

The case for reactive objects

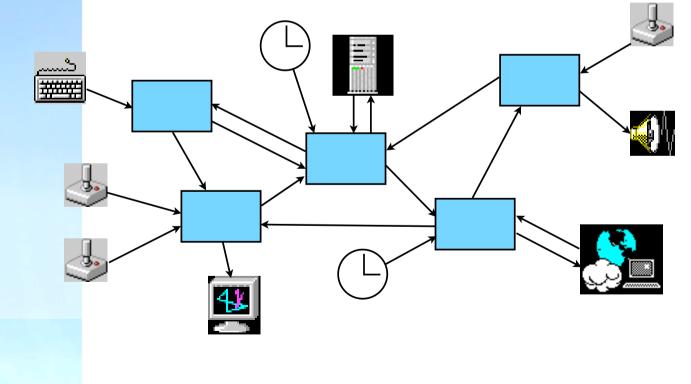
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Links meeting, April 6

Links killer apps

A challenge to implement!

- Web services...
- 🔘 Ga<mark>mes...</mark>
- Web-based games...



Particular challenges

Multiple, asynchronous inputs

 Languages tend to allow only one input at a time (read symmetric to write)

O Distributed state and concurrency

- Languages tend to decouple state from concurrency
 - OO languages structure according to state, concurrency aspect crosscuts the OO design
 - Concurrent languages structure around threads, shared state must be manually protected

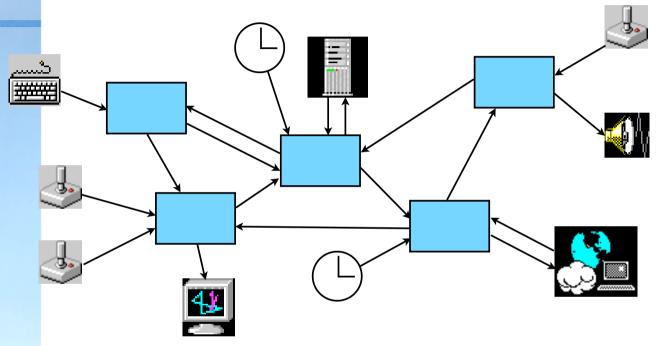


Erlang

- Supports blocking for multiple messages
- Lets state follow a process
- O However, Erlang is
 - untyped
 - not referentially transparent
 - still dependent on encodings, in order to support a model of communicating boxes
 - event-loop pattern
 - restricted use of the blocking op receive
 - disciplined use of message tags



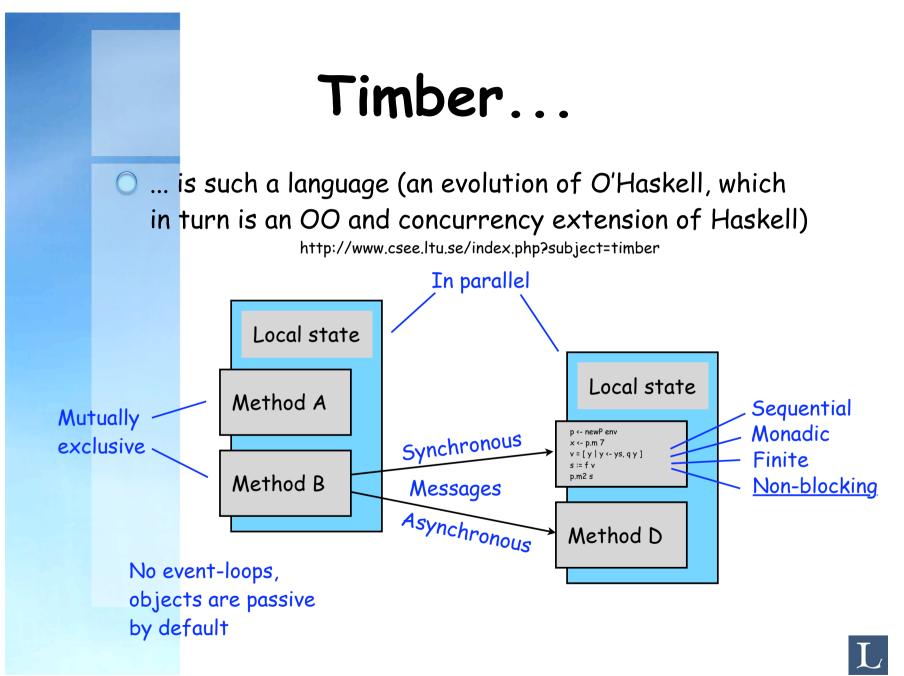
Back to our boxes



Notice the OO intuition!

