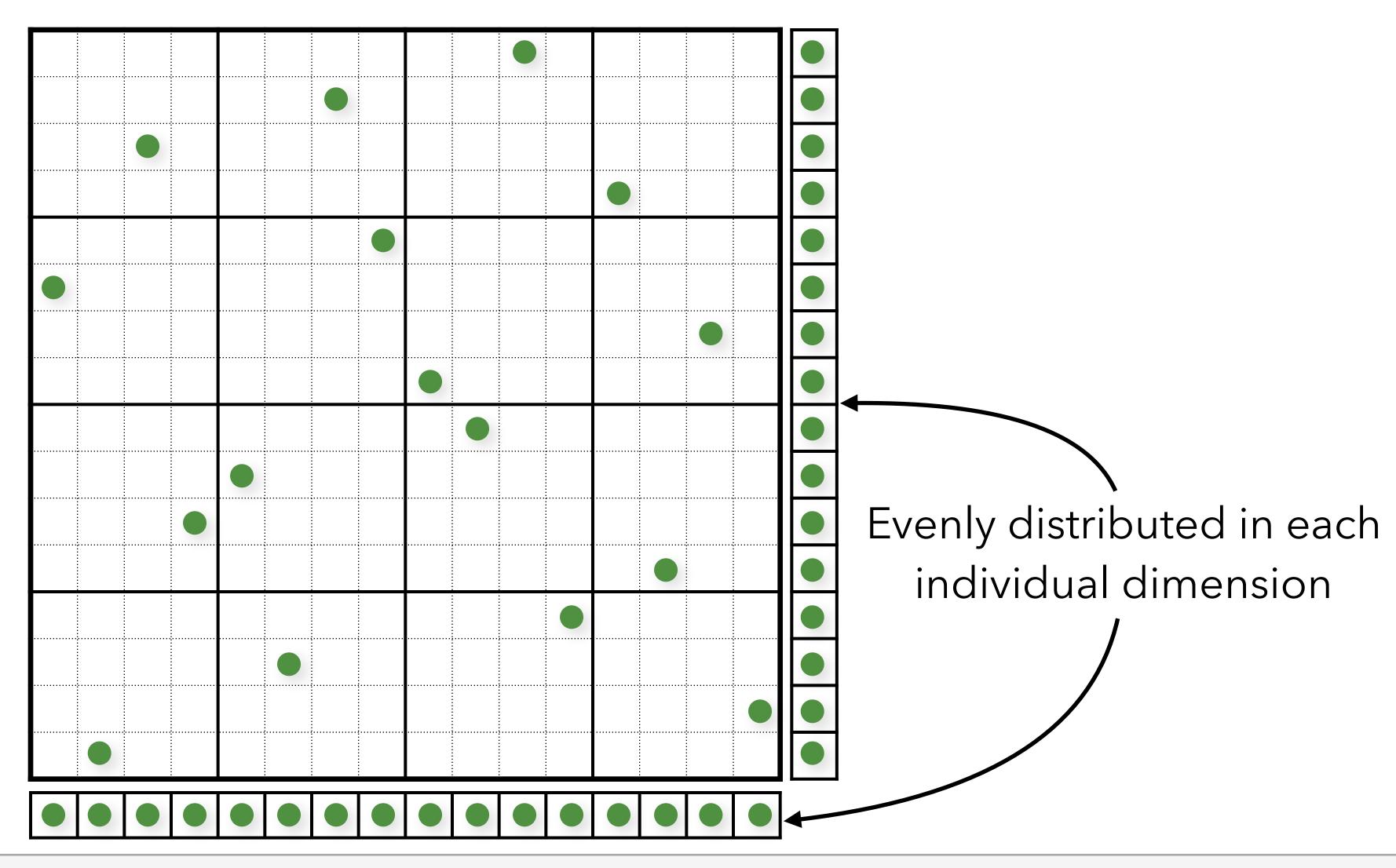




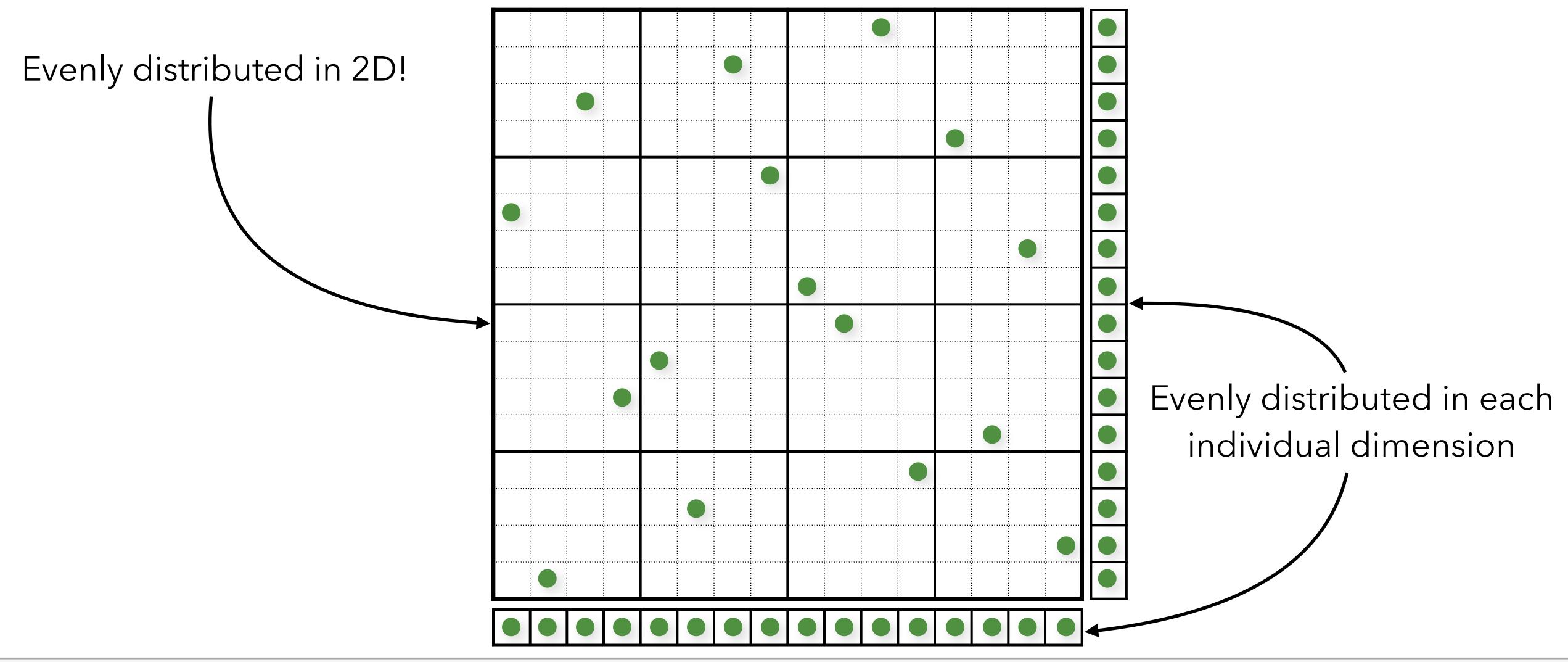




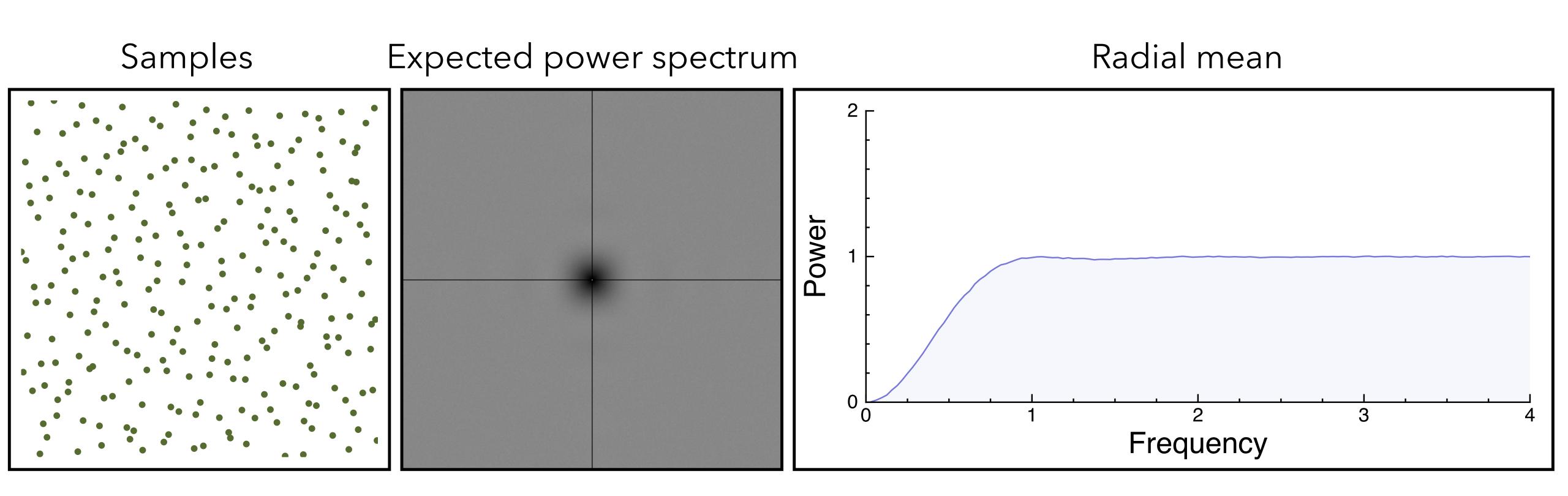




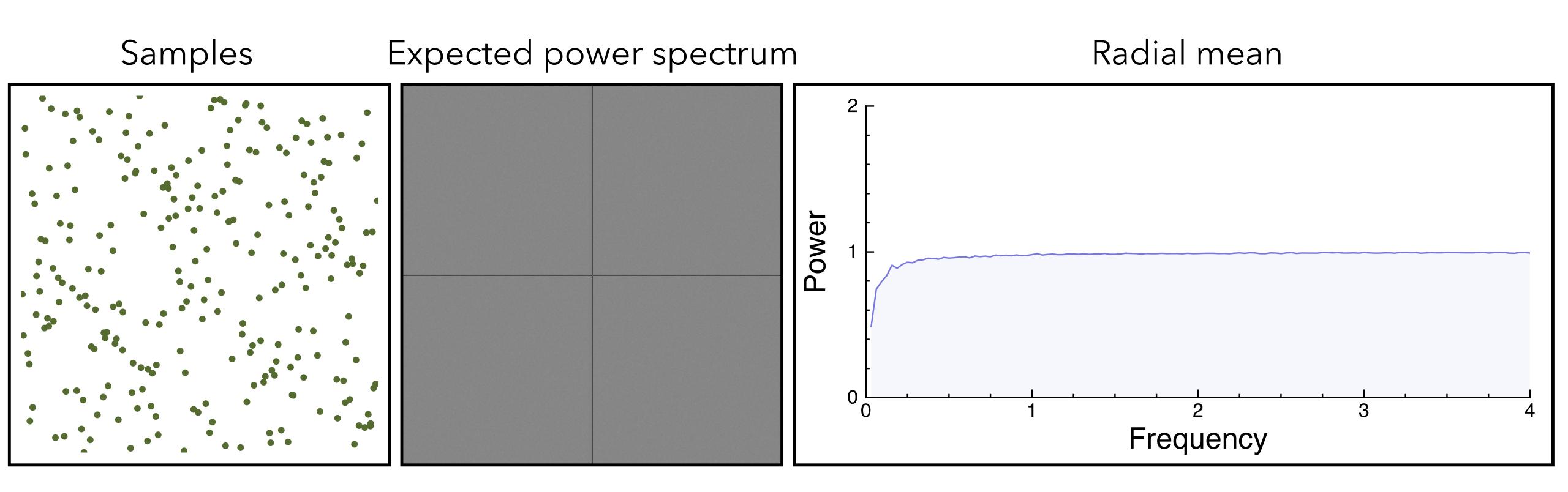






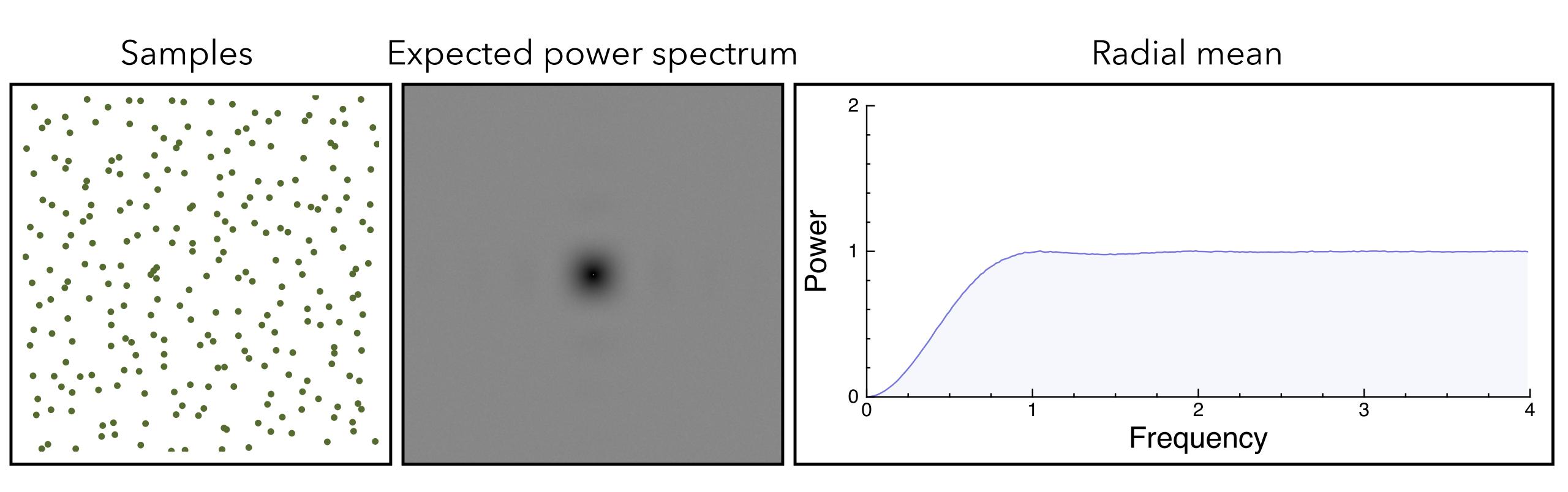


