Tools of computational neuroscience : Models of neurons

Readings: D&A Chapter 5. Izhikevich, 2004, 'which model to use for cortical spiking neurons'

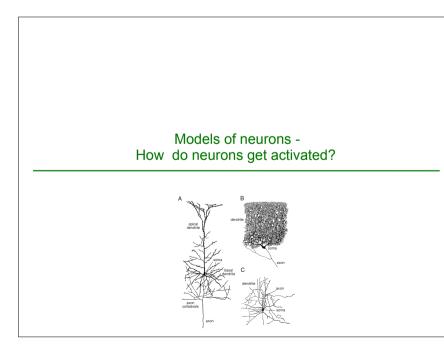
Types of models: descriptive vs explanatory

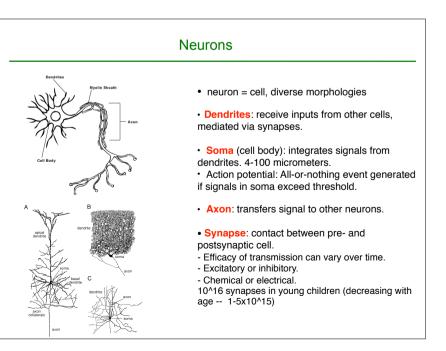
• Until now, descriptive/phenomenological models of statistics of responses (spike count). short hand for describing neural data. (what) [question: knowing the statistics of the response, how can we relate the responses with behavior?]

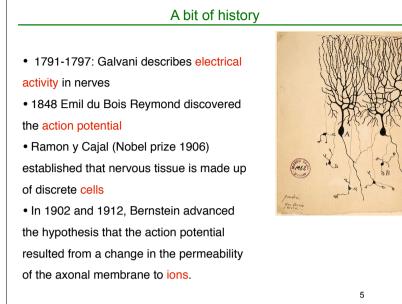
• explanatory -- mechanistic models / dynamical systems -- circuits [questions: what are the mechanisms & circuits involved? what is the influence of some part of the circuit (e.g. inhibition/neuromodulator/dynamic synapses) on global behaviour? (e.g. gain modulation/oscillations/ variability)]

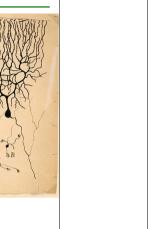
Identify the building blocks of brain function. (how)

• Multiple level of abstraction are possible/ Neurons and Networks.









Hodgkin & Huxley (1952)

- Cambridge (1935-1952)
- · experimental measurements theory of the

action potential

Used the giant axon of the squid which enabled them to record ionic currents
voltage clamp technique: to measure ionic currents across membrane by holding potential constant.

http://www.youtube.com/watch?v=k48jXzFGMc

Point neurons (1)

- We describe the membrane potential by a single variable V.
- membrane capacitance: Due to excess of negative charges inside the neuron, positive charges outside the neuron, membrane acts like a capacitor
- V and the amount of charges Q are related by the standard equation for capacitor: $Q = C_m V \label{eq:Q}$
- From this we can determine how V changes when charges change:

$$C_m \frac{dV}{dt} = \frac{dQ}{dt} = -i_n$$

here, by convention i_m is positive outwards

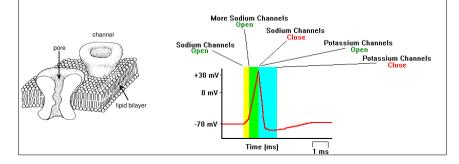
This is the basic equation used to model neurons.

$$C_m \frac{dV}{dt} = -\sum_{ion} I_{ion} + I_{ext}(t)$$
-Q

+Q

Membrane potential and action potential

- lons channels across the membrane, allowing ions to move in and out, with selective permeability (mainly Na+, K+, Ca2+,Cl-)
- Vm: difference in potential between interior and exterior of the neuron.
- at rest, Vm~-70 mV (more Na+ outside, more K+ inside, due to N+/K+ pump)
- Following activation of (Glutamatergic) synapses, depolarization occurs.
- if depolarization > threshold, neuron generates an action potential (spike) (fast 100 mv depolarization that propagates along the axon, over long distances).