What stops languages from directly supporting boxes that are <u>both</u> objects (encapsulating a state, communicating with messages) and processes (evolving in parallel)?





The role of objects

Core programming model:

Every object is a process

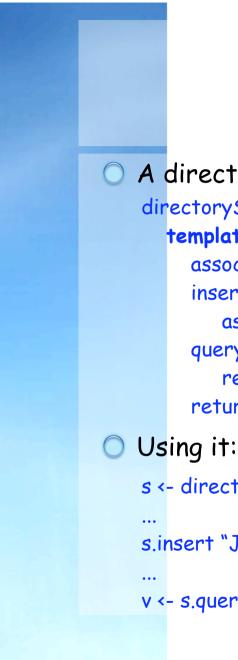
Equally important:

Everything is not an object!

- Values (lists, trees, records, functions, ...) replace most uses of objects in traditional OO
- Timber objects correspond closely to Erlang processes (including efficiency implications)
- Timber is strict, and purely functional (in the Haskell sense), with a stratified formal semantics (λ+CHAM)

Also first-class: methods (important for callbacks)





Example

A directory server: directoryServer = template assoc := [] insert k v = action assoc := (k,v) : assoc query k = request return (lookup k assoc) return (Directory {...})

s <- directoryServer ... s.insert "Johan" 12345 ... v <- s.query "Johan" In Erlang: serverloop(Assoc) ->
 receive
 {insert, K, V} ->
 serverloop([{K,V}|Assoc]);
 {query, K, Pid} ->
 Pid ! {reply,lookup(K,Assoc)},
 serverloop(Assoc)
 end.

S = spawn(fun()->serverloop([]) end),

S!{insert, "Johan", 12345},

```
S! {query, "Johan", self()},
receive {reply,V} -> ... end
```

Types

- Message-passing = calling methods
- Object/process interfaces can thus be described as a product of methods (c.f. using channels and sum types):

struct Directory a =

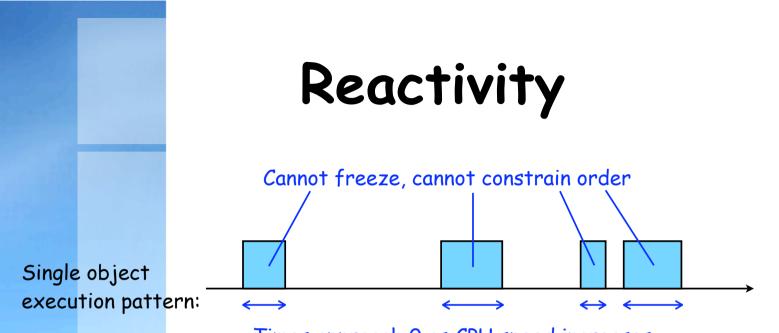
insert :: Key -> a -> Actionasynchronous methodquery :: Key -> Request (Maybe a)synchronous method

 Note that communication semantics, including rendezvous result, is visible in types

O Unreliable communication can also be captured:

unreliable_query :: Key -> (Maybe a -> Action) -> Action

In general, object interfaces can be <u>any data structure</u> containing methods, and a single object can support <u>multiple interfaces</u>



Times approach 0 as CPU speed increases

Objects are "always" responsive

Events unify with method <u>calls</u> (never with returns)

Decentralized event-handling by every object

Close to the plain communicating-boxes-model (no stuck states that transparently hook up clients)



More

Components:

comp1 :: A -> Template B
comp2 :: B -> Template C
comp3 = comp1 <||> comp2
comp3 :: A -> Template C

- Declare object generators, not objects directly (stateless source code)
- No global interfaces, object dependencies through parameters only
- Nominal subtyping system, integrated in qualified types framework
- Upper and lower time-constraints on methods (timedriven behavior and deadline scheduling)



Last slide

Reactive objects (à la Timber) offers:

- event handling and concurrency, with enforced
 - state encapsulation
 - state protection (mutual exclusion)
 - responsivity
- object-orientation (not in the Java sense, but in the classical modelling sense)
- type-safe communication with precise interfaces
- a matching context for purely functional programming
- **Would any of that fit into Links**?