# N-Rooks Sampling





# Jittered Sampling



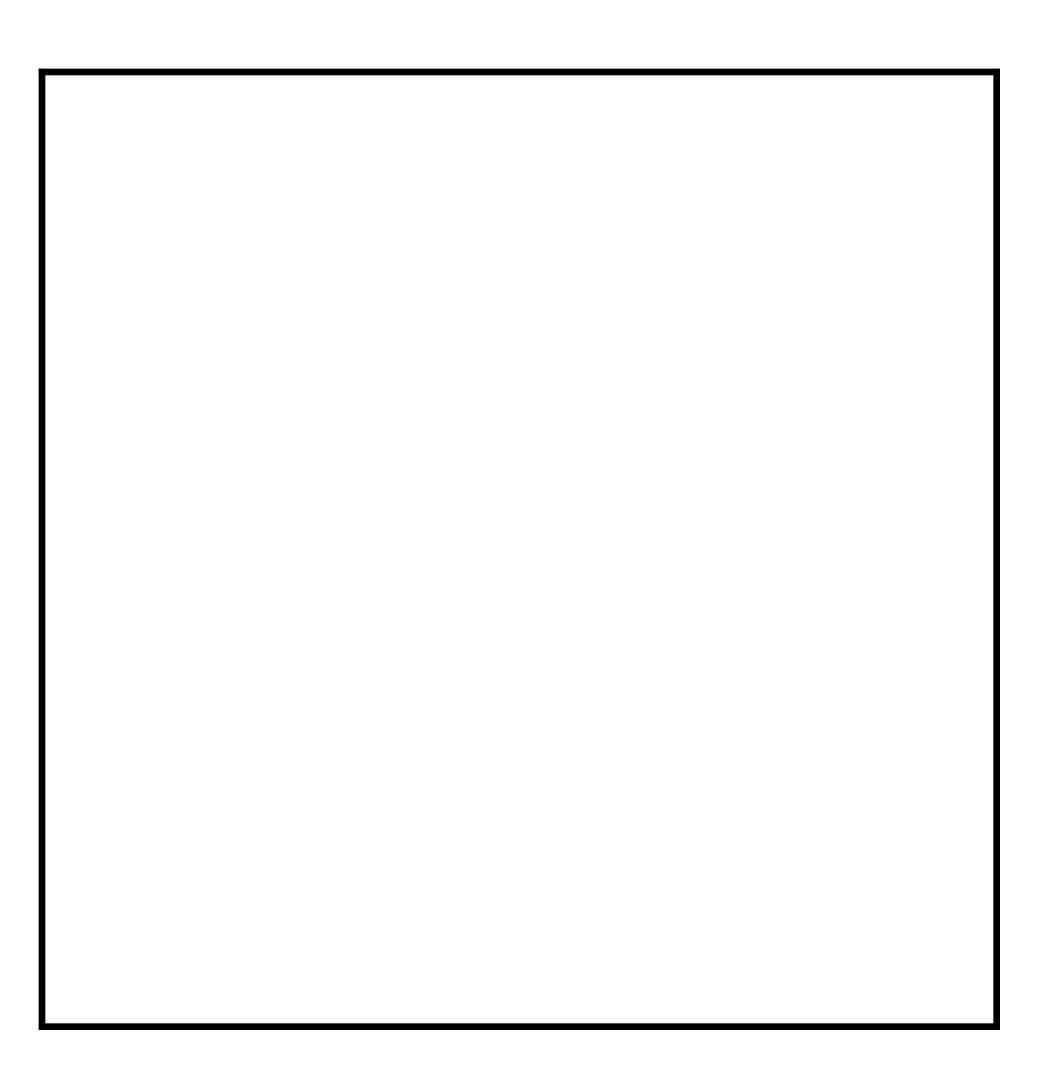
#### Poisson-Disk/Blue-Noise Sampling

#### Enforce a minimum distance between points

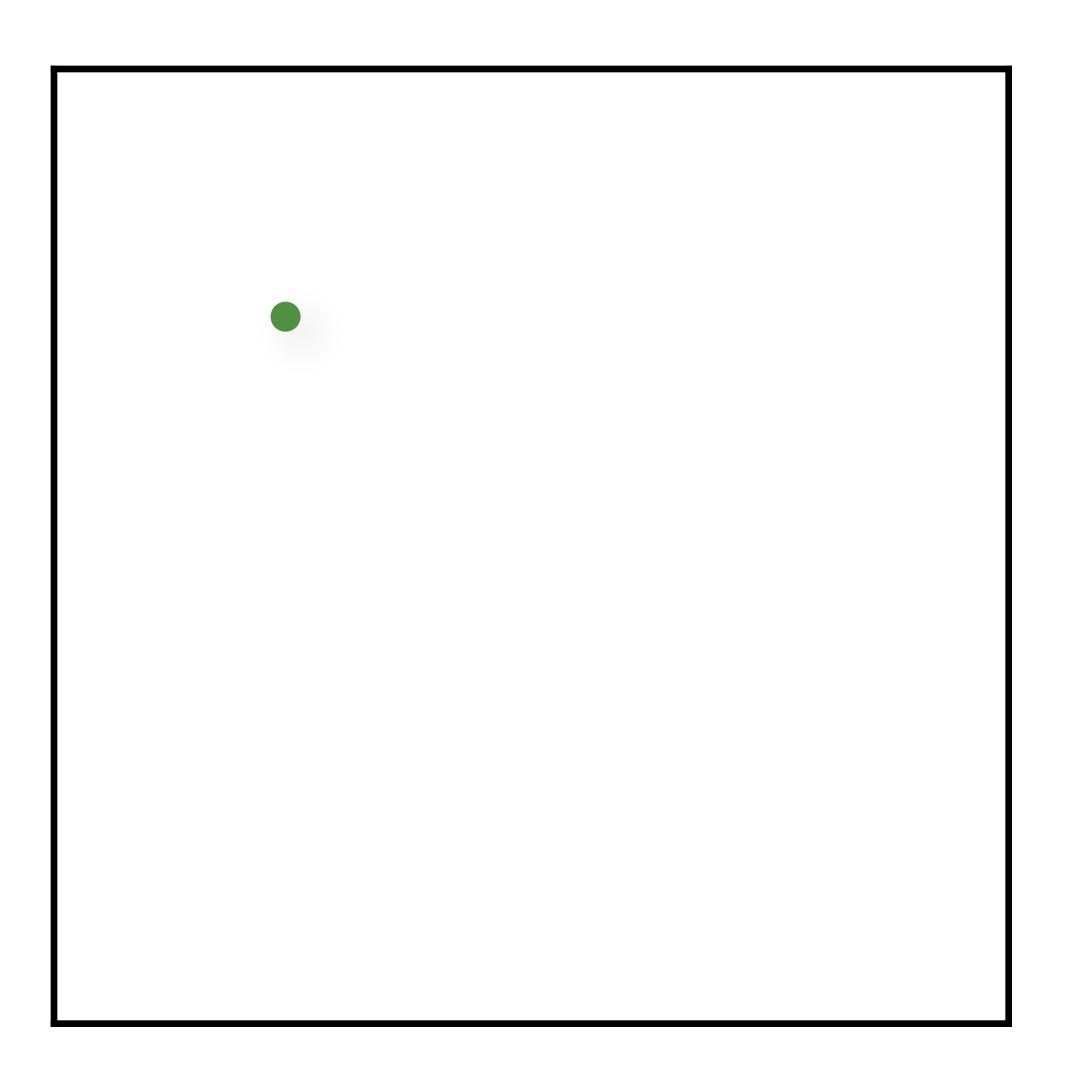
#### Poisson-Disk Sampling:

- Mark A. Z. Dippé and Erling Henry Wold. "Antialiasing through stochastic sampling." *ACM SIGGRAPH,* 1985.
- Robert L. Cook. "Stochastic sampling in computer graphics." *ACM Transactions on Graphics*, 1986.
- Ares Lagae and Philip Dutré. "A comparison of methods for generating Poisson disk distributions." *Computer Graphics Forum*, 2008.

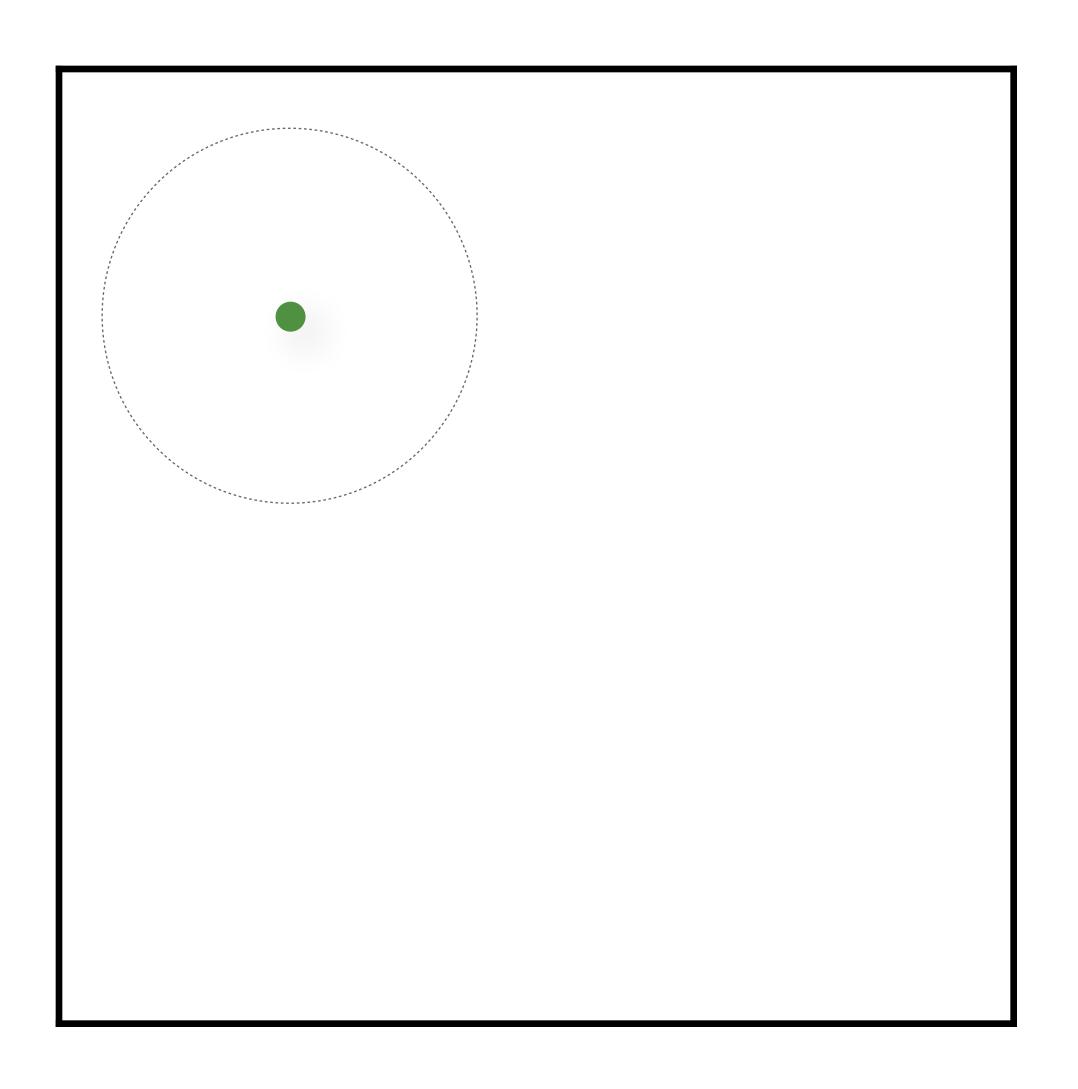




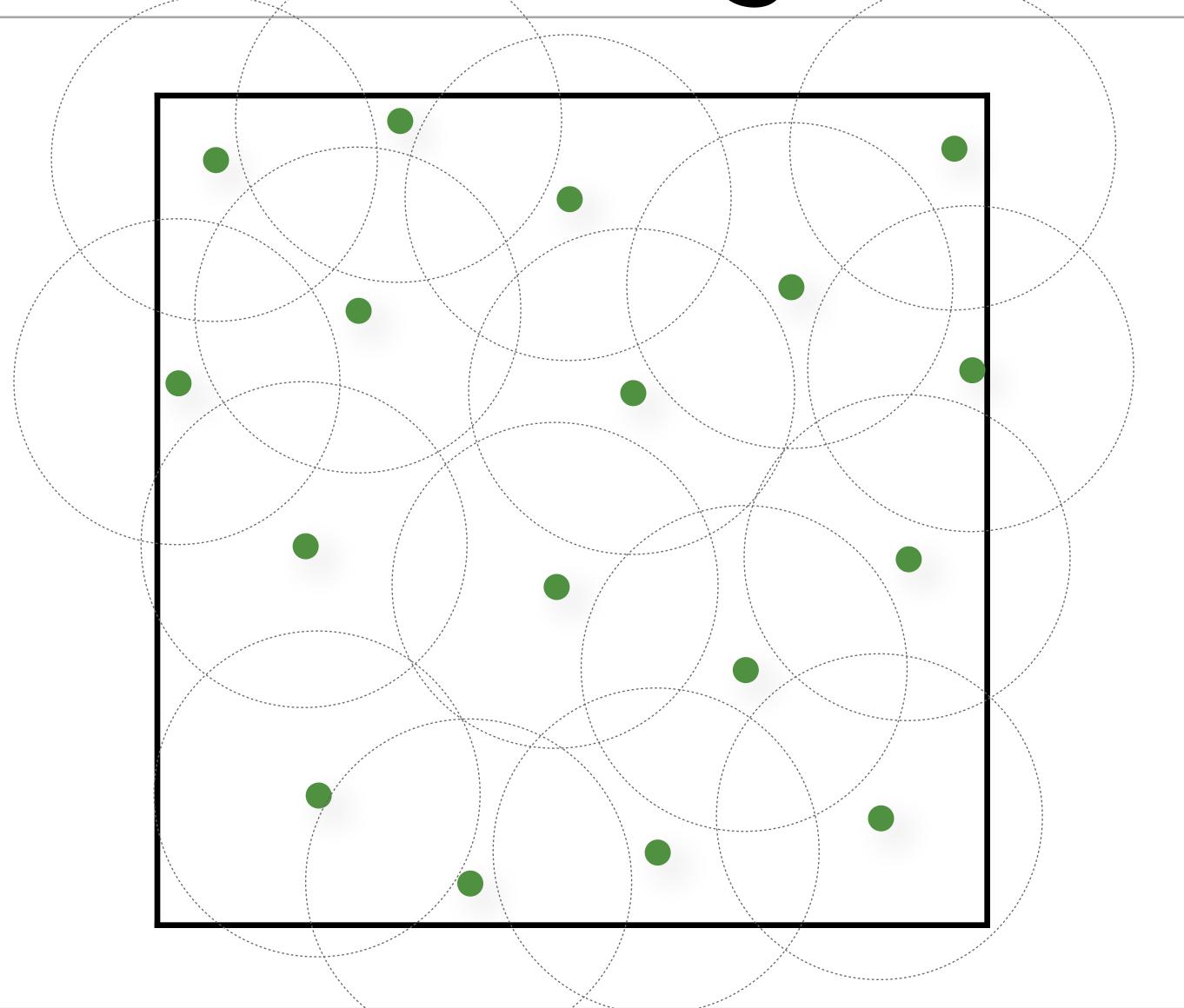


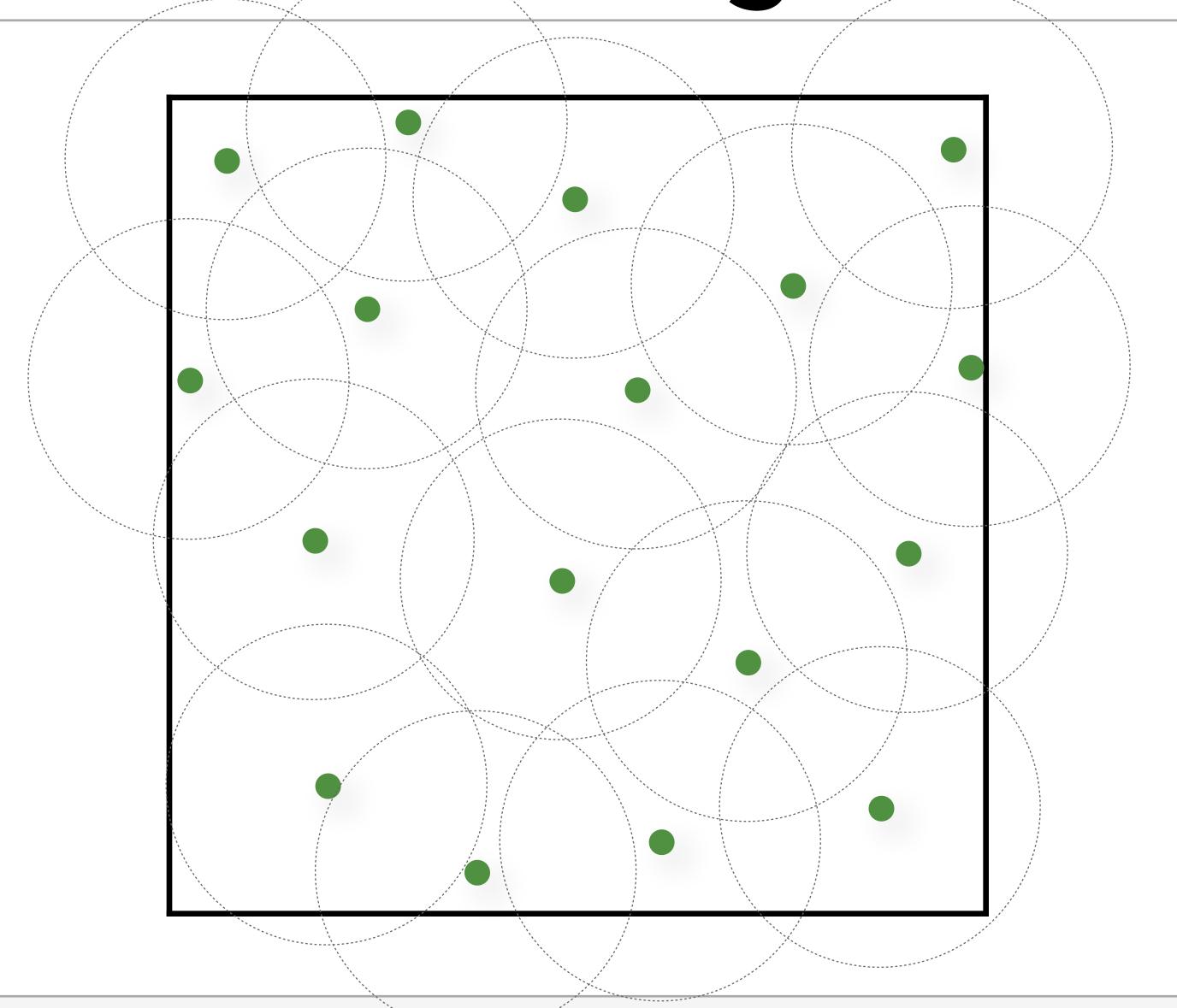




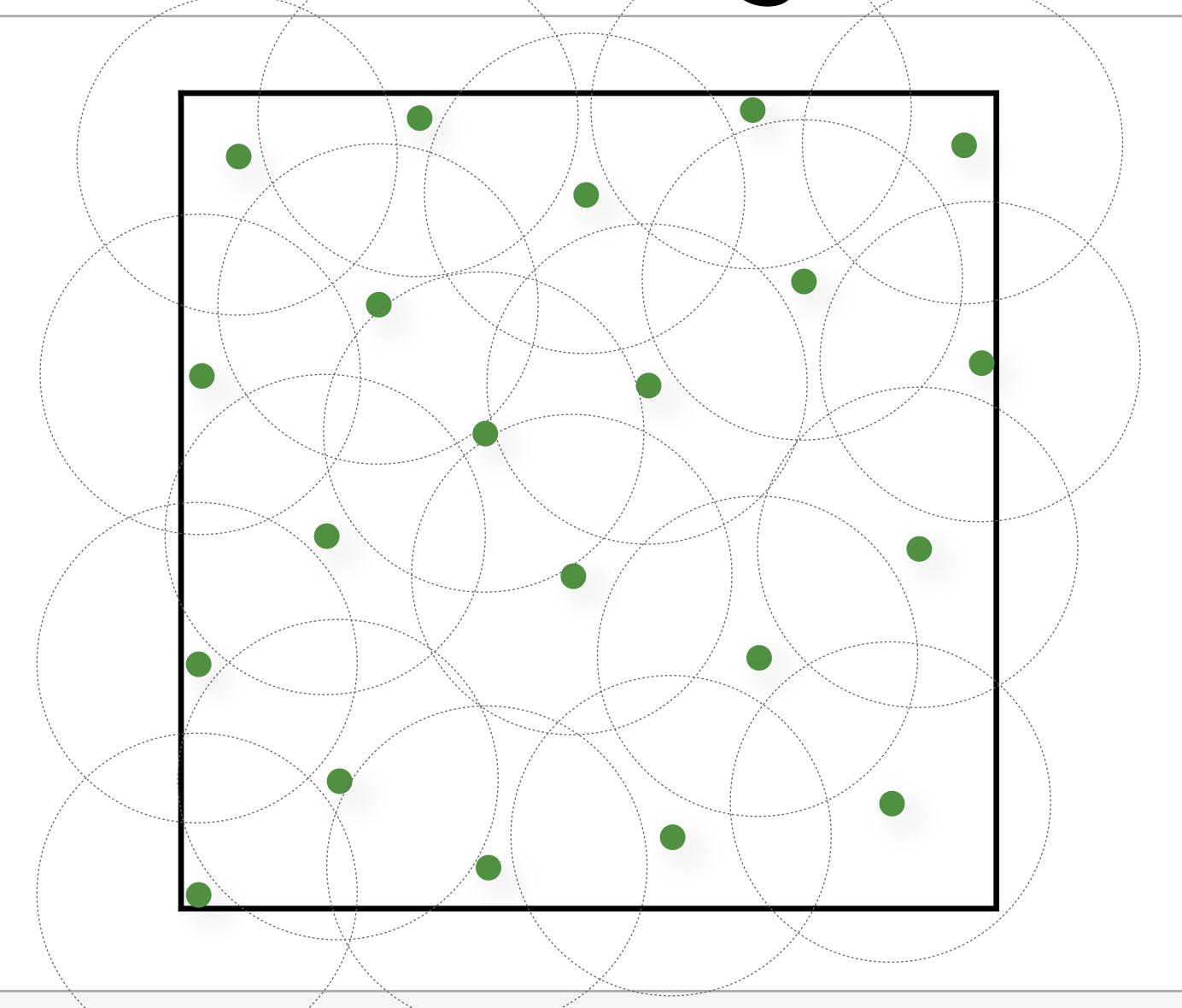




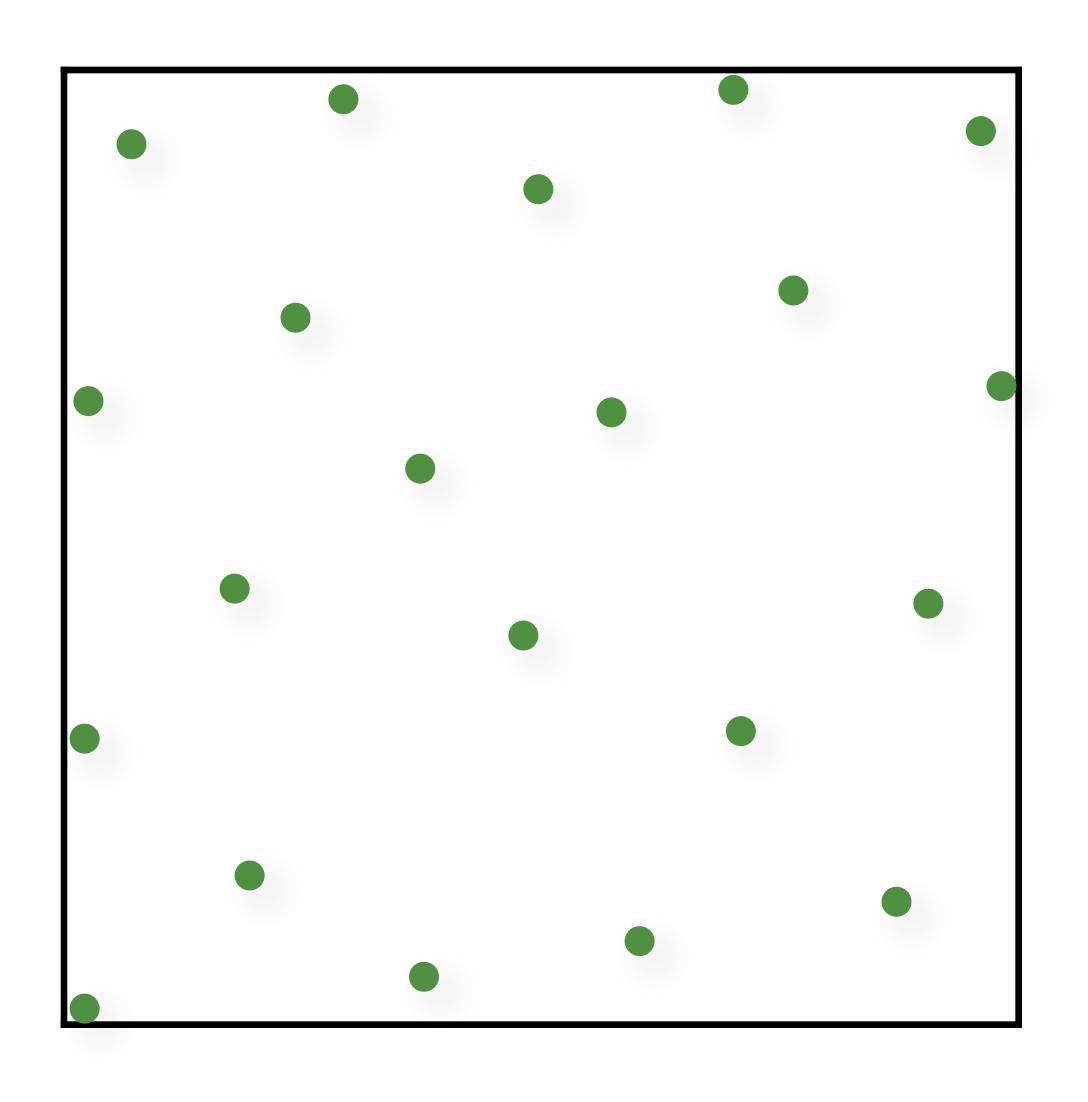






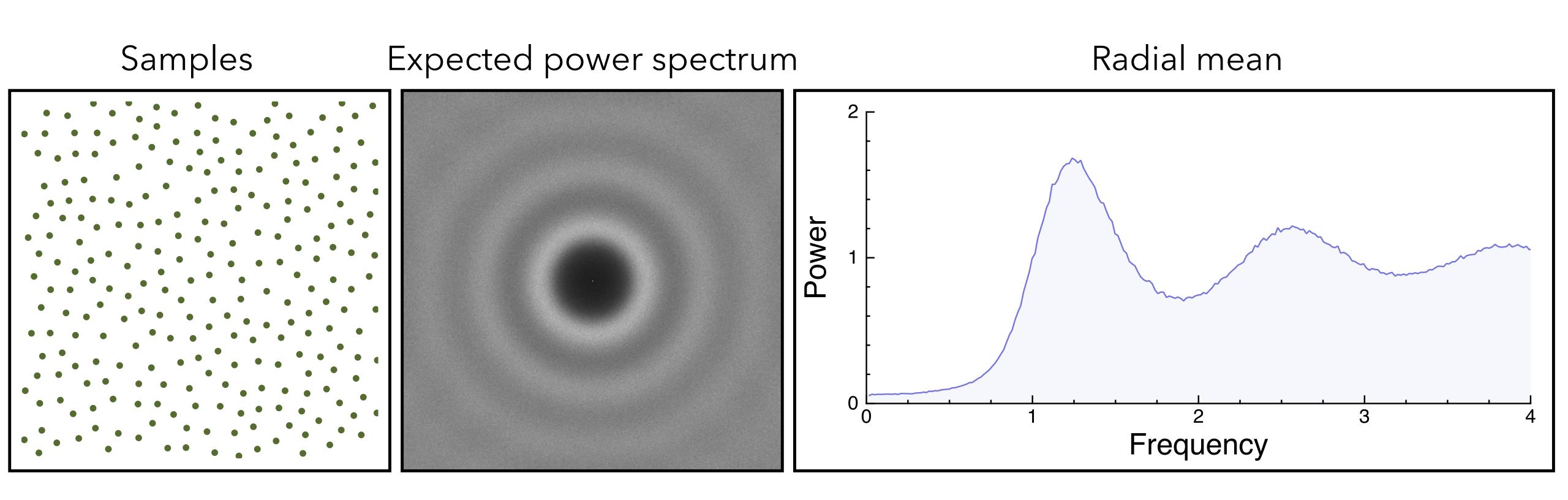








## Poisson Disk Sampling



#### Blue-Noise Sampling (Relaxation-based)



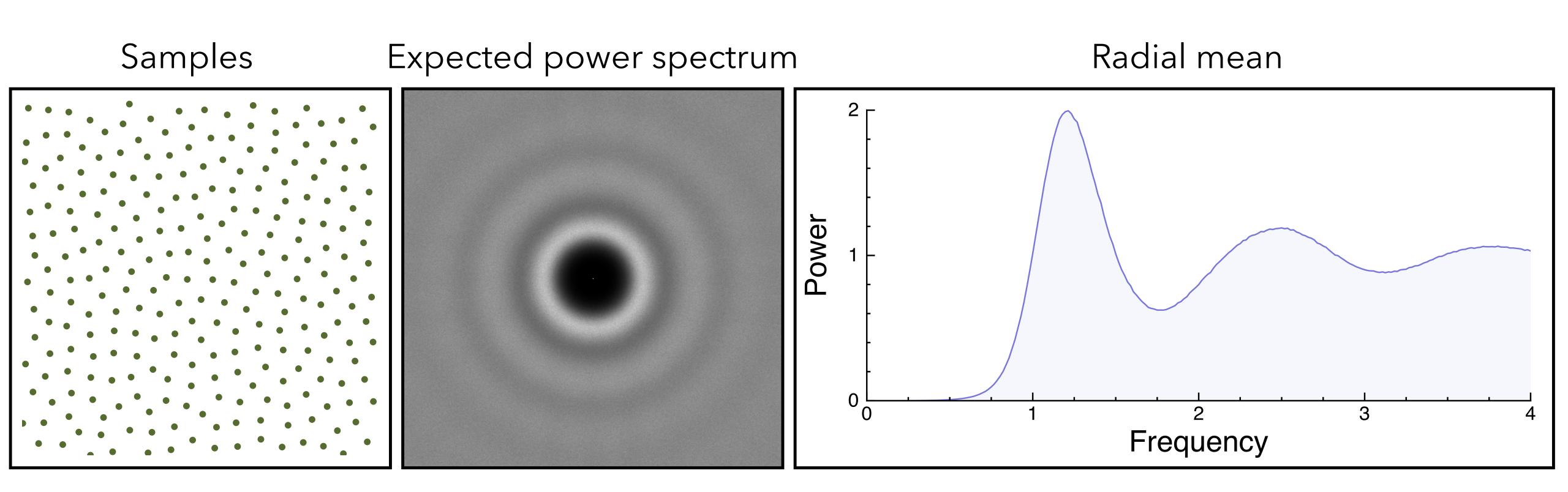
#### Blue-Noise Sampling (Relaxation-based)

1. Initialize sample positions (e.g. random)

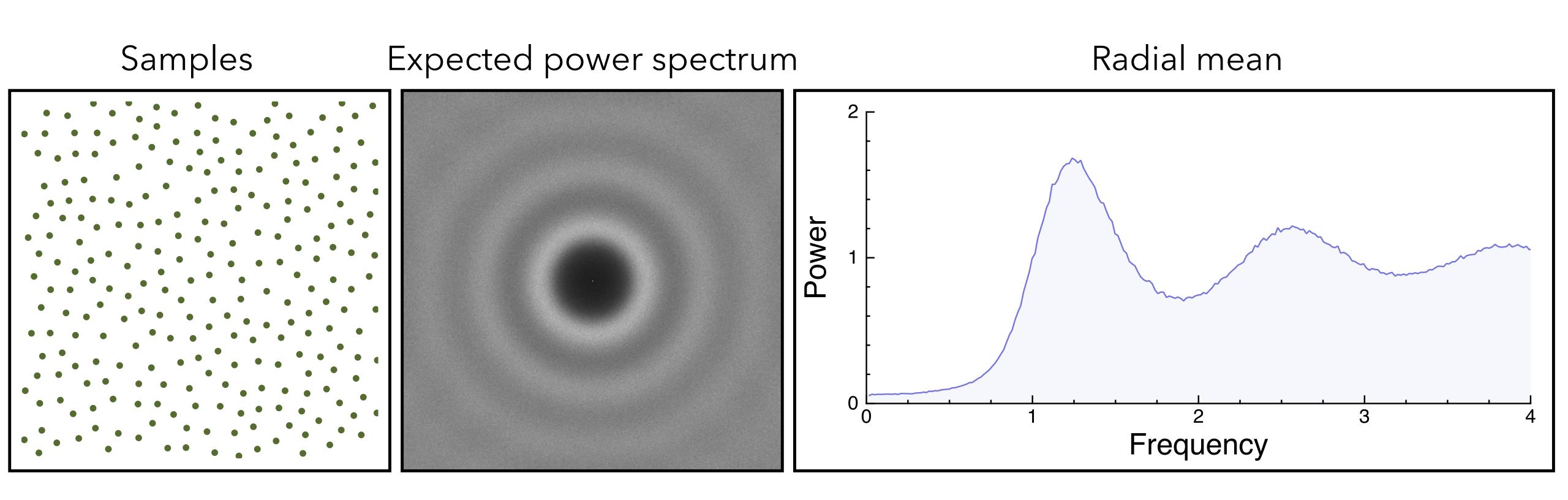