Point neurons (2)

$$C_m \frac{dV}{dt} = -\sum_{ion} I_{ion} + I_{ext}(t)$$

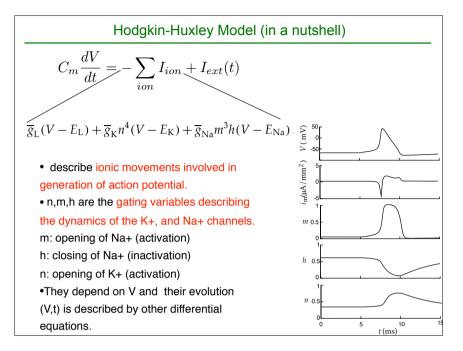
• The ion movements are due to channels that are open all the time (leakage), or that open at specific times, dependent on V, e.g. to generate action potential, or following synaptic events.

• Each current can be described in terms of a conductance g_i and equilibrium or reversal potential E_i . E_i describes the value of potential at which the current would stop, because the forces driving the ions (diffusion and electric forces) would cancel.

$$I_i = g_i (V - E_i)$$

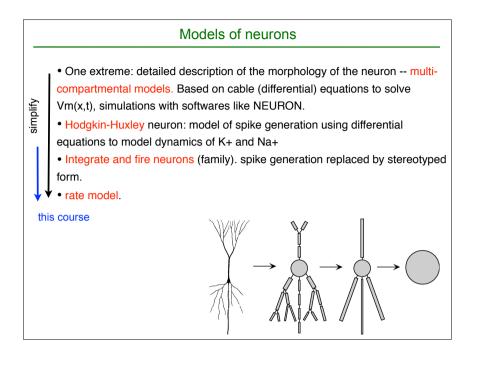
A conductance with reversal potential E_i will tend to move Vm towards E_i E_{K+} ~-70--90 mV, E_{Na+} ~50mV, E_{cl-} ~-60mV--65mV.

Hodgkin-Huxley Model (in a nutshell)	
 n,m, and h are also described using differential equations 	
$dm/dt=a_m(V)(1-m)-b_m(V)m$ $a_m(V)$	V) = opening rate $b_n(V)$ = closing rate V) = opening rate $b_m(V)$ = closing rate V) = opening rate $b_h(V)$ = closing rate
$a_{n} = (0.01(V+55))/(1-\exp(-0.1(V+55)))/(1-\exp(-0.1(V+40)))/(1-\exp(-0.1(V+40)))/(1-\exp(-0.1(V+40)))/(1-\exp(-0.05(V+65)))$	



HH : Conclusion

- The Hodgkin Huxley model : one of the most influential models of computational neuroscience
- In terms of models 3 success: (1) good model system (2) introduction of computers (3) right level of details for describing phenomenon --> link microscopic ion channels to macroscopic currents and AP.
- Led to many predictions and experiments, e.g. gating charge movements, that Na+ and K+ channels were separate molecular identities with different pore sizes, other dynamics.
- most biophysical models of spiking neurons still based on H-H equations.



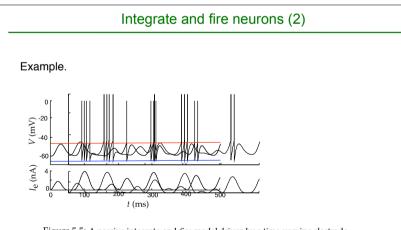


Figure 5.5: A passive integrate-and-fire model driven by a time-varying electrode current. The upper trace is the membrane potential and the bottom trace the driving current. The action potentials in this figure are simply pasted onto the membrane potential trajectory whenever it reaches the threshold value. The parameters of the model are $E_{\rm L} = V_{\rm reset} = -65$ mV, $V_{\rm th} = -50$ mV, $\tau_{\rm m} = 10$ ms, and $R_{\rm m} = 10$ MΩ.

Integrate and fire neurons (1)

1. Only describe ion movements due to channels that are open all the time (leakage)= passive properties.

$$C_m \frac{dV}{dt} = -g_l (V - E_L) + I_{ext}(t)$$

Can be also written, using $R_m C_m = \tau_m$

EL= resting potential; R_m=1\g_I = membrane resistance; tau_m= membrane time constant;

 $\tau_m \frac{dV}{dt} = -V + E_L + R_m * I_{ext}(t)$

2. When $V>V_{thres}$ (e.g. -55 mV) an action potential is triggered (V set to V_{spike} (e.g. 50 mV)) and V reset to V_{reset} e.g. -75 mV.

Integrate and fire neurons (3)

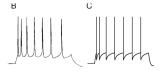
• The firing rate of an integrate and fire neuron in response to a constant injected current can be computed analytically (cf D&A).