#### Blue-Noise Sampling (Relaxation-based)

- 1. Initialize sample positions (e.g. random)
- 2. Use an iterative relaxation to move samples away from each other.

## CCVT Sampling [Balzer et al. 2009]



## Poisson Disk Sampling



## Low-Discrepancy Sampling

Deterministic sets of points specially crafted to be evenly distributed (have low discrepancy).

Entire field of study called Quasi-Monte Carlo (QMC)



Radical Inverse  $\Phi_b$  in base 2

$ k $   Base 2   $\Phi_b$	
---------------------------	--



Radical Inverse  $\Phi_b$  in base 2

k	Base 2	$\Phi_b$
1	1	.1 = 1/2

Radical Inverse  $\Phi_b$  in base 2

K	Base 2	$\Phi_b$
1	1	.1 = 1/2
2	10	.01 = 1/4

Radical Inverse  $\Phi_b$  in base 2

K	Base 2	$\Phi_b$
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4

Radical Inverse  $\Phi_b$  in base 2

k	Base 2	$\Phi_b$
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8

Radical Inverse  $\Phi_b$  in base 2

k	Base 2	$\Phi_b$
1	1	.1 = 1/2
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4	100	.001 = 1/8
5	101	.101 = 5/8



Radical Inverse  $\Phi_b$  in base 2

k	Base 2	$\Phi_b$
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8



Radical Inverse  $\Phi_b$  in base 2

K	Base 2	$\Phi_b$
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8



Radical Inverse  $\Phi_b$  in base 2

K	Base 2	$\Phi_b$
1	1	.1 = 1/2
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4	100	.001 = 1/8
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6	110	.011 = 3/8
7	111	.111 = 7/8



Halton: Radical inverse with different base for each dimension:

$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

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$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

- The bases should all be relatively prime.

Halton: Radical inverse with different base for each dimension:

$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

- The bases should all be relatively prime.
- Incremental/progressive generation of samples

Halton: Radical inverse with different base for each dimension:

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- The bases should all be relatively prime.
- Incremental/progressive generation of samples

Hammersley: Same as Halton, but first dimension is k/N:

$$\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

Halton: Radical inverse with different base for each dimension:

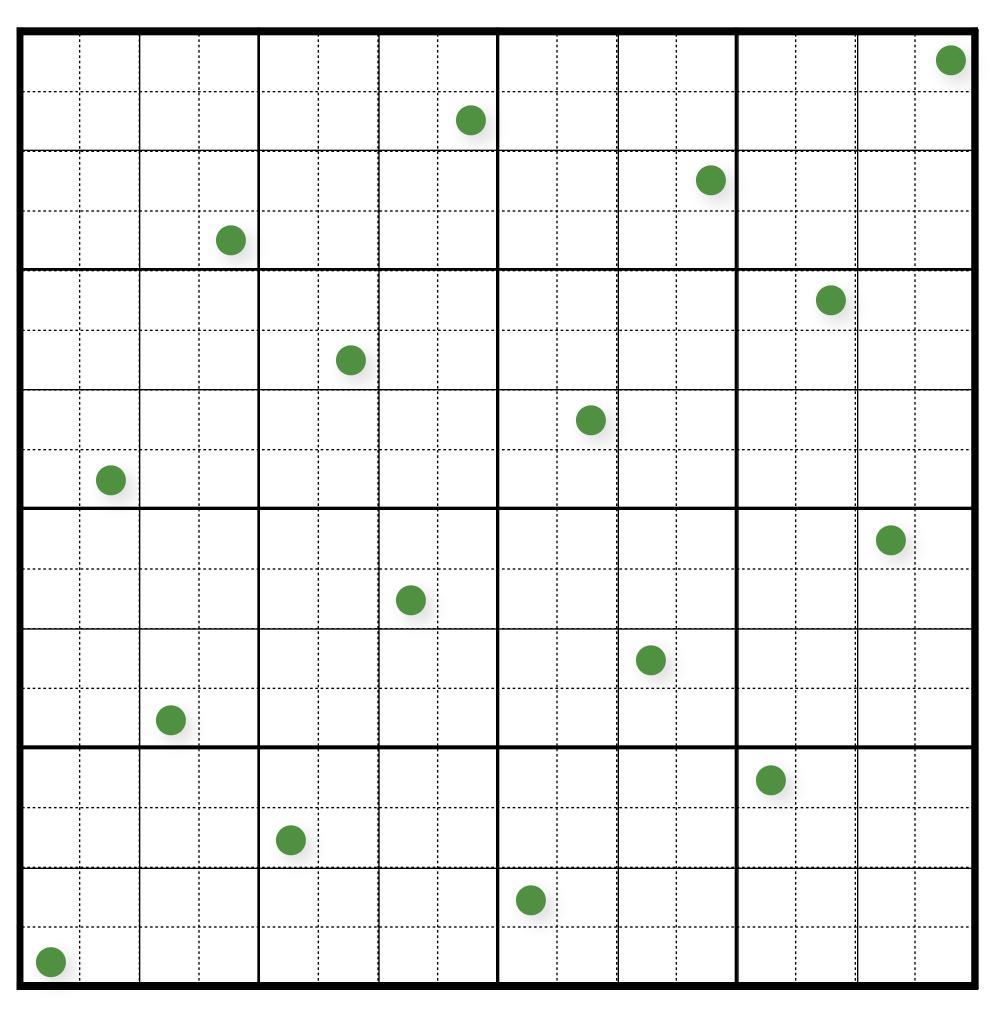
$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

- The bases should all be relatively prime.
- Incremental/progressive generation of samples

Hammersley: Same as Halton, but first dimension is k/N:

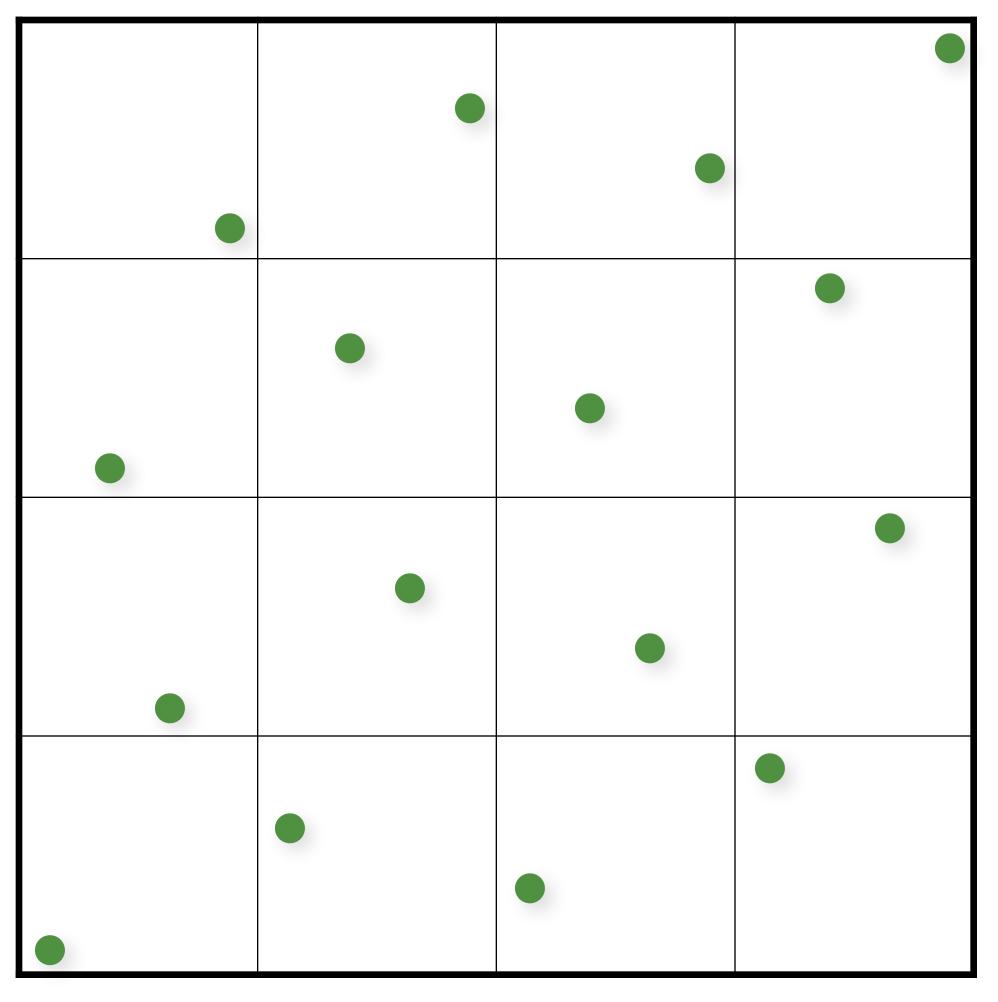
$$\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

- Not incremental, need to know sample count, N, in advance



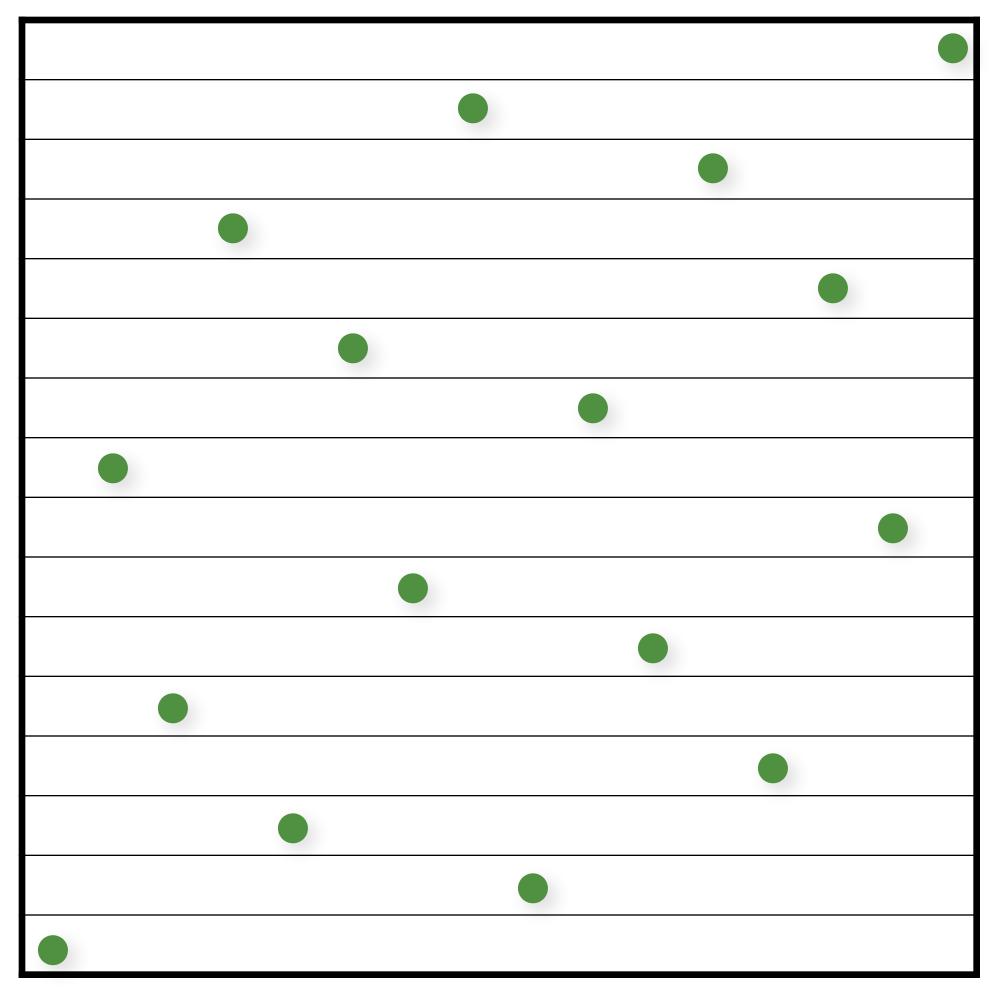
1 sample in each "elementary interval"