• Integrate and fire neurons = <u>a family of models</u>.

Inputs can be modeled as a current, or conductances (better model of synapses).

• Can be modified to account for a repertoire of dynamics e.g. can include a model of refractoriness and spike rate adaptation (and more)

• conductance-based IAF: these phenomena + inputs are modelled using added conductances.



spike rate adaptation

Integrate and fire neurons (4): adding spike rate adaptation

• spike rate adaptation can be modeled as an hyperpolarizing K+ current

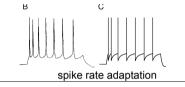
$$\tau_m \frac{dV}{dt} = E_L - V - r_m g_{sra}(t)(V - E_K) + R_m I_d$$

• when neuron spikes, gsra is increased by a given amount:

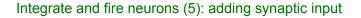
$$g_{sra} \to g_{sra} + \Delta g_{sra}$$

- the conductance relaxes to 0 exponentially with time constant $\ au_{sra}$

$$\tau_{sra} \frac{dg_{sra}(t)}{dt} = -g_{sra}(t)$$



Conductances triggered by spiking are used to model refractory period, bursting... Synaptic input can be modeled similarly (but triggered by presynaptic spike)



• Synaptic inputs are modeled as depolarizing or hyperpolarizing conductances

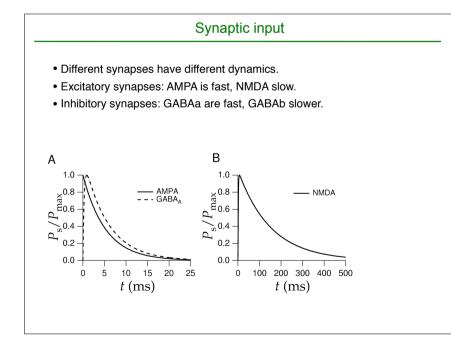
$$\tau_{\rm m} \frac{dV}{dt} = E_{\rm L} - V - \overline{r_{\rm m} \overline{g}_{\rm s} P_{\rm s} (V - E_{\rm s})} + R_{\rm m} I_{\rm e} \,.$$

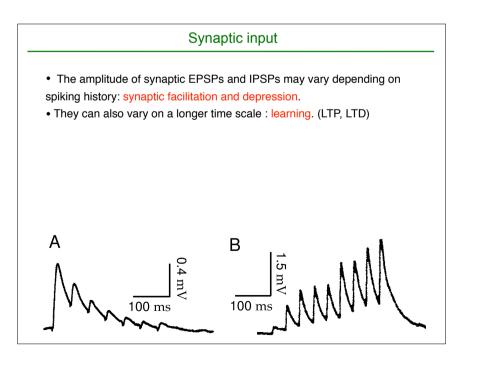
• Each time a presynaptic spike occurs (+ synaptic delay), P_s is modified. For example, Ps can be modeled using an alpha-function:

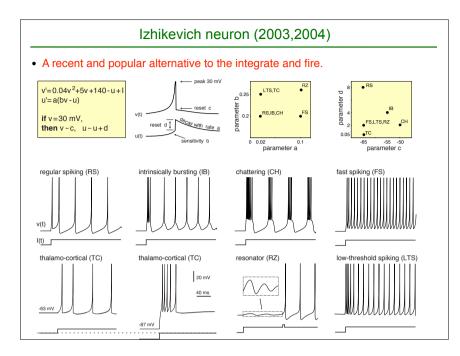
$$P_s(t) = \frac{P_{max}t}{\tau_s} \exp(1 - \frac{t}{\tau})$$

• a variety of models can be used for Ps depending on dynamics that we want to account for (slow/fast synapses)

• Es=0 for excitatory synapses, Es=-70--90 mV for inhibitory synapses.







On Numerical Integration

- Sometimes the differential equations can be solved analytically
- Usually though, they are solved numerically
- The simplest method is known as Euler's method: a system

$$\frac{dy}{dt} = f(y)$$

can be simulated by choosing the initial condition y(0) and repeatedly performing the Euler integration step:

$$y(t+dt) = y(t) + dtf(y)$$

Higher order and adaptive methods, such as Runge-Kutta are commonly used (check 'numerical recipes', matlab ode23, ode45, and Hansel et al 1998 for an evaluation of such methods with IAF neurons).