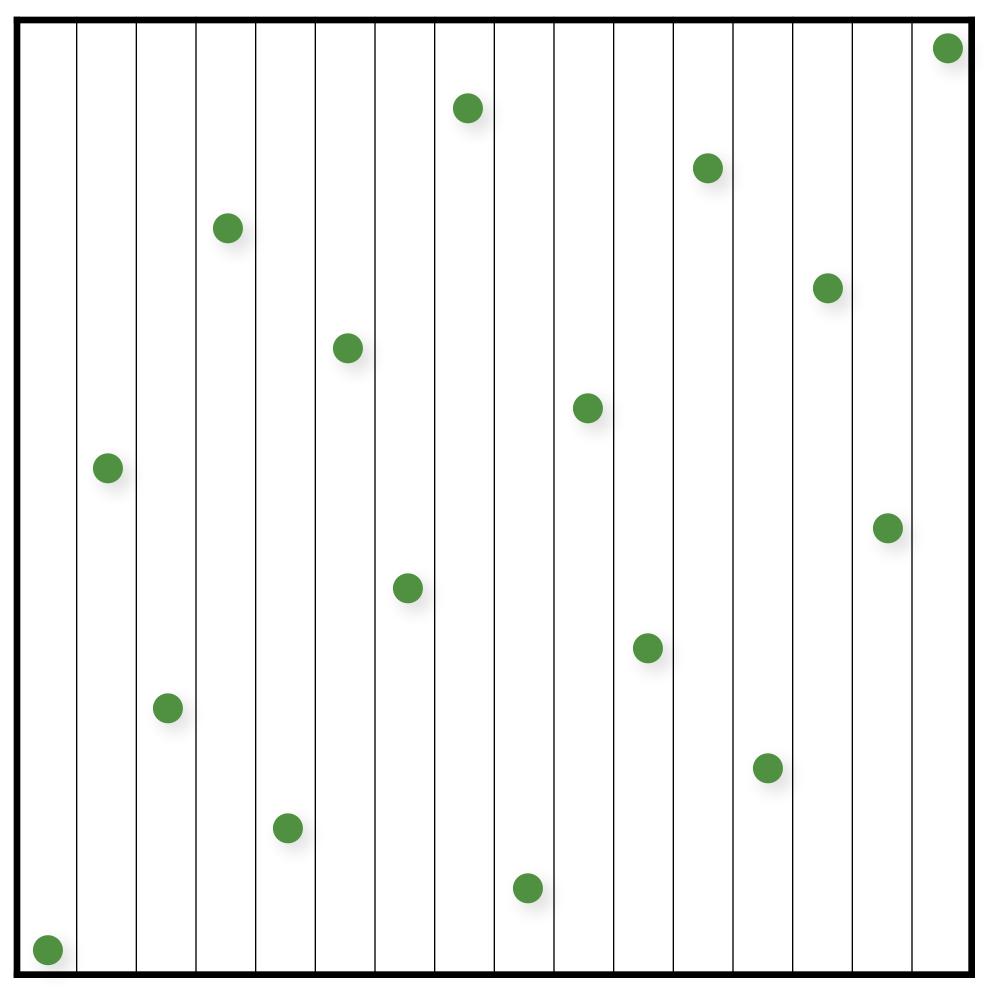
1 sample in each "elementary interval"





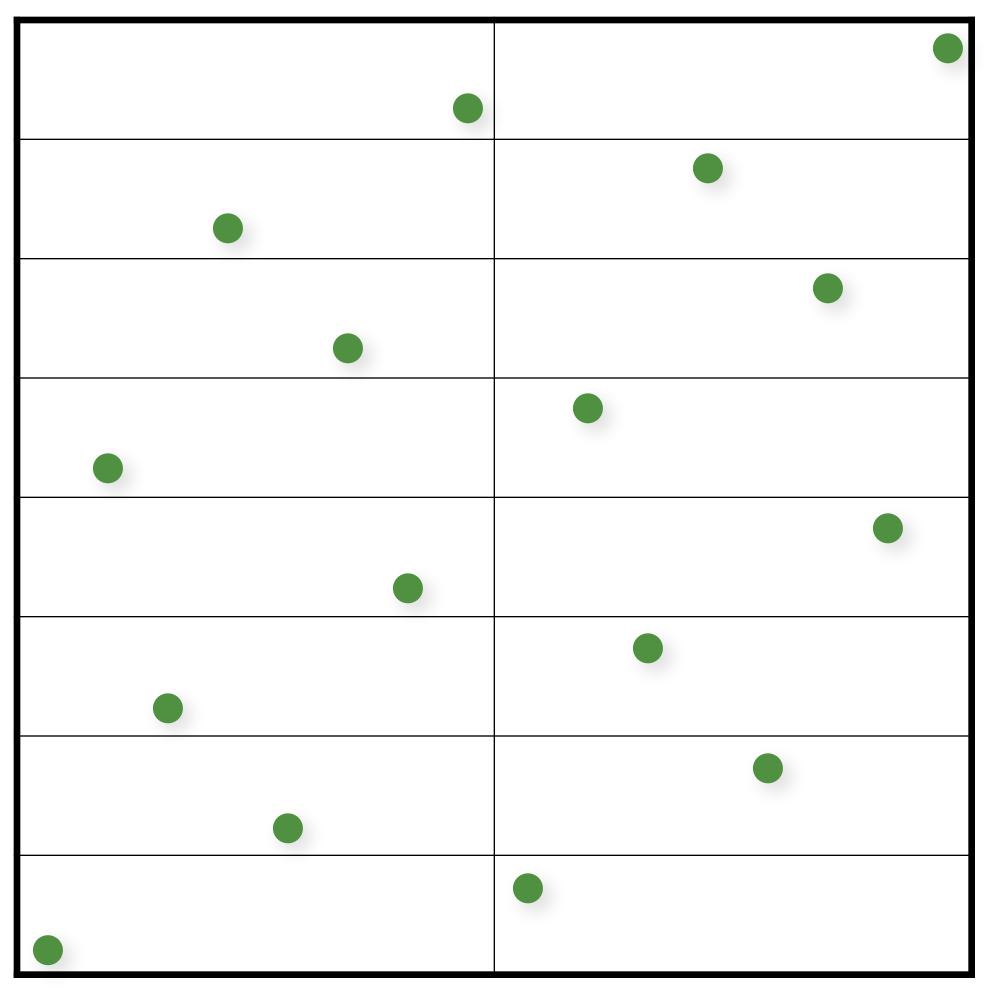
1 sample in each "elementary interval"





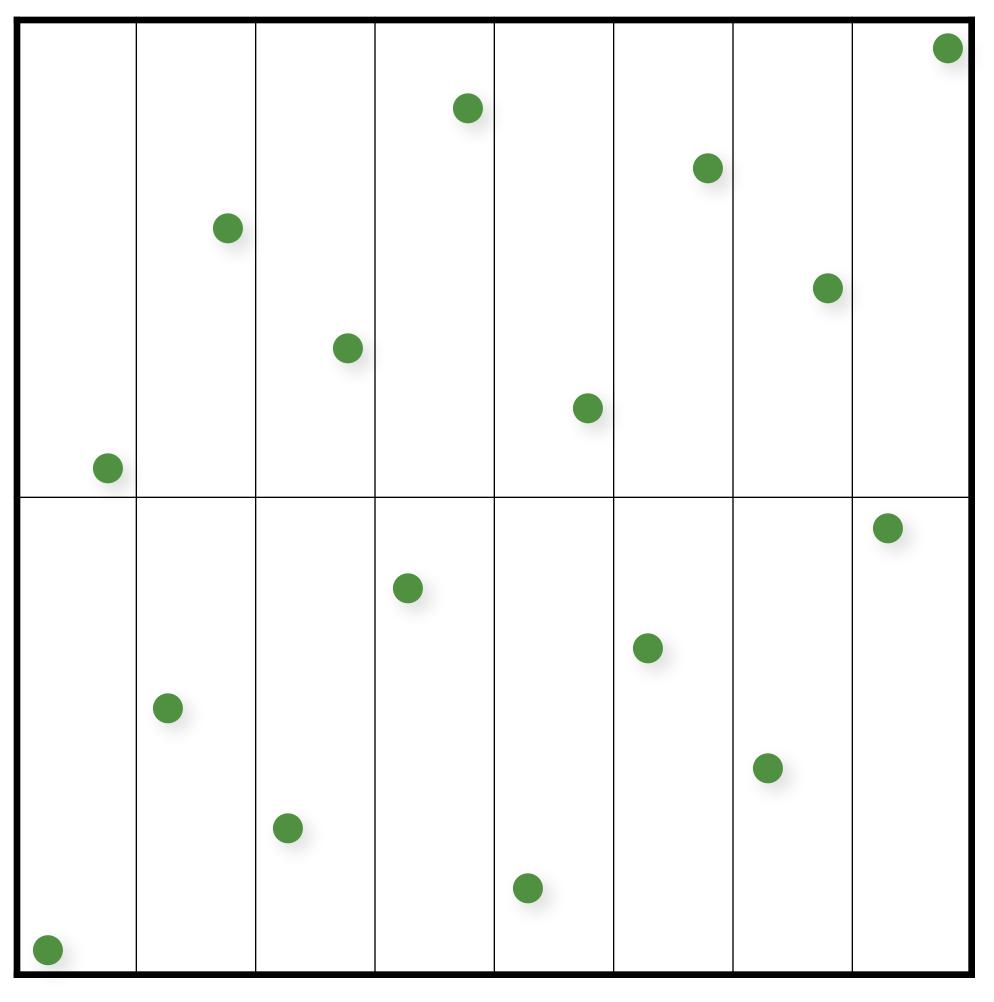
1 sample in each "elementary interval"





1 sample in each "elementary interval"

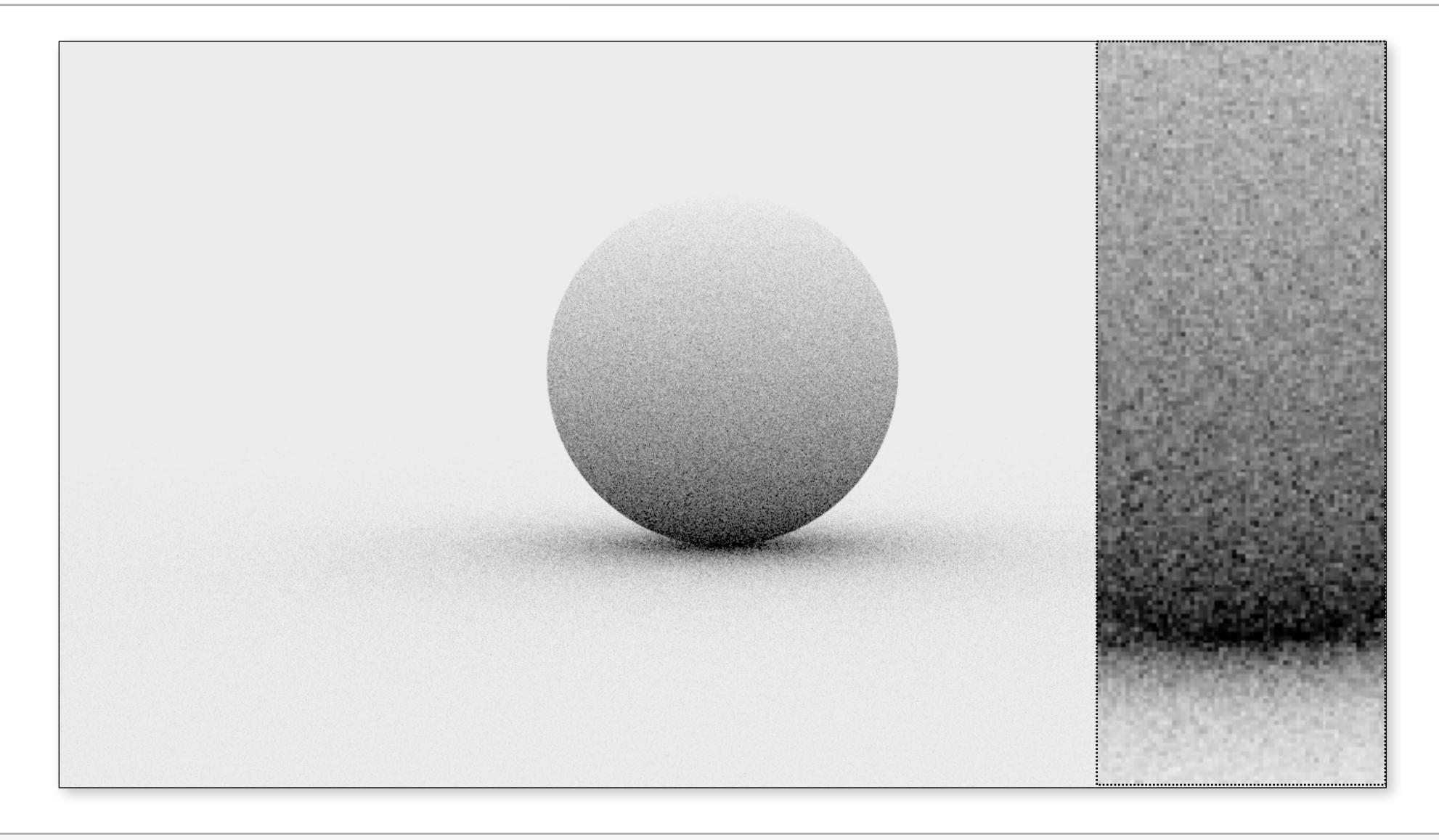




1 sample in each "elementary interval"

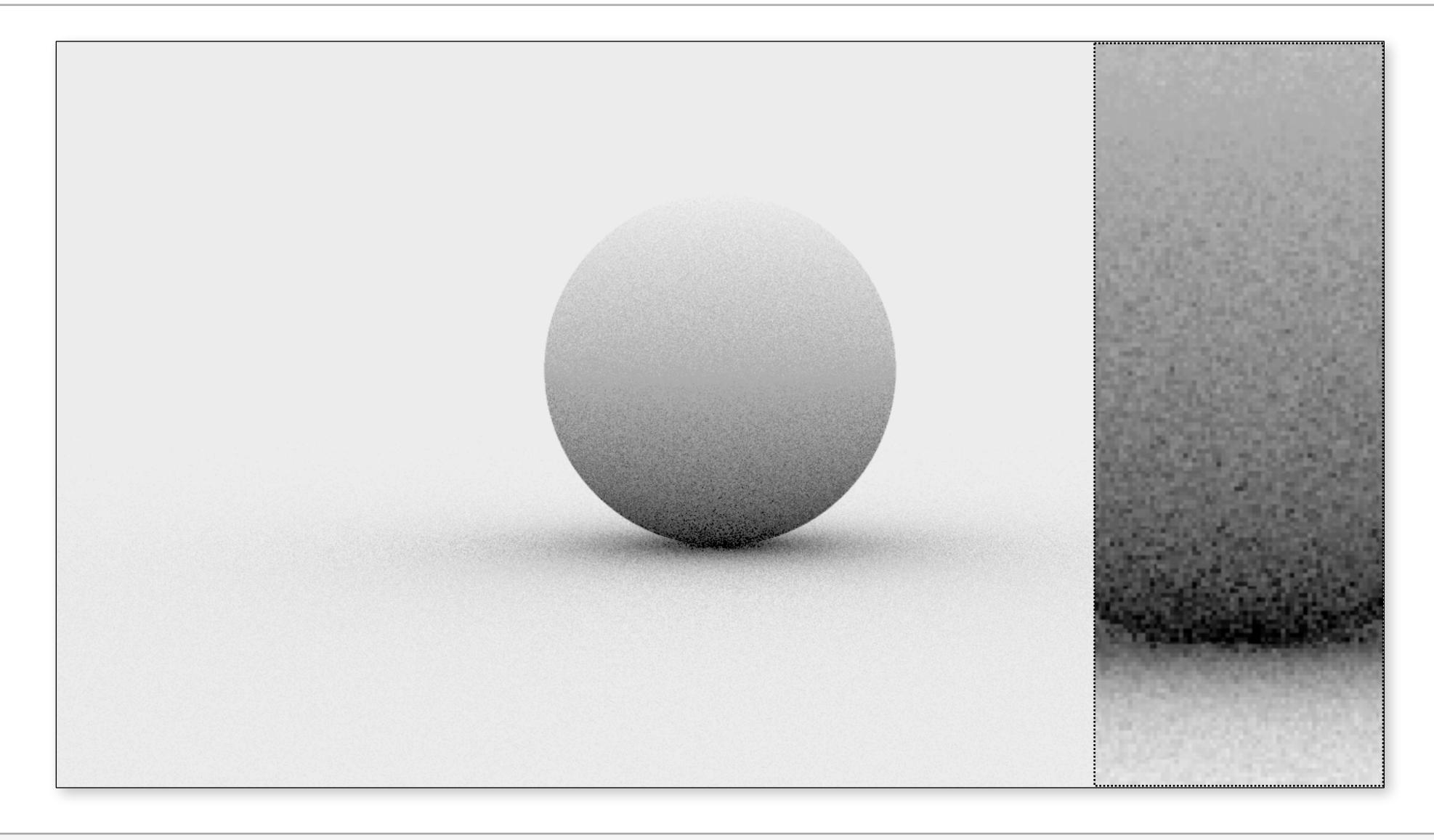


#### Monte Carlo (16 random samples)



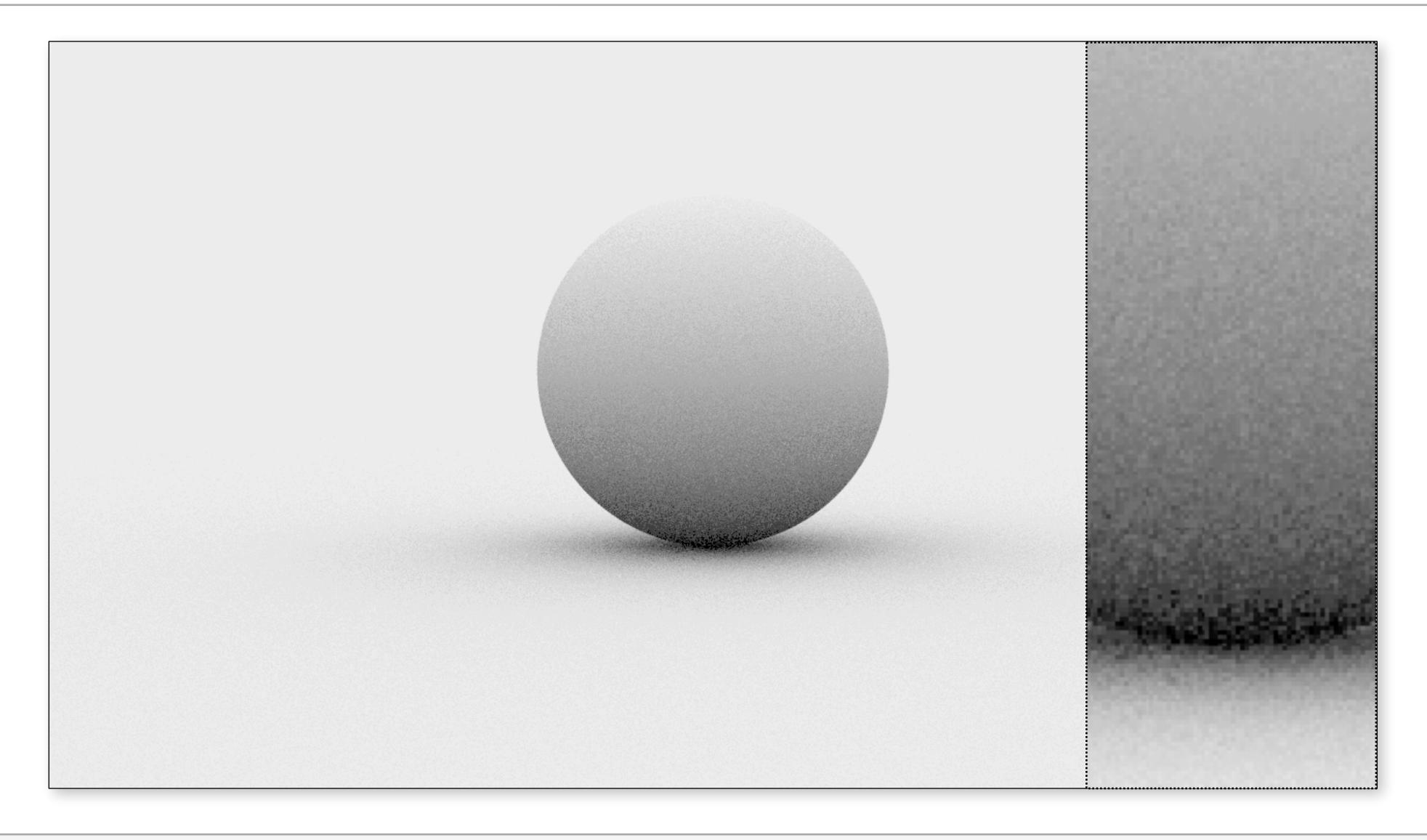


# Monte Carlo (16 jittered samples)





# Scrambled Low-Discrepancy Sampling





#### More info on QMC in Rendering

S. Premoze, A. Keller, and M. Raab. *Advanced (Quasi-) Monte Carlo Methods for Image Synthesis.*In SIGGRAPH 2012 courses.

#### How can we predict error from these?

